

# Complete 12-Bit 40 MSPS Imaging Signal Processor

# AD9821

#### **FEATURES**

Differential Sensor Input with 1 V p-p Input Range 0 dB to 36 dB 10-Bit Variable Gain Amplifier (VGA) Low Noise Optical Black Clamp Circuit Analog Preblanking Function 12-Bit 40 MSPS A/D Converter (ADC) 3-Wire Serial Digital Interface 3 V Single-Supply Operation Low Power: 150 mW @ 3 V Supply 48-Lead LQFP Package

#### **APPLICATIONS**

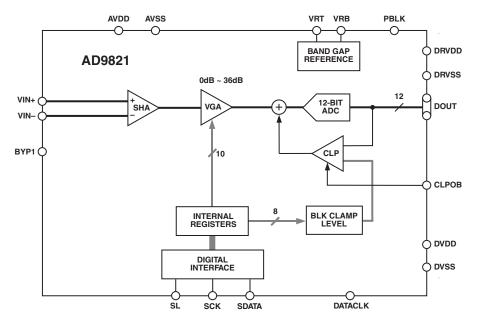
Digital Still Cameras Using CMOS Imagers Industrial/Scientific Imaging

#### **GENERAL DESCRIPTION**

The AD9821 is a complete analog signal processor for imaging applications that do not require Correlated Double Sampling (CDS). It features a 40 MHz single-channel architecture designed to sample and condition the outputs of CMOS imagers and CCD arrays already containing on-chip CDS. The AD9821's signal chain consists of a differential input sample-and-hold amplifier (SHA), digitally controlled variable gain amplifier (VGA), black level clamp, and a 12-bit ADC.

The internal registers are programmed through a 3-wire serial digital interface. Programmable features include gain adjustment, black level adjustment, and power-down modes.

The AD9821 operates from a single 3 V power supply, typically dissipates 150 mW, and is packaged in a 48-lead LQFP.



### FUNCTIONAL BLOCK DIAGRAM

### REV.0

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# AD9821-SPECIFICATIONS

# **GENERAL SPECIFICATIONS** ( $T_{MIN}$ to $T_{MAX}$ , AVDD = DVDD = 3.0 V, $f_{DATACLK}$ = 40 MHz, unless otherwise noted.)

Parameter	Min	Тур	Max	Unit		
TEMPERATURE RANGE						
Operating	-20		+85	°C		
Storage	-65		+150	°C		
POWER SUPPLY VOLTAGE						
Analog, Digital, Digital Driver	2.7		3.6	V		
POWER CONSUMPTION						
Normal Operation	(Specified	under Each Mod	de of Operation)			
Power-Down Modes						
Standby		5		mW		
Total Power-Down		1		mW		
MAXIMUM CLOCK RATE	40			MHz		
A/D CONVERTER						
Resolution	12			Bits		
Differential Nonlinearity (DNL)		$\pm 0.5$		LSB		
No Missing Codes	12			Bits Guaranteed		
Full-Scale Input Voltage		2.0		V		
Data Output Coding		Straight Binary				
VOLTAGE REFERENCE						
Reference Top Voltage (VRT)		2.0				
Reference Bottom Voltage (VRB)		1.0				

Specifications subject to change without notice.

# **DIGITAL SPECIFICATIONS** (DRVDD = 2.7 V, C<sub>L</sub> = 20 pF, unless otherwise noted.)

Parameter	Symbol	Min	Тур	Max	Unit
LOGIC INPUTS					
High Level Input Voltage	V <sub>IH</sub>	2.1			V
Low Level Input Voltage	V <sub>IL</sub>			0.6	V
High Level Input Current	I <sub>IH</sub>		10		μA
Low Level Input Current	I <sub>IL</sub>		10		μA
Input Capacitance	C <sub>IN</sub>		10		pF
LOGIC OUTPUTS					
High Level Output Voltage, I <sub>OH</sub> = 2 mA	V <sub>OH</sub>	2.2			V
Low Level Output Voltage, $I_{OL} = 2 \text{ mA}$	V <sub>OL</sub>			0.5	V

Specifications subject to change without notice.

