



# TC7106/A/TC7107/A

## 3-1/2 Digit Analog-to-Digital Converters

### Features

- Internal Reference with Low Temperature Drift
  - TC7106/7: 80ppm/°C Typical
  - TC7106A/7A: 20ppm/°C Typical
- Drives LCD (TC7106) or LED (TC7107) Display Directly
- Zero Reading with Zero Input
- Low Noise for Stable Display
- Auto-Zero Cycle Eliminates Need for Zero Adjustment
- True Polarity Indication for Precision Null Applications
- Convenient 9V Battery Operation (TC7106A)
- High Impedance CMOS Differential Inputs:  $10^{12}\Omega$
- Differential Reference Inputs Simplify Ratiometric Measurements
- Low Power Operation: 10mW

### Applications

- Thermometry
- Bridge Readouts: Strain Gauges, Load Cells, Null Detectors
- Digital Meters: Voltage/Current/Ohms/Power, pH
- Digital Scales, Process Monitors
- Portable Instrumentation

### Device Selection Table

Package Code	Package	Pin Layout	Temperature Range
CPI	40-Pin PDIP	Normal	0°C to +70°C
IPL	40-Pin PDIP	Normal	-25°C to +85°C
IJL	40-Pin CERDIP	Normal	-25°C to +85°C
CKW	44-Pin PQFP	Formed Leads	0°C to +70°C
CLW	44-Pin PLCC	—	0°C to +70°C

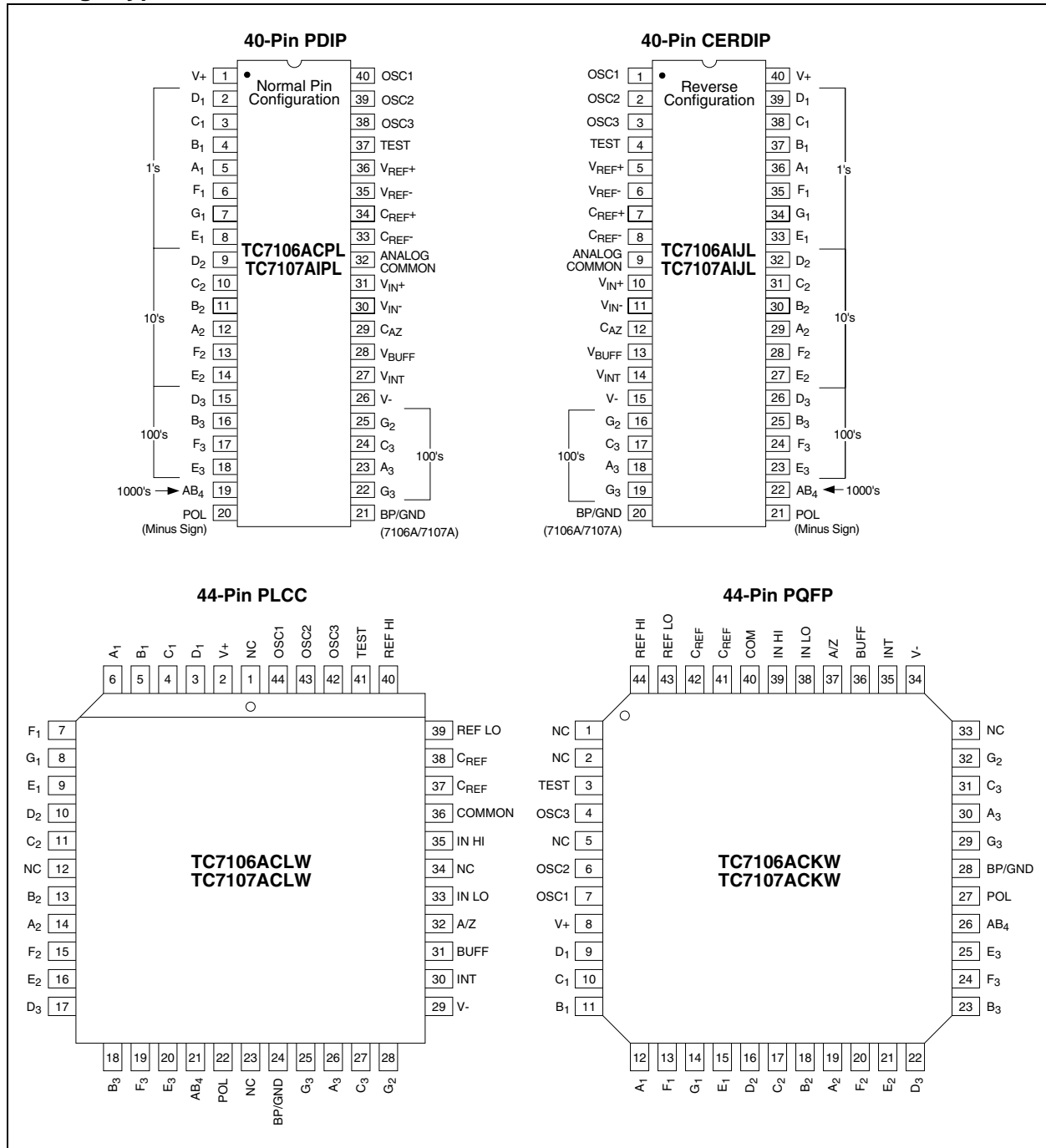
### General Description

The TC7106A and TC7107A 3-1/2 digit direct display drive analog-to-digital converters allow existing 7106/7107 based systems to be upgraded. Each device has a precision reference with a 20ppm/°C max temperature coefficient. This represents a 4 to 7 times improvement over similar 3-1/2 digit converters. Existing 7106 and 7107 based systems may be upgraded without changing external passive component values. The TC7107A drives common anode light emitting diode (LED) displays directly with 8mA per segment. A low cost, high resolution indicating meter requires only a display, four resistors, and four capacitors. The TC7106A low power drain and 9V battery operation make it suitable for portable applications.

The TC7106A/TC7107A reduces linearity error to less than 1 count. Rollover error – the difference in readings for equal magnitude, but opposite polarity input signals, is below  $\pm 1$  count. High impedance differential inputs offer 1pA leakage current and a  $10^{12}\Omega$  input impedance. The differential reference input allows ratiometric measurements for ohms or bridge transducer measurements. The  $15\mu V_{P-P}$  noise performance ensures a “rock solid” reading. The auto-zero cycle ensures a zero display reading with a zero volts input.

