# 5.0 A H-Bridge with Load Current Feedback

The 33887 is a monolithic H-Bridge Power IC with a load current feedback feature making it ideal for closed-loop DC motor control. The IC incorporates internal control logic, charge pump, gate drive, and low  $R_{\rm DS(ON)}\,{\rm MOSFET}$  output circuitry. The 33887 is able to control inductive loads with continuous DC load currents up to 5.0 A, and with peak current active limiting between 5.2 A and 7.8 A. Output loads can be pulse width modulated (PWM-ed) at frequencies up to 10 kHz. The load current feedback feature provides a proportional (1/375th of the load current) constant-current output suitable for monitoring by a microcontroller's A/D input. This feature facilitates the design of closed-loop torque/speed control as well as open load detection.

A Fault Status output terminal reports undervoltage, short circuit, and overtemperature conditions. Two independent inputs provide polarity control of two half-bridge totem-pole outputs. Two disable inputs force the H-Bridge outputs to tri-state (exhibit high impedance).

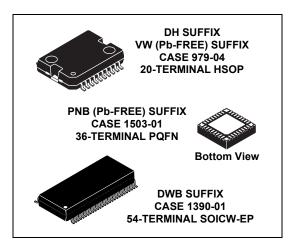
The 33887 is parametrically specified over a temperature range of  $-40^{\circ}\text{C} \le T_{A} \le 125^{\circ}\text{C}$  and a voltage range of 5.0 V  $\le$  V+  $\le$  28 V. The IC can also be operated up to 40 V with derating of the specifications.

#### **Features**

- 5.0 V to 40 V Continuous Operation
- 120 mΩ R<sub>DS(ON)</sub> H-Bridge MOSFETs
- · TTL/CMOS Compatible Inputs
- PWM Frequencies up to 10 kHz
- Active Current Limiting (Regulation) via Internal Constant OFF-Time PWM (with Temperature-Dependent Threshold Reduction)
- Output Short Circuit Protection (Short to V+ or Short to GND)
- · Undervoltage Shutdown
- · Fault Status Reporting
- Sleep Mode with Current Draw ≤50 µA (Inputs Floating or Set to Match Default Logic States)
- Pb-Free Packaging Designated by Suffix Codes VW and PNB

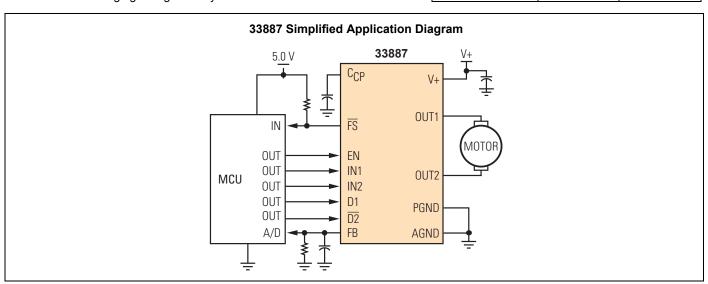
# 33887

# 5.0 A H-BRIDGE WITH LOAD CURRENT FEEDBACK



#### **ORDERING INFORMATION**

Device	Temperature Range (T <sub>A</sub> )	Package
MC33887DH/R2		20 HSOP
PC33887VW/R2	-40°C to 125°C	20 113OF
MC33887PNB/R2	-40 0 10 123 0	36 PQFN
MC33887DWB/R2		54 SOICW-EP



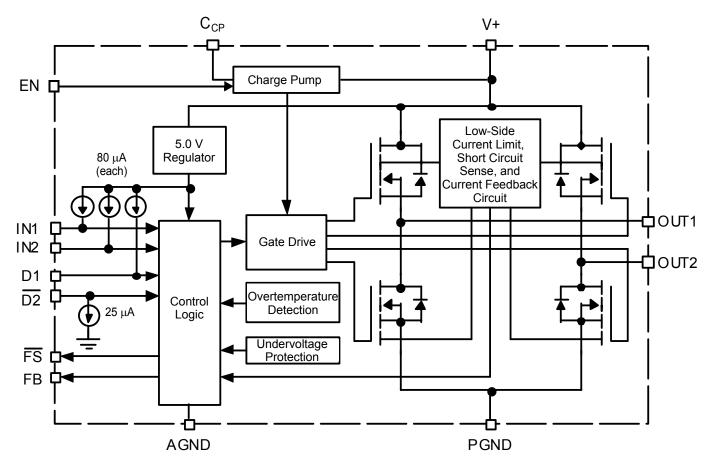
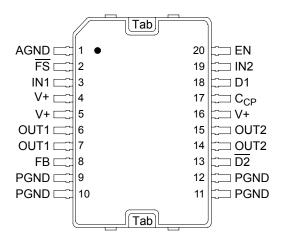


Figure 1. 33887 Simplified Internal Block Diagram

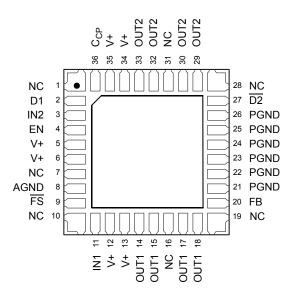


#### **HSOP TERMINAL DEFINITIONS**

A functional description of each terminal can be found in the System/Application Information section, page 19.

Terminal	Terminal Name	Formal Name	Definition
1	AGND	Analog Ground	Low-current analog signal ground.
2	FS	Fault Status for H-Bridge	Open drain active LOW Fault Status output requiring a pullup resistor to 5.0 V.
3	IN1	Logic Input Control 1	Logic input control of OUT1 (i.e., IN1 logic HIGH = OUT1 HIGH).
4, 5, 16	V+	Positive Power Supply	Positive supply connections
6,7	OUT1	H-Bridge Output 1	Output 1 of H-Bridge.
8	FB	Feedback for H-Bridge	Current sensing feedback output providing ground referenced 1/375th (0.00266) of H-Bridge high-side current.
9–12	PGND	Power Ground	High-current power ground.
13	D2	Disable 2	Active LOW input used to simultaneously tri-state disable both H-Bridge outputs. When D2 is Logic LOW, both outputs are tri-stated.
14, 15	OUT2	H-Bridge Output 2	Output 2 of H-Bridge.
17	C <sub>CP</sub>	Charge Pump Capacitor	External reservoir capacitor connection for internal charge pump capacitor.
18	D1	Disable 1	Active HIGH input used to simultaneously tri-state disable both H-Bridge outputs. When D1 is Logic HIGH, both outputs are tri-stated.
19	IN2	Logic Input Control 2	Logic input control of OUT2 (i.e., IN2 logic HIGH = OUT2 HIGH).
20	EN	Enable	Logic input Enable control of device (i.e., EN logic HIGH = full operation, EN logic LOW = Sleep Mode).
Tab/Pad	Thermal Interface	Exposed Pad Thermal Interface	Exposed pad thermal interface for sinking heat from the device.  Note Must be DC-coupled to analog ground and power ground via very low impedance path to prevent injection of spurious signals into IC substrate.

