

# ***MASTERS 2015***

The premier technical training conference for embedded control engineers



## **19005 ARD**

# **Introduction to chipKIT™ Development Platform**

# Who am I?

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Please feel free to ask questions at any time.

# Class Objectives

- **Learn what the chipKIT™ Platform is**
- **How the chipKIT platform relates to Arduino**
- **Understand the chipKIT Core, the runtime system and supporting IDEs**
- **Know how to use MPIDE to create, compile and run sketches**

# Class Agenda

- **What is Arduino?**
- **What is the chipKIT™ platform?**
- **Compatibility: chipKIT system vs Arduino system**
- **Overview of chipKIT hardware and software**
- **Using the MPIDE**



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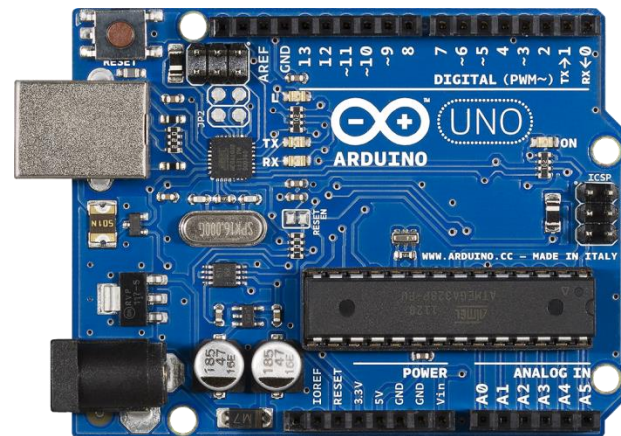
# WHAT IS ARDUINO?



# What is Arduino?

**“Arduino is an open-source electronics prototyping platform based on flexible, easy-to-use hardware and software. It's intended for artists, designers, hobbyists, and anyone interested in creating interactive objects or environments.”**

from [www.arduino.cc](http://www.arduino.cc)





# Goals of Arduino System

- **Ease of use**
- **Provide non-technical people (such as artists) the ability to use microcontrollers and embedded control in their projects**
- **Introduce beginners to embedded control using microcontrollers**



# What is Arduino?

- **An “open hardware”/“open source” embedded development platform**
  - Integrated Development Environment (IDE), compilers, linkers
  - Hardware platform specification
  - Hardware abstraction layer
  - Support libraries
- **Family of low cost microcontroller boards based**
- **An Italian company that manufactures and sells “Arduino” boards**





# Hardware Abstraction Layer

- **Digital I/O uses logical pin numbers rather than ports and bits**
- **Analog input**
- **Pseudo-analog (PWM) output**
- **Timing functions**
- **External interrupts**
- **Communication Libraries**
  - **UART, SPI, I<sup>2</sup>C™**

# Arduino Software

- **A simple IDE**
- **“Sketch” - the software program (artists, hobbyists, etc.)**
- **Preprocessing hides complexity**
- **Programming language: C++ compatible**
- **Software libraries**
  - Hardware abstracted peripheral support
  - Abstracted support classes



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# WHAT IS THE chipKIT™ PLATFORM?

# What is the chipKIT™ Platform?

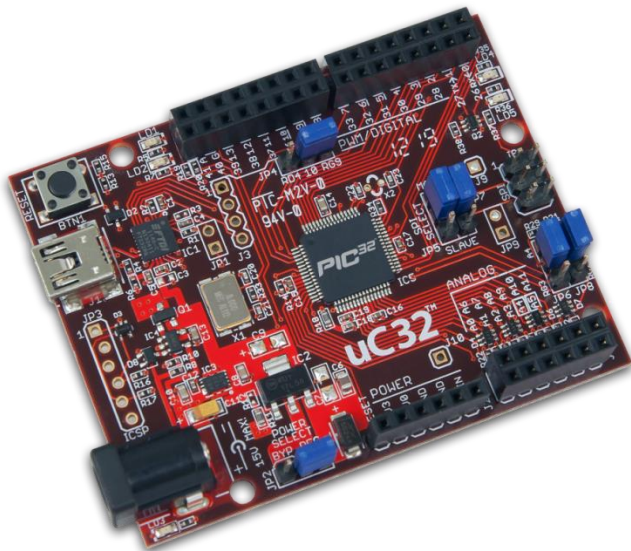
- Professional quality open hardware, open software, and support libraries using Microchip PIC32 MCUs
- An embedded chipKIT core supported by multiple IDEs (MPIDE, UECIDE, and MPLAB® X IDE)
- A full-featured tool suite (compilers, linkers, and debuggers)
- Arduino-compatible core functions and compatibility classes

# Goals of chipKIT™ Platform

- **Easy access to professional applications and libraries for new users**
- **Rapid prototype development tools**
- **Migration between easy to use IDEs and professional IDEs**
- **The same ease-of-use as Arduino when using Arduino-style IDEs**
- **Substantial source code compatibility with Arduino**



# Some chipKIT™ Boards



uC32



WF32

# chipKIT™ Core - Software

- **The chipKIT Core**

- Embedded core runtime functions
- Arduino-compatible core runtime functions
- Extensive peripheral libraries
- Arduino-compatible libraries
- Microchip chipKIT compiler and build tools
- C/C++ Runtime library

- **Supported IDEs**

- Ease of Use IDEs (no additional hardware needed)
  - **MPIDE**
  - **UECIDE**
  - **Arduino IDE (in the works)**
- Professional IDE (requires ICSP™ hardware debugger)
  - **MPLAB® X IDE**



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# **COMPATIBILITY: chipKIT™ SYSTEM VS. ARDUINO**





# Software Compatibility

- **Arduino version 023 core files and standard libraries ported to PIC32 platform**
- **Most sketches using only core files and standard libraries will work without change**
- **Arduino compatibility classes are layered on top of more advanced PIC32 libraries**
- **Timing-dependent code may have to be rewritten**
- **Libraries or sketches containing AVR-specific code must be rewritten to work with PIC32**
- **Work in progress to support compatibility with Arduino 1.6x standard**



# 5V vs 3.3V Operation

- **Most Arduino boards operate at 5V**
  - Exceptions include Arduino Due, Fio, Pro(168), LilyPad(168), LilyPad USB
- **All chipKIT™ boards operate at 3.3V**
  - Produce 3.3V outputs
  - PIC32MX boards: inputs 5V tolerant
  - PIC32MZ boards: inputs not 5V tolerant, accept 3.3V inputs only
- **Shields capable of accepting 3.3v inputs should work**
- **Shields that produce 5V outputs can't be used with PIC32MZ-based boards**

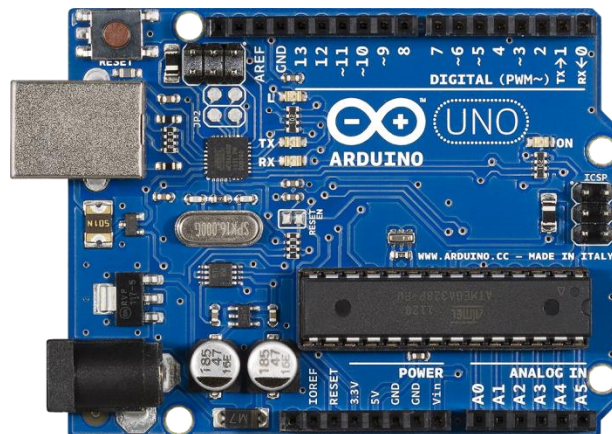


# uC32 vs Uno

- **PIC32MX340F512H**
- **512K flash, 32K RAM, 1K EEPROM**
- **42 I/O pins**
- **2 UART**
- **2 SPI**
- **2 I<sup>2</sup>C™**
- **12 10-bit A/D inputs**
- **5 output compare/PWM**



