MC145403

Drivers/Receivers EIA-232-E and CCITT V.28

These devices are silicon gate CMOS ICs that combine both the transmitter and receiver to fulfill the electrical specifications of EIA Standard 232–E and CCITT V.28. The drivers feature true TTL input compatibility, slew rate limiting outputs, 300 Ω power–off source impedance, and output typically switching to within 25% of the supply rails. The receivers can handle up to \pm 25 V while presenting 3 to 7 k Ω impedance. Hysteresis in the receivers aid in the reception of noisy signals. By combining both drivers and receivers in a single CMOS chip, these devices provide efficient, low–power solutions for both EIA–232–E and V.28 applications.

These devices offer the following performance features:

Drivers

- ± 5 to ± 12 V Supply Range
- 300 Ω Power–Off Source Impedance
- Output Current Limiting
- TTL and CMOS Compatible Inputs
- Driver Slew Rate Range Limited to 30 V/μs Maximum

Receivers

- ± 25 V Input Range
- 3 to 7 kΩ Input Impedance
- 0.8 V of Hysteresis for Enhanced Noise Immunity
- TTL and CMOS Compatible Outputs

Available Driver/Receiver Combinations

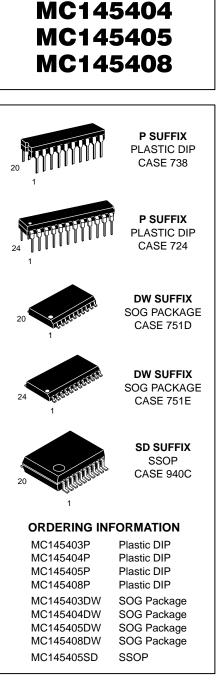
Device	Drivers	Receivers	Figure	No. of Pins
MC145403	3	5	1	20
MC145404	4	4	2	20
MC145405	5	3	3	20
MC145408	5	5	4	24

Alternative EIA-232 devices to consider are:

Three Supply MC145406 (3 x 3)

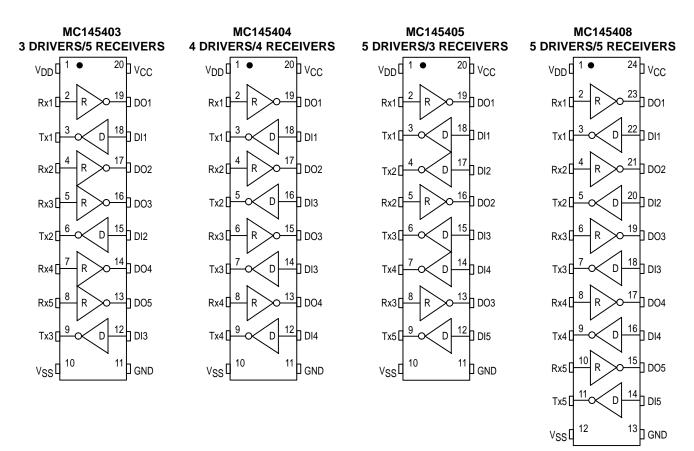
Single Supply

MC145407 (3 x 3) MC145705 (2 x 3) with Power Down MC145706 (3 x 2) with Power Down MC145707 (3 x 3) with Power Down

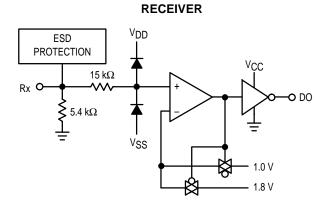




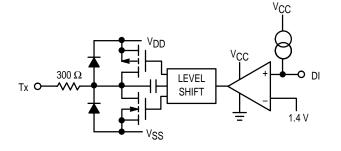
PIN ASSIGNMENTS (DIP, SOG, AND SSOP)



FUNCTIONAL DIAGRAM



DRIVER



ABSOLUTE MAXIMUM RATINGS

(Voltages referenced to GND, except where noted)