#### **Transparent Top View of Package**

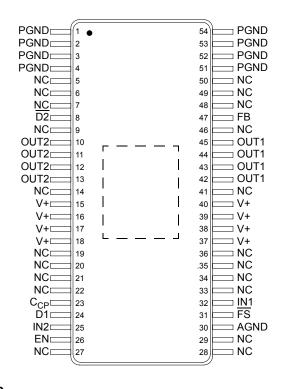


#### **PQFN TERMINAL DEFINITIONS**

A functional description of each terminal can be found in the System/Application Information section, page 19.

Terminal	Terminal Name	Formal Name	Definition
1, 7, 10, 16, 19, 28, 31	NC	No Connect	No internal connection to this terminal.
2	D1	Disable 1	Active HIGH input used to simultaneously tri-state disable both H-Bridge outputs. When D1 is Logic HIGH, both outputs are tri-stated.
3	IN2	Logic Input Control 2	Logic input control of OUT2 (i.e., IN2 logic HIGH = OUT2 HIGH).
4	EN	Enable	Logic input Enable control of device (i.e., EN logic HIGH = full operation, EN logic LOW = Sleep Mode).
5, 6, 12, 13, 34, 35	V+	Positive Power Supply	Positive supply connections.
8	AGND	Analog Ground	Low-current analog signal ground.
9	FS	Fault Status for H-Bridge	Open drain active LOW Fault Status output requiring a pullup resistor to 5.0 V.
11	IN1	Logic Input Control 1	Logic input control of OUT1 (i.e., IN1 logic HIGH = OUT1 HIGH).
14, 15, 17, 18	OUT1	H-Bridge Output 1	Output 1 of H-Bridge.
20	FB	Feedback for H-Bridge	Current feedback output providing ground referenced 1/375th ratio of H-Bridge high-side current.
21–26	PGND	Power Ground	High-current power ground.
27	D2	Disable 2	Active LOW input used to simultaneously tri-state disable both H-Bridge outputs. When $\overline{D2}$ is Logic LOW, both outputs are tri-stated.
29, 30, 32, 33	OUT2	H-Bridge Output 2	Output 2 of H-Bridge.
36	C <sub>CP</sub>	Charge Pump Capacitor	External reservoir capacitor connection for internal charge pump capacitor.
Pad	Thermal Interface	Exposed Pad Thermal Interface	Exposed pad thermal interface for sinking heat from the device.  Note Must be DC-coupled to analog ground and power ground via very low impedance path to prevent injection of spurious signals into IC substrate.

#### **Transparent Top View of Package**



#### **SOICW-EP TERMINAL DEFINITIONS**

A functional description of each terminal can be found in the System/Application Information section, page 19.

Terminal	Terminal Name	Formal Name	Definition
1–4, 51–54	PGND	Power Ground	High-current power ground.
5-7, 9, 14, 19-22, 27-29, 33-36, 41, 46, 48-50	NC	No Connect	No internal connection to this terminal.
8	D2	Disable 2	Active LOW input used to simultaneously tri-state disable both H-Bridge outputs. When $\overline{D2}$ is Logic LOW, both outputs are tri-stated.
10–13	OUT2	H-Bridge Output 2	Output 2 of H-Bridge.
15-18, 37-40	V+	Positive Power Supply	Positive supply connections.
23	C <sub>CP</sub>	Charge Pump Capacitor	External reservoir capacitor connection for internal charge pump capacitor.
24	D1	Disable 1	Active HIGH input used to simultaneously tri-state disable both H-Bridge outputs. When D1 is Logic HIGH, both outputs are tri-stated.
25	IN2	Logic Input Control 2	Logic input control of OUT2 (i.e., IN2 logic HIGH = OUT2 HIGH).
26	EN	Enable	Logic input Enable control of device (i.e., EN logic HIGH = full operation, EN logic LOW = Sleep Mode).
30	AGND	Analog Ground	Low-current analog signal ground.
31	FS	Fault Status for H-Bridge	Open drain active LOW Fault Status output requiring a pullup resistor to 5.0 V.
32	IN1	Logic Input Control 1	Logic input control of OUT1 (i.e., IN1 logic HIGH = OUT1 HIGH).
42-45	OUT1	H-Bridge Output 1	Output 1 of H-Bridge.
47	FB	Feedback for H-Bridge	Current feedback output providing ground referenced 1/375th ratio of H-Bridge high-side current.
Pad	Thermal Interface	Exposed Pad Thermal Interface	Exposed pad thermal interface for sinking heat from the device.  Note Must be DC-coupled to analog ground and power ground via very low impedance path to prevent injection of spurious signals into IC substrate.

#### **MAXIMUM RATINGS**

All voltages are with respect to ground unless otherwise noted.

Rating	Symbol	Value	Unit
ELECTRICAL RATINGS			<b>,</b>
Supply Voltage	V+	40	V
Input Voltage (Note 1)	V <sub>IN</sub>	-0.3 to 7.0	V
FS Status Output (Note 2)	V <sub>FS</sub>	7.0	V
Continuous Current (Note 3)	I <sub>OUT</sub>	5.0	А
DH Suffix HSOP ESD Voltage Human Body Model (Note 4)			V
Each Terminal to AGND	V <sub>ESD1</sub>	±1000	
Each Terminal to PGND	V <sub>ESD1</sub>	±1500	
Each Terminal to V+	V <sub>ESD1</sub>	±2000	
Each I/O to All Other I/Os	V <sub>ESD1</sub>	±2000	
Machine Model (Note 5)	V <sub>ESD2</sub>	±200	
VW Suffix HSOP ESD Voltage			V
Human Body Model (Note 4)	V <sub>ESD1</sub>	±2000	
Machine Model (Note 5)	V <sub>ESD2</sub>	±200	
PQFN ESD Voltage			V
Human Body Model (Note 4)	V <sub>ESD1</sub>	±2000	
Machine Model (Note 5)	V <sub>ESD2</sub>	±200	
SOICW-EP ESD Voltage			V
Human Body Model (Note 4)	V <sub>ESD1</sub>	±1600	
Machine Model (Note 5)	V <sub>ESD2</sub>	±200	
THERMAL RATINGS			
Storage Temperature	T <sub>STG</sub>	-65 to 150	°C
Operating Temperature (Note 6)			°C
Ambient	T <sub>A</sub>	-40 to 125	
Junction	TJ	-40 to 150	
Peak Package Reflow Temperature During Solder Mounting (Note 7)	T <sub>SOLDER</sub>		°C
HSOP		220	

#### Notes

**PQFN** 

SOICW-EP

- 1. Exceeding the input voltage on IN1, IN2, EN, D1, or  $\overline{D2}$  may cause a malfunction or permanent damage to the device.
- 2. Exceeding the pullup resistor voltage on the open Drain FS terminal may cause permanent damage to the device.
- 3. Continuous current capability so long as junction temperature is ≤ 150°C.
- 4. ESD1 testing is performed in accordance with the Human Body Model ( $C_{ZAP}$  = 100 pF,  $R_{ZAP}$  = 1500  $\Omega$ ).
- 5. ESD2 testing is performed in accordance with the Machine Model ( $C_{ZAP}$  = 200 pF,  $R_{ZAP}$  = 0  $\Omega$ ).
- 6. The limiting factor is junction temperature, taking into account the power dissipation, thermal resistance, and heat sinking provided. Brief nonrepetitive excursions of junction temperature above 150°C can be tolerated as long as duration does not exceed 30 seconds maximum. (nonrepetitive events are defined as not occurring more than once in 24 hours.)
- 7. Terminal soldering temperature limit is for 10 seconds maximum duration. Not designed for immersion soldering. Exceeding these limits may cause malfunction or permanent damage to the device.