- **ATmega328**
- **32K flash, 2K RAM, 1K EEPROM**
- **22 I/O pins**
- **1 UART**
- **1 SPI**
- **1 I<sup>2</sup>C™**
- **6 10-bit A/D inputs**
- **6 output compare/PWM**





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# IDE ENVIRONMENTS AND COMPATIBILITY

# Development Environment

- **MPIDE forked from the Java-based Arduino IDE, (open source)**
- **UECIDE forked from MPIDE, but substantially rewritten (open source)**
- **MPLAB<sup>®</sup> X IDE, NetBeans-based professional IDE (not open source)**
- **Cross platform (Windows, Mac, Linux)**
- **GCC based (Gnu C++ Compiler)**



# Microchip Tool Compatibility

- **Start with easy-to-use IDEs for rapid prototype development or evaluation**
- **Migrate to MPLAB® X IDE at any time**

**OR**

- **Develop advanced code in MPLAB X IDE**
- **Deploy professionally developed code to the non-technical community with easy-to-use IDEs**

# MPLAB<sup>®</sup> Harmony vs. chipKIT<sup>™</sup> Platforms

- All chipKIT boards can be used directly with MPLAB X IDE and MPLAB Harmony
- Use Microchip MPLAB X IDE and XC32 C/C++
- Use with standard Microchip programmer/debugger tools
  - PICkit<sup>™</sup> 3 debugger, MPLAB ICD 3, MPLAB REAL ICE<sup>™</sup> in-circuit emulator, etc.
- MPLAB Harmony and chipKIT development environments are different and source incompatible



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# **chipKIT™ PLATFORM IN MORE DETAIL**



# Key Platform Elements

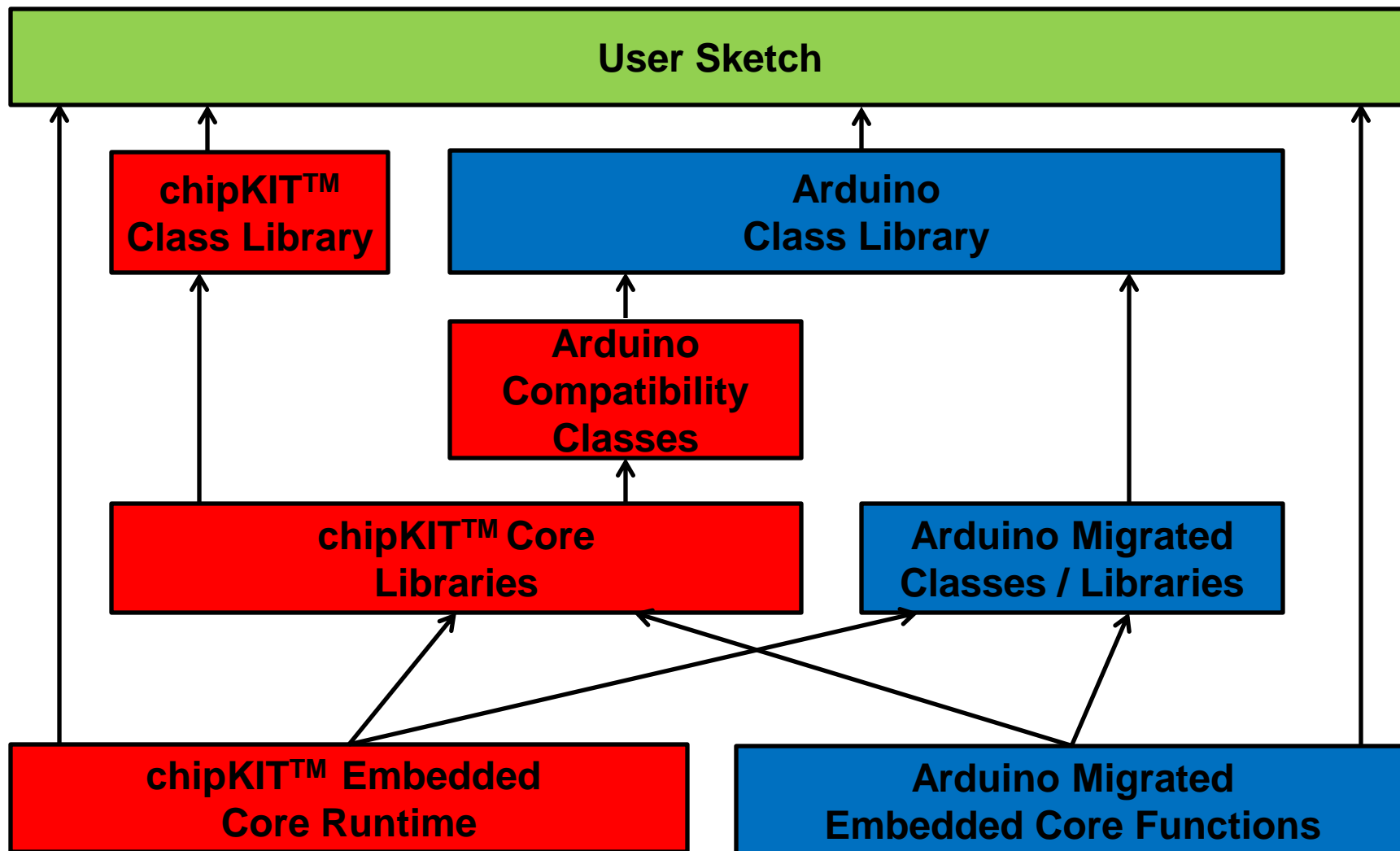
- **PIC32 Microcontroller**
- **chipKIT™ Embedded Core**
- **chipKIT Libraries**
- **Hardware Abstraction Layer**
- **Standard Runtime Libraries**
- **Bootloader**
- **Serial communications interface**

# PIC32 Microcontroller

- **32-bit MIPS processor core**
- **40MHz to 200MHz clock speeds**
- **Most instructions are single cycle**
- **Good set of standard peripherals**
  - UART, SPI, I<sup>2</sup>C™, Timers, etc.
- **Advanced peripherals**
  - USB OTG, 10/100MAC, CAN, etc.



