ELOTECH

R 2000 - N4 . .

Temperature Controller 4 - Zones "heat-only" 4 - Zones "heating-off-cooling"



Installation depth: 122 mm DIN-Format: 96 x 96 mm

Description and operating manual

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2 General Information

| E o.R I | Messages shown by the controller display | | |
|---------|--|--|--|
| <§> | Symbolizes the value of the factory adjustment of the respective parameters. | | |
| >3< | This parameter is available in 3-point controllers only. | | |

3 Installation Instructions

Make certain that the device is used for the intended purpose only.

R2400 controllers are designed for installation in control panels. Protect the device against impermissible humidity and contamination.

Ambient temperature may not exceed 50 °C (122 °F). Electrical connections must be made according to valid regulations and by properly qualified personnel.

If using thermocouple sensors, compensation lines have to be connected directly to the controller terminals. Sensors may be connected only in compliance with the programmed range.

Sensor cables and signal lines (e.g. logic or linear voltage outputs) must be laid separately from control lines and mains voltage supply cables (power cables). It is not permitted to connect the grounds of the sensor-inputs and Logic-outputs with each other.

Separate installation of controller and inductive loads is recommended.

Interference from contactor coils must be suppressed by connecting adapted RC-combinations parallel to the coils.

Control circuits (e.g. for contactors) should not be connected to the mains power supply terminals of the controller.

The configuration parameters are generally to be selected first.

Disclaimer of Liability

We have checked the contents of this document for conformity with the hardware and software described. Nevertheless, we are unable to preclude the possibility of deviations so that we are unable to assume warranty for full compliance. However, the information given in the publication is reviewed regularly. Necessary amendments are incorporated in the following editions.

We would be pleased to receive any improvement proposals which you may have.

The information contained herein is subject to change without notice.

Electronic scrap and components are subject to special treatment and must be disposed of by authorized companies.



4 Type Code



5 Connection Diagram

5.1 Power Supply and Outputs





Type: N421, N431



Type: N437



5.2 Sensor Inputs



It is not permitted to connect the grounds of the sensor-inputs and Logic-outputs with each other.

External Contacts:

| Sotopint Switch: | K 1 | Open | Setpoint 1 (SP1) valid for all zones | |
|--------------------|------------|--------|--|--|
| | | Closed | Setpoint 2 (SP2) valid for all zones | |
| | | | | |
| Adjustment Lock: | KO | Open | Adjustment lock off | |
| Aujustment Lock. | | Closed | Adjustment lock on (see parameter "Adjustment lock") | |
| | | | | |
| Sotooint Changing: | K3 | Open | Individual setpoint 1 adjustment for each zone | |
| Serpoint Onanging. | | Closed | Setpoint 1 will be overtaken for all other zones automatically | |

6 Display and Keyboard



| LED 1: | Control output "heating" of the choosen zone active | LED 2: | Control output "cooling" of the choosen zone active |
|---------|---|----------|---|
| LED A1: | Alarm output A1, indication | LED 🦯 | Setpoint ramp of the choosen zone active |
| LED A2: | Alarm output A2, indication | LED SP2: | Setpoint 2 valid (for all zones) |

Key functions:

| ZONE | Zone preselection |
|------|--|
| Р | Parameter key (parameter preselection) |
| | Adjustment of chosen parameter (e.g. setpoint) to higher or lower values.Short operation:single-step adjustmentLonger operation:quick-scanningWhen the parameter adjustments have been altered but not entered,the display will flash bright/dark. |
| E | Confirmation and storage of the preselected values. The display will show a light chain as a control of this function. |
| Р | Sets the parameter back to the originally stored value. Any alterations made to the parameters, that are not confirmed (E-key) within 30 seconds, will not be accepted and the parameter will return to its originally stored value. The actual process value and the setpoint value will be indicated. |
| F1 | Function key, E. g. all zones are displayed cyclic (zone scanning on/off). Zones, which are not in action (OFF), are not displayed. The function of this key can be programmed into the configuration level of zone 0. See parameter "Co.F1". |

