

## TEMPERATURE SENSING APPLICATION USING ICmic DAC (ICM7363/7343/7323)

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ICM7363, ICM7343 and ICM7323 are 12-, 10- and 8- bit low power Digital to Analog Converters (DAC). This application note describes the usage of these DAC to acquire low frequency analog data. This provides an alternative method to acquiring data without using an expensive Analog to Digital Converter (ADC).

This option is worth considering in many applications that are typically implemented with an ADC since it can result in lower power consumption, reduced system cost and more flexibility. This approach is particularly useful if one or more of the following are true.

- Repetitive high bandwidth transient signal is to be measured. The advantage in such a case is that we can replace an expensive, high bandwidth ADC with a much cheaper DAC and comparator combination. Only the comparator has to be able to sustain the entire bandwidth of the signal while the DAC can have a long settling time without affecting the quality of the measurement. However if the signal is single shot event then the ADC method is preferable.
- DAC is already being used in the system for some other application and it can be utilized to double as an ADC when it is not being used as a DAC, thus removing the need for a separate ADC. This would help reduce the system cost and form factor.
- Low frequency data is to be measured with high accuracy and low system cost. Using a DAC might be desirable for the reason that it can sometimes reduce the amount of overhead on the processor if the processing part can be moved in the analog domain. An example of this case is when low battery alarm has to be generated, it might be desirable to use a simple DAC to provide reference (negative input) and a comparator comparing the battery voltage (positive input). The processor needs to react only in the event that the comparator output goes low thus triggering the low battery alarm.

Apart from the above mentioned cases and examples there are many cases where using a DAC is a better option than the conventional method of using an ADC. This application note gives an example of persuading the DAC to act as an accurate ADC for temperature sensing.

### Temperature Sensing using a DAC

This is an application that is typically implemented with an analog to digital converter (ADC). However this note provides an alternative method of implementing such a design. This approach is particularly suitable in many cases, some of which have been mentioned in the previous section.

We can implement this system as in the block diagram below.

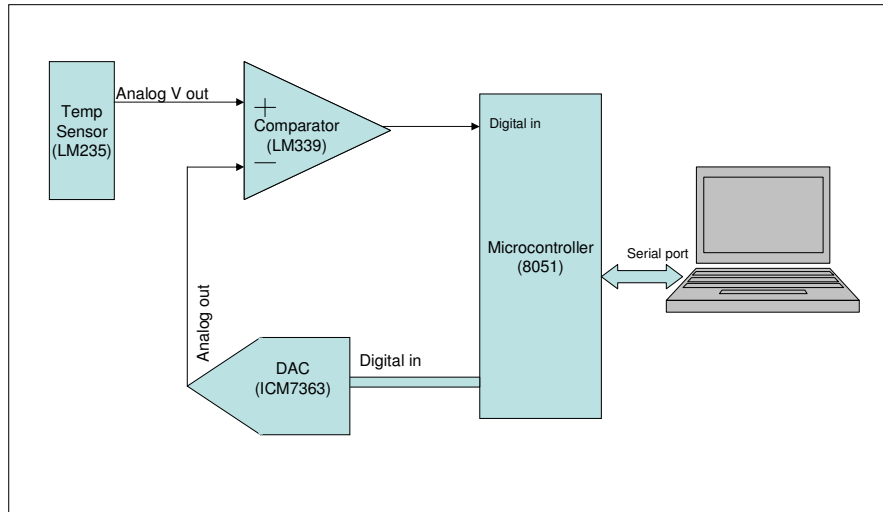


Figure 1: Digitizing temperature sensor output using ICM7363 DAC

The DAC / comparator combination can act as a successive approximation ADC. This can be done in a number of ways but the quickest is by using binary trial of weights as described below.

## Successive Approximation Method

In order to digitize an analog value each bit starting from the most significant one is first set to 1 and the corresponding analog value is compared with the actual value. If the actual value is greater than the resulting value then the bit is set to one otherwise it is reset to 0. The process is repeated for all the bits till we reach the least significant bit. The algorithm for this conversion is given below.