260

240

#### **MAXIMUM RATINGS (continued)**

All voltages are with respect to ground unless otherwise noted.

Rating	Symbol	Value	Unit				
THERMAL RESISTANCE (AND PACKAGE DISSIPATION) RATINGS (Note 8), (Note 9), (Note 10), (Note 11)							
Junction-to-Board (Bottom Exposed Pad Soldered to Board)	$R_{ heta JB}$		°C/W				
HSOP (6.0 W)		~5.0					
PQFN (4.0 W)		~4.3					
SOICW-EP (2.0 W)		~8.0					
Junction-to-Ambient, Natural Convection, Single-Layer Board (1s) (Note 12)	$R_{ heta JA}$		°C/W				
HSOP (6.0 W)		~41					
PQFN (4.0 W)		~TBD					
SOICW-EP (2.0 W)		~62					
Junction-to-Ambient, Natural Convection, Four-Layer Board (2s2p) (Note 13)	$R_{ heta JMA}$		°C/W				
HSOP (6.0 W)		~30					
PQFN (4.0 W)		~21.3					
SOICW-EP (2.0 W)		~TBD					
Junction-to-Case (Exposed Pad) (Note 14)	$R_{ heta JC}$		°C/W				
HSOP (6.0 W)		~0.5					
PQFN (4.0 W)		~0.9					
SOICW-EP (2.0 W)		~1.5					

- 8. The limiting factor is junction temperature, taking into account the power dissipation, thermal resistance, and heat sinking.
- 9. Exposed heatsink pad plus the power and ground terminals comprise the main heat conduction paths. The actual  $R_{\theta JB}$  (junction-to-PC board) values will vary depending on solder thickness and composition and copper trace thickness. Maximum current at maximum die temperature represents ~16 W of conduction loss heating in the diagonal pair of output MOSFETs. Therefore, the  $R_{\theta JC}$ -total must be less than 5.0 °C/W for maximum load at 70°C ambient. Module thermal design must be planned accordingly.
- 10. Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.
- 11. Junction temperature is a function of on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board, and board thermal resistance.
- 12. Per SEMI G38-87 and JEDEC JESD51-2 with the single-layer board (JESD51-3) horizontal.
- 13. Per JEDEC JESD51-6 with the board horizontal.
- 14. Indicates the average thermal resistance between the die and the exposed pad surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1) with the cold plate temperature used for the case temperature.

#### STATIC ELECTRICAL CHARACTERISTICS

Characteristics noted under conditions 5.0 V  $\leq$  V+  $\leq$  28 V and -40°C  $\leq$  T<sub>A</sub>  $\leq$  125°C unless otherwise noted. Typical values noted reflect the approximate parameter mean at T<sub>A</sub> = 25°C under nominal conditions unless otherwise noted.

Characteristic	Symbol	Min	Тур	Max	Unit		
POWER SUPPLY							
Operating Voltage Range (Note 15)	V+	5.0	_	40	V		
Sleep State Supply Current (Note 16) $I_{OUT} = 0 \text{ A, V}_{EN} = 0 \text{ V}$	I <sub>Q(sleep)</sub>	-	25	50	μА		
Standby Supply Current I <sub>OUT</sub> = 0 A, V <sub>EN</sub> = 5.0 V	<sup>I</sup> Q(standby)	-	_	20	mA		
Threshold Supply Voltage Switch-OFF Switch-ON Hysteresis	V+(thres-OFF) V+(thres-ON) V+(hys)	4.15 4.5 150	4.4 4.75 –	4.65 5.0 –	V V mV		
CHARGE PUMP	·						
Charge Pump Voltage V+ = 5.0 V 8.0 V ≤ V+ ≤ 40 V	V <sub>CP</sub> -V+	3.35		- 20	V		
CONTROL INPUTS	1	I	l .				
Input Voltage (IN1, IN2, D1, $\overline{D2}$ ) Threshold HIGH Threshold LOW Hysteresis	V <sub>IH</sub> V <sub>IL</sub> V <sub>HYS</sub>	3.5 - 0.7	- - 1.0	- 1.4 -	V		
Input Current (IN1, IN2, D1) V <sub>IN</sub> - 0.0 V	I <sub>INP</sub>	-200	-80	_	μА		
Input Current ( $\overline{D2}$ , EN) V $\overline{D2}$ = 5.0 V	I <sub>INP</sub>	-	25	100	μА		

- 15. Specifications are characterized over the range of  $5.0 \text{ V} \le \text{V} + \le 28 \text{ V}$ . Operation > 28 V will cause some parameters to exceed listed min/max values. Refer to typical operating curves to extrapolate values for operation > 28 V but  $\le 40 \text{ V}$ .
- 16. I<sub>Q(sleep)</sub> is with sleep mode function enabled.

#### STATIC ELECTRICAL CHARACTERISTICS (continued)

Characteristics noted under conditions  $5.0 \text{ V} \leq \text{V} + \leq 28 \text{ V}$  and  $-40^{\circ}\text{C} \leq T_{A} \leq 125^{\circ}\text{C}$  unless otherwise noted. Typical values noted reflect the approximate parameter mean at  $T_{A}$  =  $25^{\circ}\text{C}$  under nominal conditions unless otherwise noted.

Characteristic	Symbol	Min	Тур	Max	Unit
POWER OUTPUTS (OUT1, OUT2)	1	•		•	
Output ON-Resistance (Note 17)	R <sub>DS(ON)</sub>				mΩ
$5.0 \text{ V} \leq \text{V+} \leq 28 \text{ V}, \text{ T}_{\text{J}} = 25^{\circ}\text{C}$		_	120	_	
$8.0~V \le V + \le 28~V,~T_J = 150^{\circ}C$		_	_	225	
$5.0~\text{V} \leq \text{V+} \leq 8.0~\text{V},~\text{T}_\text{J}$ = $150^{\circ}\text{C}$		_	-	300	
Active Current Limiting Threshold (via Internal Constant OFF-Time PWM) on Low-Side MOSFETs (Note 18)	I <sub>LIM</sub>	5.2	6.5	7.8	Α
High-Side Short Circuit Detection Threshold	I <sub>SCH</sub>	11	-	-	Α
Low-Side Short Circuit Detection Threshold	I <sub>SCL</sub>	8.0	-	-	Α
Leakage Current (Note 19)	I <sub>OUT(leak)</sub>				μΑ
V <sub>OUT</sub> = V+		_	100	200	
V <sub>OUT</sub> = Ground		-	30	60	
Output MOSFET Body Diode Forward Voltage Drop	V <sub>F</sub>				V
I <sub>OUT</sub> = 3.0 A		_	-	2.0	
Overtemperature Shutdown					°C
Thermal Limit	$T_{LIM}$	175	_	225	
Hysteresis	T <sub>HYS</sub>	10	-	30	
HIGH-SIDE CURRENT SENSE FEEDBACK	•				
Feedback Current	I <sub>FB</sub>				
I <sub>OUT</sub> = 0 mA		_	_	600	μΑ
I <sub>OUT</sub> = 500 mA		1.07	1.33	1.68	mA
I <sub>OUT</sub> = 1.5 A		3.6	4.0	4.62	mA
I <sub>OUT</sub> = 3.0 A		7.2	8.0	9.24	mA
I <sub>OUT</sub> = 6.0 A		14.4	16	18.48	mA
FAULT STATUS (Note 20)					
Fault Status Leakage Current (Note 21)	I <sub>FS(leak)</sub>				μΑ
V <sub>FS</sub> = 5.0 V		-	ı	10	
Fault Status SET Voltage (Note 22)	V <sub>FS(LOW)</sub>				V
I <del>FS</del> = 300 μA		_	-	1.0	

