

# UM7106R/07AR/07BR

## 3 1/2-Digit A/D Converter

#### Features

- Guaranteed zero reading with zero input
- True polarity indication for precision null detection
- Low noise
- Convenient 9V battery operation
- Low power operation-10mW
- High Impedance CMOS differential inputs 10<sup>12</sup> Ω
- True differential input and reference

- Direct display drive for UM7106R LCD, UM7107AR/BR LED
- No additional active components required
- Low linearity error: guaranteed less than 1 count
- Internal reference with low temperature drift
- Applications: digital panel meters, digital multimeters, thermometers, capacitance meters, PH meters, photometers etc.

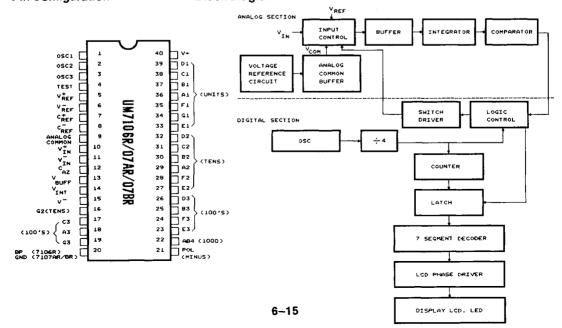
### **General Description**

The UM7106R and UM7107AR/BR are high performance, low power 3 1/2-digit A/D converters. All the necessary active devices are contained in a single CMOS IC, including seven-segment decoder, display driver, voltage reference and clock. UM7106R is designed to interface with a liquid crystal display (LCD) and UM7107AR/BR will directly drive an instrument-sized light emitting diode (LED) display. The UM7106R and UM7107AR/BR

bring the combination of high accuracy,versatility and economy. High accuracy, like auto-zero to less than 100  $\mu V$  for 2.000V full-scale measurement, or  $10 \mu V$  for 200.0 mV full-scale measurement, input bias current of 10pA max, and rollover of less than one count. The versatility of true differential input and voltage reference is useful in all systems, such as strain gauges or bridge-type tranducers.

#### Pin Configuration

### **Block Diagram**



 $V \cap V \cap V \cap V \cap V \cap V$ 



## **Absolute Maximum Ratings\***

Supply Voltage (V+ to V-)
Analog Input Voltage (either input) V+ to V-
Reference Input Voltage (either input) V+ to V-
Clock Input Test to V+
Power Dissipation 800mW
Operating Temperature 0°C to +70°C
Storage Temperature
Lead Temperature (Soldering, 60 sec)

#### \*Comments

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only. Functional operation of this device at these or any other conditions above those indicated in the operational sections of this specification is not implied and exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## **DC Electrical Characteristics**

Unless otherwise noted, specifications apply to UM7106R at  $V_{supply}$  ( $V^{\dagger}$  to  $V^{-}$ ) = 9.0V, and UM7107AR/BR at  $V_{supply}$  ( $V^{\dagger}$  to  $V^{-}$ ) = 10.0V

Ta = 25°C, f clock = 48 KHz, UM7106R is tested in the CKT of Fig 8, UM7107AR/BR is tested in the CKT of Fig 9.

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Zero input Reading	-	-000.0	±000.0	+000.0	Digital Reading	Vin = 0.0V Full Scale = 200.0mV
Ratiometric Reading	-	999	999/1000	1000	Digital Reading	Vin = Vref Vref = 100.0mV
Linearity (Max. Deviation From Best Straight Line Fit)	-	-1	±0.2	+1	Counts	Full Scale 200.0 mV or 2.000V
Noise	Vn	=	15	-	μ∨	Vin = 0V Full Scale 200.0mV
Leakage Current Input	ILEAK		1	10	pA	Vin = 0V
Zero Reading Drift	-		0.2	1	μV/°C	Vin = 0 0° < TA < 70°C
Scale Factor Temp Coeff	-	_	1	5	ppm/°C	Vin = 199.0mV 0° < TA < 70°C
Analog Common Voltage (With Respect to Positive Supply)	VANA-COM	2.7	3.0	3.3	v	25K   Between  Common and Positive  Supply
Temp Coeff of Analog Common	_	<del>-</del>	20	50	ppm/*C	25K   Between  Common and Positive  Supply



