

# MC14526B

## Presetable 4-Bit Down Counters

The MC14526B binary counter is constructed with MOS P-channel and N-channel enhancement mode devices in a monolithic structure.

This device is presetable, cascadable, synchronous down counter with a decoded "0" state output for divide-by-N applications. In single stage applications the "0" output is applied to the Preset Enable input. The Cascade Feedback input allows cascade divide-by-N operation with no additional gates required. The Inhibit input allows disabling of the pulse counting function. Inhibit may also be used as a negative edge clock.

This complementary MOS counter can be used in frequency synthesizers, phase-locked loops, and other frequency division applications requiring low power dissipation and/or high noise immunity.

- Supply Voltage Range = 3.0 Vdc to 18 Vdc
- Logic Edge-Clocked Design — Incremented on Positive Transition of Clock or Negative Transition of Inhibit
- Asynchronous Preset Enable
- Capable of Driving Two Low-power TTL Loads or One Low-power Schottky TTL Load Over the Rated Temperature Range

### MAXIMUM RATINGS (Voltages Referenced to $V_{SS}$ ) (Note 2.)

Symbol	Parameter	Value	Unit
$V_{DD}$	DC Supply Voltage Range	-0.5 to +18.0	V
$V_{in}$ , $V_{out}$	Input or Output Voltage Range (DC or Transient)	-0.5 to $V_{DD} + 0.5$	V
$I_{in}$ , $I_{out}$	Input or Output Current (DC or Transient) per Pin	$\pm 10$	mA
$P_D$	Power Dissipation, per Package (Note 3.)	500	mW
$T_A$	Operating Temperature Range	-55 to +125	°C
$T_{stg}$	Storage Temperature Range	-65 to +150	°C
$T_L$	Lead Temperature (8-Second Soldering)	260	°C

2. Maximum Ratings are those values beyond which damage to the device may occur.

3. Temperature Derating:  
Plastic "P and D/DW" Packages: -7.0 mW/°C From 65°C To 125°C

This device contains protection circuitry to guard against damage due to high static voltages or electric fields. However, precautions must be taken to avoid applications of any voltage higher than maximum rated voltages to this high-impedance circuit. For proper operation,  $V_{in}$  and  $V_{out}$  should be constrained to the range  $V_{SS} \leq (V_{in} \text{ or } V_{out}) \leq V_{DD}$ .

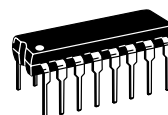
Unused inputs must always be tied to an appropriate logic voltage level (e.g., either  $V_{SS}$  or  $V_{DD}$ ). Unused outputs must be left open.



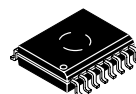
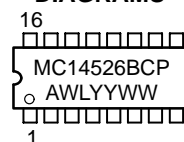
ON Semiconductor

<http://onsemi.com>

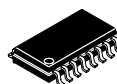
### MARKING DIAGRAMS



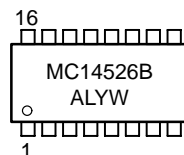
PDIP-16  
P SUFFIX  
CASE 648



SOIC-16  
DW SUFFIX  
CASE 751G



SOEIAJ-16  
F SUFFIX  
CASE 966



A = Assembly Location  
WL, L = Wafer Lot  
YY, Y = Year  
WW, W = Work Week

### ORDERING INFORMATION

Device	Package	Shipping
MC14526BCP	PDIP-16	2000/Box
MC14526BDW	SOIC-16	47/Rail
MC14526BDWR2	SOIC-16	1000/Tape & Reel
MC14526BF	SOEIAJ-16	See Note 1.







1. For ordering information on the EIAJ version of the SOIC packages, please contact your local ON Semiconductor representative.

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## PIN ASSIGNMENT

Q3	1	●	16	V <sub>DD</sub>
P3	2		15	Q2
PE	3		14	P2
INHIBIT	4		13	CF
P0	5		12	"0"
CLOCK	6		11	P1
	7		10	RESET
V <sub>SS</sub>	8		9	Q1

## FUNCTION TABLE

Inputs					Output	Resulting Function
Clock	Reset	Inhibit	Preset Enable	Cascade Feedback	"0"	
X	H	X	L	L	L	Asynchronous reset*
X	H	X	H	L	H	Asynchronous reset
X	H	X	X	H	H	Asynchronous reset
X	L	X	H	X	L	Asynchronous preset
	L	H	L	X	L	Decrement inhibited
L	L		L	X	L	Decrement inhibited
	L	L	L	L	L	No change** (inactive edge)
H	L		L	L	L	No change** (inactive edge)
	L	L	L	L	L	Decrement**
H	L		L	L	L	Decrement**

X = Don't Care

NOTES:

\* Output "0" is low when reset goes high only if PE and CF are low.