6.1 Tendency Display

After switching the instrument "on" a temperature tendency display will be shown, to give an overview about the temperatures deviations relating to the setpoints in the individual controller zones.

| 9 | Display examples: | | | |
|---|--|--|--|--|
| Zone: 1 2 3 4 | Zone 1: Controller output active temperature OK (Bar central) | | | |
| PROCESS ZONE | Zone 2: Controller output not active Process value is higher than setpoint >0,5 % of measuring range (Bar top) | | | |
| | Zone 3: Controller output not active temperature OK (Bar central) | | | |
| | Zone 4: Controller output active Process value is lower than setpoint <0,5 % of measuring range (Bar bottom) | | | |
| Zone: | Zone 1: Top range end has been reached (sensor break) | | | |
| | Zone 2: Bottom range end has been reached (sensor error, open) | | | |
| $\cup \cup \cap \cup$ | Zone 3: Selftuning algorithm is active | | | |
| PROCESS ZONE | Zone 4: Manual mode | | | |
| The displayed decimal points show the actual situation of the controller output. Flashing digit: Alarm indication in the matching zone | | | | |

6.2 Operating Levels



7 Parameter descriptions:

7.1 Configuration Parameters, Valid for the Complete Device

Alarm configurations, general information:



Each alarm contact works as a common alarm for all zones. The individual alarms A1 (A2) of all zones are connected to the common contact A1 (A2). The selected configuration is valid for all active zones.

Please note:

Care should be taken to ensure that the setpoints of the alarm contacts are programmed within the selected measuring range. If a setpoint ramp has been programmed, the alarms that are relative to the setpoint (signal contact, limit comparator) follow the setpoint ramp.

In case of sensor error the alarms react in the same way as range override.

The alarm contacts therefore do not offer protection against all types of plant breakdown. We recommend the use of a second, independent monitoring unit. The different alarm configurations define the working mode of the alarm. If the controller features a heater current monitoring, two additional heater current alarms are available. The actual alarm values have to be set in the operating level.

| [08] | BFF | Alarm OFF, no alarm signalisation <§> | | |
|---|--|--|--|--|
| Alarm Configuration | / | Signal contact: off-on | | |
| (switches relay A1) | | Limit contact: off-on | | |
| | _ // _ 3 | Limit comparator: off-on-off | | |
| | - <u> </u> | Signal contact: on-off | | |
| | -6-5 | Limit contact: on-off | | |
| | -4-6 | Limit comparator: on-off-on | | |
| | <i>_R_</i> 7 | Limit comparator with start-up suppression: off-on-off | | |
| | 8 | Heater current monitoring, limit contact: off-on | | |
| | -1-9 | Heater current monitoring, limit contact: on-off | | |
| r E.A. I | Here the relay function may be inverted: | | | |
| Switching behaviour Relay A1 | direct | on:LED A1 "on",Relay A1 "activated"off:LED A1 "off",Relay A1 "not active"The relay is switched on if the controller displays an alarmmessage.<§> | | |
| | inverse | on: LED A1 "on", Relay A1 "not active" off: LED A1 "off", Relay A1 "activated" The relay is switched off if the controller displays an alarm message. | | |
| E o. A 2 Alarm Configuration (switches relay A1) | Identical a | Identical adjustment as | | |
| r E.R.2 Switching behaviour Relay A2 | Identical a | adjustment as | | |

Heater current monitoring (option)

The heater current monitoring function is valid for all connected zones. The following parameters are displayed when the alarm configuration is programmed to "heater current" (8 or 9).

The alarm value (heater current value) is programmed as an absolute value.

Please note: Ensure that the limit value is set correctly to avoid false alarms in case supply voltage changes. The alarm can be delayed by selecting a delay time "**dL.Ax**".

The monitoring function and all parameters are valid for all connected zones.