# **IMAGER-MODE SPECIFICATIONS** ( $T_{MIN}$ to $T_{MAX}$ , AVDD = DVDD = 3.0 V, $f_{DATACLK}$ = 40 MHz, unless otherwise noted.)

Parameter	Min	Тур	Max	Unit	Notes
POWER CONSUMPTION		150		mW	See TPC 1 for Power vs. Sample Rate
MAXIMUM CLOCK RATE	40			MHz	
ANALOG INPUTS (VIN+, VIN–) Input Common-Mode Range* Max Input Amplitude* Max Optical Black Pixel Amplitude*	0 1.0	±30	1.8	V V p-p mV	Linear operating range for VIN+, VIN– Defined as VIN+ minus VIN– For stable Clamp at max VGA gain
VARIABLE GAIN AMPLIFIER (VGA) Gain Control Resolution Gain Monotonicity Gain Range Min Gain (VGA Gain Code 00) Max Gain (VGA Gain Code 1023)		1024 Guara 0 36	nteed	Steps dB dB	See Figure 11 for VGA Gain Curve
BLACK LEVEL CLAMP Clamp Level Resolution Clamp Level Min Clamp Level Max Clamp Level		256 0 255		Steps LSB LSB	Measured at ADC Output
SYSTEM PERFORMANCE Gain Accuracy Min Gain Max Gain Peak Nonlinearity, 500 mV Input Total Output Noise Power Supply Rejection (PSR)	-1 34.5	0 35.5 0.3 0.5 40	+1 36.5	dB dB % LSB rms dB	Specifications Include Entire Signal Chain 12 dB Gain Applied AC Grounded Input, 6 dB Gain Applied Measured with Step Change on Supply
POWER-UP RECOVERY TIME Reference Standby Mode Total Power-Down Mode Power-Off Condition		1 3 10		ms ms ms	Normal Clock Signals Applied

\*Input Signal Characteristics defined as follows:

INPUT CM RANGE VIN+ VIN-¥ ŧ GND -

Specifications subject to change without notice.

# **TIMING SPECIFICATIONS** ( $C_L = 20 \text{ pF}$ , $f_{SAMP} = 40 \text{ MHz}$ , Imager-Mode Timing in Figures 5 and 6, Serial Timing in Figures 7–9)

Parameter	Symbol	Min	Тур	Max	Unit
SAMPLE CLOCKS					
DATACLK Clock Period	t <sub>CONV</sub>	25	25		ns
DATACLK Hi/Low Pulsewidth	t <sub>ADC</sub>	11	12.5		ns
CLPOB Pulsewidth*	t <sub>COB</sub>	2	20		Pixels
Internal Clock Delay	t <sub>ID</sub>		3.0		ns
DATA OUTPUTS					
Output Delay	t <sub>OD</sub>		13	16	ns
Output Hold Time	t <sub>H</sub>	7.0	7.6		ns
Pipeline Delay			9		Cycles
SERIAL INTERFACE					
Maximum SCK Frequency	f <sub>SCLK</sub>	10			MHz
SL to SCK Setup Time	t <sub>LS</sub>	10			ns
SCK to SL Hold Time	t <sub>LH</sub>	10			ns
SDATA Valid to SCK Rising Edge Setup	t <sub>DS</sub>	10			ns
SCK Falling Edge to SDATA Valid Hold	t <sub>DH</sub>	10			ns
SCK Falling Edge to SDATA Valid Read	t <sub>DV</sub>	10			ns

\*Minimum CLPOB pulsewidth is for functional operation only. Wider typical pulses are recommended to achieve low noise clamp performance. Specifications subject to change without notice.

