

## F2961

## LINEAR INTEGRATED CIRCUIT

## HIGH EFFICIENT DIRECT PWM DRIVE IC

#### DESCRIPTION

The UTC **F2961** is a high efficient, single phase and bipolar drive direct PWM drive motor driver IC. It is suitable for variable speed control FAN of personal computer's power supply radiation and CPU cooler with over temperature protection.

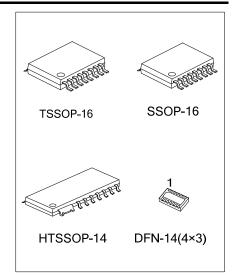
### FEATURES

- \* Single phase bipolar drive(16V,1A output transistor built in.)
- \* Built in variable speed function with thermistor input signal. (External excitations direct PWM of upper side transistor control, low noise and low vibration.)
- \* Include re-circulation Diode and external parts are few.
- \* Include Hall bias circuit and thermal shut down circuit.
- \* Minimum speed settable.
- \* Full drive at open thermistor.
- \* Lock protect and auto restart function.
- \* FG output and RD output signal available.

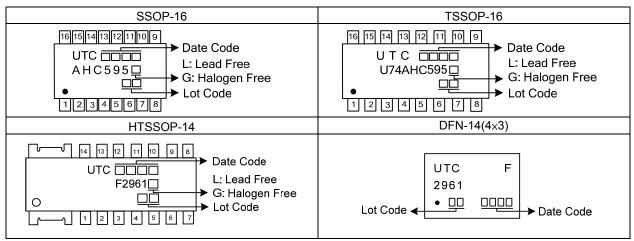
#### ORDERING INFORMATION

Ordering	Number	Daakaga	Packing	
Lead Free	Halogen Free	Package		
F2961L-R16-R	F2961G-R16-R	SSOP-16	Tape Reel	
F2961L-P16-R	F2961G-P16-R	TSSOP-16	Tape Reel	
F2961L-N14-R	F2961G-N14-R	HTSSOP-14	Tape Reel	
F2961L-K14-4030-R	F2961G-K14-4030-R	DFN-14(4×3)	Tape Reel	

F2961 <u>G-R14-R</u>	(1) Packing Type (2) Package Type (3) Green Package	(1) R: Tape Reel (2) R16: SSOP-16, P16: TSSOP-16, N14: HTSSOP-14 K14-4030: DFN-14(4×3) (3) G: Halogen Free and Lead Free, L: Lead Free
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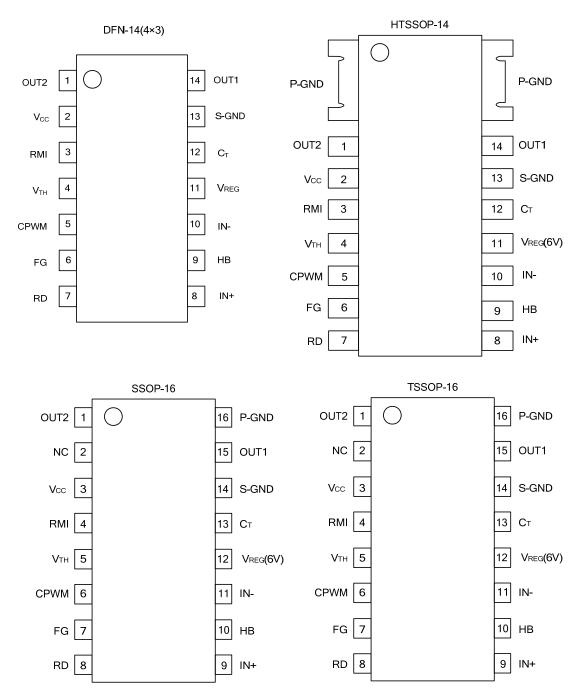
#### MARKING