## DC Electrical Characteristics (continued)

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Supply Current (Doesn't Include LED and Com. Current)	loo	_	0.8	1.8	mA	Vin = 0
UM7106R Only, Pk-Pk Segment Drive Voltage	VLCDS	4	5	6	, V	
UM7106R Only, Pk-Pk Back Plane Drive Voltage	VLCDS	4	5	6	٧	
UM7107AR/BR Only, Segment Sinking Current (Except Pin 22)	ILED	5	8.0	-	mA	Vsupply = 5.0V Segment Voltage = 3V
UM7107AR/BR Only, Segment Sinking Current (Pin 22 Only)	ILED	10	16	-	mA	Vsupply = 5.0V Segment Voltage = 3V
Rollover Error	-	-1	±0.2	+1	Counts	Vin = Vin = 200.0mV
Common-mode Rejection Ratio	-		50	200	μV/V	Vcm = ±1Vin, Vin = 0V Full-scale = 200.0mV

## Pin Description

Pin No.	Designation	Description
1	OSC1	Pins 1, 2, & 3 make up the oscillator section. For a 48 KHz clock (3 readings per Second), connect pin 1 to the junction of a 100KΩ resistor and a 100 pF capacitor. The 100KΩ resistor is tied to pin 2 and the 100pF capacitor is tied to pin 3
2	OSC2	See pin 1
3	оѕсз	See pin 1
4	TEST	Lamp test. When pulled high (to $V^{\dagger}$ ), all segments will be turned on and the display should read *-1888*. It may also be used as a negative supply for externally generated decimal points
5	V <sup>+</sup> REF	This analog input is required to generate a full-scale output (1,999 counts).Place 100 mV between pins 5 and 6 for 200.0 mV full-scale. Place 1.00 volt between pins 5 and 6 for 2.000 volt full-scale



## Pin Description (continued)

Pin No.	Designation	Description
6	VREF	See pin 5
7	CREF	A $0.1\mu F$ capacitor is used in most applications. If a large common-mode voltage exists (for example the $VIN$ pin is not at analog common), and a 200 mV scale is used, a $1.0\mu F$ capacitor is recommended which will hold the rollover error to 0.5 count
8	CREF	See pin 7
9	Analog Common	This pin is primarily used to set the analog common-mode voltage for battery operation or in systems where the input signal is referenced to the power supply
10	V <sub>I</sub> N	The analog high input signal is connected to this pin
11	VĪN	The analog low input is connected to this pin
12	Caz	The size of the auto-zero capacitor influences the system noise. Use a $0.47\mu F$ capacitor for a 200.0mV full-scale, and a $0.047\mu F$ capacitor for a 2.000 volt full-scale
13	VBUFF	Integration resistor connection. Use 47K $\Omega$ for a 200mV full-scale range and 470K $\Omega$ for 2.000V full-scale range
14	VINT	Integrator output. Connection point for integration capacitor
15	v	Negative power supply voltage
16	G2	Activates the G section of the tens display
17	СЗ	Activates the C section of the hundreds display
18	A3	Activates the A section of the hundreds display
19	G3	Activates the G section of the hundreds display
20	BP GND	LCD Backplane drive output (UM7106R) Digital Ground (UM7107AR), but keep floating for UM7107BR
21	POL	Activates the negative polarity display
22	AB4	Activates both halves of the 1 in the thousands display



## Pin Description (continued)

Pin No.	Designation	Description
23	E3	Activates the E section of the hundreds display
24	F3	Activates the F section of the hundreds display
25	B3	Activates the B section of the hundreds display
26	D3	Activates the D section of the hundreds display
27	E2	Activates the E section of the tens display
28	F2	Activates the F section of the tens display
29	A2	Activates the A section of the tens display
30	B2	Activates the B section of the tens display
31	C2	Activates the C section of the tens display
32	D2	Activates the D section of the units display
33	E1	Activates the E section of the units display
34	G1	Activates the G section of the units display
35	F1	Activates the F section of the units display
36	<b>A</b> 1	Activates the A section of the units display
37	B1	Activates the B section of the units display
38	C1	Activates the C section of the units display
39	D1	Activates the D section of the units display
40	V+	Positive supply voltage



#### **Functional Description**

An input signal to be measured is applied to the integrating capacitance for a fixed time as determined by a clock counter. The accumulated charge will be proportional to the input signal, for a fixed clock rate and constant current. The resulting integral is returned to zero by integrating a reference signal of polarity opposite that of the input signal. The length of time required for the integrator to return to zero, as measured with the clock counter to display at

output, is proportional to the average magnitude of the input signal over the integration period.