The heater current measuring is designed for a current transformer 1:1000. (ELOTECH type: M2000) Heater current detection and indication range: 0...max. 60,0 A Single-phase operation.

| dLR / delay time, relay A1 | Delay time for heater current alarm A1 5 steps adjustable, unit: seconds The values depend on the current detection cycle time and the number of active controller zones. OFF = no delay time active $<$ § > | |
|--------------------------------------|---|--|
| delay time, relay A2 | Delay time for heater current alarm A2 5 steps adjustable, unit: seconds The values depend on the current detection cycle time and the number of active controller zones. | |
| Current detection interval | 1 60s <§ = 2s> Time interval between the current measurement of two successive zones | |
| Min. leakage current value | If a permanent current is detected in one zone the alarm relay will be activated and the display ary monitoring. If a permanent current is detected in one zone the alarm relay will be activated and the display "PROCESS" will show the error signalisation "Er.Cu". | |
| E <u>a</u> F I | GFF No function | |
| Select function of key "F1" | SERn Automatically zone-scanning "on"/ "off". | |
| | Self-tuning algorithm can be activated by pressing key "F1" in the matching zone. "F1" approx 2sec.: stops self-tuning. | |
| | Shows the actual percentage output ratio, while pressing "F1". | |
| | Lamp (LED) test, while pressing "F1". | |
| LOE | GFF no adjustment lock <§> | |

| Adjustment lock | Ρ[| parameter and configuration levels locked | | |
|------------------------------------|---|---|--|--|
| | n.5P / | all parameters apart from SP1 locked (not SP1) | | |
| | <u> </u> | All parameters that have been locked with All parameters that have been locked with All for the selected and read, but not adjusted. This adjustment cannot be changed if the external contact K2 is closed. | | |
| Zo.0F Zones offset preselection | Continuous numbering of the controller zones | | | |
| | The adjusted offset value is added to the displayed zone numbers in the windows. Therefore a continuous numbering of the zones can be achieved if more than one device is used. Examples: offset = off: zones numbering: 1-4, 1-6, 1-8 offset = 4: zones numbering: 5-8, 5-10, 5-12 | | | |

Serial Interface (RS232, RS485 or TTY)

The controllers of the series **R2400** can be equipped with a serial interface **RS232**, **RS485** or **0/20mA** (half-duplex) as an option.

This enables a master (PLC) to set and to read the process- and configuration parameters. The communication is always controlled by the master. The controller operates as a slave. If there are transmission or range errors detected by the slave, the message is not accepted and the existing parameter values remain valid.

Protocol descriptions and further information: Please see www.elotech.de/downloads

| Prot | ELOTECH- standard protocol <§> | | | |
|--------------------------------|---|--|--|--|
| Protocol selection | Gateway-Protocol (for special applications only) | | | |
| Rdr Device address | 1<§> 255 At this address a master communicates with the controller. Each controller needs a unique address. | | | |
| For | Adjusting the data format for the transmission: | | | |
| Data format | 7E Data bit: 7 Parity: even Stop bit: 1 | | | |
| | 7 Data bit: 7 Parity: odd Stop bit: 1 | | | |
| | Data bit: 7 Parity: even Stop bit: 2 | | | |
| | 7 o 2 Data bit: 7 Parity: odd Stop bit: 2 | | | |
| | Data bit: 7 Parity: no Stop bit: 2 | | | |
| | BE I Data bit: 8 Parity: even Stop bit: 1 | | | |
| | Bo I Data bit: 8 Parity: odd Stop bit: 1 | | | |
| | Bn / Data bit: 8 Parity: no Stop bit: 1 | | | |
| | Bn2 Data bit: 8 Parity: no Stop bit: 2 | | | |
| 占吊しる Baud rate | 0,3 9,6< § > kBaud | | | |
| 2009 ELO2 Control number | Device code End of configuration level | | | |
| | | | | |