\*\* Output "0" is high when reset is low, only if CF is high and count is 0000.

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## ELECTRICAL CHARACTERISTICS (Voltages Referenced to V<sub>SS</sub>)

Characteristic	Symbol	V <sub>DD</sub> Vdc	– 55°C		25°C			125°C		Unit
			Min	Max	Min	Typ (4.)	Max	Min	Max	
Output Voltage V <sub>in</sub> = V <sub>DD</sub> or 0	“0” Level V <sub>OL</sub>	5.0	—	0.05	—	0	0.05	—	0.05	Vdc
		10	—	0.05	—	0	0.05	—	0.05	
		15	—	0.05	—	0	0.05	—	0.05	
	“1” Level V <sub>in</sub> = 0 or V <sub>DD</sub>	5.0	4.95	—	4.95	5.0	—	4.95	—	Vdc
		10	9.95	—	9.95	10	—	9.95	—	
		15	14.95	—	14.95	15	—	14.95	—	
Input Voltage (V <sub>O</sub> = 4.5 or 0.5 Vdc) (V <sub>O</sub> = 9.0 or 1.0 Vdc) (V <sub>O</sub> = 13.5 or 1.5 Vdc)	“0” Level V <sub>IL</sub>	5.0	—	1.5	—	2.25	1.5	—	1.5	Vdc
		10	—	3.0	—	4.50	3.0	—	3.0	
		15	—	4.0	—	6.75	4.0	—	4.0	
	“1” Level (V <sub>O</sub> = 0.5 or 4.5 Vdc) (V <sub>O</sub> = 1.0 or 9.0 Vdc) (V <sub>O</sub> = 1.5 or 13.5 Vdc)	5.0	3.5	—	3.5	2.75	—	3.5	—	Vdc
		10	7.0	—	7.0	5.50	—	7.0	—	
		15	11	—	11	8.25	—	11	—	
Output Drive Current (V <sub>OH</sub> = 2.5 Vdc) (V <sub>OH</sub> = 4.6 Vdc) (V <sub>OH</sub> = 9.5 Vdc) (V <sub>OH</sub> = 13.5 Vdc)	Source I <sub>OH</sub>	5.0	– 3.0	—	– 2.4	– 4.2	—	– 1.7	—	mAdc
		5.0	– 0.64	—	– 0.51	– 0.88	—	– 0.36	—	
		10	– 1.6	—	– 1.3	– 2.25	—	– 0.9	—	
		15	– 4.2	—	– 3.4	– 8.8	—	– 2.4	—	
	Sink I <sub>OL</sub>	5.0	0.64	—	0.51	0.88	—	0.36	—	mAdc
		10	1.6	—	1.3	2.25	—	0.9	—	
		15	4.2	—	3.4	8.8	—	2.4	—	
Input Current	I <sub>in</sub>	15	—	± 0.1	—	± 0.00001	± 0.1	—	± 1.0	μAdc
Input Capacitance (V <sub>in</sub> = 0)	C <sub>in</sub>	—	—	—	—	5.0	7.5	—	—	pF
Quiescent Current (Per Package)	I <sub>DD</sub>	5.0	—	5.0	—	0.005	5.0	—	150	μAdc
		10	—	10	—	0.010	10	—	300	
		15	—	20	—	0.015	20	—	600	
Total Supply Current (5.) (6.) (Dynamic plus Quiescent, Per Package) (C <sub>L</sub> = 50 pF on all outputs, all buffers switching)	I <sub>T</sub>	5.0 10 15	I <sub>T</sub> = (1.7 μA/kHz) f + I <sub>DD</sub> I <sub>T</sub> = (3.4 μA/kHz) f + I <sub>DD</sub> I <sub>T</sub> = (5.1 μA/kHz) f + I <sub>DD</sub>							μAdc

4. Data labelled “Typ” is not to be used for design purposes but is intended as an indication of the IC’s potential performance.

5. The formulas given are for the typical characteristics only at 25°C.

6. To calculate total supply current at loads other than 50 pF:

$$I_T(C_L) = I_T(50 \text{ pF}) + (C_L - 50) Vfk$$

where: I<sub>T</sub> is in μA (per package), C<sub>L</sub> in pF, V = (V<sub>DD</sub> – V<sub>SS</sub>) in volts, f in kHz is input frequency, and k = 0.001.