- 17. Output-ON resistance as measured from output to V+ and ground.
- 18. Active current limitation applies only for the low-side MOSFETs.
- 19. Outputs switched OFF with D1 or  $\overline{D2}$ .
- 20. Fault Status output is an open Drain output requiring a pullup resistor to 5.0 V.
- 21. Fault Status Leakage Current is measured with Fault Status HIGH and not SET.
- 22. Fault Status Set Voltage is measured with Fault Status LOW and SET with  $I_{\overline{FS}}$  = 300  $\mu$ A.

#### **DYNAMIC ELECTRICAL CHARACTERISTICS**

Characteristics noted under conditions 5.0 V  $\leq$  V+  $\leq$  28 V and -40°C  $\leq$  T<sub>A</sub>  $\leq$  125°C unless otherwise noted. Typical values noted reflect the approximate parameter mean at T<sub>A</sub> = 25°C under nominal conditions unless otherwise noted.

Characteristic	Symbol	Min	Тур	Max	Unit
TIMING CHARACTERISTICS					
PWM Frequency (Note 23)	f <sub>PWM</sub>	_	10	-	kHz
Maximum Switching Frequency During Active Current Limiting (Note 24)	f <sub>MAX</sub>	_	-	20	kHz
Output ON Delay (Note 25) V+ = 14 V	t <sub>d(ON)</sub>	-	-	18	μs
Output OFF Delay (Note 25) V+ = 14 V	t <sub>d(OFF)</sub>	-	-	18	μs
I <sub>LIM</sub> Output Constant-OFF Time for Low-Side MOSFETs (Note 26), (Note 27)	t <sub>a</sub>	15	20.5	26	μS
I <sub>LIM</sub> Blanking Time for Low-Side MOSFETs (Note 28), (Note 27)	t <sub>b</sub>	12	16.5	21	μS
Output Rise and Fall Time (Note 29) V+ = 14 V, I <sub>OUT</sub> = 3.0 A	t <sub>f</sub> , t <sub>r</sub>	2.0	5.0	8.0	μs
Disable Delay Time (Note 30)	t <sub>d(disable)</sub>	_	-	8.0	μS
Power-ON Delay Time (Note 31)	t <sub>pod</sub>	_	1.0	5.0	ms
Wake-Up Delay Time (Note 31)	t <sub>wud</sub>	_	1.0	5.0	ms
Output MOSFET Body Diode Reverse Recovery Time (Note 32)	t <sub>rr</sub>	100	-	_	ns

- 23. The outputs can be PWM-controlled from an external source. This is typically done by holding one input high while applying a PWM pulse train to the other input. The maximum PWM frequency obtainable is a compromise between switching losses and switching frequency. See Typical Switching Waveforms, Figures 11 through 18, pp. 15–16.
- 24. The Maximum Switching Frequency during active current limiting is internally implemented. The internal current limit circuitry produces a constant-OFF-time pulse-width modulation of the output current. The output load's inductance, capacitance, and resistance characteristics affect the total switching period (OFF-time + ON-time) and thus the PWM frequency during current limit.
- 25. Output Delay is the time duration from the midpoint of the IN1 or IN2 input signal to the 10% or 90% point (dependent on the transition direction) of the OUT1 or OUT2 signal. If the output is transitioning HIGH-to-LOW, the delay is from the midpoint of the input signal to the 90% point of the output response signal. If the output is transitioning LOW-to-HIGH, the delay is from the midpoint of the input signal to the 10% point of the output response signal. See Figure 2, page 11.
- I<sub>LIM</sub> Output Constant-OFF Time is the time during which the internal constant-OFF time PWM current regulation circuit has tri-stated the output bridge.
- 27. Load currents ramping up to the current regulation threshold become limited at the I<sub>LIM</sub> value. The short circuit currents possess a di/dt that ramps up to the I<sub>SCH</sub> or I<sub>SCL</sub> threshold during the I<sub>LIM</sub> blanking time, registering as a short circuit event detection and causing the shutdown circuitry to force the output into an immediate tri-state latch-OFF. See <u>Figures 6</u> and <u>7</u>, page 12. Operation in Current Limit mode may cause junction temperatures to rise. Junction temperatures above ~160°C will cause the output current limit threshold to progressively "fold back", or decrease with temperature, until ~175°C is reached, after which the T<sub>LIM</sub> thermal latch-OFF will occur. Permissible operation within this foldback region is limited to nonrepetitive transient events of duration not to exceed 30 seconds. See <u>Figure 5</u>, page 11.
- 28. I<sub>LIM</sub> Blanking Time is the time during which the current regulation threshold is ignored so that the short-circuit detection threshold comparators my have time to act.
- 29. Rise Time is from the 10% to the 90% level and Fall Time is from the 90% to the 10% level of the output signal. See Figure 4, page 11.
- 30. Disable Delay Time is the time duration from the midpoint of the D (disable) input signal to 10% of the output tri-state response. See <u>Figure 3</u>, page 11.
- 31. Parameter has been characterized but not production tested.
- Parameter is guaranteed by design but not production tested.

# **Timing Diagrams**

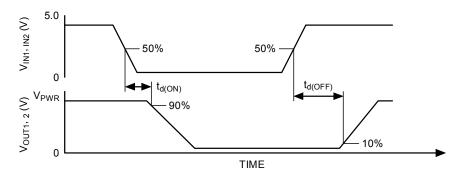


Figure 2. Output Delay Time

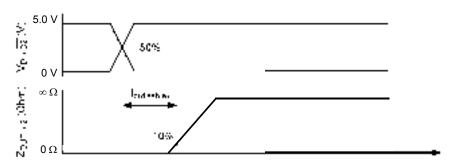


Figure 3. Disable Delay Time

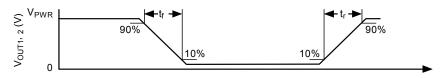


Figure 4. Output Switching Time

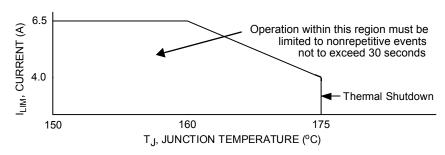


Figure 5. Active Current Limiting Versus Temperature (Typical)