## ABSOLUTE MAXIMUM RATINGS

	With Respect			
Parameter	То	Min	Max	Unit
AVDD1, AVDD2	AVSS	-0.3	+3.9	V
DVDD1, DVDD2	DVSS	-0.3	+3.9	V
DRVDD	DRVSS	-0.3	+3.9	V
Digital Outputs	DRVSS	-0.3	DRVDD + 0.3	V
DATACLK	DVSS	-0.3	DVDD + 0.3	V
CLPOB, PBLK	DVSS	-0.3	DVDD + 0.3	V
SCK, SL, SDATA	DVSS	-0.3	DVDD + 0.3	V
VRT, VRB	AVSS	-0.3	AVDD + 0.3	V
BYP1, VIN	AVSS	-0.3	AVDD + 0.3	V
Junction Temperature			150	°C
Lead Temperature			300	°C
(10 sec)				

### **ORDERING GUIDE**

Model	Temperature	Package	Package	
	Range	Description	Option	
AD9821KST	–20°C to +85°C	Thin Plastic Quad Flatpack (LQFP)	ST-48	

# THERMAL CHARACTERISTICS Thermal Resistance

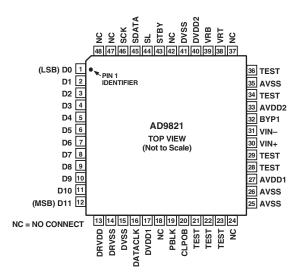
48-Lead LQFP Package  $\theta_{JA} = 56^{\circ}C/W$ 

#### CAUTION \_

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the AD9821 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



## PIN CONFIGURATION



#### PIN FUNCTION DESCRIPTIONS

Pin Number	Mnemonic	Туре	Description
1–12	D0-D11	DO	Digital Data Outputs
13	DRVDD	Р	Digital Output Driver Supply
14	DRVSS	Р	Digital Output Driver Ground
15, 41	DVSS	Р	Digital Ground
16	DATACLK	DI	Digital Data Output Latch Clock
17	DVDD1	Р	Digital Supply
18, 24, 37, 42, 47, 48	NC	NC	Internally Not Connected. May be Tied High or Low.
19	PBLK	DI	Preblanking Clock Input
20	CLPOB	DI	Black Level Clamp Clock Input
21–23	TEST	DI	Test Use Only. Tie to VDD or VSS.
25, 26, 35	AVSS	Р	Analog Ground
27	AVDD1	Р	Analog Supply
28, 29	TEST	AO	Test Use Only. Tie to VDD or VSS.
30	VIN+	AI	Positive Analog Input for Imager Signal
31	VIN-	AI	Negative Analog Input for Imager Signal
32	BYP1	AO	Internal Bias Level Decoupling
33	AVDD2	Р	Analog Supply
34, 36	TEST	AI	Test Use Only. Tie to VDD or VSS.
38	VRT	AO	ADC Top Reference Voltage Decoupling
39	VRB	AO	ADC Bottom Reference Voltage Decoupling
40	DVDD2	Р	Digital Supply
43	STBY	DI	Standby Mode, Active High. Same as Total Power-Down Mode.
44	SL	DI	Serial Digital Interface Load Pulse
45	SDATA	DI	Serial Digital Interface Data
46	SCK	DI	Serial Digital Interface Clock

TYPE: AI = Analog Input, AO = Analog Output, DI = Digital Input, DO = Digital Output, P = Power.

# **DEFINITIONS OF SPECIFICATIONS**

# Differential Nonlinearity (DNL)

An ideal ADC exhibits code transitions that are exactly 1 LSB apart. DNL is the deviation from this ideal value. Thus, every code must have a finite width. No missing codes guaranteed to 12-bit resolution indicates that all 4096 codes, respectively, must be present over all operating conditions.