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## SWITCHING CHARACTERISTICS <sup>(7.)</sup> ( $C_L = 50 \text{ pF}$ , $T_A = 25^\circ\text{C}$ )

Characteristic	Symbol	$V_{DD}$	Min	Typ <sup>(8.)</sup>	Max	Unit
Output Rise and Fall Time $t_{TLH}, t_{THL} = (1.5 \text{ ns/pF}) C_L + 25 \text{ ns}$ $t_{TLH}, t_{THL} = (0.75 \text{ ns/pF}) C_L + 12.5 \text{ ns}$ $t_{TLH}, t_{THL} = (0.55 \text{ ns/pF}) C_L + 9.5 \text{ ns}$	$t_{TLH},$ $t_{THL}$ (Figures 4, 5)	5.0 10 15	— — —	100 50 40	200 100 80	ns
Propagation Delay Time (Inhibit Used as Negative Edge Clock) Clock or Inhibit to Q $t_{PLH}, t_{PHL} = (1.7 \text{ ns/pF}) C_L + 465 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.66 \text{ ns/pF}) C_L + 197 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.5 \text{ ns/pF}) C_L + 135 \text{ ns}$  Clock or Inhibit to "0" $t_{PLH}, t_{PHL} = (1.7 \text{ ns/pF}) C_L + 155 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.66 \text{ ns/pF}) C_L + 87 \text{ ns}$ $t_{PLH}, t_{PHL} = (0.5 \text{ ns/pF}) C_L + 65 \text{ ns}$	$t_{PLH},$ $t_{PHL}$ (Figures 4, 5, 6)	5.0 10 15  5.0 10 15	— — —  — — —	550 225 160  240 130 100	1100 450 320  480 260 200	ns
Propagation Delay Time Pn to Q	$t_{PLH},$ $t_{PHL}$ (Figures 4, 7)	5.0 10 15	— — —	260 120 100	520 240 200	ns
Propagation Delay Time Reset to Q	$t_{PHL}$  (Figure 8)	5.0 10 15	— — —	250 110 80	500 220 160	ns
Propagation Delay Time Preset Enable to "0"	$t_{PHL},$ $t_{PLH}$ (Figures 4, 9)	5.0 10 15	— — —	220 100 80	440 200 160	ns
Clock or Inhibit Pulse Width	$t_w$  (Figures 5, 6)	5.0 10 15	250 100 80	125 50 40	— — —	ns
Clock Pulse Frequency (with PE = low)	$f_{max}$  (Figures 4, 5, 6)	5.0 10 15	— — —	2.0 5.0 6.6	1.5 3.0 4.0	MHz
Clock or Inhibit Rise and Fall Time	$t_r,$ $t_f$ (Figures 5, 6)	5.0 10 15	— — —	— — —	15 5 4	$\mu\text{s}$
Setup Time Pn to Preset Enable	$t_{su}$  (Figure 10)	5.0 10 15	90 50 40	40 15 10	— — —	ns
Hold Time Preset Enable to Pn	$t_h$  (Figure 10)	5.0 10 15	30 30 30	– 15 – 5 0	— — —	ns
Preset Enable Pulse Width	$t_w$  (Figure 10)	5.0 10 15	250 100 80	125 50 40	— — —	ns
Reset Pulse Width	$t_w$  (Figure 8)	5.0 10 15	350 250 200	175 125 100	— — —	ns
Reset Removal Time	$t_{rem}$  (Figure 8)	5.0 10 15	10 20 30	– 110 – 30 – 20	— — —	ns

7. The formulas given are for the typical characteristics only at 25°C.

8. Data labelled "Typ" is not to be used for design purposes but is intended as an indication of the IC's potential performance.

