The Rotational Analog Sensor (RAS) from DeltaTech Controls provides the functionality of classical potentiometers but with the advantage of contactless sensing, thereby increasing product life expectation and reliability.

The unique sensing design has been developed to provide the reliability required in demanding environmental conditions such as armrest controls and dashboards, in heavy duty and harsh industrial and off-road applications.

In addition the RAS can be reverse mounted and used as an angle sensor.

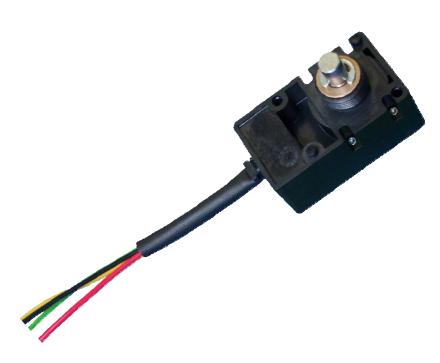
Main Features

- Contactless sensing Hall
- Life greater than 5 millior cycles
- Definable working angle
- Precise tactile feel (optional)
- Dual mountable:
 - contactless potentiomete
 - angle sensor
- One channel optional second channel for redundancy
- Integrated temperature compensation
- Short circuit protection

Custom modifications

- Angle of operation
- Force of rotation
- Length of axis
- Rotational feel (smooth or ridged)
- Redundancy





| Electrical Data | | | | | | |
|-------------------------------------|--------------------------|--|--|--|--|--|
| Supply Ratings | Voltage range DC current | 9V 16V or 5.0 V ± 5% 50 mA at 24V | | | | |
| Voltage Output | Output 1 Output 2* | 0.5V 4.5V at 5Vcc 4.5V 0.5V at 5Vcc Output proportional to Vcc | | | | |
| Pull-down resistor | Recommendation | 4.7kΩ | | | | |
| Total error | | < 10% | | | | |
| Output current | | 1 mA max. (per output channel) | | | | |
| Other electrical Characteristics | EMI | > 100 V/m | | | | |
| Mechanical Data | | | | | | |
| Life | | > 5 million cycles | | | | |
| Operating temperat | ure | - | | | | |
| - Storage | | - 40℃ to 85℃ | | | | |
| - Working | | - 35℃ to 70℃ | | | | |
| Protection Level | | IP 65 | | | | |

up to 360°

RAS deflection angle
* for redundant version

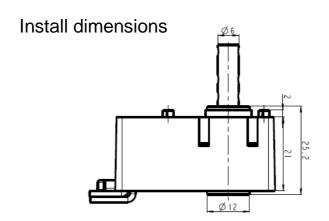
Order Code

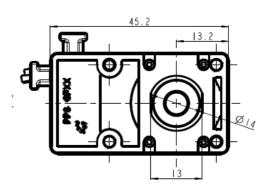


| Or | dering code | | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
|----|---------------------|--|-----|---|-----|----|------|---|---|---|---|----|
| | - | Example | RAS | Р | 160 | χN | 40.4 | S | 1 | V | 2 | 00 |
| 1 | Туре | RAS = rotational analog sensor | | 1 | 1 | 1 | 1 | 1 | | 1 | 1 | 1 |
| 2 | Version | P = potentiometer | | | | | | | | | | |
| | | AS = angle sensor | | | | | | | | | | |
| 3 | Deflection Angle | 160 = standard 160° | | | | | | | | | | |
| | _ | $x = customised x^{o}$ | | | | | | | | | | |
| 4 | Operation Force | xN = force of rotation depends on actuator | | | | | | | | | | |
| | - | · | | | | | | | | | | |
| 5 | Length of Axis | 40.4 = standard 40.4 mmm length of axis | | | | | | | | | | |
| | | Ax = customised length of axis x mm | | | | | | | | | | |
| 6 | Rotational Feel | S = smooth | | | | | | | | | | |
| | | R = ridged | | | | | | | | | | |
| 7 | Electrical supply | 0 = voltage 9 16 V | | | | | | | | | | |
| | | $1 = 5 V \pm 5\%$ | | | | | | | | | | |
| 8 | Output | V = voltage | | | | | | | | | | |
| | - | _ | | | | | | | | | | |
| 9 | Sensors | 1 = 1 sensor | | | | | | | | | | |
| | | 2 = 2 sensors (for redundancy) | | | | | | | | | | |
| 10 | Output Voltage Code | 00 = output 1 / 0.5V 4.5V; 1mA * | | | | | | | | | | |
| | | output 2 / 4.5V 0.5V; 1mA * | | | | | | | | | | |
| | | 02 = output 1 / 0.5V 4.5V; 1mA * | | | | | | | | | | |
| | | 03 = output 1 / 4.5V 0.5V; 1mA * | | | | | | | | | | |

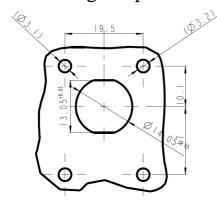
^{*} ratiometric to 5V electrial supply

Version: Angle Sensor – Mounting (AS)





Drilling template

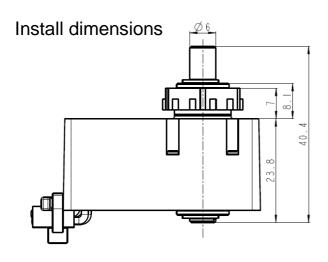


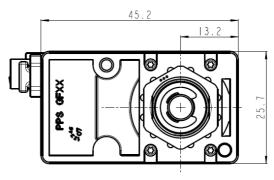
Pin Assignment standard

| PIN | Signal | Color |
|-----|--------|-------|
| 1 | VCC | BN |
| 2 | Out 1 | WH |
| 3 | GND | GN |

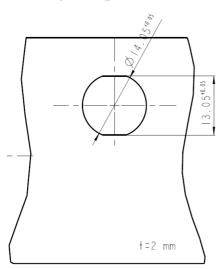
Version: Potentiometer – Mounting (P)



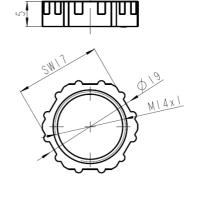




Drilling template



Screw nut



Pin Assignment redundant

| PIN | Signal | Color | | | | |
|-----|--------|-------|--|--|--|--|
| 1 | VCC | RD | | | | |
| 2 | Out 1 | GN | | | | |
| 3 | Out 2 | YE | | | | |
| 4 | GND | ВК | | | | |



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