### **Peak Nonlinearity**

Peak nonlinearity, a full signal chain specification, refers to the peak deviation of the output of the AD9821 from a true straight line. The point used as "zero scale" occurs 1/2 LSB before the first code transition. "Positive full scale" is defined as a Level 1, 1/2 LSB beyond the last code transition. The deviation is measured from the middle of each particular output code to the true straight line. The error is then expressed as a percentage of the 2 V ADC full-scale signal. The input signal is always appropriately gained up to fill the ADC's full-scale range.

## **Total Output Noise**

The rms output noise is measured using histogram techniques. The standard deviation of the ADC output codes is calculated in LSB and represents the rms noise level of the total signal chain at the specified gain setting. The output noise can be converted to an equivalent voltage using the relationship 1 LSB = (ADC Full Scale/2<sup>N</sup> codes) when N is the bit resolution of the ADC. For the AD9821, 1 LSB is 500  $\mu$ V.

## Power Supply Rejection (PSR)

The PSR is measured with a step change applied to the supply pins. This represents a very high frequency disturbance on the AD9821's power supply. The PSR specification is calculated from the change in the data outputs for a given step change in the supply voltage.

#### Internal Delay for SHA

The internal delay (also called aperture delay) is the time delay that occurs from when the sampling edge is applied to the AD9821 until the actual sample of the input signal is held. The DATACLK samples the input signal during the transition from low to high, so the internal delay is measured from each clock's rising edge to the instant the actual internal sample is taken.

## EQUIVALENT INPUT CIRCUITS

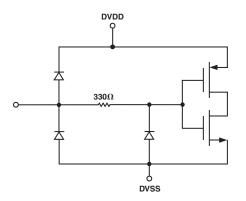


Figure 1. Digital Inputs – DATACLK, CLPOB, PBLK, SCK, SL

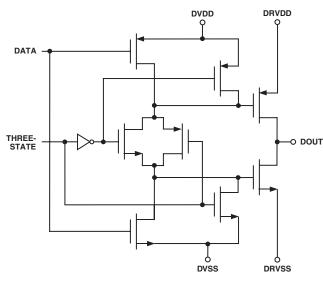


Figure 2. Data Outputs – D0–D11

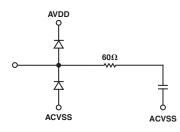


Figure 3. VIN+ and VIN– (Pins 30 and 31)

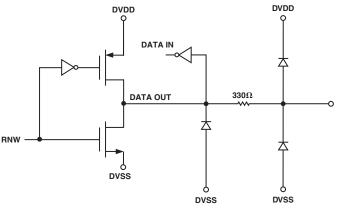
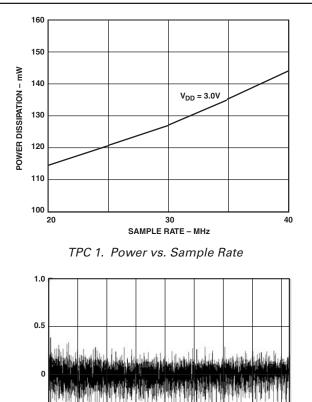
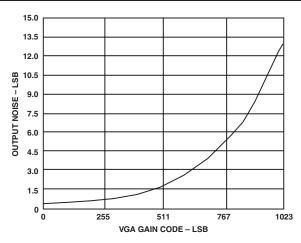


Figure 4. SDATA (Pin 47)

# Typical Performance Characteristics-AD9821





TPC 3. Output Noise vs. VGA Gain

1500 2000 TPC 2. Typical DNL Performance

2500

3000 35000

4000

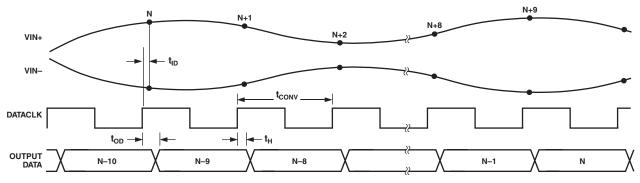
-0.5

-1.0 L 0

500

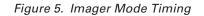
1000

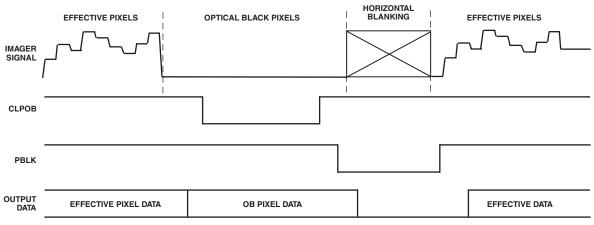
# IMAGER MODE AND AUX MODE TIMING



NOTES:

1. VIN+ AND VIN- SIGNALS ARE SAMPLED AT DATACLK RISING EDGES (CAN BE INVERTED USING THE CONTROL REGISTER). 2. INTERNAL SAMPLING DELAY (APERTURE) t<sub>ID</sub> IS TYPICALLY 3 ns. 3. OUTPUT DATA LATENCY IS NINE DATACLK CYCLES.





NOTES:

NUTES: 1. CLPOB WILL OVERWRITE PBLK. PBLK WILL NOT AFFECT CLAMP OPERATION IF OVERLAPPING CLPOB. 2. PBLK SIGNAL IS OPTIONAL. 3. DIGITAL OUTPUT DATA WILL BE ALL ZEROS DURING PBLK. OUTPUT DATA LATENCY IS NINE DATACLK CYCLES.

Figure 6. Typical Imager Mode Line Clamp Timing

### INTERNAL REGISTER MAP AND SERIAL INTERFACE TIMING

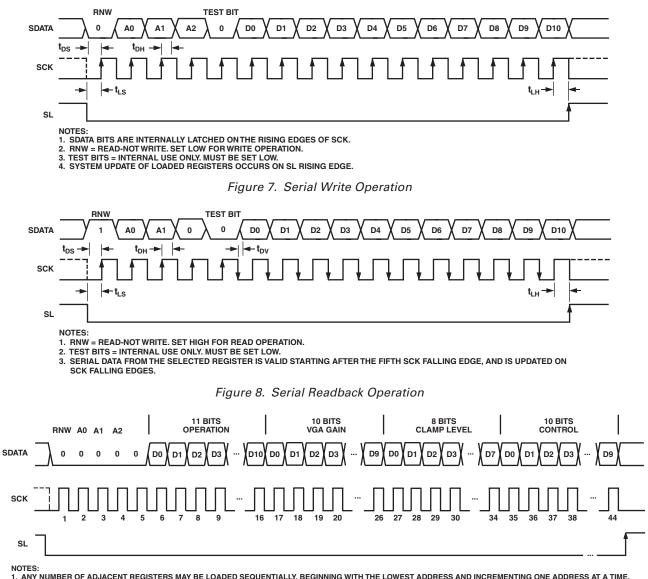
Table I.	Internal	Register	Man
I aute I.	multinal	Register	map

Register	Address				Data F	Bits						
Name	A0 A1 A2	D0 D1 D2 D		D3	<b>D</b> 4	D5	D6	D6 D7		<b>D9</b>	D10	
Operation	000	1 <b>^</b>	I		Power-Down Software Modes Reset		OB Clamp On/Off	01	1 <sup>2</sup>	01	01	01
VGA Gain	100	LSB									MSB	X
Clamp Level	010	LSB							MSB	Х	Х	X
Control	110	01	01	01	01	01	Clock Polarity Select for CLP/DATA		01	01	01	X

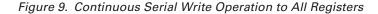
NOTES

<sup>1</sup>Internal use only. Must be set to 0.

<sup>2</sup>Must be set to 1.



1. ANY NUMBER OF ADJACENT REGISTERS MAY BE LOADED SEQUENTIALLY, BEGINNING WITH THE LOWEST ADDRESS AND INCREMENTING ONE ADDRESS AT A TIME. 2. WHEN SEQUENTIALLY LOADING MULTIPLE REGISTERS, THE EXACT REGISTER LENGTH (SHOWN ABOVE) MUST BE USED FOR EACH REGISTER. 3. ALL LOADED REGISTERS WILL BE SIMULTANEOUSLY UPDATED WITH THE RISING EDGE OF SL.