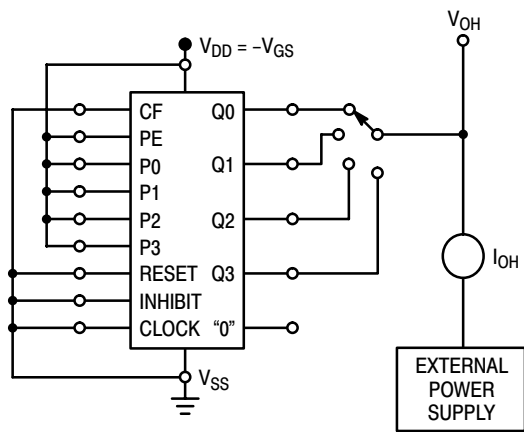


Figure 1. Typical Output Source Characteristics Test Circuit

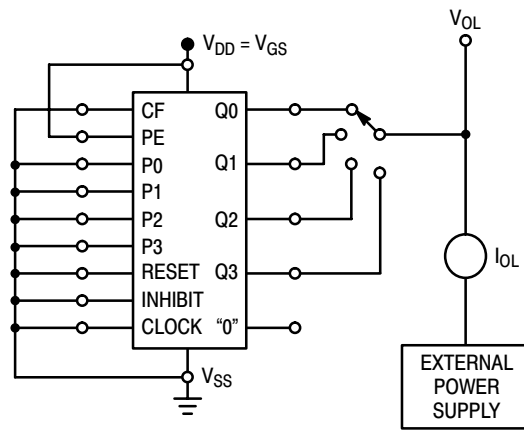


Figure 2. Typical Output Sink Characteristics Test Circuit

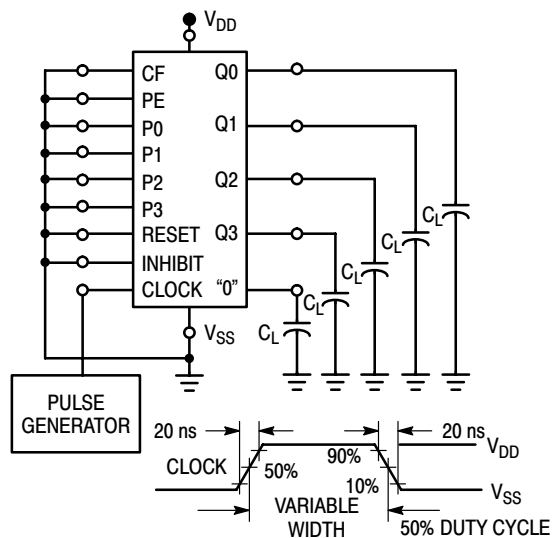
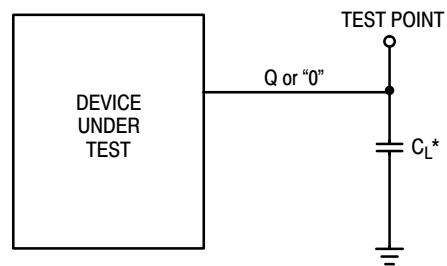


Figure 3. Power Dissipation



\* Includes all probe and jig capacitance.

Figure 4. Test Circuit

SWITCHING WAVEFORMS

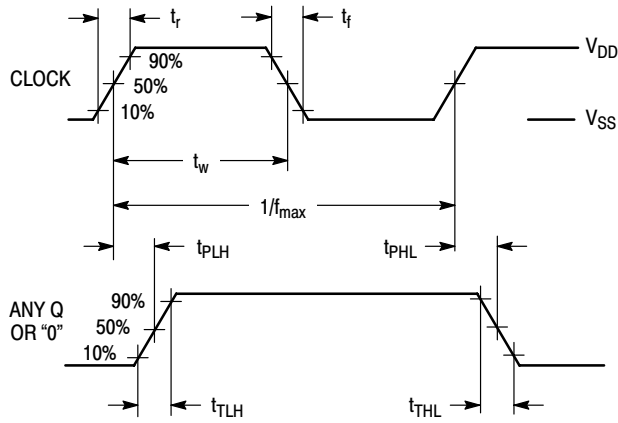


Figure 5.

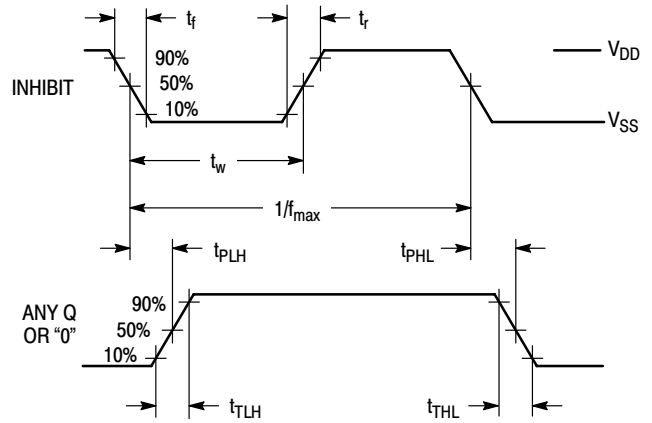


Figure 6.

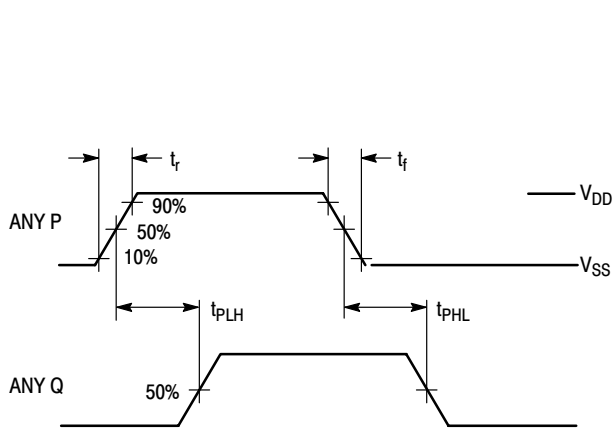


Figure 7.