Table 1: Algorithm for Digital conversion of data

<p>Begin:</p> <p>Make the most significant bit high;</p> <p>Loop:</p> <p>Convert using the current value; Wait to allow the DAC to settle;</p> <p>If comparator input is high Leave the bit high;</p> <p>Else Make the bit low;</p> <p>Make the next bit high;</p>
--

Loop till all bits are tested;  
Value after the loop would be the converted value;

Thus this process makes the minimum time for one complete conversion for the resulting successive approximation "ADC" equal to the conversion time of the DAC times the number of bits in DAC.

Total Conversion time (min.) = Settling time for DAC x Number of bits in DAC

Thus for 8-bit digital conversion the maximum rate for the conversion is equal to 1/8 of the DAC conversion rate. This is fast enough for many low frequency applications like the one discussed in this application note.

A simplified illustration of the operation of this algorithm is shown in the figure below.

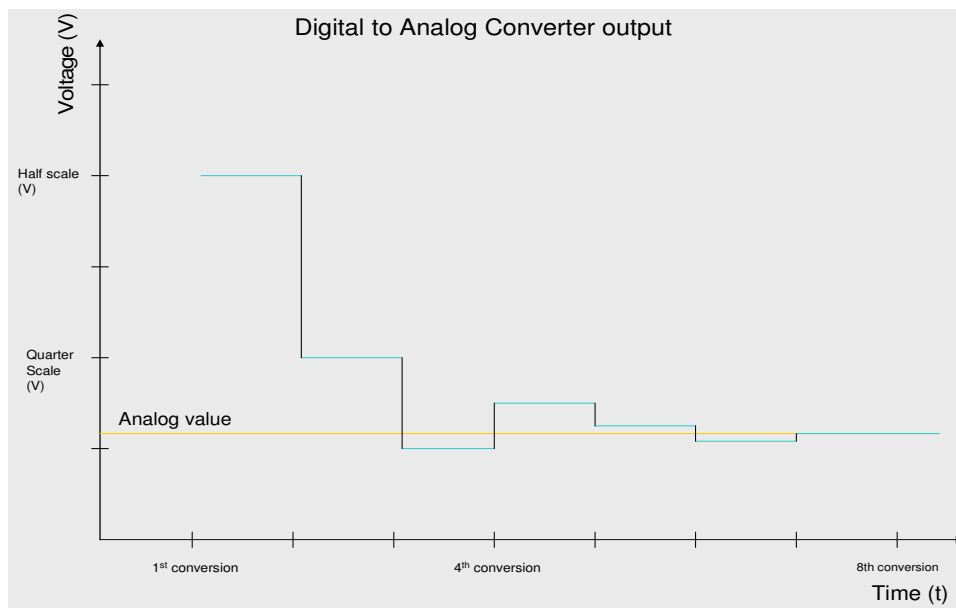


Figure 2: DAC output zeroing on analog value

## Implementation for 8051 based microcontroller

The following code is for the conversion of the analog data into digital utilizing a 8051 based microcontroller.

This example uses ICM7363 which is a 12-bit low power DAC to get a 12 bit digital value for the input voltage provided by the temperature sensor.