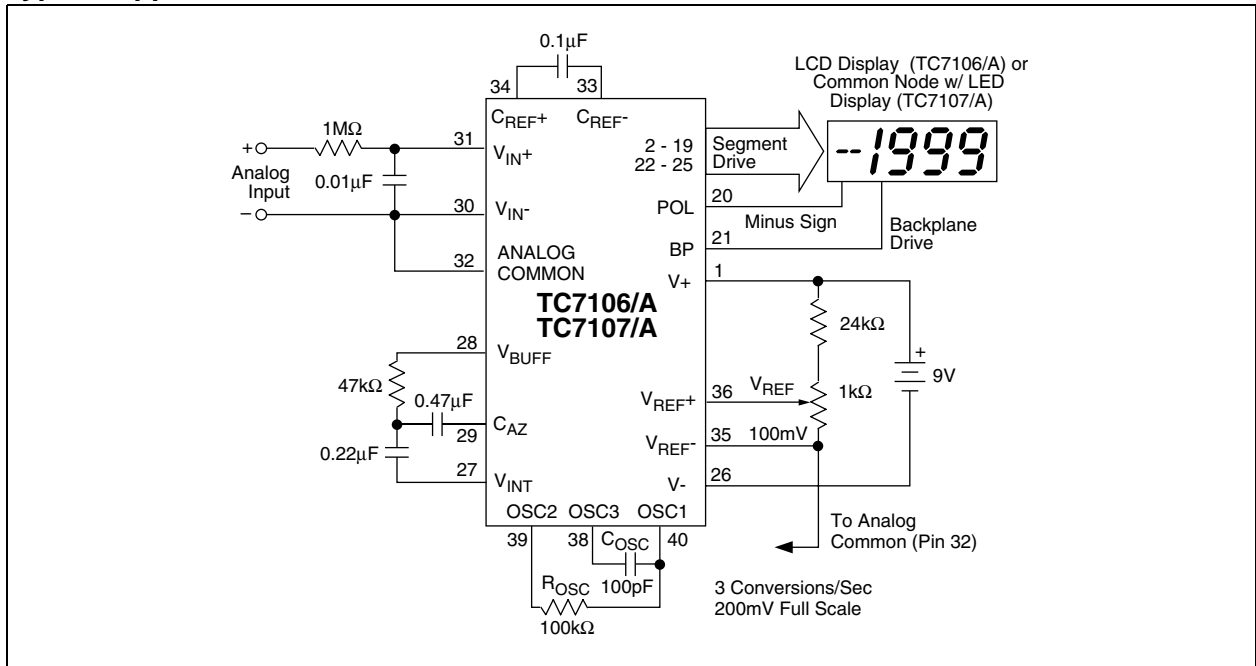
# TC7106/A/TC7107/A

## Package Type



# TC7106/A/TC7107/A

## Typical Application



# TC7106/A/TC7107/A

## 1.0 ELECTRICAL CHARACTERISTICS

### Absolute Maximum Ratings\*

#### TC7106A

Supply Voltage (V+ to V-) ..... 15V  
 Analog Input Voltage (either Input) (**Note 1**) ... V+ to V-  
 Reference Input Voltage (either Input) ..... V+ to V-  
 Clock Input ..... Test to V+

Package Power Dissipation ( $T_A \leq 70^\circ\text{C}$ ) (**Note 2**):  
 40-Pin CERDIP ..... 2.29W  
 40-Pin PDIP ..... 1.23W  
 44-Pin PLCC ..... 1.23W  
 44-Pin PQFP ..... 1.00W

Operating Temperature Range:  
 C (Commercial) Devices .....  $0^\circ\text{C}$  to  $+70^\circ\text{C}$   
 I (Industrial) Devices .....  $-25^\circ\text{C}$  to  $+85^\circ\text{C}$

Storage Temperature Range .....  $-65^\circ\text{C}$  to  $+150^\circ\text{C}$

#### TC7107A

Supply Voltage (V+) ..... +6V  
 Supply Voltage (V-) ..... -9V  
 Analog Input Voltage (either Input) (**Note 1**) ... V+ to V-  
 Reference Input Voltage (either Input) ..... V+ to V-  
 Clock Input ..... GND to V+

Package Power Dissipation ( $T_A \leq 70^\circ\text{C}$ ) (**Note 2**):  
 40-Pin CERDip ..... 2.29W  
 40-Pin PDIP ..... 1.23W  
 44-Pin PLCC ..... 1.23W  
 44-Pin PQFP ..... 1.00W

Operating Temperature Range:  
 C (Commercial) Devices .....  $0^\circ\text{C}$  to  $+70^\circ\text{C}$   
 I (Industrial) Devices .....  $-25^\circ\text{C}$  to  $+85^\circ\text{C}$

Storage Temperature Range .....  $-65^\circ\text{C}$  to  $+150^\circ\text{C}$

\*Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions above those indicated in the operation sections of the specifications is not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability.

### TC7106/A AND TC7107/A ELECTRICAL SPECIFICATIONS

**Electrical Characteristics:** Unless otherwise noted, specifications apply to both the TC7106/A and TC7107/A at  $T_A = 25^\circ\text{C}$ ,  $f_{\text{CLOCK}} = 48\text{kHz}$ . Parts are tested in the circuit of the Typical Operating Circuit.

Symbol	Parameter	Min	Typ	Max	Unit	Test Conditions
$Z_{\text{IR}}$	Zero Input Reading	-000.0	$\pm 000.0$	+000.0	Digital Reading	$V_{\text{IN}} = 0.0\text{V}$ Full Scale = 200.0mV
	Ratiometric Reading	999	999/1000	1000	Digital Reading	$V_{\text{IN}} = V_{\text{REF}}$ $V_{\text{REF}} = 100\text{mV}$
R/O	Rollover Error (Difference in Reading for Equal Positive and Negative Reading Near Full Scale)	-1	$\pm 0.2$	+1	Counts	$V_{\text{IN}^-} = + V_{\text{IN}^+} \pm 200\text{mV}$
	Linearity (Max. Deviation from Best Straight Line Fit)	-1	$\pm 0.2$	+1	Counts	Full Scale = 200mV or Full Scale = 2.000V

- Note 1:** Input voltages may exceed the supply voltages, provided the input current is limited to  $\pm 100\mu\text{A}$ .  
**Note 2:** Dissipation rating assumes device is mounted with all leads soldered to printed circuit board.  
**Note 3:** Refer to "Differential Input" discussion.  
**Note 4:** Backplane drive is in phase with segment drive for "OFF" segment,  $180^\circ$  out of phase for "ON" segment. Frequency is 20 times conversion rate. Average DC component is less than 50mV.