7.2 Zone Configuration

| 2008 | 00 | Measuring- or controller zone active <§> |
|--------------------------|-------|--|
| | 8FF | Measuring- or controller zone switched off |
| Eonf | 2P h | 2-point controller "heating-off" <§> |
| Controller configuration | 2Р с | 2-point controller "cooling-off" |
| | 28nc | 2-point controller "cooling non linear". Cooling action with non-linear cooling response curve (e.g. for vapour cooling). |
| | 3P | 3-point-controller "heating-off-cooling" >3< |
| | 3Pnc | 3-point-controller "heating-off-cooling". Cooling action with non-linear cooling response curve (e.g. for vapour cooling). >3< |
| | d, SP | Indicator, no controller action |

| SEn | If the zone | e is configured to PT100, | the following sensors are available: | |
|---|---|--|---|--|
| Sensor selection | P ;0[| Pt100 -50,0100,0°C | | |
| | P ;0F | Pt100 -58212°F | | |
| | 205 | PT100 -90,0205,0°C | | |
| | <i>Ρ2°F</i> | Pt100 -130401°F | | |
| | ργο[| Pt100 0400°C | <§> | |
| | ργορ | Pt100 32752°F | | |
| | P8°[| Pt100 0800°C | | |
| | p8of | Pt100 321472°F | | |
| | If the zone is configured to thermocouple, the following sensors are available: | | | |
| | [40[| Thermocouple (TC) Fe- | CuNi(L) 0400°C | |
| | <u> </u> | Thermocouple (TC) Fe- | CuNi(L) 32752°F | |
| | 18°E | Thermocouple (TC) Fe- | CuNi(L) 0800°C | |
| | 18°F | Thermocouple (TC) Fe- | CuNi(L) 321472°F | |
| | J80[| Thermocouple(TC) Fe- | CuNi(J) 0800°C | |
| | ۶°Fل | Thermocouple (TC) Fe- | CuNi(J) 321472°F | |
| | n ¦0[| Thermocouple (TC) Nic | Cr-Ni(K) 01200°C | |
| | n ¦of | Thermocouple (TC) Ni | Cr-Ni(K) 322192°F | |
| | 510[| Thermocouple (TC) Pt | Rh-Pt(S) 01600°C | |
| | 5;0F | Thermocouple (TC) Pt | Rh-Pt(S) 322912°F | |
| | Please note: If the sensor selection is changed, the following parameters will be reset: | | | |
| | Lc Hig Setp Act | Setpoint 1, Setpoint 2: ower setpoint limitation: gher setpoint limitation: oint ramp rising/falling: Alarm values: ual process value offset: | Setpoint limitation min. measuring range bottom measuring range top | |
| 5 <i>P</i> . <i>H</i> higher setpoint limitation | programm SP.L o | ing range: . top range | Highest adjustable setpoint value <§= 400°C> | |
| 52.6 o lower setpoint limitation | programm bottom rai | ing range: nge 5 <u>2,47</u> | Lowest adjustable setpoint value <§ = 0°C> | |
| Copy function | Copy all parameters of the actual zone to the selected zone x Select the target zone (1,2 or Copy all) with the "UP/DOWN" keys and press "E" (enter). The parameters will be copied. Note: This will only happen if the selected sensor types in the source and in the destination zone are identical. | | | |

Softstart Function in General:

If you select the softstart function, make sure that the instrument is equipped with bistable voltage (logic) outputs. This function is not allowed for instruments with relay outputs. Otherwise the relays will be damaged.

During the softstart the controller's heating output response is limited to a preselected ratio, in order to achieve a slow drying of high performance heat cartridges. This results in a slower, more regular heating period. Simultaneously the output clock frequency is quadrupled.

Once the process value reaches the softstart setpoint, it remains stable at this value for the preselected duration time.

At the end of this period the process value rises to the valid setpoint.

If the softstart is active, the controller's autotune function cannot operate ($\underline{Er}, \underline{GP}$). If a setpoint ramp has been programmed, the softstart has priority, and the ramp will become active after the softstart has been completed.