Rating	Symbol	Value	Unit
DC Supply Voltage ($V_{DD} \ge V_{CC}$)	V _{DD} V _{SS} V _{CC}	- 0.5 to + 13.5 + 0.5 to - 13.5 - 0.5 to + 6.0	V
Input Voltage Range Rx1 – Rxn DI1 – DIn	VIR	V _{SS} – 15 to V _{DD} + 15 0.5 to V _{CC} + 15	V
DC Current Drain per Pin	I	± 00	mA
Power Dissipation	PD	1	W
Operating Temperature Range	Т _А	– 40 to + 85	°C
Storage Temperature Range	T _{stg}	– 85 to + 150	°C

This device contains circuitry to protect the inputs and outputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid applications of any voltage higher than maximum rated voltages to this high impedance circuit.

For proper operation it is recommended that V_{out} and V_{in} be constrained to the ranges described as follows:

 $\begin{array}{l} \mbox{Digital I/O: Driver Inputs (DI):} \\ (GND \leq V_{DI} \leq V_{CC}). \\ \mbox{Receiver Outputs (DO):} \\ (GND \leq V_{DO} \leq V_{CC}). \\ \mbox{EIA-232 I/O: Driver Outputs (Tx):} \\ (VSS \leq VTx1 - Txn \leq V_{DD}). \\ \mbox{Receiver Inputs (Rx):} \\ \mbox{VSS - 15 V \leq V}_{Rx1} - Rxn \leq V_{DD} \\ \mbox{+ 15 V}. \end{array}$

Reliability of operation is enhanced if unused outputs are tied off to an appropriate logic voltage level (e.g., either GND or V_{CC} for DI, and GND for Rx).

DC ELECTRICAL CHARACTERISTICS (All polarities referenced to GND = 0 V, $T_A = -40 \text{ to } + 85^{\circ}C$)

Parameter		Symbol	Min	Тур	Мах	Unit
DC Supply Voltage		V _{DD} V _{SS} V _{CC}	4.5 - 4.5 4.5	5 to 12 - 5 to - 12 5	13.2 - 13.2 5.5	V
Quiescent Supply Current (Outputs Unloaded, Inputs Low)	V _{DD} = + 12 V V _{SS} = - 12 V V _{CC} = + 5 V	I _{DD} I _{SS} I _{CC}		425 - 400 110	635 600 200	μΑ

RECEIVER ELECTRICAL SPECIFICATIONS

(Voltage polarities referenced to GND = 0 V, V_{DD} = + 12 V, V_{SS} = - 12 V, T_A = - 40 to + 85°C, V_{CC} = + 5 V, ± 10%)

Characteristic		Symbol	Min	Тур	Max	Unit
Input Turn–On Threshold VDO = VOL	Rx1 – Rx <i>n</i>	V _{on}	1.35	1.8	2.35	V
Input Turn–Off Threshold V _{DO} = V _{OH}	Rx1 – Rx <i>n</i>	V _{off}	0.75	1	1.25	V
Input Threshold Hysteresis $\Delta = V_{OP} - V_{Off}$		V _{hys}	0.6	0.8	_	V
Input Resistance (V _{SS} - 15 V) \leq V Rx1 - Rx $n \leq$ (V _{DD} + 15 V)		R _{in}	3	5.4	7	kΩ
High Level Output Voltage V _{Rx} = - 3 to - 25 V* (DO1 - DO <i>n</i>)	$I_{out} = -20 \mu A$ $I_{out} = -1.0 m A$	Vон	4.9 3.8	4.9 4.3	_	V
Low Level Output Voltage V _{Rx} = + 3 to + 25 V* (DO1 – DO <i>n</i>)	l _{out} = + 2 mA l _{out} = + 4 mA	VOL	—	0.02 0.5	0.5 0.7	V

* This is the range of input voltages as specified by EIA-232-E to cause a receiver to be in the high or low.