# TC7106/A/TC7107/A

## TC7106/A AND TC7107/A ELECTRICAL SPECIFICATIONS (CONTINUED)

**Electrical Characteristics:** Unless otherwise noted, specifications apply to both the TC7106/A and TC7107/A at  $T_A = 25^\circ\text{C}$ ,  $f_{\text{CLOCK}} = 48\text{kHz}$ . Parts are tested in the circuit of the Typical Operating Circuit.

Symbol	Parameter	Min	Typ	Max	Unit	Test Conditions
CMRR	Common Mode Rejection Ratio ( <b>Note 3</b> )	—	50	—	$\mu\text{V}/\text{V}$	$V_{\text{CM}} = \pm 1\text{V}$ , $V_{\text{IN}} = 0\text{V}$ , Full Scale = 200.0mV
$e_{\text{N}}$	Noise (Peak to Peak Value not Exceeded 95% of Time)	—	15	—	$\mu\text{V}$	$V_{\text{IN}} = 0\text{V}$ Full Scale - 200.0mV
$I_{\text{L}}$	Leakage Current at Input	—	1	10	$\mu\text{A}$	$V_{\text{IN}} = 0\text{V}$
	Zero Reading Drift	—	0.2	1	$\mu\text{V}/^\circ\text{C}$	$V_{\text{IN}} = 0\text{V}$ "C" Device = $0^\circ\text{C}$ to $+70^\circ\text{C}$
		—	1.0	2	$\mu\text{V}/^\circ\text{C}$	$V_{\text{IN}} = 0\text{V}$ "I" Device = $-25^\circ\text{C}$ to $+85^\circ\text{C}$
TC <sub>SF</sub>	Scale Factor Temperature Coefficient	—	1	5	ppm/ $^\circ\text{C}$	$V_{\text{IN}} = 199.0\text{mV}$ , "C" Device = $0^\circ\text{C}$ to $+70^\circ\text{C}$ (Ext. Ref = 0ppm/ $^\circ\text{C}$ )
		—	—	20	ppm/ $^\circ\text{C}$	$V_{\text{IN}} = 199.0\text{mV}$ "I" Device = $-25^\circ\text{C}$ to $+85^\circ\text{C}$
$I_{\text{DD}}$	Supply Current (Does not include LED Current For TC7107/A)	—	0.8	1.8	mA	$V_{\text{IN}} = 0.8$
$V_{\text{C}}$	Analog Common Voltage (with Respect to Positive Supply)	2.7	3.05	3.35	V	25k $\Omega$ Between Common and Positive Supply
$V_{\text{CTC}}$	Temperature Coefficient of Analog Common (with Respect to Positive Supply)	—	—	—	—	25k $\Omega$ Between Common and Positive Supply
		7106/7/A 7106/7	20 80	50 —	ppm/ $^\circ\text{C}$ ppm/ $^\circ\text{C}$	$0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ ("C" Commercial Temperature Range Devices)
$V_{\text{CTC}}$	Temperature Coefficient of Analog Common (with Respect to Positive Supply)	—	—	75	ppm/ $^\circ\text{C}$	$0^\circ\text{C} \leq T_A \leq +70^\circ\text{C}$ ("I" Industrial Temperature Range Devices)
$V_{\text{SD}}$	TC7106A ONLY Peak to Peak Segment Drive Voltage	4	5	6	V	$V_+$ to $V_- = 9\text{V}$ <b>(Note 4)</b>
$V_{\text{BD}}$	TC7106A ONLY Peak to Peak Backplane Drive Voltage	4	5	6	V	$V_+$ to $V_- = 9\text{V}$ <b>(Note 4)</b>
	TC7107A ONLY Segment Sinking Current (Except Pin 19)	5	8.0	—	mA	$V_+ = 5.0\text{V}$ Segment Voltage = 3V
	TC7107A ONLY Segment Sinking Current (Pin 19)	10	16	—	mA	$V_+ = 5.0\text{V}$ Segment Voltage = 3V

- Note**
- 1: Input voltages may exceed the supply voltages, provided the input current is limited to  $\pm 100\mu\text{A}$ .
  - 2: Dissipation rating assumes device is mounted with all leads soldered to printed circuit board.
  - 3: Refer to "Differential Input" discussion.
  - 4: Backplane drive is in phase with segment drive for "OFF" segment,  $180^\circ$  out of phase for "ON" segment. Frequency is 20 times conversion rate. Average DC component is less than 50mV.

# TC7106/A/TC7107/A

## 2.0 PIN DESCRIPTIONS

The descriptions of the pins are listed in Table 2-1.