# chipKIT™ Core - Software





# Arduino Compatible Libraries

- **EEPROM**
- **Firmata**
- **Liquid Crystal (LCD character display)**
- **SPI**
- **Servo**
- **Stepper**
- **SD**
- **SoftSPI**
- **SoftwareSerial**
- **HardwareSerial**
- **OneWire**
- **Matrix**
- **Sprite**

# chipKIT™ Libraries

## Core Libraries

- **DSPI (SPI)**
- **DTWI (I<sup>2</sup>C™)**
- **SoftPWMServo (PWM)**
- **DEIPcK (Network)**
- **DEWFcK (WiFi)**
- **HTTPServer (HTTP)**

## Arduino Compatibility Classes

- **Wire (I<sup>2</sup>C™)**
- **Ethernet (Network)**

# Bootloader

- **Simple IDEs**

- Use bootloader to program the sketch onto the board
- Communicate with bootloader via serial interface
- No additional hardware required

- **MPLAB X<sup>®</sup> IDE**

- Requires a hardware programmer/debugger
- Programs the bootloader concurrently with the sketch
- Also programs a debug executive for debugging

# Serial Bootloader and Serial Monitor

- **Serial port is standard part of an Arduino/chipKIT™ board**
- **Used by bootloader to program sketch**
- **User can interact with the sketch at runtime**
  - MPIDE provides a serial monitor window where user can view output and provide input



# Bootloader Programming



MPIDE passes  
Avrdude the  
sketch HEX file

MPIDE spawns  
Avrdude

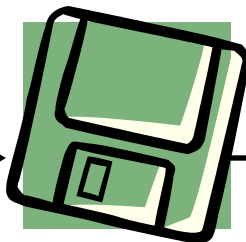


Avrdude

Virtual COM  
Port 115200  
baud

STK500v2  
Protocol

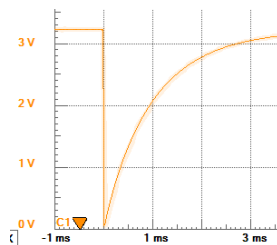
FTDI Serial  
to USB Driver



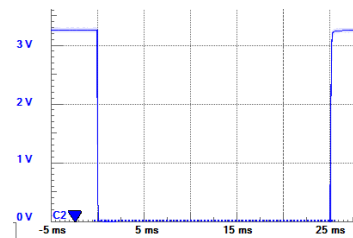
USB

Artifact of USB Enumeration  
causes the FTDI chip to pulse DTR

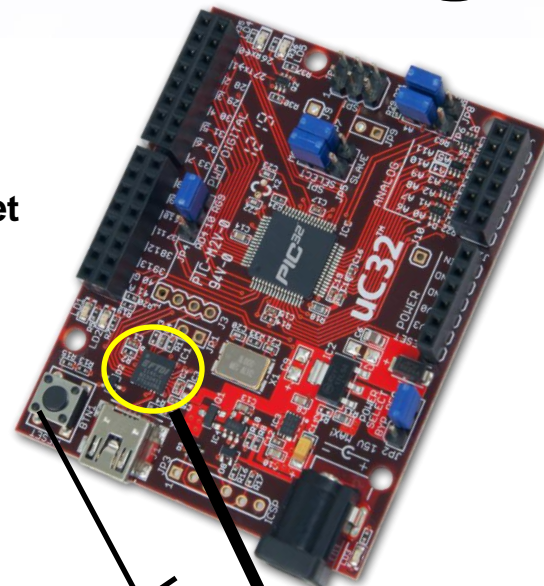
Bootloader  
programs the  
sketch on reset



Reset / MCLR



DTR

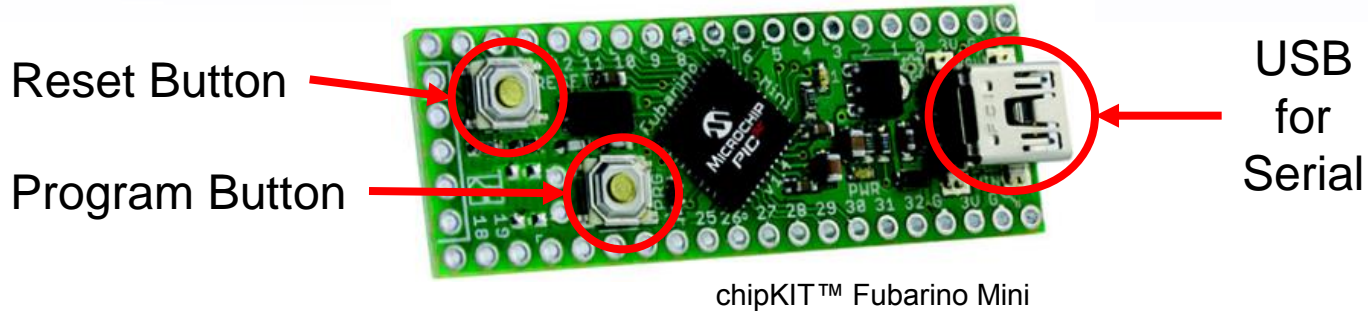


Serial 115200  
Baud





# USB for Serial



- **Some boards do not use an FTDI chip and use the PIC32 USB controller directly**
- **Reduces cost and size of board**
- **Requires install of custom USB serial device .inf**
  - Links custom serial device class to OS provided USB serial driver
- **No DTR, no auto reset; USB for Serial requires a program button**
- **Hold program button and then press reset, puts bootloader in program mode**
- **Also used to support the Serial Monitor**

# Shield Interface

- **100 mil pin header connectors**
- **Boards stack vertically**
  - Base board has female headers
  - Shield board has male headers
- **Peripheral functions assigned to specific pins**
- **chipKIT™ shields have an extra row of headers to provide more I/O**