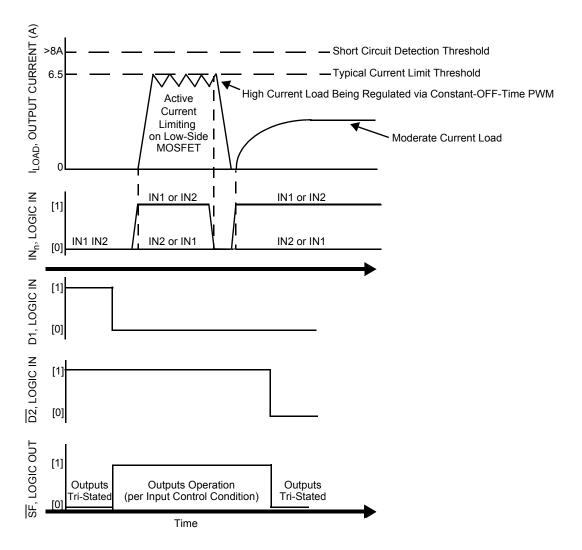


Figure 6. Operating States

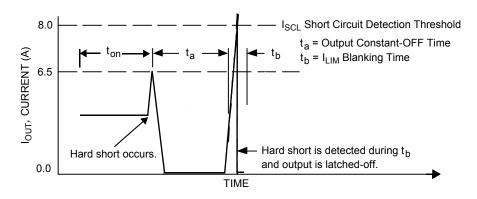


Figure 7. Example Short Circuit Detection Detail on Low-Side MOSFET

### **Electrical Performance Curves**

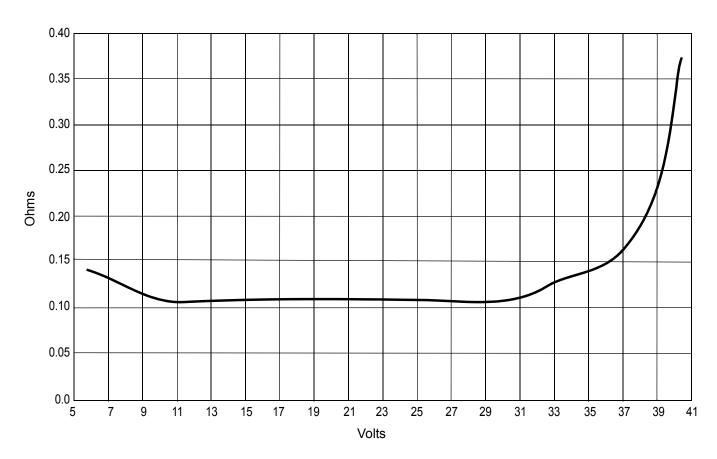


Figure 8. Typical High-Side R<sub>DS(ON)</sub> Versus V+

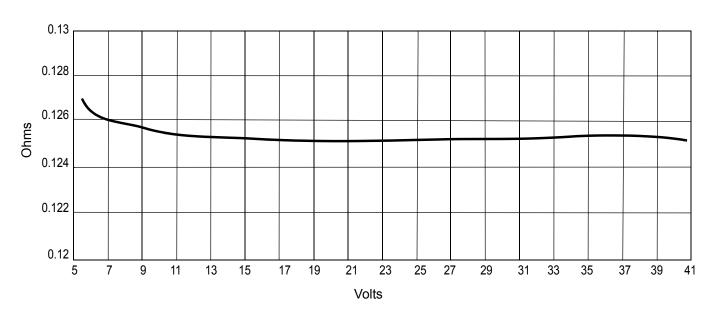


Figure 9. Typical Low-Side  $R_{DS(ON)}$  Versus V+

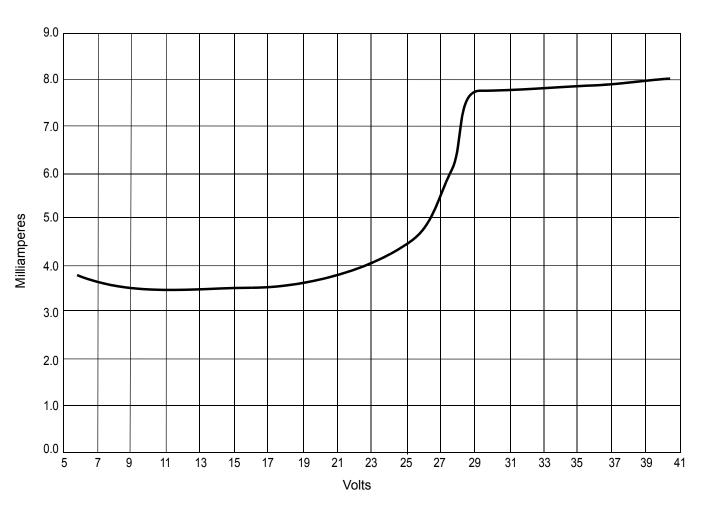


Figure 10. Typical Quiescent Supply Current Versus V+

#### **Typical Switching Waveforms**

**Important** For all plots, the following applies:

- Ch2=2.0 A per division
- $L_{LOAD}$ =533  $\mu H$  @ 1.0 kHz
- $L_{LOAD}$ =530  $\mu H$  @ 10.0 kHz
- R<sub>LOAD</sub>=4.0 Ω

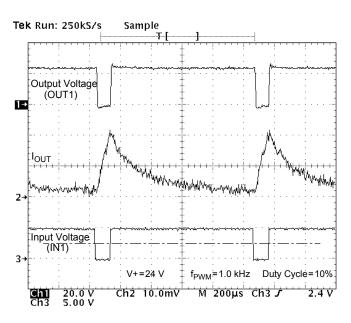


Figure 11. Output Voltage and Current vs. Input Voltage at V+ = 24 V, PMW Frequency of 1.0 kHz, and Duty Cycle of 10%

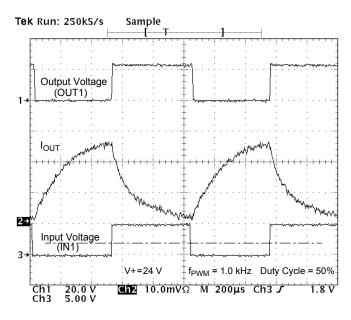


Figure 12. Output Voltage and Current vs. Input Voltage at V+ = 24 V, PMW Frequency of 1.0 kHz, and Duty Cycle of 50%

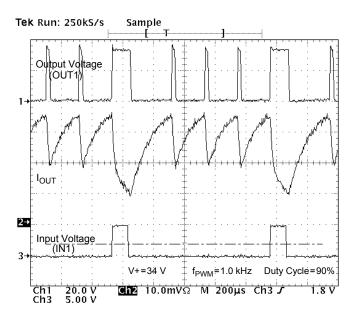


Figure 13. Output Voltage and Current vs. Input Voltage at V+ = 34 V, PMW Frequency of 1.0 kHz, and Duty Cycle of 90%, Showing Device in Current Limiting Mode

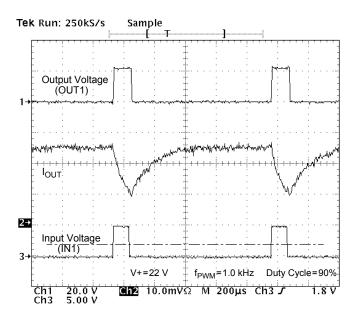


Figure 14. Output Voltage and Current vs. Input Voltage at V+ = 22 V, PMW Frequency of 1.0 kHz, and Duty Cycle of 90%