Table 2: Sample code for successive approximation method for ICM7363

```

; Description
;
; Sample code for digital conversion of analog data using ICM7363 with 8051 based microcontroller
; This example uses port 2 to communicate with the DAC. The code provides output in ASCII character 1, 0
; which has to be interpreted as a voltage according to the formula  $2 \times (V_{ref,in} \times D) / 2^n$ 
;
; MCS51 pins
; P2.0 SCK
; P2.2 SDI
; P2.3 CSB
;
; Author: Shahab A. Najmi
; Sairan Sakrani
; Feb, 2004

$MOD51 ; Contains Assembler specific directives

;=====
; NOTES:
; *> AT89S8252 Memory
; (Data) RAM: 0000H – 0100H 256 bytes
; (Data) EEPROM: 0000H – 07FFH 2K bytes (need to set EEMEN=1 with MOVX)
; (Pgm) Flash: 0000H – 2000H 8K bytes
;
; *> AT89S8252 implements 256 byte RAM. RAM addresses overlapping SFR are
; accessed using indirect addressing.
;
; *> MCS-51 RAM bit addresses
; RAM byte 0020H: 00H(LSB) – 07H(MSB)
; RAM byte 0021H: 08H(LSB) – 0FH(MSB)
; ...
; RAM byte 002FH: 78H(LSB) – 7FH(MSB)
;
; *> MCS-51 Hardware bit address
; As defined in MOD51 file
;
; *> This firmware architecture
; RAM 0000H – 0007H ( 7 bytes) R0 thru R7
; RAM 0008H – 001FH ( 24 bytes) Stack
; RAM 0020H – 0100H (224 bytes) Variables
;=====

;Hardware addresses

; SERIAL COMMUNICATION VARIABLES

P_MOSI BIT P1.5
P_MISO BIT P1.6
P_CLK BIT P1.7
SPIF EQU 10000000B

P_SCK EQU P2.0 ;P2.0 – SCK
P_CLRB EQU P2.1 ;P2.1 - CLR B
P_SDI EQU P2.2 ;P2.2 - SDI
P_CSB EQU P2.3 ;P2.3 - CSB

;Variables – Data For Port 0 signals
P0_D0 BIT 000H ;RAM 20.0
P0_D1 BIT 001H ;RAM 20.1

;Variables – Data For Port 1 signals
ICLK BIT 008H ;RAM 21.0
IPLB BIT 009H ;RAM 21.1

```

```

IDS      BIT      00AH      ;RAM 21.2
mSDO    BIT      00BH      ;RAM 21.3
P1_D4   BIT      00CH      ;RAM 21.4
P1_D5   BIT      00DH      ;RAM 21.5
P1_D6   BIT      00EH      ;RAM 21.6
P1_D7   BIT      00FH      ;RAM 21.7

;Variables – Data For Port 2 signals
mSCK    BIT      010H      ;RAM 22.0
mCLR    BIT      011H      ;RAM 22.1
mSDI    BIT      012H      ;RAM 22.2
mCSB    BIT      013H      ;RAM 22.3
ORLY    BIT      014H      ;RAM 22.4
P2_D5   BIT      015H      ;RAM 22.5
P2_D6   BIT      016H      ;RAM 22.6
P2_D7   BIT      017H      ;RAM 22.7

;Variables – Data For Port 3 signals
P3_D0   BIT      018H      ;RAM 23.0
P3_D1   BIT      019H      ;RAM 23.1
P3_D2   BIT      01AH      ;RAM 23.2
P3_D3   BIT      01BH      ;RAM 23.3
P3_D4   BIT      01CH      ;RAM 23.4
P3_D5   BIT      01DH      ;RAM 23.5
P3_D6   BIT      01EH      ;RAM 23.6
P3_D7   BIT      01FH      ;RAM 23.7

;Variables – Bit addressable flags
BITCOUNT EQU 020H      ;RAM 24.0

;Variables – DAC codes
DACCL EQU 030H      ;DAC code LOW byte
DACCH EQU 031H      ;DAC code HIGH byte

;Temporary Variables
BLKVAR EQU 032H
TEMPVAL EQU 033H      ;Temporary value holder
TEMPCNT EQU 034H      ;Temporary control sequence holder
COMPRESULT BIT 035H      ;Result of comparison
WDLYH EQU 036H      ;Delay – high byte
WDLYL EQU 037H      ;Delay – low byte
BLKVAR2 EQU 038H
SENDBUF EQU 039H
TEMPBUF EQU 03AH
TEMPBUF2 EQU 03BH

;=====
;Interrupt Vectors
ORG 0000H
LJMP BEGIN      ;0000H - RESET vector
ORG 0003H
LJMP ISEXT0      ;0003H - External 0
ORG 000BH
LJMP ISTM0      ;000BH - Timer/Counter 0
ORG 0013H
LJMP ISEXT1      ;0013H – External 1
ORG 001BH
LJMP ISTM1      ;001BH – Timer/Counter 1
ORG 0023H
LJMP ISSER      ;0023H – Serial Port

ISEXT0:
ISTM0:
ISEXT1:
ISTM1:
ISSER: RETI      ;Empty interrupt services

;=====
;Beginning of Main Routine