# chipKIT™ Shields



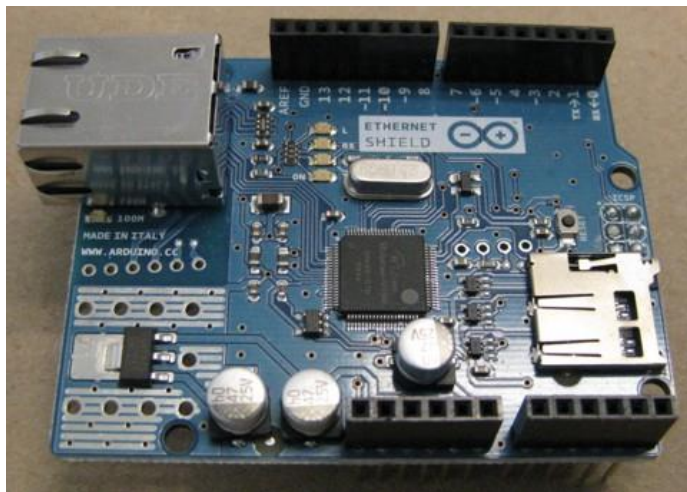
Basic I/O Shield



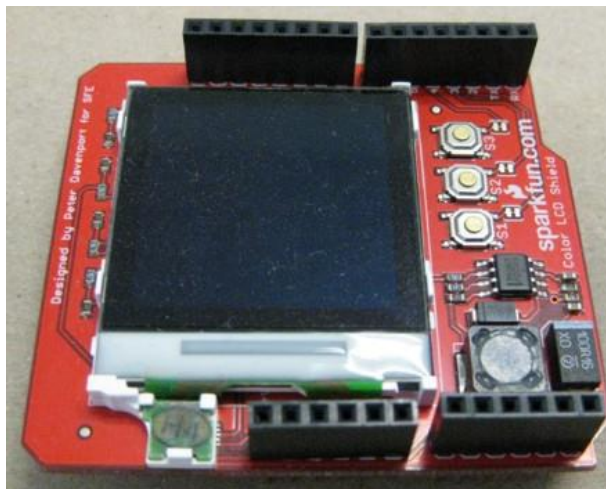
Wi-Fi® Shield



# Some Arduino Shields

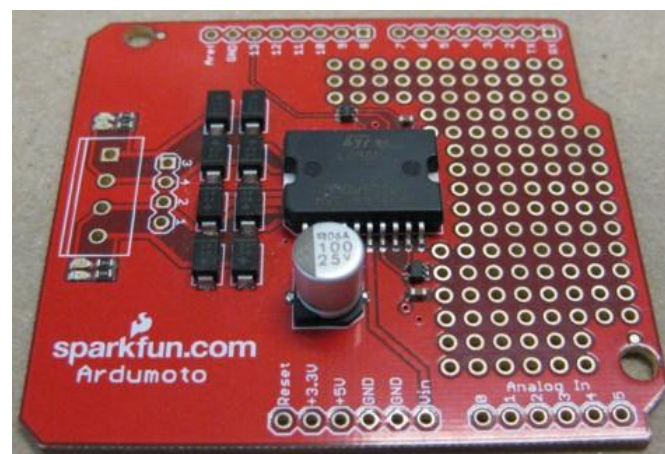


Ethernet Shield



Graphic  
Display Shield

**A large number of Arduino shields are suitable for use with chipKIT™ boards**



Motor Drive Shield



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# **PREPARATION FOR LAB: USING THE MPIDE**



# Lab Objectives

- **Walkthrough of the IDE**
- **Programming model**
- **Use of core functions**
- **Use of standard libraries**
- **Building and running sketches**



```
/*
  Blink
  Turns on an LED on for one second, then off for one second, repea

  This example code is in the public domain.
  */

void setup() {
  // initialize the digital pin as an output.
  // Pin 13 has an LED connected on most Arduino boards:
  pinMode(13, OUTPUT);
}

void loop() {
  digitalWrite(13, HIGH); // set the LED on
  delay(1000);            // wait for a second
  digitalWrite(13, LOW);  // set the LED off
  delay(1000);            // wait for a second
}
```

1 Cerebot MX7cK on COM33

# Programming Model

- **A program is called a sketch**
- **Language used is C++**
- **Embedded program event loop is built into the system**
- **Two required functions**
  - **setup ()** – one time initialization
  - **loop ()** – called repeatedly by system





# Programming Model

User program (sketch) implements two required functions.

```
void setup() {  
    // called ONCE at the beginning  
}
```

```
void loop() {  
    // called repeatedly  
}
```

# Programming Model

## Behind the Scenes (Preprocessing)

```
int main(void) {  
    init();    //system initialization  
  
    setup();   //user initialization  
  
    while (1) {  
        loop();    //sketch behavior  
    }  
    return 0;  
}
```

# Core Runtime Functions

- `pinMode(pin, dir)`
  - Sets pin direction and drive type
- `digitalRead(pin)`
  - Reads the state of a digital pin
- `digitalWrite(pin, val)`
  - Sets a digital pin to specified state
- `delay(ms)`
  - Delay the specified number of milliseconds



# Example – Blink an LED

```
int ledPin = PIN_LED1;           //led on pin 13

void setup() {
    pinMode(ledPin, OUTPUT);      //make pin an output
}

void loop() {
    digitalWrite(ledPin, HIGH);   //led on
    delay(1000);                  //wait one second
    digitalWrite(ledPin, LOW);    //led off
    delay(1000);                  //wait one second
}
```

# Core Runtime Functions

- **analogRead(pin)**
  - Returns A/D converter value for specified pin
- **analogWrite(pin, val)**
  - Pseudo-analog output using PWM. Sets output duty cycle to specified value

# Example – Dim an LED

```
int pinLed = 9;           //assume LED on pin 9
int pinPot = A0;          //assume pot on analog 0

void setup() {            //nothing needed
}

void loop() {
    int val;
    val = analogRead(pinPot);
    analogWrite(pinLed, val/(1024/256));

    delay(1000);
}
```

# Hardware Serial

- **Serial.begin(baud)**
  - Initialize the UART and set the baud rate
- **Serial.print(val)**
  - Print the specified value to UART
- **Serial.read()**
  - Read characters from UART



# Example

```
void setup() {  
    Serial.begin(9600);    //init UART  
}  
  
void loop() {  
    Serial.println();  
    Serial.println("Hello World!");  
    for (i = 1; i <= 10; i++) {  
        Serial.print(" i = ");  
        Serial.println(i, DEC);  
    }  
    delay(5000);           //wait five seconds  
}
```



# Lab Activity

- **Open the lab handout and do the lab exercises**

# Lab Summary

- **Features/use of IDE**
- **Structure of a Sketch**
- **Available runtime facilities**
- **Use of libraries**
- **Getting output from a sketch**

# Class Summary

- **What is the chipKIT™ platform?**
- **How does it compare to Arduino?**
- **chipKIT system hardware features**
- **MPIDE and runtime software features**
- **Write, build, download and execute sketches**

# Resources

- **Help and examples in MPIDE**
- **chipKIT™ Platform web site**  
<http://chipkit.net>
- **chipKIT support forum**  
<http://chipkit.net/forum>
- **Digilent sites**  
<http://digilentinc.com/chipkit>  
<http://learn.digilentinc.com>
- **Developer Help**  
<http://microchip.wikidot.com>

# chipKIT™ Cores and IDEs

- **chipKIT Core**

<https://github.com/chipKIT32/chipkit-core>

- **MPIDE**

<https://github.com/chipKIT32/chipKIT32-MAX>

<http://chipkit.s3.amazonaws.com/index.html>

- **UECIDE**

<http://uecide.org>

- **MPLAB X® IDE**

<http://www.microchip.com/mplab>



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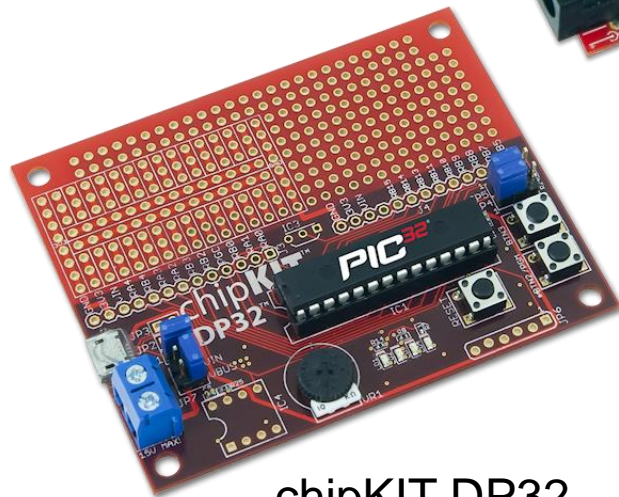
# APPENDIX