DRIVER ELECTRICAL SPECIFICATIONS

(Voltage Polarities Referenced to GND = 0 V, V_{DD} = + 12 V, V_{SS} = - 12 V, T_A = - 40 to + 85°C, V_{CC} = + 5 V, ± 10%)

Characteristic	Symbol	Min	Тур	Max	Unit
Digital Input Voltage DI1 – DI <i>n</i> Logic 0 Logic 1	VIL VIH	2		0.8	V
Input Current $DI1 - DIn$ $V_{DI} = GND$ $V_{DI} = V_{CC}$	IL IH		7	 ± 1.0	μA
$ \begin{array}{ll} \mbox{Output High Voltage} & Tx1 - Txn \\ \mbox{V}_{DI} = \mbox{Logic 0, R}_L = 3 \ \mbox{k}\Omega \\ \mbox{V}_{DD} = + \ 5.0 \ \mbox{V, V}_{SS} = - \ 5.0 \ \mbox{V} \\ \mbox{V}_{DD} = + \ 6.0 \ \mbox{V, V}_{SS} = - \ 6.0 \ \mbox{V} \\ \mbox{V}_{DD} = + \ 12.0 \ \mbox{V, V}_{SS} = - \ 12.0 \ \mbox{V} \\ \end{array} $	VOH	3.5 4.3 9.2	3.9 4.7 9.5	 	V
$\begin{array}{l} \mbox{Output Low Voltage}^{*} & Tx1 - Txn \\ \mbox{V}_{DI} = \mbox{Logic 1, R}_{L} = 3 \ k\Omega \\ \mbox{V}_{DD} = + \ 5.0 \ V, \ \mbox{V}_{SS} = - \ 5.0 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	VOL	- 4 - 4.5 - 10	- 4.3 - 5.2 - 10.3	 	V
Input Current Tx1 – Txn (Figure 5)	Z _{off}	300	—	_	Ω
Output Short Circuit Current $Tx1 - Txn$ $V_{DD} = + 12 V$, $V_{SS} = -12 V$ Tx Shorted to GND** Tx Shorted to $\pm 15 V^{***}$	ISC		± 22 ± 60	± 60 ± 100	mA

* Voltage specifications are in terms of absolute values.

** Specification is for one Tx output pin to be shorted at a time. Should all three driver outputs be shorted simultaneously, device power dissipation limits will be exceeded.

*** This condition could exceed package limitations.

Characteristic		Min	Тур	Max	Unit
Drivers					
Propagation Delay Time Tx Low-to-High	^t PLH				ns
$R_L = 3 k\Omega$, $C_L = 50 pF$		—	500	1000	
High–to–Low R _L = 3 k Ω , C _L = 50 pF	^t PHL	_	700	1000	
Output Slew Rate Minimum Load	SR				V/µs
$R_L = 7 k\Omega$, $C_L = 0 pF (V_{DD} = 6 to 12 V, V_{SS} = -6 to - 12 V)$		_	± 6	± 30	
Maximum Load R _L = 3 kΩ, C _L = 2500 pF (V _{DD} = 12 V, V _{SS} = – 12 V, V _{CC} = 5 V)		4	_	_	

Receivers (C_L = 50 pF)

Propagation Delay Time Low–to–High	^t PLH	_	360	610	ns
High-to-Low	^t PHL	—	130	610	
Output Rise Time	t _r	—	250	400	ns
Output Fall Time	t _f	—	40	100	ns

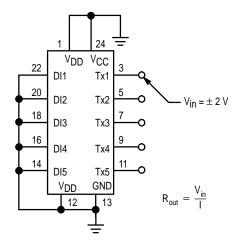
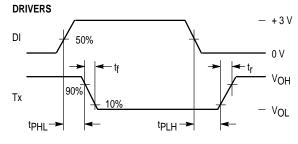


Figure 1. Power–Off Source Resistance Illustrated for MC145408



RECEIVERS

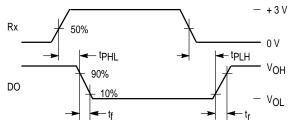


Figure 2. Switching Characteristics

PIN DESCRIPTIONS

V_{CC}

Digital Power Supply

The digital supply pin, which is connected to the logic power supply (+ 5.5 V maximum).