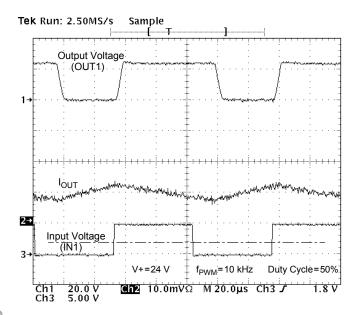


Figure 15. Output Voltage and Current vs. Input Voltage at V+ = 24 V, PMW Frequency of 10 kHz, and Duty Cycle of 50%

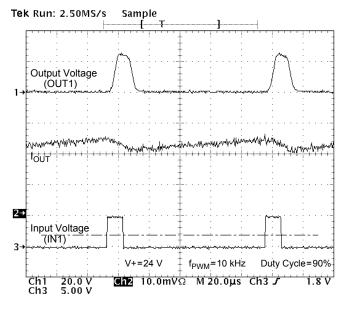


Figure 16. Output Voltage and Current vs. Input Voltage at V+ = 24 V, PMW Frequency of 10 kHz, and Duty Cycle of 90%

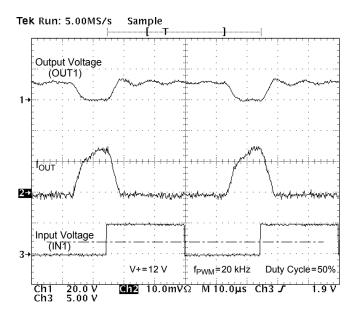


Figure 17. Output Voltage and Current vs. Input Voltage at V+ = 12 V, PMW Frequency of 20 kHz, and Duty Cycle of 50% for a Purely Resistive Load

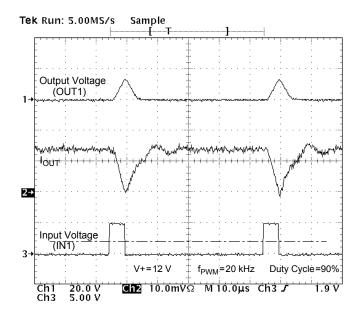


Figure 18. Output Voltage and Current vs. Input Voltage at V+ = 12 V, PMW Frequency of 20 kHz, and Duty Cycle of 90% for a Purely Resistive Load

#### Table 1. Truth Table

The tri-state conditions and the fault status are reset using D1 or  $\overline{D2}$ . The truth table uses the following notations: L = LOW, H = HIGH, X = HIGH or LOW, and Z = High impedance (all output power transistors are switched off).

Device State	Input Conditions					Fault Status Flag	Output States	
	EN	D1	D2	IN1	IN2	FS	OUT1	OUT2
Forward	Н	L	Н	Н	L	Н	Н	L
Reverse	Н	L	Н	L	Н	Н	L	Н
Freewheeling Low	Н	L	Н	L	L	Н	L	L
Freewheeling High	Н	L	Н	Н	Н	Н	Н	Н
Disable 1 (D1)	Н	Н	Х	Х	Х	L	Z	Z
Disable 2 (D2)	Н	Х	L	Х	Х	L	Z	Z
IN1 Disconnected	Н	L	Н	Z	Х	Н	Н	Х
IN2 Disconnected	Н	L	Н	Х	Z	Н	Х	Н
D1 Disconnected	Н	Z	Х	Х	Х	L	Z	Z
D2 Disconnected	Н	Х	Z	Х	Х	L	Z	Z
Undervoltage (Note 33)	Н	Х	Х	Х	Х	L	Z	Z
Overtemperature (Note 34)	Н	Х	Х	Х	Х	L	Z	Z
Short Circuit (Note 34)	Н	Х	Х	Х	Х	L	Z	Z
Sleep Mode EN	L	Х	Х	Х	Х	Н	Z	Z
EN Disconnected	Z	Х	Х	Х	Х	Н	Z	Z

- 33. In the case of an undervoltage condition, the outputs tri-state and the fault status is SET logic LOW. Upon undervoltage recovery, fault status is reset automatically or automatically cleared and the outputs are restored to their original operating condition.
- 34. When a short circuit or overtemperature condition is detected, the power outputs are tri-state latched-OFF independent of the input signals and the fault status flag is SET logic LOW.

#### SYSTEM/APPLICATION INFORMATION

#### INTRODUCTION

Numerous protection and operational features (speed, torque, direction, dynamic braking, PWM control, and closed-loop control), in addition to the 5.0 A current capability, make the 33887 a very attractive, cost-effective solution for controlling a broad range of small DC motors. In addition, a pair of 33887 devices can be used to control bipolar stepper motors. The 33887 can also be used to excite transformer primary windings with a switched square wave to produce secondary winding AC currents.

As shown in Figure 1, Simplified Internal Block Diagram, page 2, the 33887 is a fully protected monolithic H-Bridge with Enable, Fault Status reporting, and High-Side current sense feedback to accommodate closed-loop PWM control. For a DC motor to run, the input conditions need be as follows: Enable input logic HIGH, D1 input logic LOW,  $\overline{D2}$  input logic HIGH,  $\overline{FS}$  flag cleared (logic HIGH), one IN logic LOW and the other IN logic HIGH (to define output polarity). The 33887 can execute dynamic braking by simultaneously turning on either both high-side MOSFETs or both low-side MOSFETs in the output H-Bridge; e.g., IN1 and IN2 logic HIGH or IN1 and IN2 logic LOW.

The 33887 outputs are capable of providing a continuous DC load current of 5.0 A from a 40 V V+ source. An internal charge pump supports PWM frequencies to 10 kHz. An external pullup resistor is required at the  $\overline{\text{FS}}$  terminal for fault status reporting. The 33887 has an analog feedback (current mirror) output terminal (the FB terminal) that provides a constant-current source ratioed to the active high-side MOSFET. This can be used to provide "real time" monitoring of load current to facilitate closed-loop operation for motor speed/torque control.

Two independent inputs (IN1 and IN2) provide control of the two totem-pole half-bridge outputs. Two disable inputs (D1 and  $\overline{\text{D2}}$ ) provide the means to force the H-Bridge outputs to a high-impedance state (all H-Bridge switches OFF). An EN terminal controls an enable function that allows the 33887 to be placed in a power-conserving sleep mode.

The 33887 has undervoltage shutdown with automatic recovery, active current limiting, output short-circuit latch-OFF, and overtemperature latch-OFF. An undervoltage shutdown, output short-circuit latch-OFF, or overtemperature latch-OFF fault condition will cause the outputs to turn OFF (i.e., become high impedance or tri-stated) and the fault output flag to be set LOW. Either of the Disable inputs or V+ must be "toggled" to clear the fault flag.

Active current limiting is accomplished by a constant OFF-time PWM method employing active current limiting threshold triggering. The active current limiting scheme is unique in that it incorporates a junction temperature-dependent current limit threshold. This means the active current limiting threshold is "ramped down" as the junction temperature increases above 160°C, until at 175°C the current will have been decreased to about 4.0 A. Above 175°C, the overtemperature shutdown (latch-OFF) occurs. This combination of features allows the device to remain in operation for 30 seconds at junction temperatures above 150°C for nonrepetitive unexpected loads.

#### **FUNCTIONAL TERMINAL DESCRIPTION**

#### **PGND** and AGND

Power and analog ground terminals should be connected together with a very low impedance connection.