**TABLE 2-1: PIN FUNCTION TABLE**

Pin Number (40-Pin PDIP) Normal	Pin No. (40-Pin PDIP) (Reversed)	Symbol	Description
1	(40)	V+	Positive supply voltage.
2	(39)	D <sub>1</sub>	Activates the D section of the units display.
3	(38)	C <sub>1</sub>	Activates the C section of the units display.
4	(37)	B <sub>1</sub>	Activates the B section of the units display.
5	(36)	A <sub>1</sub>	Activates the A section of the units display.
6	(35)	F <sub>1</sub>	Activates the F section of the units display.
7	(34)	G <sub>1</sub>	Activates the G section of the units display.
8	(33)	E <sub>1</sub>	Activates the E section of the units display.
9	(32)	D <sub>2</sub>	Activates the D section of the tens display.
10	(31)	C <sub>2</sub>	Activates the C section of the tens display.
11	(30)	B <sub>2</sub>	Activates the B section of the tens display.
12	(29)	A <sub>2</sub>	Activates the A section of the tens display.
13	(28)	F <sub>2</sub>	Activates the F section of the tens display.
14	(27)	E <sub>2</sub>	Activates the E section of the tens display.
15	(26)	D <sub>3</sub>	Activates the D section of the hundreds display.
16	(25)	B <sub>3</sub>	Activates the B section of the hundreds display.
17	(24)	F <sub>3</sub>	Activates the F section of the hundreds display.
18	(23)	E <sub>3</sub>	Activates the E section of the hundreds display.
19	(22)	AB <sub>4</sub>	Activates both halves of the 1 in the thousands display.
20	(21)	POL	Activates the negative polarity display.
21	(20)	BP/GND	LCD Backplane drive output (TC7106A). Digital Ground (TC7107A).
22	(19)	G <sub>3</sub>	Activates the G section of the hundreds display.
23	(18)	A <sub>3</sub>	Activates the A section of the hundreds display.
24	(17)	C <sub>3</sub>	Activates the C section of the hundreds display.
25	(16)	G <sub>2</sub>	Activates the G section of the tens display.
26	(15)	V-	Negative power supply voltage.
27	(14)	V <sub>INT</sub>	Integrator output. Connection point for integration capacitor. See INTEGRATING CAPACITOR section for more details.
28	(13)	V <sub>BUFF</sub>	Integration resistor connection. Use a 47kΩ resistor for a 200mV full scale range and a 47kΩ resistor for 2V full scale range.
29	(12)	C <sub>AZ</sub>	The size of the auto-zero capacitor influences system noise. Use a 0.47μF capacitor for 200mV full scale, and a 0.047μF capacitor for 2V full scale. See Section 7.1 on Auto-Zero Capacitor for more details.
30	(11)	V <sub>IN-</sub>	The analog LOW input is connected to this pin.
31	(10)	V <sub>IN+</sub>	The analog HIGH input signal is connected to this pin.
32	(9)	ANALOG COMMON	This pin is primarily used to set the Analog Common mode voltage for battery operation or in systems where the input signal is referenced to the power supply. It also acts as a reference voltage source. See Section 8.3 on ANALOG COMMON for more details.
33	(8)	C <sub>REF-</sub>	See Pin 34.
34	(7)	C <sub>REF+</sub>	A 0.1μF capacitor is used in most applications. If a large Common mode voltage exists (for example, the V <sub>IN-</sub> pin is not at analog common), and a 200mV scale is used, a 1μF capacitor is recommended and will hold the rollover error to 0.5 count.
35	(6)	V <sub>REF-</sub>	See Pin 36.

# TC7106/A/TC7107/A

**TABLE 2-1: PIN FUNCTION TABLE (CONTINUED)**

Pin Number (40-Pin PDIP) Normal	Pin No. (40-Pin PDIP) (Reversed)	Symbol	Description
36	(5)	V <sub>REF+</sub>	The analog input required to generate a full scale output (1999 counts). Place 100mV between Pins 35 and 36 for 199.9mV full scale. Place 1V between Pins 35 and 36 for 2V full scale. See paragraph on Reference Voltage.
37	(4)	TEST	Lamp test. When pulled HIGH (to V+) all segments will be turned on and the display should read -1888. It may also be used as a negative supply for externally generated decimal points. See paragraph under TEST for additional information.
38	(3)	OSC3	See Pin 40.
39	(2)	OSC2	See Pin 40.
40	(1)	OSC1	Pins 40, 39, 38 make up the oscillator section. For a 48kHz clock (3 readings per section), connect Pin 40 to the junction of a 100kΩ resistor and a 100pF capacitor. The 100kΩ resistor is tied to Pin 39 and the 100pF capacitor is tied to Pin 38.

# TC7106/A/TC7107/A

## 3.0 DETAILED DESCRIPTION

(All Pin designations refer to 40-Pin PDIP.)

### 3.1 Dual Slope Conversion Principles

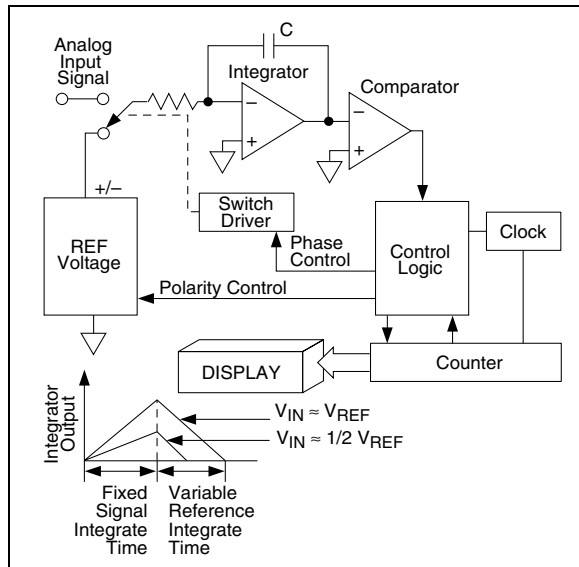
The TC7106A and TC7107A are dual slope, integrating analog-to-digital converters. An understanding of the dual slope conversion technique will aid in following the detailed operation theory.

The conventional dual slope converter measurement cycle has two distinct phases:

- Input Signal Integration
- Reference Voltage Integration (De-integration)

The input signal being converted is integrated for a fixed time period ( $T_{SI}$ ). Time is measured by counting clock pulses. An opposite polarity constant reference voltage is then integrated until the integrator output voltage returns to zero. The reference integration time is directly proportional to the input signal ( $T_{RI}$ ). See Figure 3-1.

**FIGURE 3-1: BASIC DUAL SLOPE CONVERTER**



In a simple dual slope converter, a complete conversion requires the integrator output to “ramp-up” and “ramp-down.” A simple mathematical equation relates the input signal, reference voltage and integration time.

**EQUATION 3-1:**

$$\frac{1}{RC} \int_0^{T_{SI}} V_{IN}(t) dt = \frac{V_R T_{RI}}{RC}$$

Where:

- $V_R$  = Reference voltage
- $T_{SI}$  = Signal integration time (fixed)
- $T_{RI}$  = Reference voltage integration time (variable).