GND

Ground

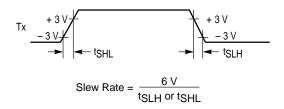
Ground return pin is typically connected to the signal ground pin of the EIA–232–E connector (Pin 7) as well as to the logic power supply ground.

V_{DD}

Most Positive Device Pin

The most positive power supply pin, which is typically + 5 to + 12 V.

DRIVERS





Vss

Most Negative Device Pin

The most negative power supply pin, which is typically – 5 to – 12 V. $\,$

Rx1 – Rx*n*

Receive Data Input Pins

These are the EIA–232–E receive signal inputs. A voltage between + 3 and + 25 V is decoded as a space, and causes the corresponding DO pin to swing to ground (0 V). A voltage between – 3 and – 25 V is decoded as a mark, and causes the corresponding DO pin to swing to V_{CC}.

DO1 – DO*n* Data Output Pins

These are the receiver digital output pins which swing from V_{CC} to GND. Each output pin is capable of driving one LSTTL input load.

DI1 – DI*n* Data Input Pins

These are the high impedance digital input pins to the drivers. Input voltage levels on these pins are LSTTL compatible and must be between V_{CC} and GND. A weak pull–up on each input sets all unused DI pins to V_{CC}, causing the corresponding unused driver outputs to be at V_{SS}.

Tx1 – TX*n*

Transmit Data Output Pins

These are the EIA–232–E transmit signal output pins, which swing from V_{DD} to V_{SS}. A logic 1 at the DI input causes the corresponding Tx output to swing to V_{SS}. A logic 0 at the DI input causes the corresponding Tx out to swing to V_{DD}. The actual levels and slew rate achieved will depend on the output loading (R_L \parallel C_L).

APPLICATION INFORMATION

POWER SUPPLY CONSIDERATIONS

Figure 4 shows a technique to guard against excessive device current.

The diode D1 prevents excessive current from flowing through an internal diode from the V_{CC} pin to the V_{DD} pin when V_{DD} < V_{CC} by approximately 0.6 V or greater. This high current condition can exist for a short period of time during power up/down. Additionally, if the + 12 V supply is switched

off while the + 5 V is on and the off supply is a low impedance to ground, the diode D1 will prevent current flow through the internal diode.

The diode D2 is used as a voltage clamp, to prevent VSS from drifting positive to V_{CC}, in the event that power is removed from V_{SS} (Pin 12). If V_{SS} power is removed, and the impedance from the V_{SS} pin to ground is greater than approximately 3 k Ω , this pin will be pulled to V_{CC} by internal circuitry causing excessive current in the V_{CC} pin.

If by design, neither of the above conditions are allowed to exist, then the diodes D1 and D2 are not required.

ESD PROTECTION

ESD protection on IC devices that have their pins accessible to the outside world is essential. High static voltages applied to the pins when someone touches them either directly or indirectly can cause damage to gate oxides and transistor junctions by coupling a portion of the energy from the I/O pin to the power supply buses of the IC. This coupling will usually occur through the internal ESD protection diodes. The key to protecting the IC is to shunt as much of the energy to ground as possible before it enters the IC. Figure 4 shows a technique which will clamp the ESD voltage at approximately \pm 15 V using the MMBZ15VDLT1. Any residual voltage which appears on the supply pins is shunted to ground through the capacitors C1 – C3. This scheme has provided protection to the interface part up to \pm 10 kV, using the human body model test.

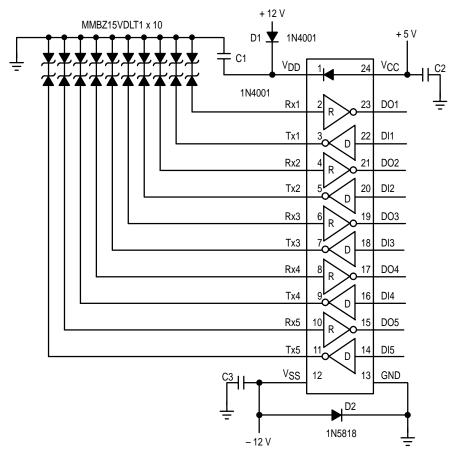
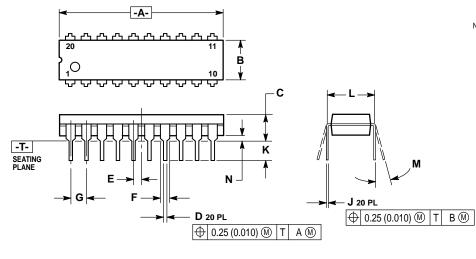


Figure 4.