# More chipKIT™ Boards



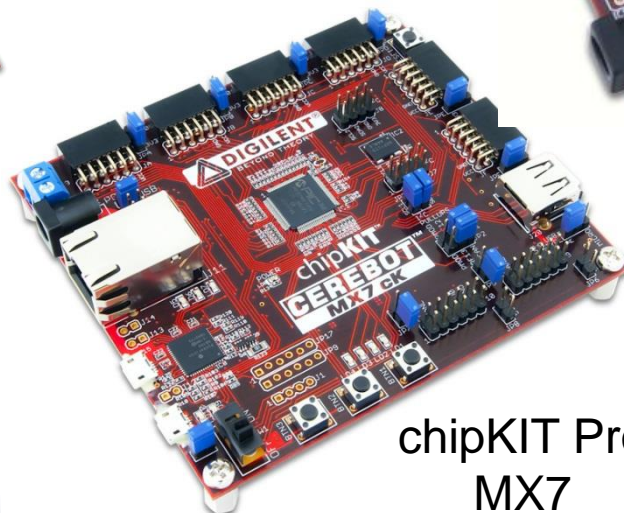
chipKIT Wi•FIRE



chipKIT DP32



chipKIT MAX32



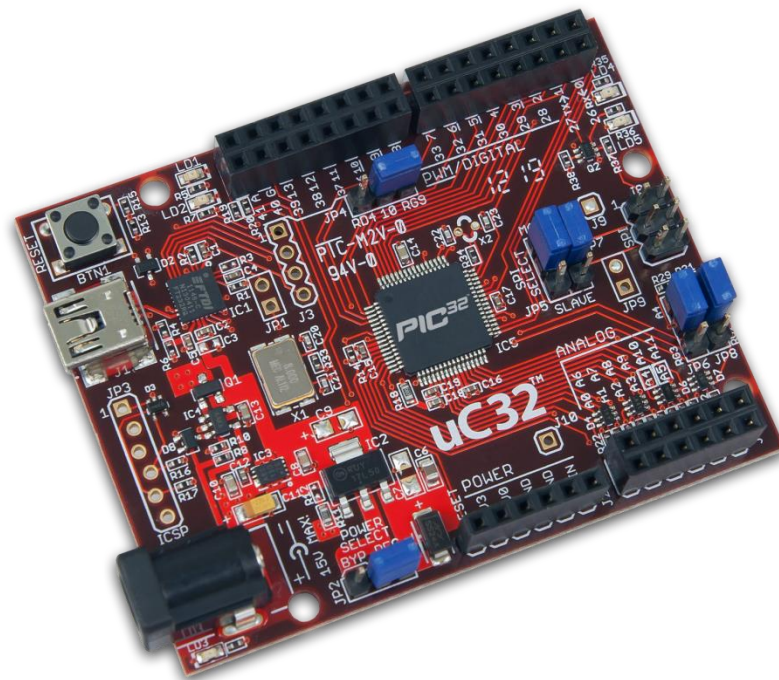
chipKIT Pro  
MX7





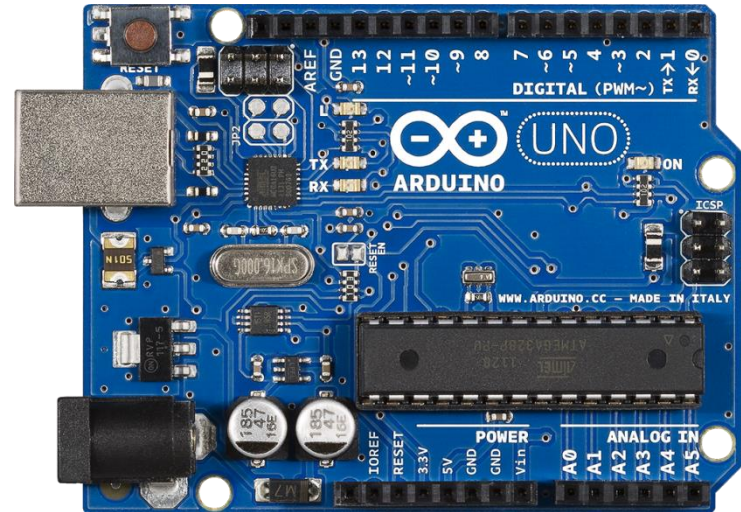
# chipKIT™ uC32 Board

- **Microchip PIC32MX340F512H**
  - 80 Mhz 32-bit MIPS
  - 512K Flash
  - 32K SRAM
- **Arduino Uno form factor**
- **42 available I/O pins**
- **Two user LEDs**
- **12 analog inputs**
- **75mA typical operating current**
- **20V input voltage (maximum)**
- **0V to 3.3V analog input voltage range**
- **+/-18mA DC current per pin**



# Arduino Uno

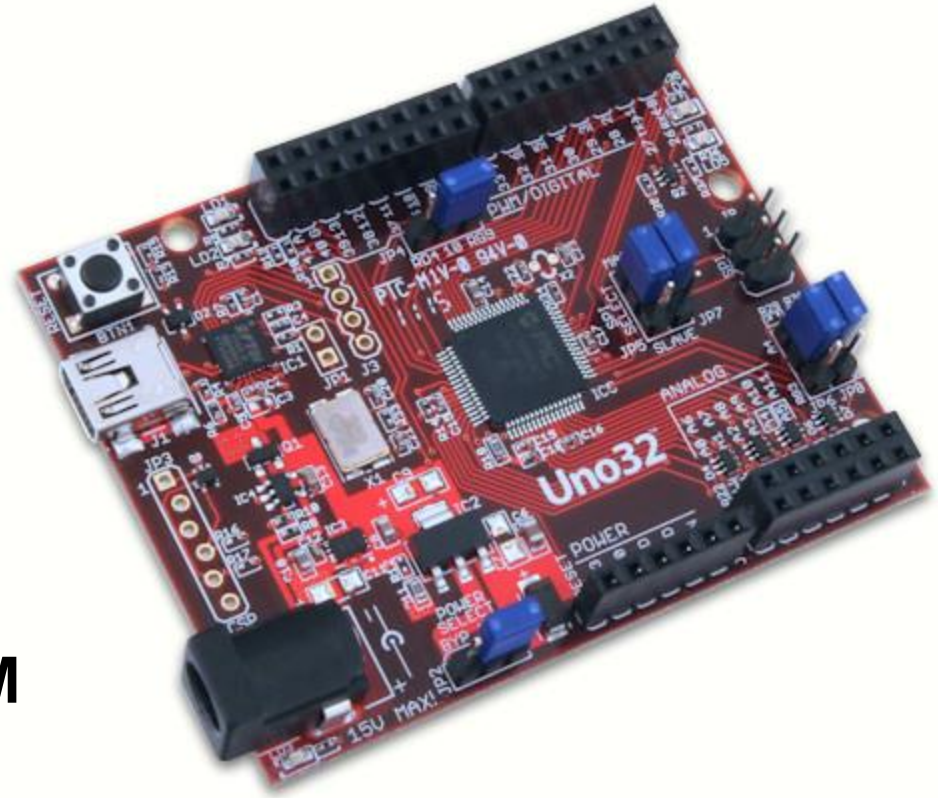
- ATmega328
- 32K flash, 2K RAM, 1K EEPROM
- 22 I/O pins
- 1 UART
- 1 SPI
- 1 I<sup>2</sup>C™
- 6 10-bit A/D inputs
- 6 output compare/PWM