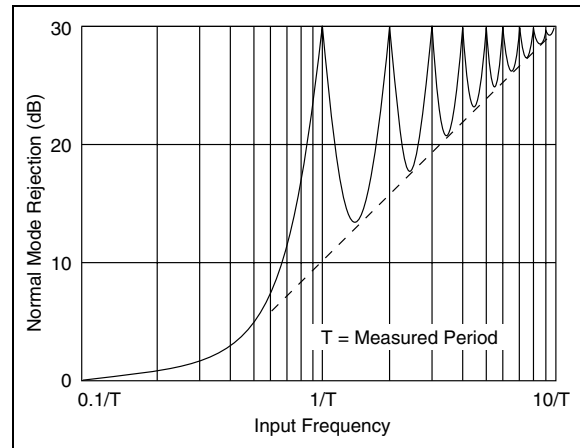
For a constant  $V_{IN}$ :

**EQUATION 3-2:**

$$V_{IN} = V_R \frac{T_{RI}}{T_{SI}}$$

The dual slope converter accuracy is unrelated to the integrating resistor and capacitor values as long as they are stable during a measurement cycle. An inherent benefit is noise immunity. Noise spikes are integrated or averaged to zero during the integration periods. Integrating ADCs are immune to the large conversion errors that plague successive approximation converters in high noise environments. Interfering signals with frequency components at multiples of the averaging period will be attenuated. Integrating ADCs commonly operate with the signal integration period set to a multiple of the 50/60Hz power line period (see Figure 3-2).

**FIGURE 3-2: NORMAL MODE REJECTION OF DUAL SLOPE CONVERTER**





## 4.0 ANALOG SECTION

In addition to the basic signal integrate and de-integrate cycles discussed, the circuit incorporates an auto-zero cycle. This cycle removes buffer amplifier, integrator, and comparator offset voltage error terms from the conversion. A true digital zero reading results without adjusting external potentiometers. A complete conversion consists of three cycles: an auto-zero, signal integrate and reference integrate cycle.

### 4.1 Auto-Zero Cycle

During the auto-zero cycle, the differential input signal is disconnected from the circuit by opening internal analog gates. The internal nodes are shorted to analog common (ground) to establish a zero input condition. Additional analog gates close a feedback loop around the integrator and comparator. This loop permits comparator offset voltage error compensation. The voltage level established on  $C_{AZ}$  compensates for device offset voltages. The offset error referred to the input is less than  $10\mu V$ .

The auto-zero cycle length is 1000 to 3000 counts.

### 4.2 Signal Integrate Cycle

The auto-zero loop is entered and the internal differential inputs connect to  $V_{IN+}$  and  $V_{IN-}$ . The differential input signal is integrated for a fixed time period. The TC7136/A signal integration period is 1000 clock periods or counts. The externally set clock frequency is divided by four before clocking the internal counters.

The integration time period is:

#### EQUATION 4-1:

$$T_{SI} = \frac{4}{F_{OSC}} \times 1000$$

Where:  $F_{OSC}$  = external clock frequency.

The differential input voltage must be within the device Common mode range when the converter and measured system share the same power supply common (ground). If the converter and measured system do not share the same power supply common,  $V_{IN-}$  should be tied to analog common.

Polarity is determined at the end of signal integrate phase. The sign bit is a true polarity indication, in that signals less than 1LSB are correctly determined. This allows precision null detection limited only by device noise and auto-zero residual offsets.

### 4.3 Reference Integrate Phase

The third phase is reference integrate or de-integrate.  $V_{IN-}$  is internally connected to analog common and  $V_{IN+}$  is connected across the previously charged reference capacitor. Circuitry within the chip ensures that the capacitor will be connected with the correct polarity to cause the integrator output to return to zero.

The time required for the output to return to zero is proportional to the input signal and is between 0 and 2000 counts.

The digital reading displayed is:

#### EQUATION 4-2:

$$1000 = \frac{V_{IN}}{V_{REF}}$$

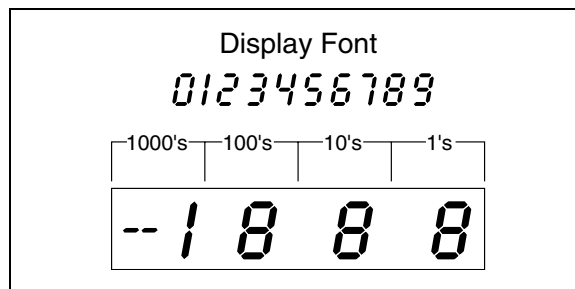
## 5.0 DIGITAL SECTION (TC7106A)

The TC7106A (Figure 5-2) contains all the segment drivers necessary to directly drive a 3-1/2 digit liquid crystal display (LCD). An LCD backplane driver is included. The backplane frequency is the external clock frequency divided by 800. For three conversions/second, the backplane frequency is 60Hz with a 5V nominal amplitude. When a segment driver is in phase with the backplane signal, the segment is "OFF." An out of phase segment drive signal causes the segment to be "ON" or visible. This AC drive configuration results in negligible DC voltage across each LCD segment. This insures long LCD display life. The polarity segment driver is "ON" for negative analog inputs. If  $V_{IN+}$  and  $V_{IN-}$  are reversed, this indicator will reverse.

When the TEST pin on the TC7106A is pulled to  $V+$ , all segments are turned "ON." The display reads -1888. During this mode, the LCD segments have a constant DC voltage impressed. DO NOT LEAVE THE DISPLAY IN THIS MODE FOR MORE THAN SEVERAL MINUTES! LCD displays may be destroyed if operated with DC levels for extended periods.

The display font and the segment drive assignment are shown in Figure 5-1.