PACKAGE DIMENSIONS

P SUFFIX PLASTIC DIP CASE 738-03



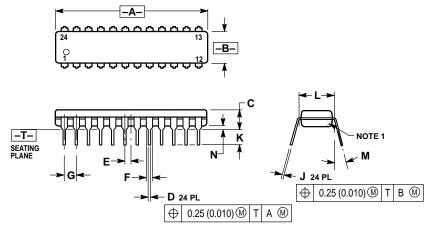
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1.	DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

2. CONTROLING DIMENSION: INCH. 3. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL. 4. DIMENSION B DOES NOT INCLUDE MOLD

FLASH.

	INC	HES	MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	1.010	1.070	25.66	27.17
В	0.240	0.260	6.10	6.60
С	0.150	0.180	3.81	4.57
D	0.015	0.022	0.39	0.55
E	0.050 BSC		1.27 BSC	
F	0.050	0.070	1.27	1.77
G	0.100	BSC	2.54	BSC
J	0.008	0.015	0.21	0.38
K	0.110	0.140	2.80	3.55
L	0.300 BSC		7.62 BSC	
М	0°	15°	0°	15°
N	0.020	0.040	0.51	1.01

P SUFFIX PLASTIC DIP CASE 724-03

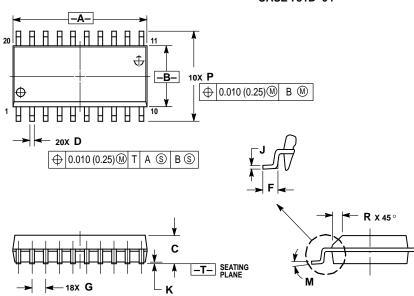


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CONNED PARALLEL.
DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
CONTROLLING DIMENSION: INCH.

	INC	HES	MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	1.230	1.265	31.25	32.13
В	0.250	0.270	6.35	6.85
С	0.145	0.175	3.69	4.44
D	0.015	0.020	0.38	0.51
Ш	0.050	BSC	1.27 BSC	
F	0.040	0.060	1.02	1.52
G	0.100 BSC		2.54	BSC
L	0.007	0.012	0.18	0.30
Κ	0.110	0.140	2.80	3.55
Г	0.300 BSC		7.62 BSC	
М	0 °	15°	0°	15°
Ν	0.020	0.040	0.51	1.01

DW SUFFIX SOG PACKAGE CASE 751D-04



NOTES:

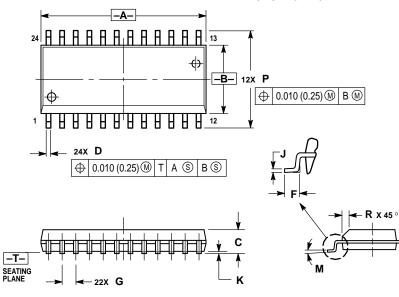
DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

- CONTROLLING DIMENSION: MILLIMETER.
 DIMENSIONS A AND B DO NOT INCLUDE
- MOLD PROTRUSION. 4. MAXIMUM MOLD PROTRUSION 0.150