# **REGISTER DETAILS**

D10	D9	D8	<b>D</b> 7	D6	Optical Black Clamp D5	Reset D4	Power-Down Modes D3 D2	Channel Selection D1 D0
01	01	01	1 <sup>2</sup>	01	<ol> <li>Enable Clamping</li> <li>Disable Clamping</li> </ol>	0 Normal 1 Reset All Registers to Default	<ol> <li>0 Normal Power</li> <li>0 1 Test Only</li> <li>1 0 Ref-Standby</li> <li>1 Total Power-Down</li> </ol>	<ol> <li>0 Test Only</li> <li>0 Test Only</li> <li>1 Test Only</li> <li>1 Test Only</li> <li>1 Imager Mode</li> </ol>

# Table II. Operation Register Contents (Default Value x000)

NOTES

<sup>1</sup>Must be set to 0.

<sup>2</sup>Set to 1.

D10	MSB D9	<b>D</b> 8	<b>D</b> 7	D6	D5	<b>D</b> 4	D3	D2	D1	LSB D0	Gain (dB)
Х	0	0	0	0	0	0	0	0	0	0	0.0
					٠						•
					٠						•
					•						•
	1	1	1	1	1	1	1	1	1	0	35.965
	1	1	1	1	1	1	1	1	1	1	36.0

# Table III. VGA Gain Register Contents (Default Value x000)

D10	D9	<b>D</b> 8	MSB D7	D6	D5	D4	D3	D2	D1	LSB D0	Clamp Level (LSB)
X	Х	Х	0	0	0	0	0	0	0	0	0
			0	0	0	0	0	0	0	1	1
			0	0	0	0	0	0	1	0	2
						•					•
						•					•
						٠					•
			1	1	1	1	1	1	1	0	254
			1	1	1	1	1	1	1	1	255

# Table IV. Clamp Level Register Contents (Default Value x080)

Table V. Control Register Contents (Default Value x000)

D10	D9	D8	<b>D</b> 7	DATACLK Polarity D6	CLPOB/PBLK Polarity D5	D4	D3	D2	D1	D0
х	0*	0*	0*	<ol> <li>0 Sample on Rising Edge</li> <li>1 Sample on Falling Edge</li> </ol>	0 Active Low 1 Active High	0*	0*	0*	0*	0*

\*Must be set to 0.

#### CIRCUIT DESCRIPTION AND OPERATION

The AD9821 signal processing chain is shown in Figure 10. Each processing step is essential in achieving a high quality image from the raw imager pixel data.

#### **Differential Input SHA**

The differential input SHA circuit is designed to accommodate a variety of different image sensor output voltages. The timing shown in Figure 8 illustrates how the DATACLK signal is used to sample both the VIN+ and VIN– signals simultaneously. The imager signal is sampled on the rising edges of DATACLK. Placement of this clock signal is critical in achieving the best performance from the imager. An internal DATACLK delay ( $t_{ID}$ ) of 3 ns is caused by internal propagation delays.

The differential input can be used in a variety of single-ended and differential configurations, as shown in Table VI. The allowable voltage range for both VIN+ or VIN- is from 0 V to 1.8 V. Signal levels outside this range will result in severely degraded performance. Regardless of the input configuration, the voltage sampled by the SHA is always equal to VIN+ minus VIN-. VIN+ must always be equal to or greater than VIN- or negative clipping will occur. A small amount of offset between the VIN+ and VIN– signals is allowable and can be corrected by the Optical Black Clamp, up to  $\pm 30$  mV.

Note that the VIN+ and VIN– inputs do not contain any dc restoration or bias circuitry. Therefore, dc-coupling is recommended when driving the AD9821 analog inputs. If ac-coupling is used, external biasing circuitry must be provided for the VIN+ and VIN– inputs to keep them in the acceptable common-mode voltage range of 0 V to 1.8 V.