#### a. Analog Section

Fig. 1 shows the block diagram of the Analog Section for UM7106R and UM7107AR/BR. Each measurement cycle is divided into three parts. They are (1) Auto-zero [A-Z] (2) Signal integrated [INT] (3) Deintegrated [DE].

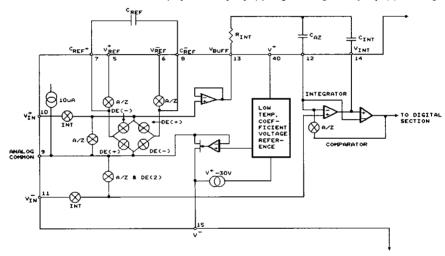


Figure 1. UM7106R/07AR/07BR Analog Section

#### 1. Auto Zero Phase

During Auto-Zero, three things happen:

- Input high and low are disconnected from PIN and shorted to analog COMMON.
- (2) The reference capacitor is charged to the reference voltage.
- (3) A feedback loop is closed around the system to charge the auto-zero capacitor CAZ to compensate for offset voltages in the buffer amplifier, integrator and comparator.

#### 2. Signal Integrate Phase

During signal integrate, the auto zero loop is opened, the internal short is removed, and the internal inputs high and low are connected to the external pins. The converter then integrates the differential voltage between input high and input low for a fixed time (1000 counts). At the end of this phase, the polarity of the integrated signal is determined.

#### 3. De-Integrate Phase

The final phase is de-integrate, or reference integrate. Input low is internally connected to Analog COMMON and input high is connected across the previously charged reference capacitor. Circuitry within the chip ensures that the capacitor will be connected with the correct polarity to cause the integrator output to return to zero. The time required to return to zero is proportional to the input signal. Specifically,the digital reading displayed is 1000 ( $\frac{\text{Ain}}{\text{Vref}}$ ).



#### b. Digital Section

Fig. 2, Fig. 3 and Fig. 4 show the digital section for the UM7106R and UM7107AR/BR, respectively. In the UM7106R, the internal digital ground is generated from a 6.2 volt Zener diode and a large p-channel follower. This supply is made stiff to absorb the relatively large capacitive current when the back plane (BP) is

switched. The BP frequency is the clock frequency divided by 800. The segments are driven at the same frequency and amplitude and are in phase with BP when OFF, but out of phase when ON. In all cases, negligible DC voltage exists across the segments.

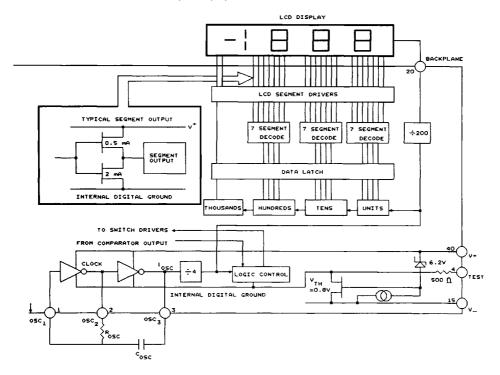


Figure 2. UM7106R Digital Section

Fig. 3 is the Digital Section of the UM7107AR. It is identical to Fig. 2. except the requlated supply and back plane drive have been eliminated and the segment drive has been increased from 2 mA to 8 mA. PIN 22 must sink current twice the drive capability.

Fig. 4 is the Digital Section of the UM7107BR. It is similar to UM7107AR except UM7107BR provides an

internal digital ground (same as UM7106R), so user does not need to provide external digital ground for UM7107BR and keep pin 20 floating. It is suggested that user place a 120  $\Omega$  resistor between V and common anode LED to limit the current into UM7107BR to gain better performance and save energy.