# chipKIT™ Uno32

(replaced by a uC32)

- **PIC32MX320F128H**
- **128K flash, 16K RAM**
- **42 I/O pins**
- **2 UART**
- **1 SPI**
- **2 I<sup>2</sup>C™**
- **12 10-bit A/D input**
- **5 output compare/PWM**





# chipKIT™ Max32

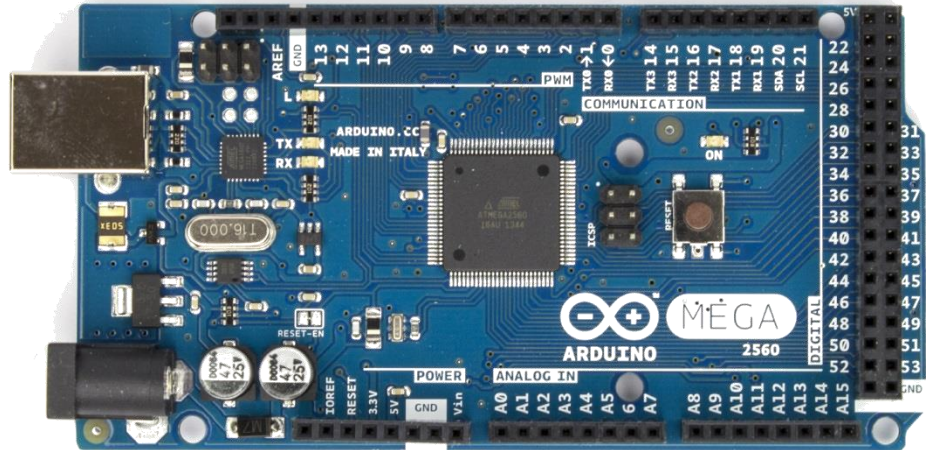
- **PIC32MX795F512L**
- **512K flash, 128K RAM**
- **83 I/O pins**
- **4 UART, 1 SPI, 2 I<sup>2</sup>C™**
- **16 10-bit A/D inputs**
- **5 output compare/PWM**
- **USB 2.0 OTG controller**
- **10/100 Ethernet MAC**
- **Dual CAN controllers**





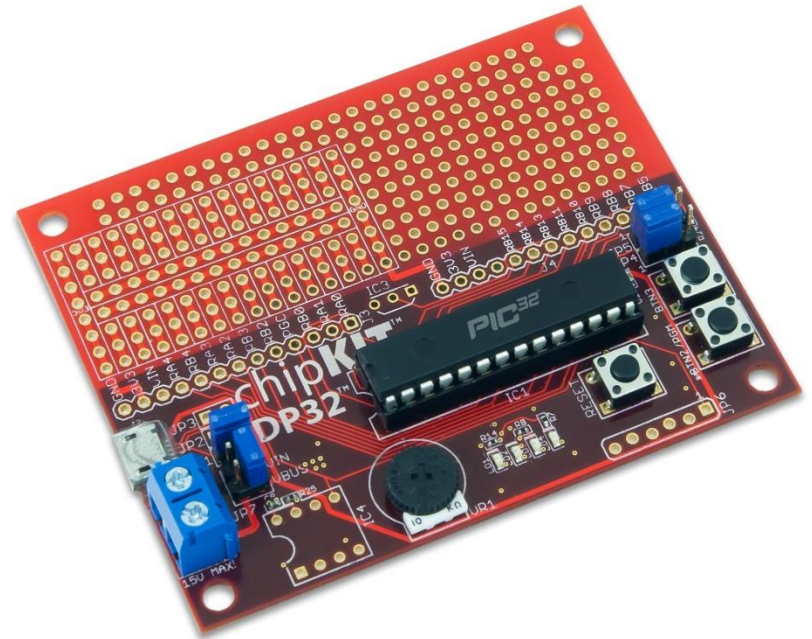
# Arduino Mega 2560

- ATmega2560
- 256K flash, 8K RAM, 4K EEPROM
- 70 I/O pins
- 4 UART
- 1 SPI
- 1 I<sup>2</sup>C™
- 16 10-bit A/D input
- 16 output compare/PWM
- 16 pins left unconnected



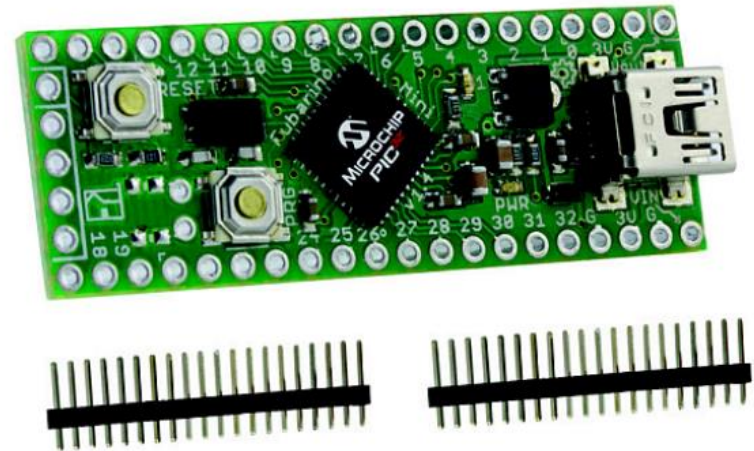
# chipKIT™ DP32 Board

- Microchip PIC32MX250F128B
  - 40/50 MHz 32-bit MIPS
  - 128K Flash
  - 32K SRAM
- 19 available I/O pins
- Four LEDs, two push-buttons
- 9 analog inputs
- Potentiometer
- Wire-wrap prototype area
- Provision for an SPI EEPROM and an analog temperature sensor
- Mounting Hole compatible with Hammond 1591XXSSBK project box



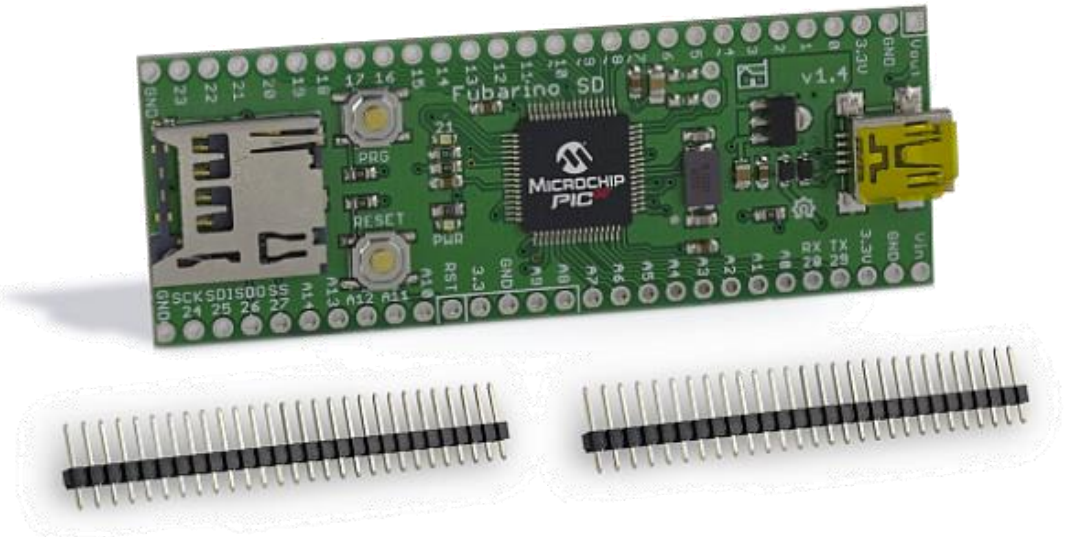
# chipKIT™ Fubarino Mini

- PIC32MX250F128D-50I/ML
  - 48MHz operation
  - 128K flash
  - 32K RAM
- DIP form factor
- Max 33 I/O pins (normally 27)
- Pads for 32 KHz crystal
- Comes with headers (not installed) for easy mounting on a breadboard
- Two buttons: RESET for resetting the board, and PRG for getting into bootloader mode and user application use