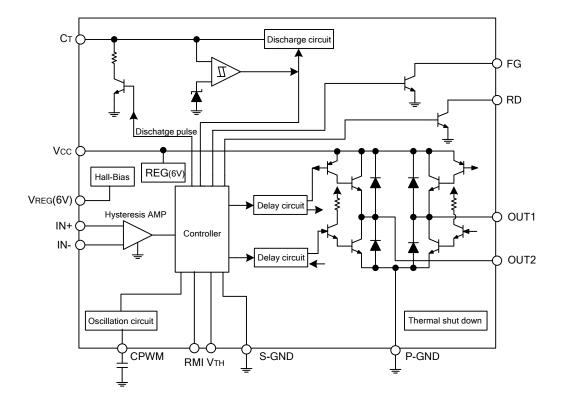
# F2961

#### ■ PIN CONFIGURATIONS





## BLOCK DIAGRAM





#### ■ ABSOLUTE MAXIMUM RATINGS

PARAMETER	SYMBOL	RATINGS	UNIT
Supply Voltage	Vcc	18	V
Output Current	Ιουτ	1	А
Output Supply Voltage	Vout	18	V
HB Output Current	I <sub>HB</sub>	10	mA
V <sub>TH</sub> Input Voltage	VIH	6	V
RD/FG Output Supply	V <sub>RD/FG</sub>	18	V
RD/FG Output Current	I <sub>RD/FG</sub>	10	mA
Operating Temperature	T <sub>OPR</sub>	-20 ~ +85	°C
Storage Temperature	T <sub>STG</sub>	-40 ~ +150	°C

Note: Absolute maximum ratings are those values beyond which the device could be permanently damaged. Absolute maximum ratings are stress ratings only and functional device operation is not implied.

#### THERMAL DATA

PARA	METER	SYMBOL	RATINGS	UNIT
	SSOP-16/TSSOP-16		160	°C/W
Junction to Ambient	HTSSOP-14	θ <sub>JA</sub>	146	°C/W
	DFN-14(4×3)		53	°C/W
Junction to Case	SSOP-16		42	°C/W
	TSSOP-16	0	39	°C/W
	HTSSOP-14	θ <sub>Jc</sub>	33	°C/W
	DFN-14(4×3)		10	°C/W

#### ■ **RECOMMENDED OPERATING CONDITION** (T<sub>A</sub>=25°C, unless otherwise specified)

PARAMETER	SYMBOL	RATINGS	UNIT
Supply Voltage	V <sub>CC</sub>	4.5 ~ 16	V
V Threshold Input Voltage Range	V <sub>TH</sub>	0~6	V
Common- mode Hall Input Voltage Range	VICM	0.2 ~ 3	V

#### ■ ELECTRICAL CHARACTERISTICS (V<sub>CC</sub>=12V, T<sub>A</sub>=25°C, unless otherwise specified)

PARAMETER		SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Operating Current Drain		ICC 1	Rotation mode	12	18	24	mA
Operating Current Drain		ICC 2	Lock protect mode	8	11	16	mA
6V Regulator		V <sub>REG(6V)</sub>	I <sub>REG</sub> =5mA	5.8	6	6.2	V
CPWM Voltage	High	V <sub>CRH</sub>		3.5	3.75	4.0	V
	Low	V <sub>CRL</sub>		1.95	2.0	2.15	V
CPWM Oscillation Frequer	ncy	FPWM	C=100pF	18	25	32	KHz
C- nin Voltago	High	V <sub>CTH</sub>			3.6	3.75	V
C⊤ pin Voltage	Low	V <sub>CTL</sub>		1.5	1.6	1.85	V
C⊤ Current	Charge	I <sub>CT1</sub>	V <sub>CT</sub> =0V	1.5	2.0	2.5	μA
C† Current	Discharge	I <sub>CT2</sub>	V <sub>CT</sub> =4.2V	0.1	0.2	0.3	μA
C⊤ Charge/Discharge Curr	ent Ratio	R <sub>CT</sub>	R <sub>CD</sub> =I <sub>CT1</sub> /I <sub>CT2</sub>	8.5	10.0	11.5	
Output Saturation Lower side upper side		V <sub>OL</sub>	I <sub>OUT</sub> =200mA		0.2	0.3	V
		V <sub>OH</sub>	I <sub>оυт</sub> =200mА		0.9	1.1	V
HB Voltage		V <sub>HB</sub>	I <sub>HB</sub> =5mA		1.25		V
Hall input sensitivity		$V_{\text{HN}}$	Zero to peak including offset and hysteresis		10	20	mV
RD/FG pin Low Voltage		$V_{FG}$	I <sub>FG</sub> =5mA		0.1	0.3	V
RD/FG pin Leak Current		I <sub>FGL</sub>	V <sub>FG</sub> =7V			30	μA