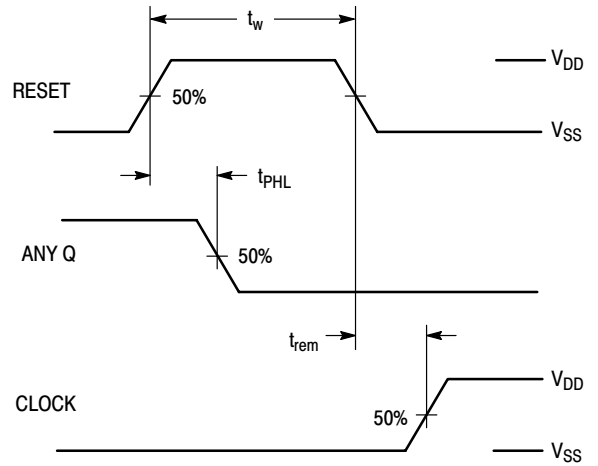


Figure 8.

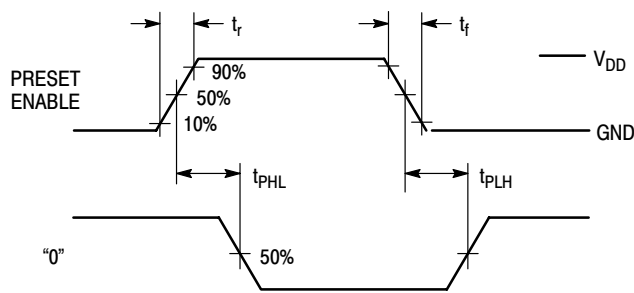


Figure 9.

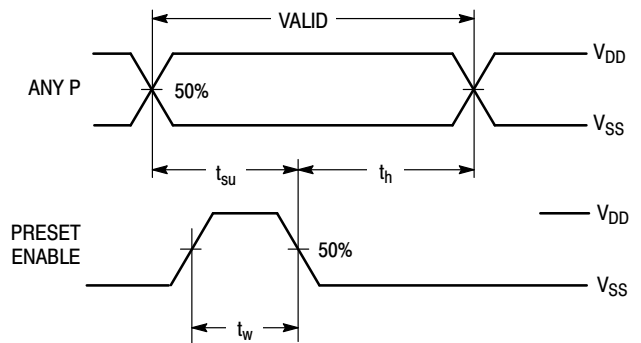


Figure 10.

## PIN DESCRIPTIONS

**Preset Enable (Pin 3)** — If Reset is low, a high level on the Preset Enable input asynchronously loads the counter with the programmed values on P0, P1, P2, and P3.

**Inhibit (Pin 4)** — A high level on the Inhibit input prevents the Clock from decrementing the counter. With Clock (pin 6) held high, Inhibit may be used as a negative edge clock input.

**Clock (Pin 6)** — The counter decrements by one for each rising edge of Clock. See the Function Table for level requirements on the other inputs.

**Reset (Pin 10)** — A high level on Reset asynchronously forces Q0, Q1, Q2, and Q3 low and, if Cascade Feedback is high, causes the “0” output to go high.

**“0” (Pin 12)** — The “0” (Zero) output issues a pulse one clock period wide when the counter reaches terminal count ( $Q0 = Q1 = Q2 = Q3 = \text{low}$ ) if Cascade Feedback is high and Preset Enable is low. When presetting the counter to a value

other than all zeroes, the “0” output is valid after the rising edge of Preset Enable (when Cascade Feedback is high). See the Function Table.

**Cascade Feedback (Pin 13)** — If the Cascade Feedback input is high, a high level is generated at the “0” output when the count is all zeroes. If Cascade Feedback is low, the “0” output depends on the Preset Enable input level. See the Function Table.

**P0, P1, P2, P3 (Pins 5, 11, 14, 2)** — These are the preset data inputs. P0 is the LSB.

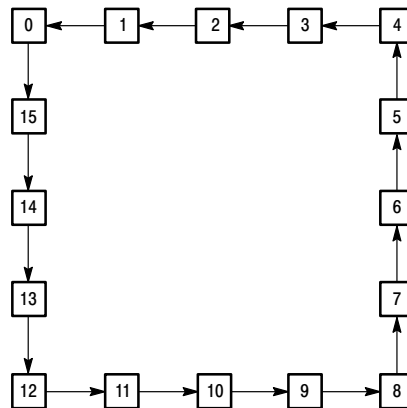
**Q0, Q1, Q2, Q3 (Pins 7, 9, 15, 1)** — These are the synchronous counter outputs. Q0 is the LSB.