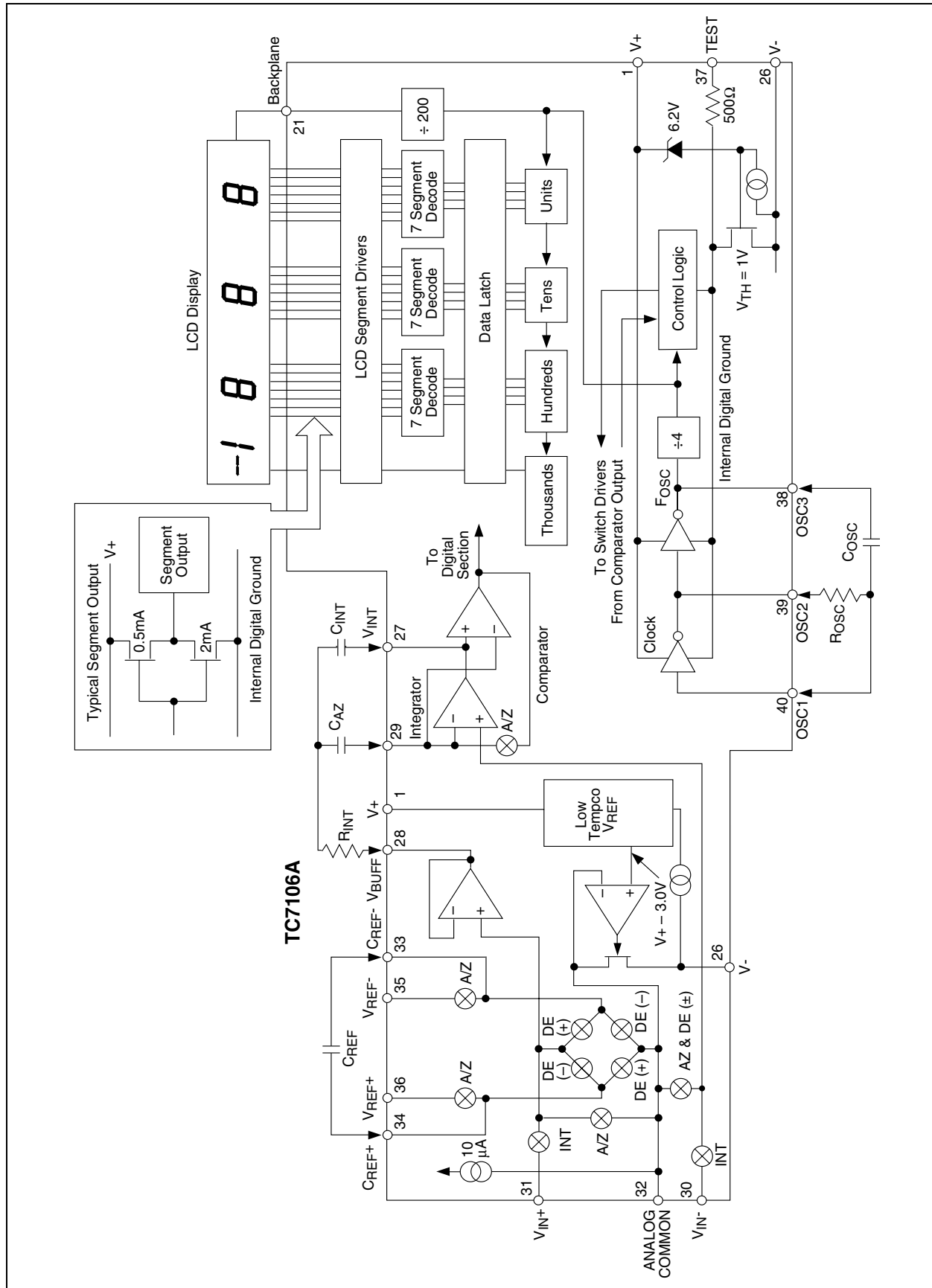
**FIGURE 5-1: DISPLAY FONT AND SEGMENT ASSIGNMENT**



In the TC7106A, an internal digital ground is generated from a 6-volt zener diode and a large P channel source follower. This supply is made stiff to absorb the large capacitive currents when the backplane voltage is switched.

# TC7106/A/TC7107/A

FIGURE 5-2: TC7106A BLOCK DIAGRAM



## 6.0 DIGITAL SECTION (TC7107A)

Figure 6-2 shows a TC7107A block diagram. It is designed to drive common anode LEDs. It is identical to the TC7106A, except that the regulated supply and backplane drive have been eliminated and the segment drive is typically 8mA. The 1000's output (Pin 19) sinks current from two LED segments, and has a 16mA drive capability.

In both devices, the polarity indication is "ON" for negative analog inputs. If  $V_{IN-}$  and  $V_{IN+}$  are reversed, this indication can be reversed also, if desired.

The display font is the same as the TC7106A.

## 6.1 System Timing

The oscillator frequency is divided by 4 prior to clocking the internal decade counters. The four-phase measurement cycle takes a total of 4000 counts, or 16,000 clock pulses. The 4000-count cycle is independent of input signal magnitude.

Each phase of the measurement cycle has the following length:

1. Auto-zero phase: 1000 to 3000 counts (4000 to 12000 clock pulses).

For signals less than full scale, the auto-zero phase is assigned the unused reference integrate time period:

2. Signal integrate: 1000 counts (4000 clock pulses).

This time period is fixed. The integration period is:

### EQUATION 6-1:

$$T_{SI} = 4000 \left( \frac{1}{F_{OSC}} \right)$$

Where:  $F_{OSC}$  is the externally set clock frequency.

3. Reference Integrate: 0 to 2000 counts (0 to 8000 clock pulses).

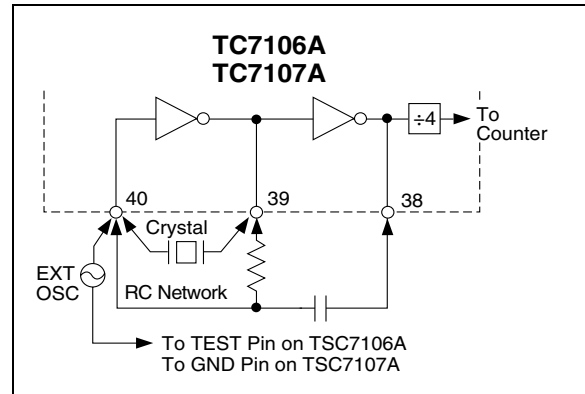
The TC7106A/7107A are drop-in replacements for the 7106/7107 parts. External component value changes are not required to benefit from the low drift internal reference.