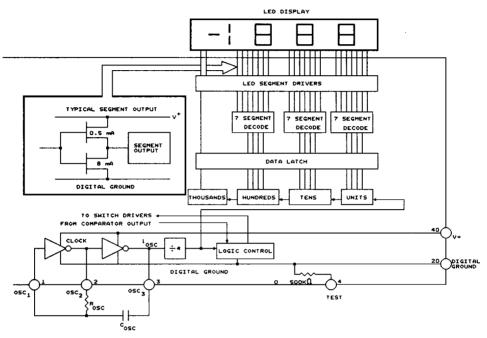


Figure 3. UM7107AR Digital Section

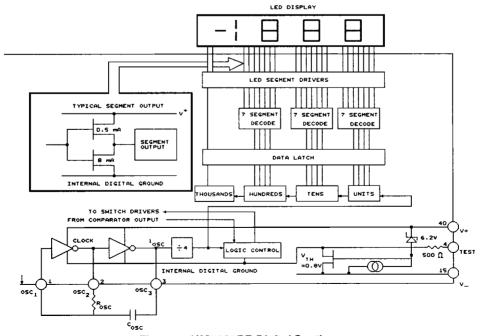


Figure 4. UM7107BR Digital Section



#### System Timing

The oscillator frequency is divided by four before it clocks the decade counters. It is then further divided to form the three convert-cycle phase. These are signal integrated (1000 counts), reference de-integrate (0 to 2000 counts) and auto-zero (1000 to 3000 counts). For signals less than full scale, auto-zero gets the unused portion of reference deintegrate. This makes complete measure cycles of 4000 (16000 clock pulses) independent of input voltage.



\* as a matter of fact, the total measurement cycle is 4001 counts for measured values less than 2000 counts. The measurement cycle becomes 4000 counts for overflow measurement.

#### **Clock Circuit:**

UM7106R/07AR/07BR may use the following three clocking methods:

- 1. An external oscillator connected to pin 1.
- 2. A crystal between pin 1 and pin 2.
- 3. An RC oscillator using all three pins (pin 1, 2 & 3).

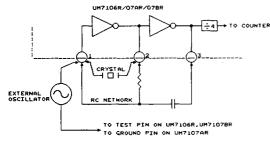


Figure 5. Clock Circuit

To achieve maximum rejection of 50/60 Hz pick up, the signal integrate cycle should be a multiple of 50/60 Hz. The following table describes the selection of oscillator frequencies for 50 or 60Hz respectively.

	Oscillator Frequencies
50 Hz	40 KHz, 50 KHz, 66 2/3 KHz, 100 KHz
60 Hz	33 1/3 KHz, 40 KHz, 48 KHz, 60 KHz, 80 KHz, 100 KHz

Note that 40KHz (2.5 readings/second) will reject both 50 and 60Hz.

#### Component Value Selection:

#### Integrating Resistor ( RINT ):

The buffer amplifier and integrator are designed with class A output stages with 100  $\mu$ A of quiescent current each. They can supply 20  $\mu$ A drive current with negligible linearity errors. RINT should be large enough to remain in linear region but small enough to reduce the leakage current on the PC board.

For 200.0mv full scale, Rint is  $47K\Omega$ ; 2.000 volt full scale needs a  $470K\Omega$  Rint.

#### Integrating Capacitor ( CINT ):

CINT should be chosen to give the maximum voltage swing without causing the saturation of integrator output swing. According to the superior temperature coefficient — 20ppm/°C of analog common will be normally used as the differential voltage reference. It is fine for a nominal ±2.000V full scale integrator output swing. For three readings/second (48KHz clock), a 0.22µF capacitor is suggested.

If a different oscillator frequency is used, CINT must be changed in inverse proportion to maintain the nominal ±2.000V full scale integrator output swing. An additional requirement of CINT is that CINT must have low dielectric absorption to minimize rollover error. Polypropylene capacitors give undetectable errors at reasonable cost.