Table VI.	Example Input V	Voltage	Configurations
-----------	-----------------	---------	----------------

	Range (V) White	VIN– Range (V) Black White		SHA Output Range (V) Black White		
Diack	white	Бласк	white	Бласк	white	
0	1.0	0	0	0	1.0	
0.5	1.5	0.5	0.5	0	1.0	
1.0	1.5	1.0	0.5	0	1.0	
0.5	1.0	0.5	0	0	1.0	
1.0	1.0	1.0	0	0	1.0	

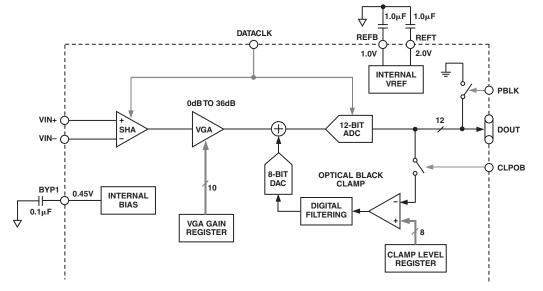


Figure 10. Internal Block Diagram

### Variable Gain Amplifier

The VGA stage provides a gain range of 0 dB to 36 dB, programmable with 10-bit resolution through the serial digital interface. A minimum gain of 6 dB is needed to match a 1 V input signal with the ADC full-scale range of 2 V. When compared to 1 V full-scale systems, the equivalent gain range is -6 dB to +30 dB.

The VGA gain curve follows a "linear-in-dB" characteristic. The exact VGA gain can be calculated for any Gain Register value by using the equation:

$$Gain(dB) = (0.0351 \times Code)$$

where the code range is 0 to 1023.

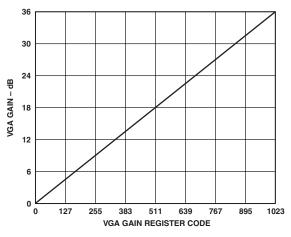


Figure 11. VGA Gain Curve

#### **Optical Black Clamp**

The optical black clamp loop is used to remove residual offsets in the signal chain, and to track low frequency variations in the CCD's black level. During the optical black (shielded) pixel interval on each line, the ADC output is compared with a fixed black level reference selected by the user in the Clamp Level Register. Any value between 0 LSB and 255 LSB may be programmed using the 8-bit Clamp Level Register. The resulting error signal is filtered to reduce noise, and the correction value is applied to the ADC input through a D/A converter. Normally, the optical black clamp loop is turned on once per horizontal line, but this loop can be updated more slowly to suit a particular application. If external digital clamping is used during the postprocessing, the AD9821 optical black clamping may be disabled using Bit D5 in the Operation Register (see Internal Register Map and Serial Interface Timing section). When the loop is disabled, the Clamp Level Register may still be used to provide programmable offset adjustment.

Horizontal timing is shown in Figure 9. The CLPOB pulse should be placed during the CCD's optical black pixels. It is recommended that the CLPOB pulse duration be at least 20 pixels wide. Shorter pulsewidths may be used, but the ability to track low frequency variations in the black level will be reduced.

As discussed in the Differential Input SHA section, the CLPOB loop is capable of correcting for an offset difference between the VIN+ and VIN– inputs. Because the clamp is located after the VGA gain stage, the clamp will be most limited when the VGA gain is at its maximum value. Under these conditions, the OB clamp loop correction range is restricted to  $\pm 30$  mV offset between the VIN+ and VIN– inputs. At minimum VGA gain, the offset correction range increases to  $\pm 250$  mV of offset. If the OB clamp loop's correction range is exceeded, then the black level at the output of the AD9821 will increase and further correction will be necessary. As mentioned previously, it is also possible to disable the AD9821's OB clamp loop.

