

PSI 9000 register list for devices with KE firmware from V2.11 (check the installed version in your device's MENU in item INFO HW, SW)

Modbus address										Access	Access condition for writing	Data type	Data length in bytes	Number of registers	Data	Example	Profibus slot / Profinet subslot	Profibus/Profinet index in slot		
Read coils (0x01)																				
Read holding registers (0x03)																				
Write single coil (0x05)																				
Write single register (0x06)																				
Write multiple registers (0x10)																				
Description																				
0	x									R		uint(16)	2	1		21, 33, 35, 37 = PSI 9000 Series	1	0		
1	x									R		char	40	20	ASCII	PSI 9080-170	1	1		
21	x									R		char	40	20	ASCII		1	2		
41	x									R		char	40	20	ASCII		1	3		
61	x									R		char	40	20	ASCII		1	4		
81	x									R		char	40	20	ASCII		1	5		
101	x									R		char	40	20	ASCII		1	6		
121	x									R		float	4	2	Floating point number IEEE754	80	1	7		
123	x									R		float	4	2	Floating point number IEEE754	170	1	8		
125	x									R		float	4	2	Floating point number IEEE754	3500	1	9		
127	x									R		float	4	2	Floating point number IEEE754	12	1	10		
131	x									R		char	40	20	ASCII	33230401	1	12		
151	x									R		char	40	20	ASCII	100010002	1	13		
171	x							x		RW	REM	char	40	20	ASCII		1	14		
191	x									R		char	40	20	ASCII	V2.01 05.09.2012	1	15		
211	x									R		char	40	20	ASCII	V2.02 13.08.2012	1	16		
231	x									R		char	40	20	ASCII	V2.01 10.09.2012	1	17		
402	x			x						RW		uint(16)	2	1	Coils : Remote	0x0000 = off; 0xFF00 = on	2	1		
405	x			x						RW	REM	uint(16)	2	1	Coils : output	0x0000 = off; 0xFF00 = on		2	4	
407	x			x						RW	REM	uint(16)	2	1	Coils : Auto-On	0x0000 = off; 0xFF00 = auto-on		3	30	
408		x			x					RW	REM	uint(16)	2	1	Reg : Power-On	0xFFFF = off; 0xFFFE = restore		2	6	
409	x				x					RW	REM	uint(16)	2	1	Coils : Operation mode	0x0000 = UIP; 0xFF00 = UIR		2	7	
410					x					W	REM	uint(16)	2	1	Coils : Restart	0xFF00 = execute		2	8	
411					x					W	REM	uint(16)	2	1	Coils : Alarms	0xFF00 = acknowledge		2	9	
416	x				x					RW	REM	uint(16)	2	1	Coils : VREF	0x0000 = 10V; 0xFF00 = 5V		2	14	
417	x				x					RW	REM	uint(16)	2	1	Coils : REM-SB Level	0x0000 = normal; 0xFF00 = inverted		2	36	
418						x				W	REM	uint(16)	2	1	Coils : REM-SB Action	0x0000 = DC off; 0xFF00 = DC auto		2	37	
426	x				x					RW	REM	uint(16)	2	1	Coils : PV mode	0x0000 = off; 0xFF00 = on		5	13	
500		x				x				RW	REM	uint(16)	2	1	0x0000 - 0xC000 (0 - 100%)	Voltage value (for translation see programming guide)		2	23	
501			x				x			RW	REM	uint(16)	2	1	0x0000 - 0xC000 (0 - 100%)	Current value (for translation see programming guide) / Irradiation		2	24	
502				x				x		RW	REM	uint(16)	2	1	0x0000 - 0xC000 (0 - 100%)	Power value (for translation see programming guide)		2	25	
503					x			x		RW	REM	uint(16)	2	1	0x0000 - 0xC000 (0 - 100%)	Resistance value (for translation see programming guide)		2	26	
505						x				R		uint(32)	4	2	Bit 0-4: Control location	0x00 = free; 0x01 = local; 0x03 = USB; 0x04 = analog; 0x05 = Profibus; 0x06 = Ethernet; 0x08 = Master/Slave; 0x09 = RS232; 0x10 = CANopen; 0x11 = Devicenet; 0x12 = Modbus TCP 1P; 0x13 = Profinet 1P; 0x14 = Ethernet 1P; 0x15 = Ethernet 2P; 0x16 = Modbus TCP 2P; 0x17 = Profinet 2P; 0x18 = GPIB; 0x19 = CAN		2	27	