The softstart only works

- if the parameter P (xp) is programmed \geq 0,1%
- if the actual process value is lower than the softstart setpoint
- 5% of the selected measuring range

It is possible to select this function for each zone individually.



| Softstart | Softstart function is not active. <§> The other softstart parameters are not displayed. Softstart function is active. |
|---|--|
| 5 <u>o</u> . <u></u> Softstart output ratio | range: 10100% <§ = 30> |
| 5 <u>o</u> .5 <u>P</u> Softstart setpoint | range: <u>5<i>PL</i> o</u> <u>5<i>PH</i> <§ = 100></u> |
| Softstart duration time | range: []FF , 0.1 9,9 min. <§ = 2.0> |

| KRnd | <u>OFF</u> | Controller mode <§> |
|-------------|-------------------------------|--|
| Output mode | Βυζο Automatic Mode | In the event of sensor break the last valid output ratio is maintained. |
| | | An "H" is then displayed as the first digit in the setpoint display, followed by the valid output ratio. Like the setpoint, the output ratio can be changed manually. |
| | | Under the following circumstances, the output ratio will be 0%: if the output ratio at the time of the sensor break was 100%. if a setpoint ramp is active. if the control deviation was more than 0,25% of the total range at the time of sensor break. if the Proportional-band (P) = off. if the softstart was active at the time of the sensor break. |
| | | A few seconds after the sensor break has been rectified, the controller returns to automatic operation and calculates the required output ratio. |
| | | An additional signal can be issued in the event of sensor break, if the alarm contacts are programmed accordingly. |
| | Manual Mode | The controller now operates only as an actuator. The control function (PID) is inactive. |
| | | PROCESS: Actual process value is shown. Display of setpoint: First an "H", then the actual adjustable output ratio. Negative value: cooling, positive value: heating |
| | | Like the setpoint, the output ratio can be changed manually. |

7.3 Control Parameters, Zone Dependent

| valid output ratio | 0 100% The output ratio shows the momentary calculated ratio. It cannot be altered. The display is in percent of the installed performance capability for heating or cooling. Output ratio for cooling is shown as a negative value. | |
|---|--|--|
| IGHT Output ratio limit "heating" | 0 100%<§ > The limitation of the output ratio is only necessary if the heating energy supply is grossly overdimensioned compared to the power required. Under normal conditions a limitation is not necessary (setting = 100%). The limitation becomes effective when the controller's calculated output ratio is greater than the maximum permissible (limited) ratio. Warning! | |
| 29.K , Output ratio limit ,,cooling" | 0 100%< § > | |

Adjustment of the control parameters:

As standard the controller operates in PD/I control mode, i. e. controlling without deviation and with practically no overshoot during start-up.

3-point controllers (marked with: **>**3**<**) have a second "cooling" parameter set. The control action can be altered in its structure by adjusting the following values to the parameters:

| a. | no | control | action, | on-off |
|----|----|---------|---------|-------------|
| | | | | • • • • • • |

e. PD/I

c. PD-action d. PI- setting P =**DFF**setting D and I =**DFF**settingI =**DFF**settingD =

modified PID-mode (set: P, D, I) According to the configuration, certain parameters are not visible.

| prop. band (P) "heating" | SFF ; 0,1100,0 % $<$ §=3,0 > If P = SFF (control action: on-off, without feedback) next parameter: FSd . |
|----------------------------------|---|
| ہے۔ rate (D) "heating" | () F F 1 200 sec <§ = 30> |
| ff reset(I) "heating" | ()FF 1 1000 sec <§ = 150> |
| cycle time "heating" | 0,5 240,0 sec <§=10,0> The switching frequency of the actuator can be determined by adjusting the cycle time. In this time interval the controller switches on and off once. Voltage outputs for SSRs cycle time: 0,510 s Optimal value for fast control loops: 0,8s |
| | Relay outputs: cycle time: > 10 s The cycle time should be adjusted to a time as long as possible to minimize the wear of the relay contacts. |