 MAXIMUM MOLD PROTRUSION 0.150
 (0.006) PER SIDE.
 DIMENSION D DOES NOT INCLUDE
 DAMBAR PROTRUSION. ALLOWABLE
 DAMBAR PROTRUSION SHALL BE 0.13
 (0.005) TOTAL IN EXCESS OF D DIMENSION
 TOTAL IN EXCESS OF D DIMENSION
 TOTAL IN EXCESS OF D DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIN	IETERS	INC	HES		
DIM	MIN	MAX	MIN	MAX		
Α	12.65	12.95	0.499	0.510		
В	7.40	7.60	0.292	0.299		
С	2.35	2.65	0.093	0.104		
D	0.35	0.49	0.014	0.019		
F	0.50	0.90	0.020	0.035		
G	1.27	BSC	0.050	BSC		
J	0.25	0.32	0.010	0.012		
Κ	0.10	0.25	0.004	0.009		
М	0 °	7 °	0 °	7 °		
Ρ	10.05	10.55	0.395	0.415		
R	0.25	0.75	0.010	0.029		

DW SUFFIX SOG PACKAGE CASE 751E-04



NOTES:

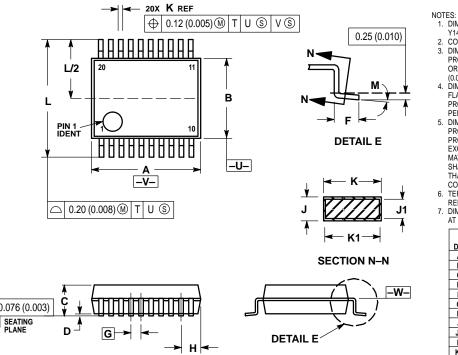
- OTES: 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982. 2. CONTROLLING DIMENSION: MILLIMETER. 3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION. 4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) DEP SIDE

PER SIDE. 5. DIMENSION D DOES NOT INCLUDE DAMBAR

DIMENSION D DUES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.13 (0.005) TOTAL IN EXCESS OF D DIMENSION AT MAXIMUM MATERIAL CONDITION.

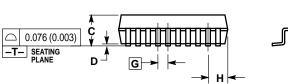
	MILLIMETERS		INCHES	
DIM	MIN	MAX	MIN	MAX
Α	15.25	15.54	0.601	0.612
В	7.40	7.60	0.292	0.299
С	2.35	2.65	0.093	0.104
D	0.35	0.49	0.014	0.019
F	0.41	0.90	0.016	0.035
G	1.27 BSC		0.050 BSC	
J	0.23	0.32	0.009	0.013
K	0.13	0.29	0.005	0.011
М	0°	8°	0 °	8°
Ρ	10.05	10.55	0.395	0.415
R	0.25	0.75	0.010	0.029

SD SUFFIX SSOP CASE 940C-03



- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982. CONTROLLING DIMENSION: MILLIMETER.
- DIMENSION A DOES NOT INCLUDE MOLD FLASH,
- PROTRUSIONS OR GATE BURRS, MOLD FLASH OR GATE BURRS SHALL NOT EXCEED 0.15 (0.006) PER SIDE
- DIMENSION B DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSION. INTERLEAD FLASH OR PROTRUSION SHALL NOT EXCEED 0.15 (0.006) PER SIDE
- DIMENSION K DOES NOT INCLUDE DAMBAR PROTRUSION/INTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.13 (0.005) TOTAL IN EXCESS OF K DIMENSION AT MAXIMUM MATERIAL CONDITION. DAMBAR INTRUSION SHALL NOT REDUCE DIMENSION K BY MORE THAN 0.07 (0.002) AT LEAST MATERIAL CONDITION
- TERMINAL NUMBERS ARE SHOWN FOR
- REFERENCE ONLY. 7. DIMENSION A AND B ARE TO BE DETERMINED AT DATUM PLANE -W-

	MILLIMETERS		INCHES	
DIM	MIN	MAX	MIN	MAX
A	7.07	7.33	0.278	0.288
В	5.20	5.38	0.205	0.212
С	1.73	1.99	0.068	0.078
D	0.05	0.21	0.002	0.008
F	0.63	0.95	0.024	0.037
Ð	0.65 BSC		0.026 BSC	
Н	0.59	0.75	0.023	0.030
J	0.09	0.20	0.003	0.008
J1	0.09	0.16	0.003	0.006
K	0.25	0.38	0.010	0.015
K1	0.25	0.33	0.010	0.013
L	7.65	7.90	0.301	0.311
Μ	0 °	8 °	0 °	8 °



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