## A/D Converter (ADC)

The AD9821 uses high performance ADC architecture, optimized for high speed and low power. Differential nonlinearity (DNL) performance is typically better than 0.5 LSB, as shown in TPC 2. Instead of the 1 V full-scale range used by the earlier AD9801 and AD9803 products from Analog Devices, the AD9821's ADC uses a 2 V input range. Better noise performance results from using a larger ADC full-scale range (see TPC 3).

#### **APPLICATIONS INFORMATION**

The AD9821 is a complete Analog Front End (AFE) product for a variety of imager applications using CMOS image sensors and CCDs with on-chip CDS. As shown in Figure 10, the imager output is generally buffered and sent to the AD9821's analog inputs, either as a differential or single-ended signal. The AD9821 performs the sample-and-hold operation, gain adjustment, black level correction, and analog-to-digital conversion. The AD9821's digital output data is then processed by the image processing ASIC. The internal registers of the AD9821—used to control gain, offset level, and other functions—are programmed by the ASIC or microprocessor through a 3-wire serial digital interface. A system timing generator provides the clock signals for both the imager and the AFE.

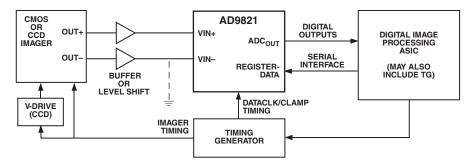


Figure 12. System Applications Diagram

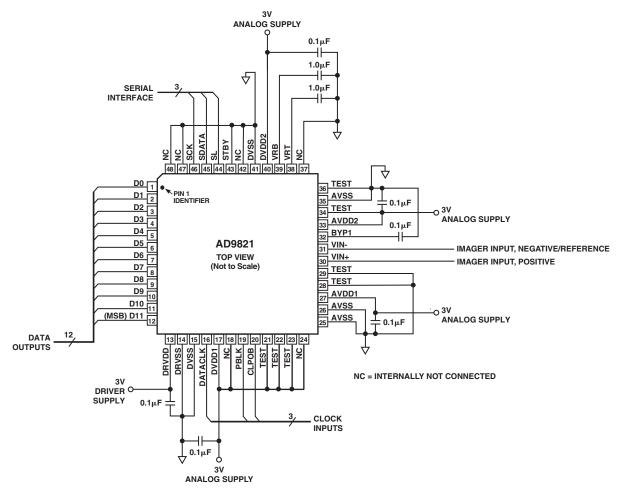


Figure 13. Recommended Circuit Configuration

## Internal Power-On Reset Circuitry

After power-on, the AD9821 will automatically reset all internal registers and perform internal calibration procedures. This takes approximately 1 ms to complete. During this time, normal clock signals and serial write operations may occur. However, serial register writes will be ignored until the internal reset operation is completed.

#### Grounding and Decoupling Recommendations

As shown in Figure 13, a single ground plane is recommended for the AD9821. This ground plane should be as continuous as possible, particularly around Pins 25 through 39. This will ensure that all analog decoupling capacitors provide the lowest possible impedance path between the power and bypass pins and their respective ground pins. All decoupling capacitors should be located as close as possible to the package pins. A single clean power supply is recommended for the AD9821, but a separate digital driver supply may be used for DRVDD (Pin 13). DRVDD should always be decoupled to DRVSS (Pin 14), which should be connected to the analog ground plane. Advantages of using a separate digital driver supply include using a lower voltage (2.7 V) to match levels with a 2.7 V ASIC, reducing digital power dissipation, and reducing potential noise coupling. If the digital outputs (Pins 1–12) must drive a load larger than 20 pF, buffering is recommended to reduce digital code transition noise. Alternatively, placing series resistors close to the digital output pins may also help reduce noise.

### **OUTLINE DIMENSIONS**

#### 48-Lead Plastic Quad Flatpack [LQFP] 1.4 mm Thick

(ST-48)

Dimensions shown in millimeters