| Switch point difference "heating" und "cooling" >3< | <i>OFF</i>: 0,1<§ > 20,0 °C for range without decimal point <i>OFF</i>: 0,01 2,00 °C for range with decimal point If the controller is in heating mode, the actual process value has to rise by the adjusted value above the setpoint before the cooling mode will become active. By this the switching frequency between the heating and cooling outputs can be reduced. Simultaneous activation of heating and cooling outputs is not possible. | | |
|---|--|--|--|
| 2 P prop. band (P) "cooling" >3< | $\begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} $ | | |
| rate (D) "cooling" | (]FF; 1 200 s <§ = 30> | | |
| reset(I) "cooling" >3< | 3FF ; 1 1000 s <§ = 150> | | |
| cycle time "cooling" >3< | OFF 0,5 240,0 s <§ = 10,0> The switching frequency of the actuator can be determined by adjusting the cycle time. In this time interval the controller switches on and off once. Voltage outputs for SSRs cycle time: 0,510 s Optimal value for fast control loops: 0,8s Relay outputs: cycle time: > 10 s The cycle time should be adjusted to a time as long as possible to minimize the wear of the relay contacts. | | |
| switch sensitivity "cooling" | Only if "P- Band" = off (on-off action, without feedback) Only if "P- Band" = off (on-off action, without feedback) Only if "P- Band" = off (on-off action, without feedback) Only if "P- Band" = off (on-off action, without feedback) Only if "P- Band" = off (on-off action, without feedback) Only if "P- Band" = off (on-off action, without feedback) only if "P- Band" = off (on-off action, without feedback) if "P- Band" = off (on-off action, without feedback) if "P- Band" = off (on-off action, without feedback) if "P- Band" = off (on-off action, without decimal point if "P- Band" = of | | |
| | | | |

Autotune:

The tuning algorithm determines the characteristic values within the controlled process and calculates the valid feedback parameters (P,D,I) and the cycle time (= $0.3 \times D$) of a PD/I-controller for a wide section of the range.

The autotune mode is activated during start-up shortly before the setpoint is reached. If activated after the setpoint has already been reached, the temperature will first drop by approx. 5% of the measuring range in order to detect the exact amplification of the process.

The setpoint must amount to at least 5% of the measuring range.

The tuning algorithm can be activated at any time by selecting the 3PE = on and pressing the **"E**"-key.

After having calculated the correct feedback parameters, the controller will lead the process value to the setpoint.

Zone display: During self tuning is **BPE** shown in the display, alternating with the setpoint value. Tendency display: **"O**" is shown.

Please note: If the softstart function is active, the autotune cannot be activated.

Selecting PE = OFF will stop the autotune function.



| GPE | GFF autotune / self tuning out of action<§> | | |
|-----------------------------|---|--|--|
| Autotune | on autotune / self tuning on request (one time) | | |
| Process value offset | 999 OFF <§> 1000 °C/°F for range without decimal point 99,9 OFF <§> 100,0 °C/°F for range with decimal point This parameter serves to correct the input signal, e.g. for: the correction of a gradient between the measuring point and the sensor tip the line resistance balancing of 2-line RTD (Pt100) sensors correction of the control deviation when using P- or PD-action If for example the offset value is set to +5°C, the real temperature measured by the sensor (when process is balanced) is 5 °C less than the setpoint and the displayed actual process value. Make sure that the corrected temperature process value does not leave the selected measuring range. | | |

7.4 Operating Level

SP2 Setpoint 2

0FF<\$>; <u>5PL o</u>... <u>5P</u>Hi

If the external contact K1 is closed, the setpoint 2 becomes active in all zones in which Setpoint 2 is not set to \car{OFF}

Ramp function:

A programmed ramp is always activated when the setpoint is changed or when the mains supply is switched on. The ramp starts at the actual process value and ends at the preselected setpoint. The ramp can be activated for both setpoint 1 and setpoint 2. By programming the second setpoint accordingly a setpoint profile can be obtained.(Please see example below.)