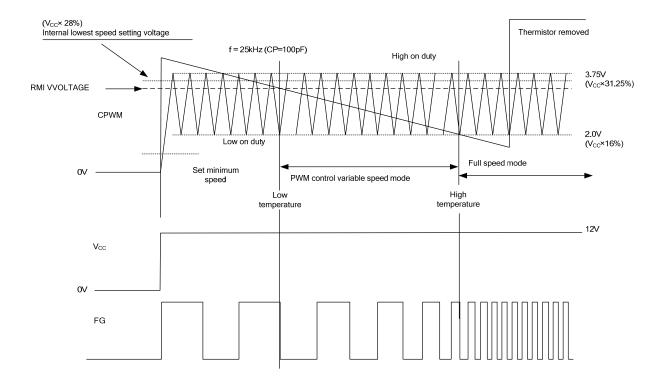


#### TRUTH TABLE

IN-	IN+	CPWM	СТ	OUT1	OUT2	FG	RO	MODE
Н	L			Н	L	L		ROTATION(DRIVE)
L	Н	L	L	L	Н	OFF		PWM OFF
Н	L	Ц		OFF	L	L		ROTATION(RECIRCULATION)
L	Н	H	L	L	OFF	OFF		PWM OFF
Н	L		Н	Н	OFF	L		ROCK PROTECT
L	Н			OFF	Н	OFF		ROCKPROTECT

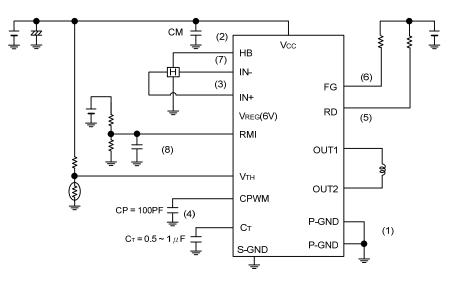
Note: CPWM-H = CPWM>V<sub>TH</sub>, CPWM-L = CPWM<V<sub>TH</sub>

### CONTROL TIMING CHART





## TYPICAL APPLICATION CIRCUIT



#### (1) Voltage source-GND line layout

P-GND is connected to motor supply stage and S-GND is connected to control stage. Divides each line and external parts of control stage are connect to S-GND.

(2) Capacitor of re-circulation stability

CM capacitor that is for PWM drive and kick back absorption to be  $0.1 \sim 1\mu$ F for restrain V<sub>CC</sub> rising by kick back voltage. This IC is upper side transistor switching type then re-circulation current through lower side transistor. CM capacitor connects between V<sub>CC</sub>(VM) and P-GND with shortest and wide line.

(3) Hall input

To be short lines for avoid noise. Hall input amplifier has 20mV hysteresis. Then we recommend the hall input revel to be 60mV or over.

(4) **PWM oscillation frequency setting capacitor** 

PWM basic frequency becomes 25KHz when put on CP=100PF.

(5) RD output

Terminal is open corrector output. Low at rotation mode and High at stop mode. Open the terminal at no use.

(6) FG output

Output is open corrector. FG output according to rotation speed by phase change. Open the terminal at no use.

(7) **HB pin** 

1.25V voltage reference for hall element bias.

(8) RMI pin

The pin must be connected to  $V_{\text{TH}}$  pin if no use. Lowest speed voltage is settled 10% duty inside.

If you set full speed mode when fan will start, capacitor is required.

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