# chipKIT™ Fubarino SD

- PIC32MX795F512H
  - 80MHz operation
  - 512K Flash
  - 128K RAM
- DIP form factor
- uSD card connector
- 45 available I/Os
- 15 analog inputs
- Two UART
- Comes with headers (not installed) for easy mounting on a breadboard
- Two buttons: RESET for resetting the board, and PRG for getting into bootloader mode and user application use





# chipKIT™ WF32 Board

- Microchip PIC32MX695F512L  
80 Mhz 32-bit MIPS  
512K Flash  
128K SRAM
- 802.11g Wi-Fi®, MRF24WG0MA
- USB Host/Device
- uSD card connector
- Uno32 shield compatible
- 42 available I/O pins
- Four LEDs, 2 Push buttons
- Potentiometer
- 12 analog inputs
- Switching power supply



# chipKIT™ Wi•FIRE™ Board

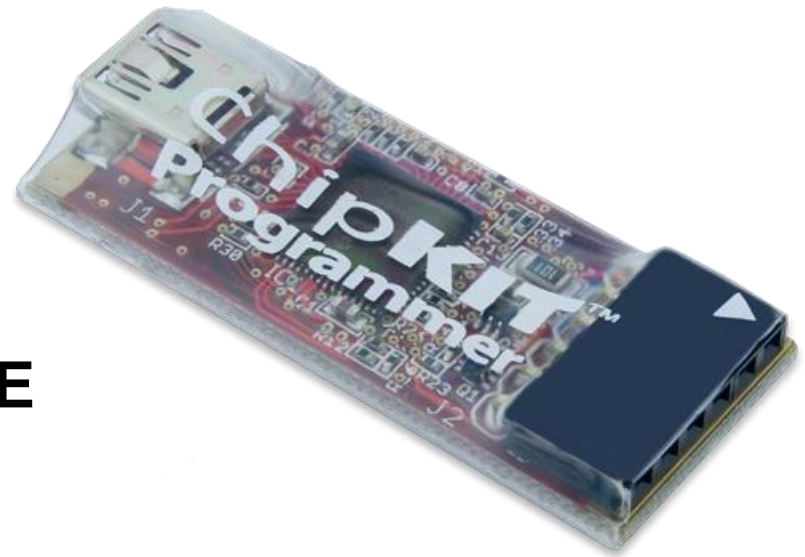
- **PIC32MZ2048EFG**
  - 200MHz MIPS microAptive core
  - 2048K Flash
  - 512K RAM
- **802.11/g Wi-Fi®, MRF24WG0MA**
- **USB 2.0 High Speed Host/Device**
- **uSD card socket**
- **Uno32 shield compatible with Arduino R3 enhancement**
- **42 available I/O pins**
- **Four LEDs, two push-buttons**
- **Potentiometer**
- **Switching power supply**





# chipKIT™ PGM Programmer

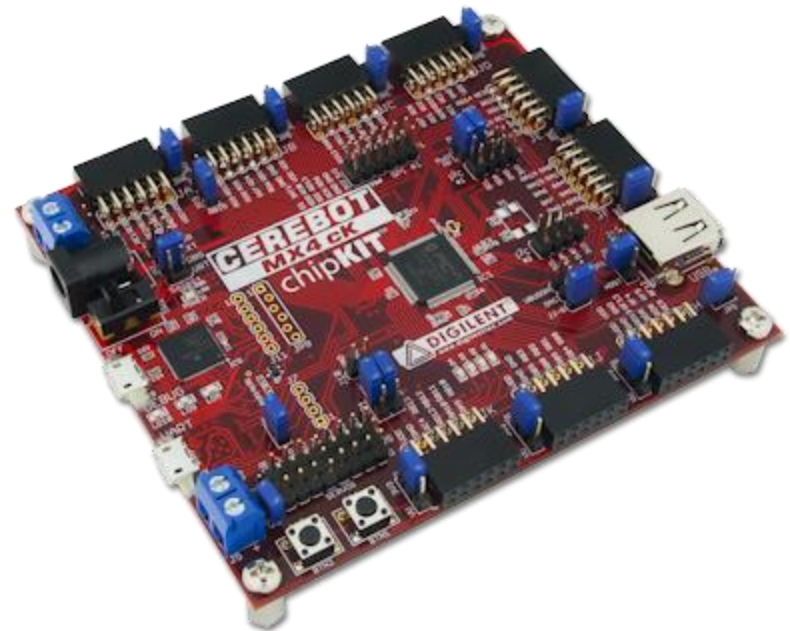
- Provides in-system programming and debugging for Microchip PIC® MCU-based microcontroller boards
- Intended for use with chipKIT boards
- Works with the MPLAB® IDE and MPLAB X IDE





# chipKIT™ Pro MX4 Board

- **PIC32MX460F512L**
  - 80 MHz operation
  - 512K flash memory
  - 32K RAM memory
- **74 available I/O pins, 9 Pmod, 2 I<sup>2</sup>C™, 8 servo connectors, 2 push buttons, 4 LEDs**
- **2 UART, 2 SPI, 2 I<sup>2</sup>C**
- **5 output compare, PWM**
- **14 10-bit A/D inputs**
- **MPLAB® IDE compatible licensed debugger**