**V<sub>SS</sub> (Pin 8)** — The most negative power supply potential. This pin is usually ground.

**V<sub>DD</sub> (Pin 16)** — The most positive power supply potential. V<sub>DD</sub> may range from 3 to 18 V with respect to V<sub>SS</sub>.

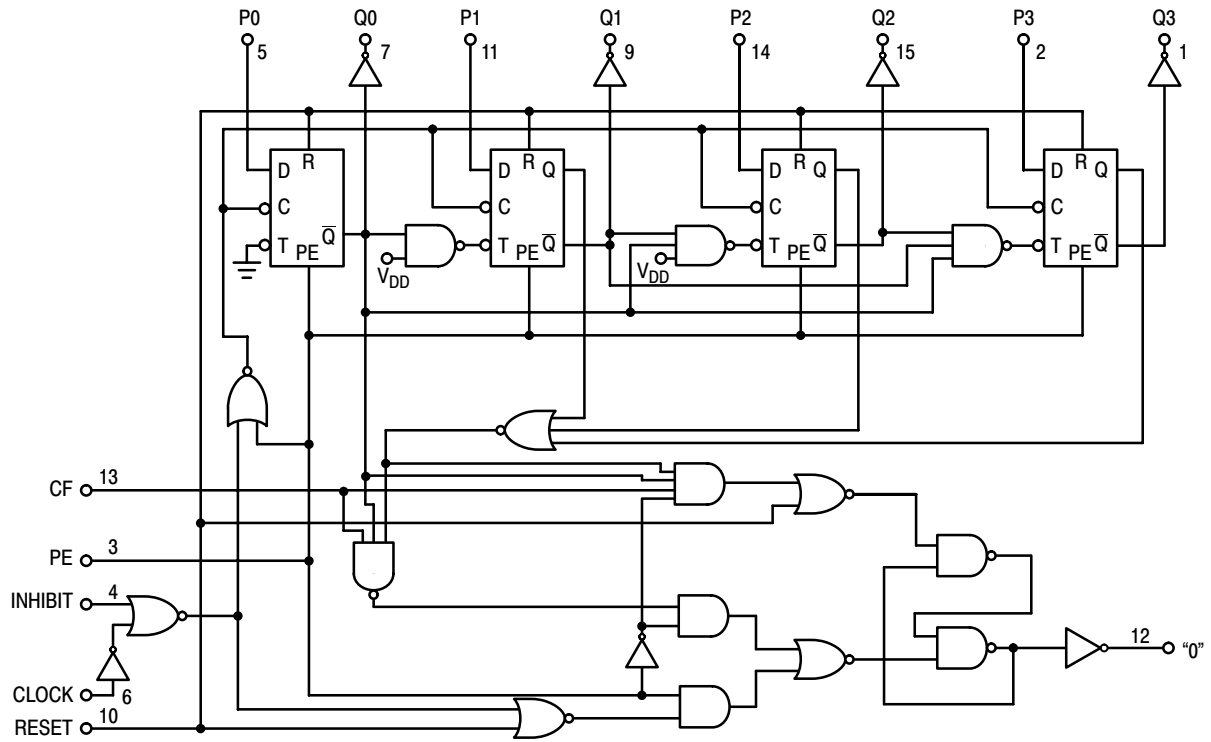
## STATE DIAGRAM

MC14526B



## MC14526B

### MC14526B LOGIC DIAGRAM (Binary Down Counter)





## APPLICATIONS INFORMATION

## Divide-By-N, Single Stage

Figure 11 shows a single stage divide-by-N application.

To initialize counting a number, N is set on the parallel inputs (P0, P1, P2, and P3) and reset is taken high asynchronously. A zero is forced into the master and slave of each bit and, at the same time, the "0" output goes high. Because Preset Enable is tied to the "0" output, preset is enabled. Reset must be released while the Clock is high so the slaves of each bit may receive N before the Clock goes low. When the Clock goes low and Reset is low, the "0" output goes low (if P0 through P3 are unequal to zero).

The counter downcounts with each rising edge of the Clock. When the counter reaches the zero state, an output pulse occurs on "0" which presets N. The propagation delays from the Clock's rising and falling edges to the "0" output's rising and falling edges are about equal, making the "0" output pulse approximately equal to that of the Clock pulse.

The Inhibit pin may be used to stop pulse counting. When this pin is taken high, decrementing is inhibited.

## Cascaded, Presetable Divide-By-N

Figure 12 shows a three stage cascade application. Taking Reset high loads N. Only the first stage's Reset pin (least significant counter) must be taken high to cause the preset for all stages, but all pins could be tied together, as shown.