## 6.2 Clock Circuit

Three clocking methods may be used (see Figure 6-1):

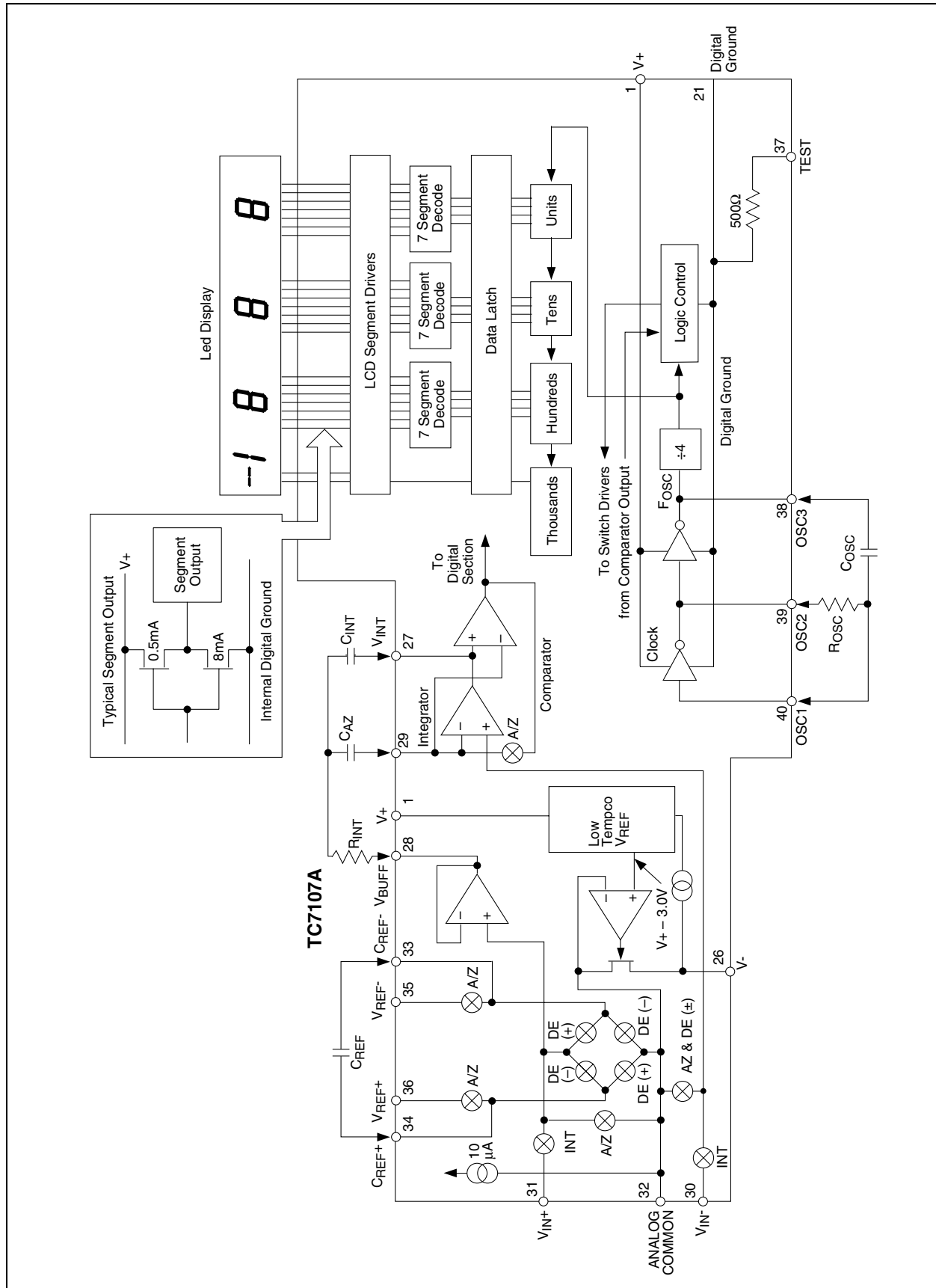
1. An external oscillator connected to Pin 40.
2. A crystal between Pins 39 and 40.
3. An RC oscillator using all three pins.

FIGURE 6-1: CLOCK CIRCUITS



# TC7106/A/TC7107/A

FIGURE 6-2: TC7107A BLOCK DIAGRAM



## 7.0 COMPONENT VALUE SELECTION

### 7.1 Auto-Zero Capacitor ( $C_{AZ}$ )

The  $C_{AZ}$  capacitor size has some influence on system noise. A  $0.47\mu\text{F}$  capacitor is recommended for 200mV full scale applications where 1LSB is  $100\mu\text{V}$ . A  $0.047\mu\text{F}$  capacitor is adequate for 2.0V full scale applications. A mylar type dielectric capacitor is adequate.

### 7.2 Reference Voltage Capacitor ( $C_{REF}$ )

The reference voltage used to ramp the integrator output voltage back to zero during the reference integrate cycle is stored on  $C_{REF}$ . A  $0.1\mu\text{F}$  capacitor is acceptable when  $V_{IN-}$  is tied to analog common. If a large Common mode voltage exists ( $V_{REF-}$  – analog common) and the application requires 200mV full scale, increase  $C_{REF}$  to  $1.0\mu\text{F}$ . Rollover error will be held to less than 1/2 count. A mylar dielectric capacitor is adequate.

### 7.3 Integrating Capacitor ( $C_{INT}$ )

$C_{INT}$  should be selected to maximize the integrator output voltage swing without causing output saturation. Due to the TC7106A/7107A superior temperature coefficient specification, analog common will normally supply the differential voltage reference. For this case, a  $\pm 2\text{V}$  full scale integrator output swing is satisfactory. For 3 readings/second ( $F_{OSC} = 48\text{kHz}$ ), a  $0.22\mu\text{F}$  value is suggested. If a different oscillator frequency is used,  $C_{INT}$  must be changed in inverse proportion to maintain the nominal  $\pm 2\text{V}$  integrator swing.

An exact expression for  $C_{INT}$  is:

#### EQUATION 7-1:

$$C_{INT} = \frac{(4000) \left( \frac{1}{F_{OSC}} \right) \left( \frac{V_{FS}}{R_{INT}} \right)}{V_{INT}}$$

Where:

- $F_{OSC}$  = Clock Frequency at Pin 38
- $V_{FS}$  = Full Scale Input Voltage
- $R_{INT}$  = Integrating Resistor
- $V_{INT}$  = Desired Full Scale Integrator Output Swing

$C_{INT}$  must have low dielectric absorption to minimize rollover error. A polypropylene capacitor is recommended.

### 7.4 Integrating Resistor ( $R_{INT}$ )

The input buffer amplifier and integrator are designed with class A output stages. The output stage idling current is  $100\mu\text{A}$ . The integrator and buffer can supply  $20\mu\text{A}$  drive currents with negligible linearity errors.  $R_{INT}$  is chosen to remain in the output stage linear drive region, but not so large that printed circuit board leakage currents induce errors. For a 200mV full scale,  $R_{INT}$  is  $47\text{k}\Omega$ . 2.0V full scale requires  $470\text{k}\Omega$ .