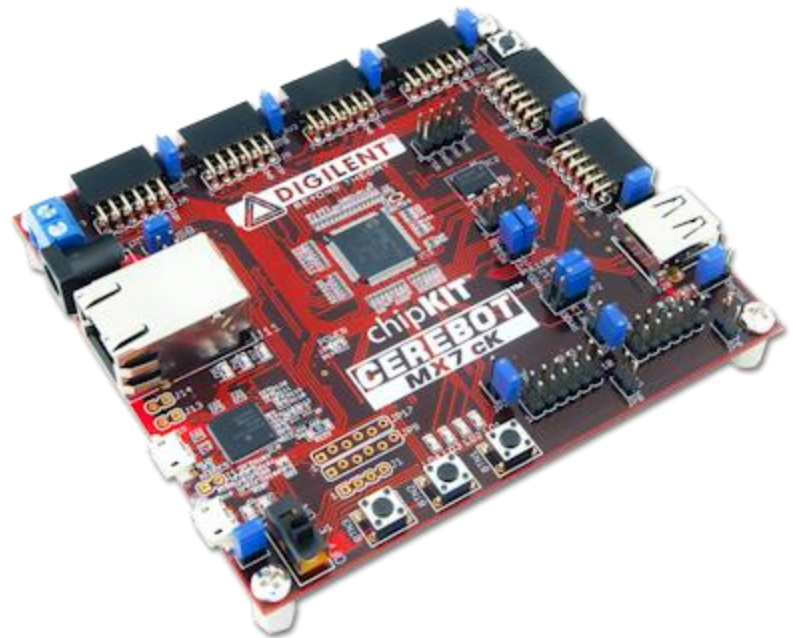






# chipKIT™ Pro MX7 Board

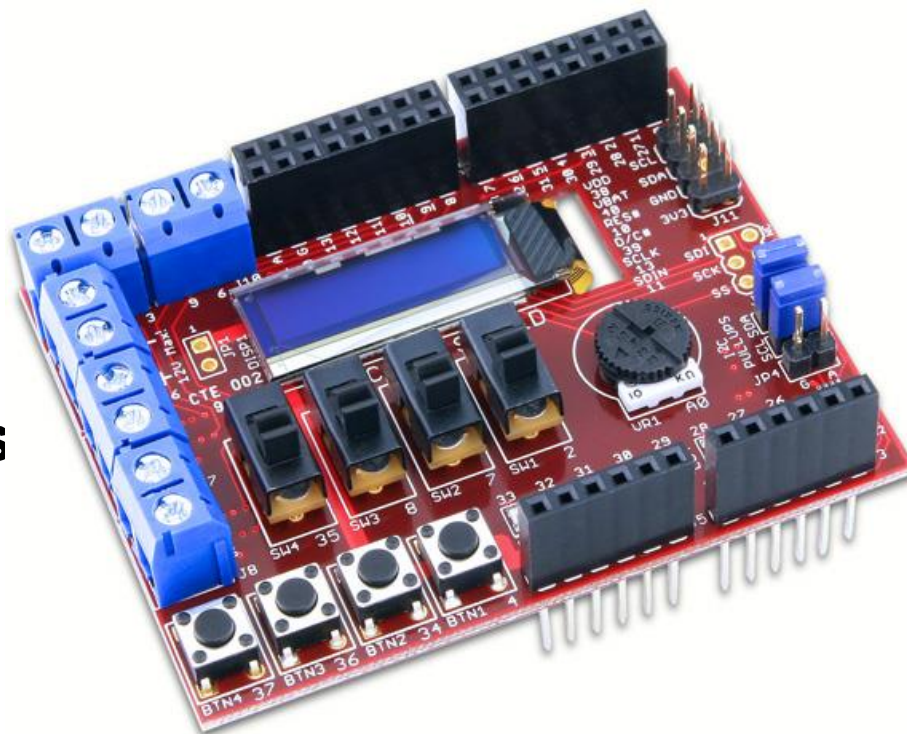
- **PIC32MX795F512L**
  - 80 MHz operation
  - 512K flash
  - 128K RAM
- **64 available I/O pins**
- **6 Pmod connectors**
- **10/100 Ethernet, 2 CAN, USB 2.0 OTG Host/Device**
- **2 UART, 3 SPI, 2 I<sup>2</sup>C™**
- **5 output compare/PWM**
- **12 10-bit analog input**
- **MPLAB® IDE compatible licensed debugger**





# Basic I/O Shield

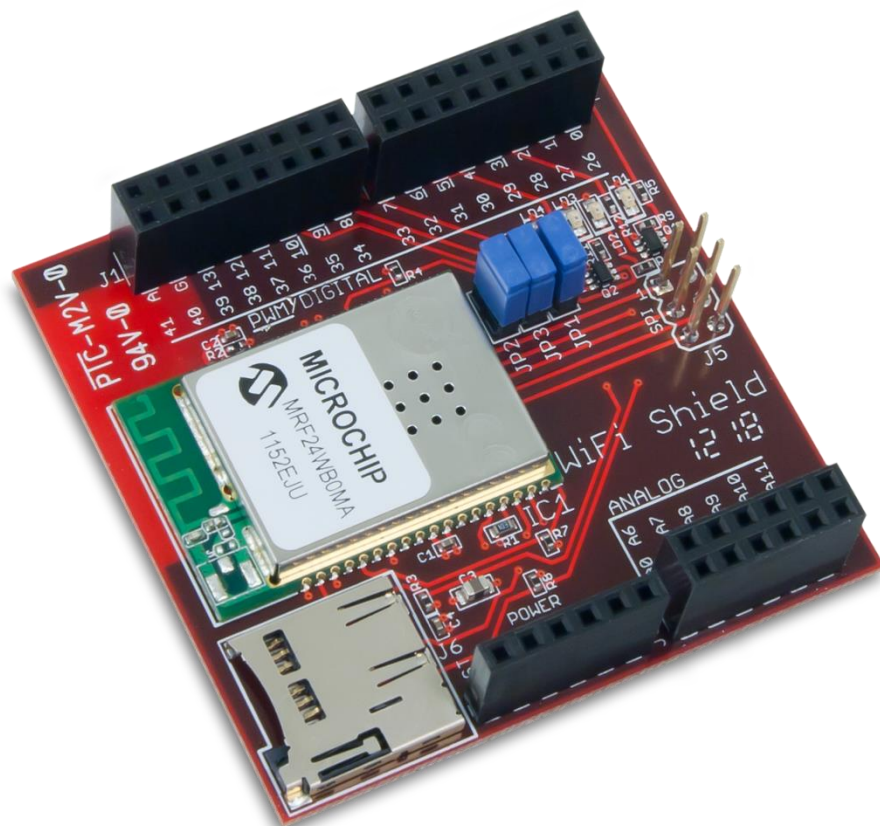
- Uno32 form factor
- 128x32 OLED display
- Four buttons
- Four slide switches
- Eight LEDs
- Four open drain FETs
- I<sup>2</sup>C™ EEPROM
- I<sup>2</sup>C Temp sensor
- Potentiometer





# chipKIT™ WiFi Shield Board

- IEEE 802.11b-compliant RF transceiver
- serialized unique MAC address
- 1 and 2Mbps data rates
- IEEE 802.11b/g/n-compatible
- integrated PCB antenna
- range: up to 400m (1300 ft.)
- radio regulation certification for the FCC, IC, ETSI, and ARIB
- Wi-Fi® certified (WFA ID: WFA7150)
- micro SD card connector
- four LEDs





# Network Shield

- Expands I/O on Max32
- USB Host & Device connectors
- 10/100 Ethernet PHY and connector
- Dual CAN transceivers and connectors
- Dual I<sup>2</sup>C<sup>TM</sup> connectors
- I<sup>2</sup>C EEPROM
- 32Khz oscillator



The Network Shield in combination with the Max32 provides access to all of the features of the PIC32MX795F512L.



# chipKIT™ Motor Shield Board

- Two h-bridge DC motor channels
- Quadrature encoder feedback inputs
- Four RC servo outputs
- Four low side N-FET outputs
- I<sup>2</sup>C™ I/O expander with four LEDs, two push buttons, two jumpers
- Fits Uno32 style shield connector footprint