```

```

=====
ORG    0100H

BEGIN:
    MOV    IE,#00H        ;Disable interrupts

;----- Initialize interface to DACs
    CLR    P_CLRB        ;CLRB=LOW
    SETB   P_CSB         ;CSB(P2.3)=HIGH
    CLR    P_SCK         ;SCK(P2.0)=LOW
    CLR    P_SDI         ;SDI(P2.2)=LOW
    SETB   P_CLRB        ;CLRB(P2.1)=HIGH
    SETB   P3.2          ;TO BE USED AN INPUT
    MOV    A, #0
    MOV    BLKVAR, #0
    MOV    BLKVAR2, #0
    MOV    DACCL, #0FFH
    MOV    DACCH, #08FH
    LCALL SNDDAC

    MOV    DACCL, #00H    ;Initialize DAC lower byte
    MOV    DACCH, #0E0H

CONVERSION:

    MOV    BITCOUNT, #0BH    ;Initialize the bit counter

CONVHS:
    MOV    A, #00H           ;Conversion High Byte setup
    MOV    TEMPCNT, #08H
    MOV    TEMPVAL, #00H
    MOV    DACCL, #00H       ;Initialize DAC lower byte
    MOV    DACCH, #050H     ;Initialize DAC Upper byte

CONVH:
    MOV    B, #02H          ;To divide by this to move bits
    MOV    TEMPVAL, DACCH   ;Saves the old value temp
    MOV    A, DACCH
    ORL   A, TEMPCNT
    MOV    DACCH, A
    LCALL SNDDAC
    LCALL DL1MS
    LCALL DL1MS
    LCALL DL1MS
    LCALL DL1MS
    LCALL DL1MS

    JB    P3.2, NRESTH     ;if (pin 12==1){NRESTH}
    MOV    DACCH, TEMPVAL

NRESTH:
    MOV    A, TEMPCNT
    DIV   AB
    MOV    TEMPCNT, A
    JZ    CONVLS
    LJMPL CONVH

CONVLS:

    MOV    A, #80H
    MOV    TEMPCNT, A

```

```

MOV    TEMPVAL, #00H

CONVL:

MOV    B, #02H           ;To divide by this to move bits
MOV    TEMPVAL, DACCL   ;Saves the old value temp
MOV    A, DACCL
ORL    A, TEMPCNT
MOV    DACCL, A

LCALL  SNDDAC
LCALL  DL1MS
LCALL  DL1MS
LCALL  DL1MS
LCALL  DL1MS
LCALL  DL1MS

JB     P3.2, NRESTL     ;if (pin 12==0){NRESTL}
MOV    DACCL, TEMPVAL

NRESTL:
MOV    A, TEMPCNT
DIV    AB
MOV    TEMPCNT, A
JZ     ENDCONV
LJMP   CONVL

ENDCONV:

MOV    SENDBUF, DACCH
LCALL  SERIALTRANS
MOV    SENDBUF, DACCL
LCALL  SERIALTRANS

MOV    SENDBUF, #10
LCALL  RS232
MOV    SENDBUF, #13
LCALL  RS232

LJMP   CONVERSION

;=====
;End of Main Routine
;=====

;----- Send code to all DACs and update simultaneously
;
;LCALL  SNDDAC           ;Send the high and low bytes to DAC
;
;
;MOV    A, DPL
;CJNE  A, TBENDL, SWND1
;MOV    A, DPH           ;[12cyc]
;CJNE  A, TBENDH, SWND2 ;[24cyc]
;
;
;CLR    P2.7            ;[12cyc]
;SETB  P2.7            ;[12cyc]
;CLR    P3.6            ;[12cyc]
;SETB  P3.6            ;[12cyc]
;DJNZ  WAVEPER, SWRPT ;[24cyc]
;RET
;

;SWRPT:
;MOV    DPTR, #SNTBL1+1 ;[24cyc]
;LJMP   SWLUP           ;[24cyc]
;

;SWND1:
;NOP                    ;[12cyc]