8 Error Messages

| Error Message | Cause | Possible remedy |
|------------------|---|---|
| 5 <i>P.L o</i> | Lower setpoint limit has been reached | Reduce limit, if need be |
| <u>59.K.</u> | Upper setpoint limit has been reached | Increase limit, if need be |
| 105 | Parameter has been locked | Unlock, if need be Device parameter-> Adjustment lock |
| <u>Er.Ki</u> | Top range end has been exceeded, sensor defect | Check sensor and cable |
| Erlo | Bottom range end has been exceeded, sensor defect | Check sensor and cable Check process value offset |
| <u>Er.0P</u> | Self tuning error | Quit error message by pressing the key "E". Check the self tuning conditions and restart. |
| Er.53 | System error | Quit error message by pressing the key "E". Check all parameters. If the error message continues, please send the controller back to the manufacturer. |
| [08] | Alarmconfiguration of alarm A1: OFF | No alarm signal available |
| <u>[o.82</u> | Alarmconfiguration of alarm A2: OFF | No alarm signal available |
| - no - - PR - | Parameter not available in this zone. | |
| Erlu | Permanent current indicated | |

9 Technical Data

| Input PT100 (RTD) | 2- or 3- wire connection possible Built-in protection against sensor breakage and short circuit Sensor current: $\leq 1 \text{ mA}$ Calibration accuracy: $\leq 0,2 \text{ \%}$ Linear error: $\leq 0,2 \text{ \%}$ Influence of the ambient temperature: $\leq 0,01 \text{ \%}$ / K | | |
|--|---|---|--|
| Input Thermocouple | Built-in internal compensation point and protection against sensor breakage and incorrect polarity. Re-calibration not required for a line resistance of up to 50 Ohm. Calibration accuracy: $\leq 0,25 \%$ Linear error: $\leq 0,22 \%$ Influence of the ambient temperature: $\leq 0,01 \%$ / K | | |
| External contacts | Designed for connecting external potential-free contacts. The contact voltage (approx. 24 V DC, max. 1mA) is provided at controller terminal 75. | | |
| Heater current monitoring | Measuring input range: 0 100mA corresponding 0,0 99,9A when using a current transformer 1:1000. If the value of 100mA is exceeded, the controller may be damaged. | | |
| Control outputs | Bist. voltage signal, 0/18 V DC, max. 10 mA, short-circuit proof or Relay, max. 250 VAC, max. 3 A (cos-phi = 1) | | |
| Alarm outputs | Relay, max. 250 VAC, max. 3 A (cos-phi = 1) | | |
| 7-Segment-Display: | Process: 10 mm red, Set: 10 mm red | | |
| Data protection | EAROM When using a Fieldbus interface please note: Permissible writing operations per parameter must not exceed 1 000 000. | | |
| CE-mark | Tested according to 2004/108/EG; EN 61326-1 Electrical safety: EN 61010-1 | | |
| Power supply | Depends on the version of the device: - 230 V AC, +/-10 %, 48 62 Hz; approx. 10VA - 115 V AC, +/-10 %, 48 62 Hz; approx. 10VA - 24 V DC, +/-25 %, approx. 10W | | |
| Connections | Screw terminals, Protection mode IP 20 (DIN 40050), Insulation class C | | |
| Permissible operating conditions | Operating temperature: Storage temperature: Climate class: | 0 50°C / 32 122°F -30 70°C / -22 158°F KWF DIN 40040; equivalent to annual average max. 75 % rel. humidity, no condensation | |
| Casing | Format, case: Panel cutout: Material: Protection mode: | ¹ / ₄ -DIN; 96 x 96 mm (DIN 43700), installation depth 122 mm 92 +0,5 mm x 92 +0,5 mm Noryl, self-extinguishing, non-drip, UL 94-V1 IP 20 (DIN 40050), IP 50 front side | |
| Weight | Approx. 800g, depends on the version of the device | | |
| Fieldbus Interface (optically isolated) | Depends on the version of the device: - Serial: RS232, RS485, TTY (20mA) | | |

Subject to technical improvements.

10 Notes