### Reference Voltage Capacitor ( CREF ):

The reference voltage used to ramp the integrator output voltage back to zero during the reference integrate cycle is stored on CREF. A  $0.1\mu\mathrm{F}$  capacitor gives good performance when V in is tied to analog common. If a large analog common voltage exists (V REF unequal analog common) and a 200.0mV scale is used, a larger value is required to prevent rollover error. Generally  $1.0~\mu\mathrm{F}$  will hold the rollover error to 0.5 count. In this case a mylar type dielectric capacitor is adequate.

### Auto-Zero Capacitor ( Caz ):

The Caz value has some influence on system noise. The following combination is recommended:

Application	Adequate Caz
200.0mV Full Scale	0.47µF
2.000V Full Scale	0.047µF

It is better to use a mylar type capacitor to implement CAZ

#### Oscillator Components ( Rosc , Cosc ):

While using RC oscillator, the Rosc (between pin 1 and pin 2) should be 100K0 and Cosc is selected from the following equation:

Fosc = 
$$\frac{0.45}{\text{Rosc. Cosc}}$$
 (Rosc in Ma, Cosc in  $\mu$ F)

### **Reference Voltage Selection:**

The analog input required to generate full scale output (2000 counts) is Vin = 2 VREF, thus:

Required Full Scale Voltage	VREF
200.0mV	100.0mV
2.000V	1.000V

However, in many applications where A/D converter is connected to a transducer, there may exist a non-unity scale factor between the input voltage and the digital reading. For instance, a pressure transducer output is 400mV for 2000 lb/in, ather than dividing the input voltage by two, the VREF should be set to 200.0mV, then permit the transducer input to be used directly.

The differential Voltage reference can also be used to read a digital zero when Vin is not zero. This case is common in temperature measuring instrumentation. A compensating offset voltage can be applied between analog common and V IN and the transducer output is connected between V IN and analog common. The circuit is shown in Figure 6.

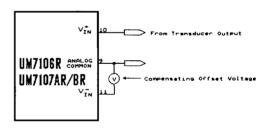
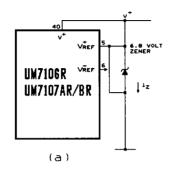


Figure 6. Circuit used to read a digital zero when V<sub>IN</sub> is not zero.



An external reference may be added to improve temperature stability; thus, the UM7106R/07AR/07BR

devices with lower analog common temperature drift may be used. The circuit is shown in Figure 7.



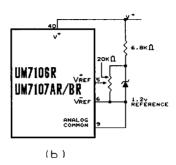


Figure 7. External Reference Voltage Circuits

Application Circuits (for reference only)

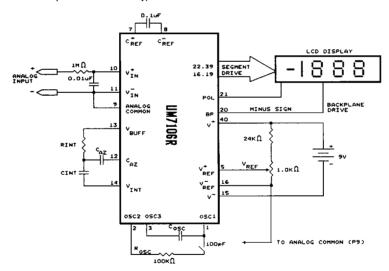


Figure 8

Component	Nominal Full-Scal	e Voltage
Value	2.000V	200.0mV
CAZ	0.047μF	0.47µF
RINT	470KΩ	47K Ω
CINT	0.22µF	0.22µF
VREF	1.000V	100.0mV



## **Application Circuits (continued)**

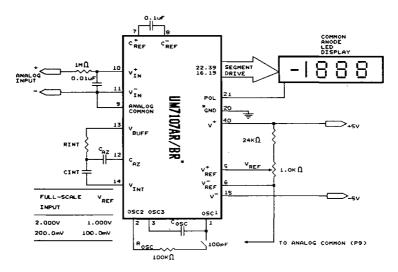


Figure 9

Component	Nominal Full-Scale Voltage		
Value	2.000V	200.0mV	
Caz	0.047μF	0.47µF	
Rint	470KΩ	47ΚΩ	
CINT	0.22µF	0.22μF	
VREF	1.000V	100.0mV	

<sup>\*</sup> Note: For UM7107BR, pin20 must be kept floating. Place a 120 Ω resistor between V<sup>†</sup>and common anode LED. The digital ground of UM7107BR is internally generated in order to improve PCB layout.

## **Ordering Information**

Part No.	Package	Function
UM7106R	40L DIP	LCD display
UM7107AR/BR	40L DIP	LED display