When the first stage's Reset pin goes high, the "0" output is latched in a high state. Reset must be released while Clock is high and time allowed for Preset Enable to load N into all stages before Clock goes low.

When Preset Enable is high and Clock is low, time must be allowed for the zero digits to propagate a Cascade Feedback to the first non-zero stage. Worst case is from the most significant bit (M.S.B.) to the L.S.B., when the L.S.B. is equal to one (i.e.  $N = 1$ ).

After N is loaded, each stage counts down to zero with each rising edge of Clock. When any stage reaches zero and the leading stages (more significant bits) are zero, the "0" output goes high and feeds back to the preceding stage. When all stages are zero, the Preset Enable automatically loads N while the Clock is high and the cycle is renewed.

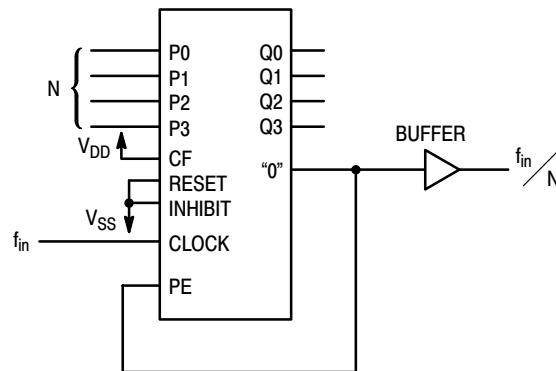
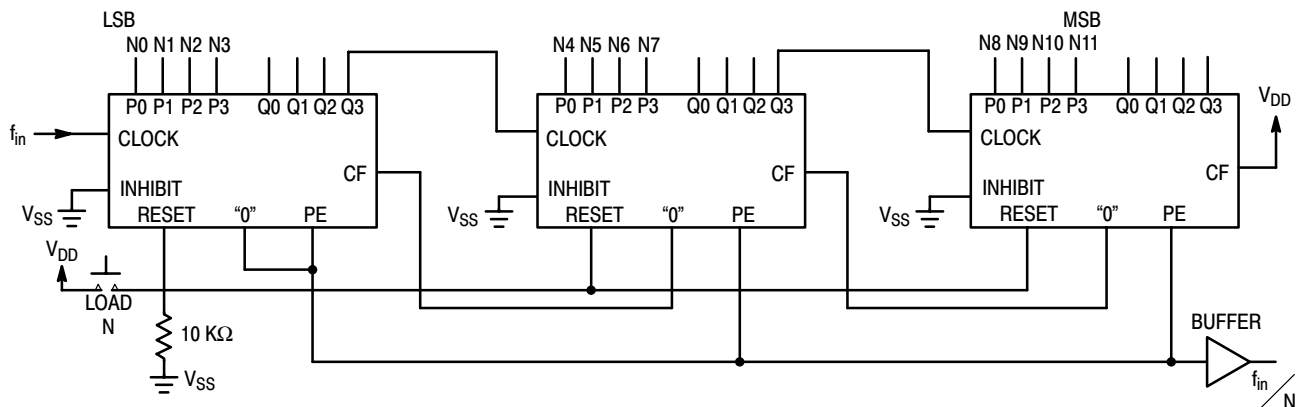
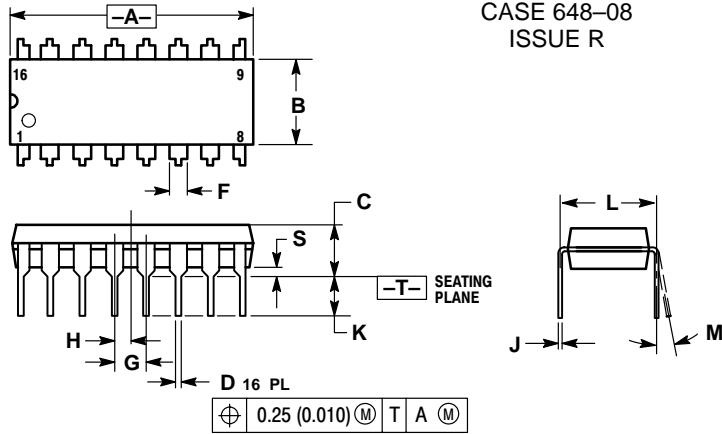
Figure 11.  $\div N$  Counter