```

```

;
;      NOP                      ;[12cyc]
;      NOP                      ;[12cyc]
;
;SWND2:
;
;      NOP                      ;[12cyc]
;      NOP                      ;[12cyc]
;      NOP                      ;[12cyc]
;      NOP                      ;[12cyc]
;      NOP                      ;[12cyc]
;      NOP                      ;[12cyc]
;      NOP                      ;[12cyc]
;      NOP                      ;[12cyc]
;      NOP                      ;[12cyc]
;      LJMPL SWLUP              ;[24cyc]
;
;=====
;Subroutine:  SNDDAC
;Description:  Send 16 bits of data to DAC.
;              First, CSB is set to LOW, then 16 bits are sent,
;              then, CSB is brought back HIGH.
;Arguments:   DACCH = Data high byte (Bit15 thru Bit8)
;              DACCL = Data low byte (Bit7 thru Bit0)
;Trashed:    Whatever trashed by subr SN8BIT
;*****
SNDDAC:      SETB   P_CSB          ;CSB should already HIGH initially, do it anyhow
             CLR   P_CSB          ;CSB=LOW, initiate the data transfe
             MOV   A,DACCH        ;
             LCALL SN8BIT         ;Send high byte – note the subr do the POP
             MOV   A,DACCL        ;
             LCALL SN8BIT         ;Send low byte
             SETB  P_CSB          ;CSB=HIGH, end the data transfer
             RET                   ;Done
;=====
;
;=====
;Subroutine:  SN8BIT
;Description:  Send 8 bits of data on P2.2 (SDI)
;              Clock the P2.0 (SCK) as needed.
;Arguments:   A = data to be sent
;Trashed:    C,R0
;*****
SN8BIT:      MOV   R0,#8          ;Init loop counter
SN8LUP:      CLR   P_SCK          ;CLK=L
             RLC   A              ;Set C=bit to be sent
             MOV   P_SDI,C        ;Set SDI=bit to be sent
             SETB  P_SCK          ;CLK=H, ICM7363 latches data on SDI at +ve edge
;
             DJNZ  R0,SN8LUP      ;Decrement counter, loop if more bits to sent
             CLR   P_SCK          ;CLK=L
             RET                   ;Done
;=====
;
;=====
;Subroutine:  DL1MS
;Description:  Delay about 1ms ( for crystal @7.3728 MHz )
;              Each ms needs about 0.001sec/7.3728e+6 = 7372.8 = 7372 cycles
;Arguments:   None
;Trashed:    R5, R6, R7
;*****
DL1MS:      MOV   R5,#150        ;12 cyc; Init delay counter
             MOV   R6,#3         ;12 cyc
             MOV   R7,#1         ;12 cyc
;
DL1MSL:     DJNZ  R5,DL1MSL      ;24 cyc      (0 + (3+0*150-1)*150) x 24
             DJNZ  R6,DL1MSL      ;24 cyc      (3 + 0*150) x 24
             DJNZ  R7,DL1MSL      ;24 cyc      (1) x 24
             RET
;=====

```



```

;=====
;Subroutine:      WVDLY
;Description:     Delay about N x 1ms ( for crystal @7.3728 MHz )
;                Each ms needs about 0.001sec/7.3728e+6 = 7372.8 = 7372 cycles
;
;Arguments:      WDLYH, WDLYL – delay count in ms
;Trashed:        R5, R6, R7
;*****
;
WVDLY:
    MOV     A,WDLYL
    JNZ    WVDLYL
    MOV     A,WDLYH
    JZ     WVDLYE

WVDLYL:LCALL   DL1MS
    DEC     WDLYL
    MOV     A,WDLYL
    JNZ    WVDLYL

    MOV     A,WDLYH
    JZ     WVDLYE
    DEC     WDLYH

    SJMP   WVDLYL

WVDLYE:      RET
;=====

;=====
;Subroutine:      SERIALOUT
;Description:     WRITES SERIAL DATA OUT THROUGH SCL, MOSI, MISO
;                A HAS INPUT DATA
;
;Trashes:        A, SPDR
;=====
SERIALOUT:

    SETB P_MOSI
    SETB P_MISO
    SETB P_CLK
    MOV SPCR, #01010111B
;MOV A, SENDBUF

    MOV SPDR, SENDBUF

BBB:
    MOV A, SPSR
    ANL A, #SPIF
    JZ BBB

    RET

;WRITE TO SERIAL SBUF WITH RS232

;Subroutine RS232

RS232:
    MOV TMOD, #20H
    MOV TH1, #-2
    MOV SCON, #50H
    SETB TR1

TRANS:
    MOV SBUF, SENDBUF
;MOV SBUF, #'A'

HERE:
    JNB TI, HERE
    CLR TI