																Bit 5 : -				
																Bit 6 : Master-slave type	0 = Slave; 1 = Master			
																Bit 7 : Output state	0 = off; 1 = on			
																Bit 8 : -				
																Bit 10-9: Regulation mode	00 = CV; 01 = CR; 10 = CC; 11 = CP			
																Bit 12-11 : -				
																Bit 13 : Function mode	0 = off; 1 = on			
																Bit 14 : External sense	0 = off; 1 = on			
																Bit 15 : Alarms	0 = none; 1 = active			
																Bit 16 : OVP	0 = none; 1 = active			
																Bit 17 : OCP	0 = none; 1 = active			
																Bit 18 : OPP	0 = none; 1 = active			
																Bit 19 : OT	0 = none; 1 = active			
																Bit 20 : OTpre	0 = none; 1 = active			
																Bit 21 : Power fail 1	0 = none; 1 = active			
																Bit 22 : Power fail 2	0 = none; 1 = active			
																Bit 23 : Power fail 3	0 = none; 1 = active			
																Bit 24 : UVD	0 = none; 1 = active			
																Bit 25 : OVD	0 = none; 1 = active			
																Bit 26 : UCD	0 = none; 1 = active			
																Bit 27 : OCD	0 = none; 1 = active			
																Bit 28 : OPD	0 = none; 1 = active			
																Bit 29 : MSS	0 = OK; 1 = Master-slave in secure mode			
																Bit 30 : REM-SB	0 = DC enabled; 1 = REM-SB disables power output			
507									x	R		uint(16)	2	1	0x0000 - 0xFFFF (0 - 125%)	Actual voltage (for translation see programming guide)		2	28	
508										R		uint(16)	2	1	0x0000 - 0xFFFF (0 - 125%)	Actual current (for translation see programming guide)		2	29	
509										R		uint(16)	2	1	0x0000 - 0xFFFF (0 - 125%)	Actual power (for translation see programming guide)		2	30	
520					x					R	-	uint(16)	2	1	0x0000 - 0xFFFF	Count		3	20	
521					x					R	-	uint(16)	2	1	0x0000 - 0xFFFF	Count		3	21	
522					x					R	-	uint(16)	2	1	0x0000 - 0xFFFF	Count		3	22	
523					x					R	-	uint(16)	2	1	0x0000 - 0xFFFF	Count		3	23	
524					x					R	-	uint(16)	2	1	0x0000 - 0xFFFF	Count		3	24	
550					x				x	RW	REM	uint(16)	2	1	0x0000 - 0xE147 (0 - 110%)	OVP threshold (for translation see programming guide)		3	0	
553					x				x	RW	REM	uint(16)	2	1	0x0000 - 0xE147 (0 - 110%)	OCP threshold (for translation see programming guide)		3	3	
556					x				x	RW	REM	uint(16)	2	1	0x0000 - 0xE147 (0 - 110%)	OPP threshold (for translation see programming guide)		3	6	
559					x				x	RW	REM	uint(16)	2	1	0x0000 - 0xC000 (0 - 100%)	UVD threshold (for translation see programming guide)		3	9	
560					x				x	RW	REM	uint(16)	2	1	Coils : Adjustable UVD notification	0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm		3	10	
561					x				x	RW	REM	uint(16)	2	1	0x0000 - 0xC000 (0 - 100%)	OVD threshold (for translation see programming guide)		3	11	
562					x				x	RW	REM	uint(16)	2	1	Coils : Adjustable OVD notification	0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm		3	12	
563					x				x	RW	REM	uint(16)	2	1	0x0000 - 0xC000 (0 - 100%)	UCD threshold (for translation see programming guide)		3	13	
564					x				x	RW	REM	uint(16)	2	1	Coils : Adjustable UCD notification	0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm		3	14	
565					x				x	RW	REM	uint(16)	2	1	0x0000 - 0xC000 (0 - 100%)	OCD threshold (for translation see programming guide)		3	15	
566					x				x	RW	REM	uint(16)	2	1	Coils : Adjustable OCD notification	0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm		3	16	