#### V+

V+ terminals are the power supply inputs to the device. All V+ terminals must be connected together on the printed circuit board with as short as possible traces offering as low impedance as possible between terminals.

V+ terminals have an undervoltage threshold. If the supply voltage drops below a V+ undervoltage threshold, the output power stage switches to a tri-state condition and the fault status flag is SET and the Fault Status terminal voltage switched to a logic LOW. When the supply voltage returns to a level that is above the threshold, the power stage automatically resumes normal operation according to the established condition of the input terminals and the fault status flag is automatically reset logic HIGH.

#### Fault Status (FS)

The FS terminal is the device fault status output. This output is an active LOW open drain structure requiring a pullup resistor to 5.0 V. Refer to <u>Table 1</u>, <u>Truth Table</u>, page 17.

#### IN1, IN2, D1, and $\overline{D2}$

These terminals are input control terminals used to control the outputs. These terminals are 5.0 V CMOS-compatible inputs with hysteresis. The IN1 and IN2 independently control OUT1 and OUT2, respectively. D1 and  $\overline{\text{D2}}$  are complementary inputs used to tri-state disable the H-Bridge outputs.

When either D1 or  $\overline{D2}$  is SET (D1 = logic HIGH or  $\overline{D2}$  = logic LOW) in the disable state, outputs OUT1 and OUT2 are both tristate disabled; however, the rest of the device circuitry is fully operational and the supply  $I_{Q(standby)}$  current is reduced to a few milliamperes. Refer to <u>Table 1. Truth Table</u>, and <u>STATIC ELECTRICAL CHARACTERISTICS</u> table, page 8.

#### **OUT1 and OUT2**

These terminals are the outputs of the H-Bridge with integrated output MOSFET body diodes. The bridge output is controlled using the IN1, IN2, D1, and  $\overline{D2}$  inputs. The low-side MOSFETs have active current limiting above the I<sub>LIM</sub> threshold.

The outputs also have thermal shutdown (tri-state latch-OFF) with hysteresis as well as short circuit latch-OFF protection.

A disable timer (time  $t_b$ ) incorporated to detect currents that are higher than current limit is activated at each output activation to facilitate hard short detection (see <u>Figure 7</u>, page 12).

### $C_{CP}$

A filter capacitor (up to 33 nF) can be connected from the charge pump output terminal and PGND. The device can operate without the external capacitor, although the  $C_{CP}$  capacitor helps to reduce noise and allows the device to perform at maximum speed, timing, and PWM frequency.

#### ΕN

The EN terminal is used to place the device in a sleep mode so as to consume very low currents. When the EN terminal voltage is a logic LOW state, the device is in the sleep mode. The device is enabled and fully operational when the EN terminal voltage is logic HIGH. An internal pulldown resistor maintains the device in sleep mode in the event EN is driven through a high impedance I/O or an unpowered microcontroller, or the EN input becomes disconnected.

#### FB

The 33887 has a feedback output (FB) for "real time" monitoring of H-Bridge high-side current to facilitate closed-loop operation for motor speed and torque control.

The FB terminal provides current sensing feedback of the H-Bridge high-side drivers. When running in the forward or reverse direction, a ground referenced 1/375th (0.00266) of load current is output to this terminal. Through the use of an external resistor to ground, the proportional feedback current can be converted to a proportional voltage equivalent and the controlling microcontroller can "read" the current proportional voltage with its analog-to-digital converter (ADC). This is intended to provide the user with motor current feedback for motor torque control. The resistance range for the linear operation of the FB terminal is  $100 < R_{FB} < 200 \ \Omega$ .

If PWM-ing is implemented using the disable terminal inputs (either D1 or D2), a small filter capacitor (1.0  $\mu\text{F}$  or less) may be required in parallel with the external resistor to ground for fast spike suppression.

#### PERFORMANCE FEATURES

#### **Short Circuit Protection**

If an output short circuit condition is detected, the power outputs tri-state (latch-OFF) independent of the input (IN1 and IN2) states, and the fault status output flag is SET logic LOW. If the D1 input changes from logic HIGH to logic LOW, or if the  $\overline{\text{D2}}$  input changes from logic LOW to logic HIGH, the output bridge will become operational again and the fault status flag will be reset (cleared) to a logic HIGH state.

The output stage will always switch into the mode defined by the input terminals (IN1, IN2, D1, and  $\overline{\text{D2}}$ ), provided the device junction temperature is within the specified operating temperature range.

#### **Active Current Limiting**

The maximum current flow under normal operating conditions is internally limited to  $I_{LIM}$  (5.2 A to 7.8 A). When the maximum current value is reached, the output stages are tristated for a fixed time (t  $_{a}$ ) of 20  $\mu s$  typical. Depending on the time constant associated with the load characteristics, the current decreases during the tri-state duration until the next output ON cycle occurs (see <u>Figures 7</u> and <u>13</u>, page 12 and page 15, respectively).

The current limiting threshold value is dependent upon the device junction temperature. When -40°C  $\leq T_{J} \leq 160^{\circ}C,\ I_{LIM}$  is between 5.2 A to 7.8 A. When  $T_{J}$  exceeds 160°C, the  $I_{LIM}$  current decreases linearly down to 4.0 A typical at 175°C. Above 175°C the device overtemperature circuit detects  $T_{LIM}$  and overtemperature shutdown occurs (see Figure 5, page 11). This feature allows the device to remain operational for a longer time but at a regressing output performance level at junction temperatures above 160°C.

#### **Overtemperature Shutdown and Hysteresis**

If an overtemperature condition occurs, the power outputs are tri-stated (latched-OFF) and the fault status flag is SET to logic LOW.

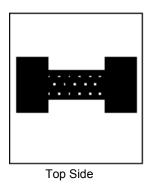
To reset from this condition, D1 must change from logic HIGH to logic LOW, or  $\overline{D2}$  must change from logic LOW to logic HIGH. When reset, the output stage switches ON again, provided that the junction temperature is now below the overtemperature threshold limit minus the hysteresis.

**Note** Resetting from the fault condition will clear the fault status flag.

#### **PACKAGE INFORMATION**

The 33887 packages are designed for thermal performance. The significant feature of these packages is the exposed pad on which the power die is soldered. When soldered to a PCB, this pad provides a path for heat flow to the ambient environment. The more copper area and thickness on the PCB, the better the power dissipation and transient behavior will be.

**Example** Characterization on a double-sided PCB: bottom side area of copper is 7.8 cm<sup>2</sup>; top surface is 2.7 cm<sup>2</sup> (see Figure 19); grid array of 24 vias 0.3 mm in diameter.



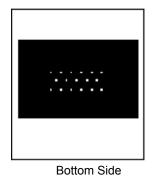


Figure 19. PCB Test Layout

<u>Figure 20</u> shows the thermal response with the device in the HSOP package soldered on to the test PCB described in Figure 19.

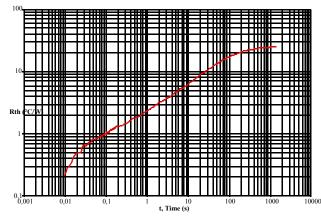


Figure 20. 33887 Thermal Response, HSOP Package

#### **APPLICATIONS**

<u>Figure 21</u> shows a typical application schematic. For precision high-current applications in harsh, noisy

environments, the V+ by-pass capacitor may need to be substantially larger.