Figure 12. 3 Stages Cascaded

# MC14526B

## PACKAGE DIMENSIONS

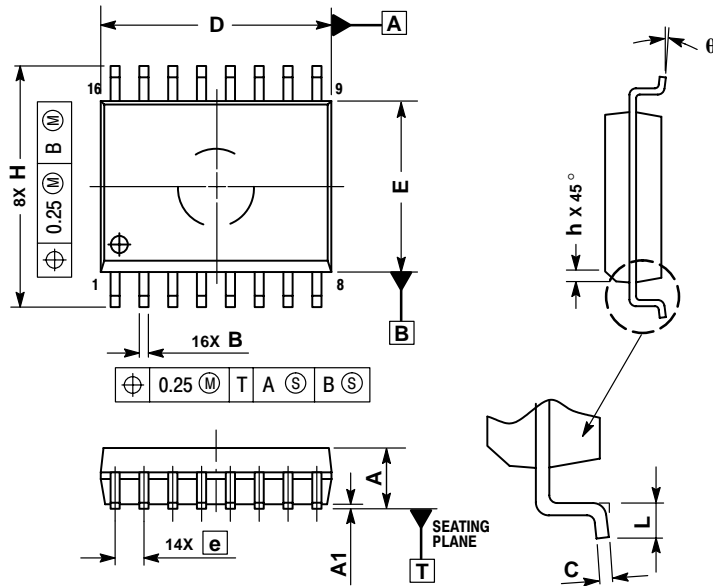
### PDIP-16 P SUFFIX PLASTIC DIP PACKAGE CASE 648-08 ISSUE R



#### NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
5. ROUNDED CORNERS OPTIONAL.

### SOIC-16 DW SUFFIX PLASTIC SOIC PACKAGE CASE 751G-03 ISSUE B



#### NOTES:

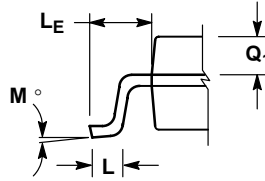
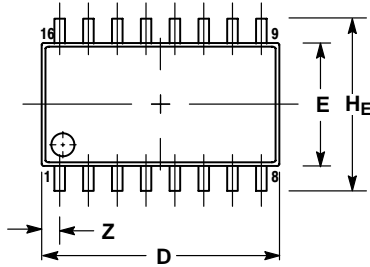
1. DIMENSIONS ARE IN MILLIMETERS.
2. INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14.5M, 1994.
3. DIMENSIONS D AND E DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15 PER SIDE.
5. DIMENSION B DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.13 TOTAL IN EXCESS OF THE B DIMENSION AT MAXIMUM MATERIAL CONDITION.

DIM	MIN	MAX
A	2.35	2.65
A1	0.10	0.25
B	0.35	0.49
C	0.23	0.32
D	10.15	10.45
E	7.40	7.60
e	1.27 BSC	
H	10.05	10.55
h	0.25	0.75
L	0.50	0.90
θ	0°	7°

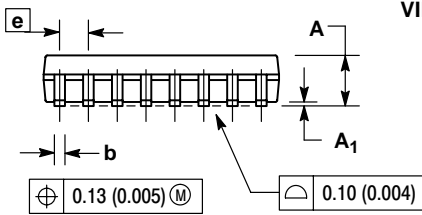
# MC14526B

## PACKAGE DIMENSIONS

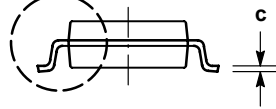
SOEIAJ-16  
F SUFFIX  
PLASTIC EIAJ SOIC PACKAGE  
CASE 966-01  
ISSUE O



DETAIL P




VIEW P



### NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: MILLIMETER.
3. DIMENSIONS D AND E DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS AND ARE MEASURED AT THE PARTING LINE. MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED 0.15 (0.006) PER SIDE.
4. TERMINAL NUMBERS ARE SHOWN FOR REFERENCE ONLY.
5. THE LEAD WIDTH DIMENSION (b) DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08 (0.003) TOTAL IN EXCESS OF THE LEAD WIDTH DIMENSION AT MAXIMUM MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON THE LOWER RADIUS OR THE FOOT. MINIMUM SPACE BETWEEN PROTRUSIONS AND ADJACENT LEAD TO BE 0.46 (0.018).

DIM	MILLIMETERS		INCHES	
	MIN	MAX	MIN	MAX
A	---	2.05	---	0.081
A <sub>1</sub>	0.05	0.20	0.002	0.008
b	0.35	0.50	0.014	0.020
c	0.18	0.27	0.007	0.011
D	9.90	10.50	0.390	0.413
E	5.10	5.45	0.201	0.215
e	1.27 BSC		0.050 BSC	
H <sub>E</sub>	7.40	8.20	0.291	0.323
L	0.50	0.85	0.020	0.033
L <sub>E</sub>	1.10	1.50	0.043	0.059
M	0°	10°	0°	10°
Q <sub>1</sub>	0.70	0.90	0.028	0.035
Z	---	0.78	---	0.031

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