567					x				x	RW	REM	uint(16)	2	1	0x0000 - 0xC000 (0 - 100%)	OPD threshold (for translation see programming guide)		3	17	
568					x				x	RW	REM	uint(16)	2	1	Coils : Adjustable OPD notification	0x0000 = nothing; 0x0001 = signal; 0x0002 = warning; 0x0003 = alarm		3	18	
650					x				x	RW	REM	uint(16)	2	1	Coils : Mode	0x0000 = Slave; 0xFF00 = Master		4	0	
651					x				x	RW	REM	uint(16)	2	1	Reg : Address	0x0001...0x000F		4	1	
653					x				x	RW	REM	uint(16)	2	1	Coils : MS on/off	0x0000 = off; 0xFF00 = on		4	3	
654									x	W	REM	uint(16)	2	1	Coils : MS start init	0xFF00 = Start init		4	4	
655					x				x	R		uint(16)	2	1	Reg : MS status	0x0000 = not initialised; 0x0001 = init running; 0xFFFD = Different models detected, init not OK; 0xFFFF = init OK		4	5	
656					x					R		float	4	2	Floating point number IEEE754	500		4	6	
658									x	R		float	4	2	Floating point number IEEE754	300		4	7	
660									x	R		float	4	2	Floating point number IEEE754	150		4	8	
662					x					R		uint(16)	2	1		...15		4	9	
663					x					R		uint(16)	2	1	Coils : Remote?	0x0000 = free; 0xFFFF = Remote				
850					x				x	RW	REM	uint(16)	2	1	Coils : Start/Stop	0x0000 = Stop; 0xFF00 = Start		5	0	
851					x				x	RW	REM	uint(16)	2	1	Coils : U	0x0000 = not assigned; 0xFF00 = Assign function to voltage		5	1	
852					x				x	RW	REM	uint(16)	2	1	Coils : I	0x0000 = not assigned; 0xFF00 = Assign function to current		5	2	
854					x				x	RW	REM	uint(16)	2	1	Coils : U-I	0x0000 = not assigned; 0xFF00 = Assign function to U-I curve		5	4	
855					x				x	RW	REM	uint(16)	2	1	Coils : I-U	0x0000 = not assigned; 0xFF00 = Assign function to I-U curve		5	5	
858									x	W	REM	uint(16)	2	1	Coils : Submit for XY	0xFF00 = Submit curve data		5	8	
859					x				x	RW	REM	uint(16)	2	1	0x0001...0x0064			5	9	
860					x				x	RW	REM	uint(16)	2	1	0x0001...0x0064			5	10	
861					x				x	RW	REM	uint(16)	2	1	0x0000...0x03E7	0x0000 = infinite		5	11	
900					x					x					16	Bytes 3-0: Us/Is(AC) in V Bytes 7-4: Ue/le(AC) in V Bytes 15-12: fs(1/T) in Hz Bytes 19-16: fe(1/T) in Hz Bytes 11-8: Angle in degrees Bytes 23-20: Us/Is(DC) in V Bytes 27-24: Ue/le(DC) in V Bytes 31-28: Sequence time in µs	Floating point number in IEEE754 format, see device manual for value range, chapter about function generator Integer in IEEE754 format: 0°...359° Floating point number in IEEE754 format, see device manual for value range, chapter about function generator Floating point number in IEEE754 format: 100µs...36,000,000,000µs	6	0	
2484					x					x						16	Bytes 3-0: Us/Is(AC) in V Bytes 7-4: Ue/le(AC) in V Bytes 15-12: fs(1/T) in Hz Bytes 19-16: fe(1/T) in Hz Bytes 11-8: Angle in degrees Bytes 23-20: Us/Is(DC) in V Bytes 27-24: Ue/le(DC) in V Bytes 31-28: Sequence time in µs	Floating point number in IEEE754 format, see device manual for value range, chapter about function generator Integer in IEEE754 format: 0°...359° Floating point number in IEEE754 format, see device manual for value range, chapter about function generator Floating point number in IEEE754 format: 100µs...36,000,000,000µs	6	99
2600					x					x						16	UI mode: set voltage value IU mode: set current value (16 values block)	value = real set value of voltage * 0.8 / Unom * 32768 or value = real set value of current * 0.8 / Iom * 32		