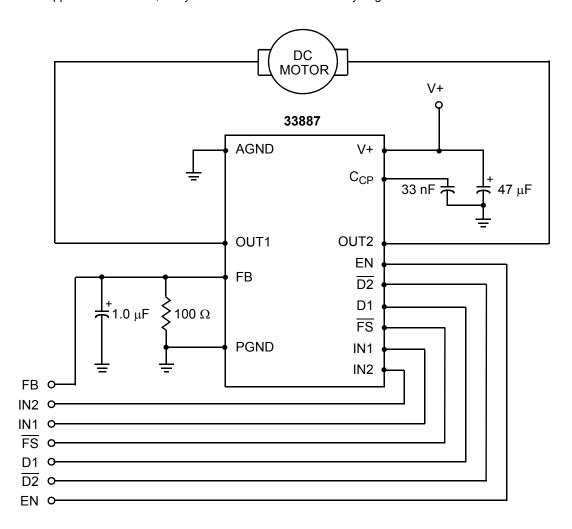
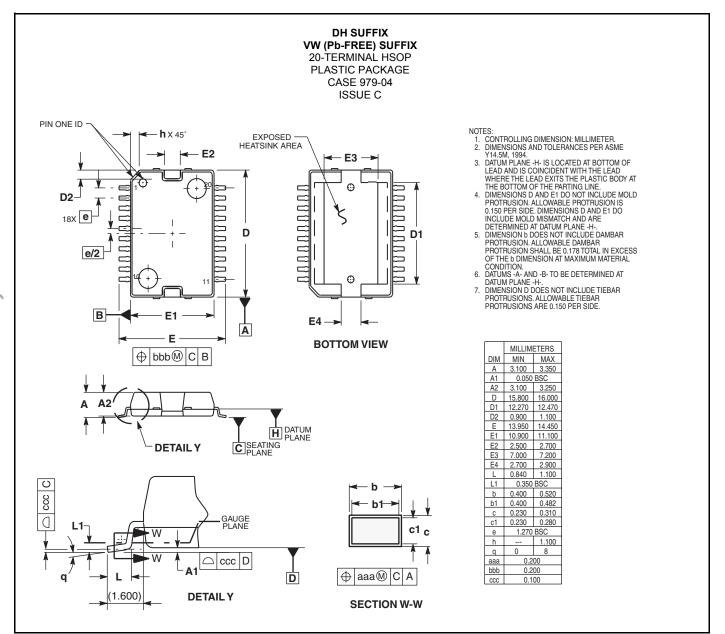


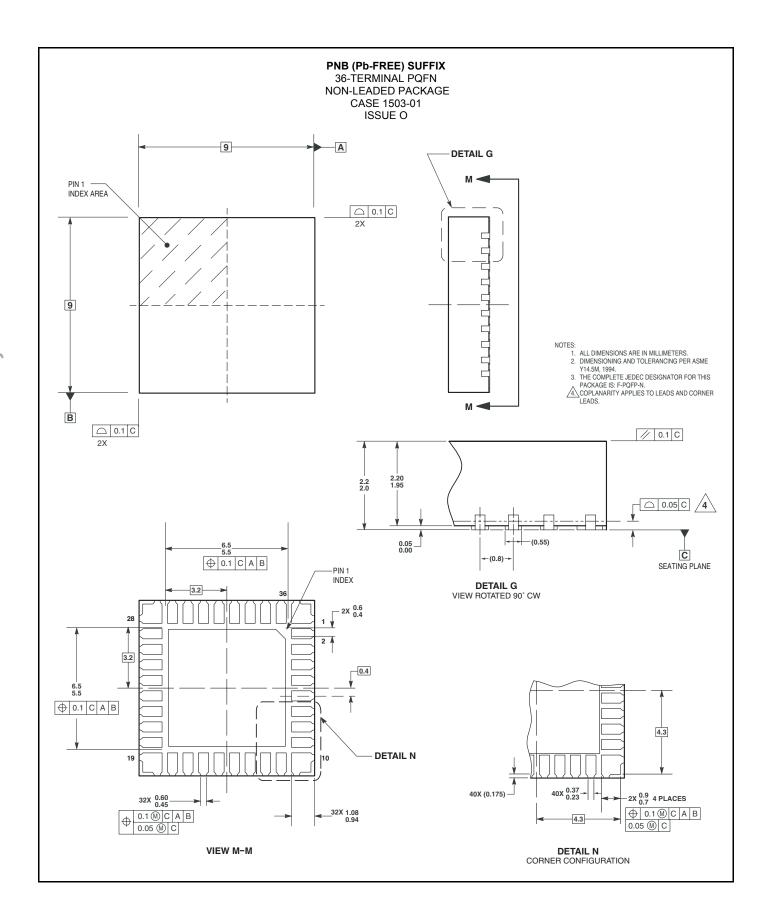
Figure 21. 33887 Typical Application Schematic

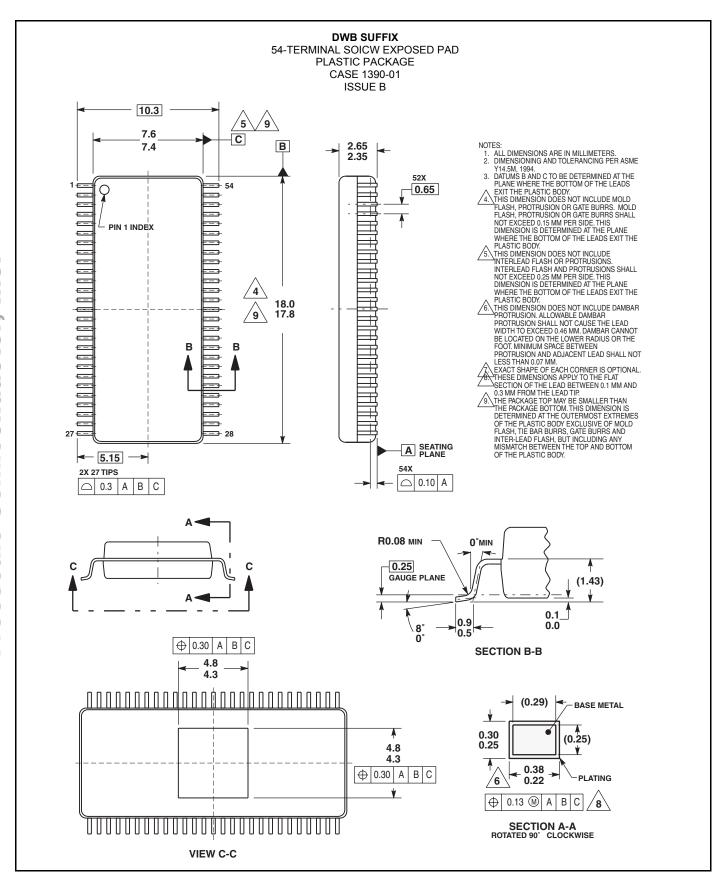
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#### **PACKAGE DIMENSIONS**







**NOTES** 

**NOTES** 

**NOTES** 

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