```

```

RET
;=====
; Subroutine:    SERIALTRANS
; Description:   Transmits each bit of the conversion separately in ASCII to the serial buffer
; Trashes:      A, Whatever is trashed by RS232
;=====

SERIALTRANS:
    MOV TEMPBUF, SENDBUF
SERIALTRANS0:
    MOV A, TEMPBUF
    ANL A, #10000000B
    JZ CALLTRANSZERO0
    LJMP CALLTRANSONE0
CALLTRANSZERO0:
    LCALL TRANSZERO
    LJMP SERIALTRANS1
CALLTRANSONE0:
    LCALL TRANSONE
    LJMP SERIALTRANS1

SERIALTRANS1:
    MOV A, TEMPBUF
    ANL A, #01000000B
    JZ CALLTRANSZERO1
    LJMP CALLTRANSONE1
CALLTRANSZERO1:
    LCALL TRANSZERO
    LJMP SERIALTRANS2
CALLTRANSONE1:
    LCALL TRANSONE
    LJMP SERIALTRANS2

SERIALTRANS2:
    MOV A, TEMPBUF
    ANL A, #00100000B
    JZ CALLTRANSZERO2
    LJMP CALLTRANSONE2
CALLTRANSZERO2:
    LCALL TRANSZERO
    LJMP SERIALTRANS3
CALLTRANSONE2:
    LCALL TRANSONE
    LJMP SERIALTRANS3

SERIALTRANS3:
    MOV A, TEMPBUF
    ANL A, #00010000B
    JZ CALLTRANSZERO3
    LJMP CALLTRANSONE3
CALLTRANSZERO3:
    LCALL TRANSZERO
    LJMP SERIALTRANS4
CALLTRANSONE3:
    LCALL TRANSONE
    LJMP SERIALTRANS4

SERIALTRANS4:
    MOV A, TEMPBUF
    ANL A, #00001000B
    JZ CALLTRANSZERO4
    LJMP CALLTRANSONE4
CALLTRANSZERO4:
    LCALL TRANSZERO
    LJMP SERIALTRANS5
CALLTRANSONE4:
    LCALL TRANSONE
    LJMP SERIALTRANS5

```

```

SERIALTRANS5:
    MOV A, TEMPBUF
    ANL A, #00000100B
    JZ CALLTRANSZERO5
    LJMP CALLTRANSONE5
CALLTRANSZERO5:
    LCALL TRANSZERO
    LJMP SERIALTRANS6
CALLTRANSONE5:
    LCALL TRANSONE
    LJMP SERIALTRANS6

SERIALTRANS6:
    MOV A, TEMPBUF
    ANL A, #00000010B
    JZ CALLTRANSZERO6
    LJMP CALLTRANSONE6
CALLTRANSZERO6:
    LCALL TRANSZERO
    LJMP SERIALTRANS7
CALLTRANSONE6:
    LCALL TRANSONE
    LJMP SERIALTRANS7

SERIALTRANS7:
    MOV A, TEMPBUF
    ANL A, #00000001B
    JZ CALLTRANSZERO7
    LJMP CALLTRANSONE7
CALLTRANSZERO7:
    LCALL TRANSZERO
    LJMP SERIALTRANS8
CALLTRANSONE7:
    LCALL TRANSONE
    LJMP SERIALTRANS8

SERIALTRANS8:

    MOV SENDBUF, TEMPBUF
    RET

;=====
; Subroutines to transmit an ASCII 0 and 1
; Description: If a zero is to be transmitted then this subroutine sends out an ASCII zero
;              and a ASCII 1 in case of a one
; Trashes: SENDBUF
;=====
TRANSZERO:
    MOV SENDBUF, #'0'
    LCALL RS232
    RET
TRANSONE:
    MOV SENDBUF, #'1'
    LCALL RS232
    RET
END

```

## Contact Information

For any other questions / queries please feel free to contact us at [support@icmic.com](mailto:support@icmic.com) or contact us at the following address.

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