Component Value	Nominal Full Scale Voltage	
	200.0mV	2.000V
$C_{AZ}$	$0.47\mu\text{F}$	$0.047\mu\text{F}$
$R_{INT}$	$47\text{k}\Omega$	$470\text{k}\Omega$
$C_{INT}$	$0.22\mu\text{F}$	$0.22\mu\text{F}$

**Note:**  $F_{OSC} = 48\text{kHz}$  (3 readings per sec).

### 7.5 Oscillator Components

$R_{OSC}$  (Pin 40 to Pin 39) should be  $100\text{k}\Omega$ .  $C_{OSC}$  is selected using the equation:

#### EQUATION 7-2:

$$F_{OSC} = \frac{0.45}{RC}$$

For  $F_{OSC}$  of  $48\text{kHz}$ ,  $C_{OSC}$  is  $100\text{pF}$  nominally.

Note that  $F_{OSC}$  is divided by four to generate the TC7106A internal control clock. The backplane drive signal is derived by dividing  $F_{OSC}$  by 800.

To achieve maximum rejection of 60Hz noise pickup, the signal integrate period should be a multiple of 60Hz. Oscillator frequencies of  $240\text{kHz}$ ,  $120\text{kHz}$ ,  $80\text{kHz}$ ,  $60\text{kHz}$ ,  $48\text{kHz}$ ,  $40\text{kHz}$ , etc. should be selected. For 50Hz rejection, oscillator frequencies of  $200\text{kHz}$ ,  $100\text{kHz}$ ,  $66\text{-}2/3\text{kHz}$ ,  $50\text{kHz}$ ,  $40\text{kHz}$ , etc. would be suitable. Note that  $40\text{kHz}$  (2.5 readings/second) will reject both 50Hz and 60Hz.

### 7.6 Reference Voltage Selection

A full scale reading (2000 counts) requires the input signal be twice the reference voltage.

Required Full Scale Voltage*	$V_{REF}$
200.0mV	100.0mV
2.000V	1.000V

\*  $V_{FS} = 2V_{REF}$ .

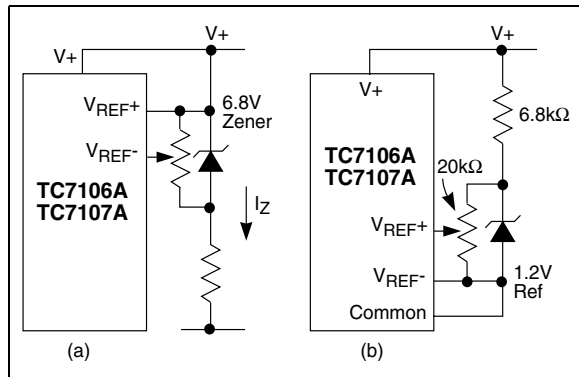
In some applications, a scale factor other than unity may exist between a transducer output voltage and the required digital reading. Assume, for example, a pressure transducer output is  $400\text{mV}$  for  $2000\text{ lb/in}^2$ . Rather than dividing the input voltage by two, the reference voltage should be set to  $200\text{mV}$ . This permits the transducer input to be used directly.

# TC7106A/TC7107A

The differential reference can also be used when a digital zero reading is required when  $V_{IN}$  is not equal to zero. This is common in temperature measuring instrumentation. A compensating offset voltage can be applied between analog common and  $V_{IN-}$ . The transducer output is connected between  $V_{IN+}$  and analog common.

The internal voltage reference potential available at analog common will normally be used to supply the converter's reference. This potential is stable whenever the supply potential is greater than approximately 7V. In applications where an externally generated reference voltage is desired, refer to Figure 7-1.

**FIGURE 7-1: EXTERNAL REFERENCE**



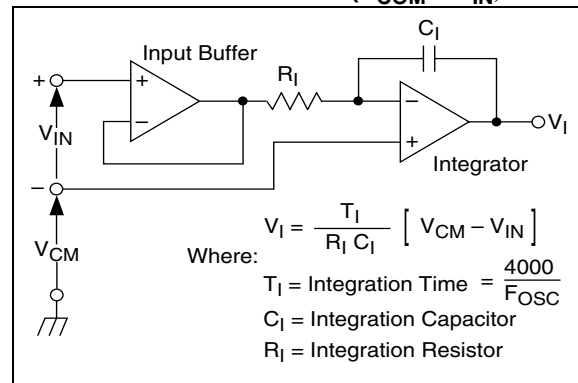
## 8.0 DEVICE PIN FUNCTIONAL DESCRIPTION

### 8.1 Differential Signal Inputs $V_{IN+}$ (Pin 31), $V_{IN-}$ (Pin 30)

The TC7106A/7017A is designed with true differential inputs and accepts input signals within the input stage common mode voltage range ( $V_{CM}$ ). The typical range is  $V+ - 1.0$  to  $V+ + 1V$ . Common mode voltages are removed from the system when the TC7106A/TC7107A operates from a battery or floating power source (isolated from measured system) and  $V_{IN-}$  is connected to analog common ( $V_{COM}$ ) (see Figure 8-2).

In systems where Common mode voltages exist, the 86dB Common mode rejection ratio minimizes error. Common mode voltages do, however, affect the integrator output level. Integrator output saturation must be prevented. A worst case condition exists if a large positive  $V_{CM}$  exists in conjunction with a full scale negative differential signal. The negative signal drives the integrator output positive along with  $V_{CM}$  (see Figure 8-1). For such applications the integrator output swing can be reduced below the recommended 2.0V full scale swing. The integrator output will swing within 0.3V of  $V+$  or  $V-$  without increasing linearity errors.

**FIGURE 8-1: COMMON MODE VOLTAGE REDUCES AVAILABLE INTEGRATOR SWING ( $V_{COM} \neq V_{IN}$ )**



### 8.2 Differential Reference $V_{REF+}$ (Pin 36), $V_{REF-}$ (Pin 35)

The reference voltage can be generated anywhere within the  $V+$  to  $V-$  power supply range.

To prevent rollover type errors being induced by large Common mode voltages,  $C_{REF}$  should be large compared to stray node capacitance.

The TC7106A/TC7107A circuits have a significantly lower analog common temperature coefficient. This gives a very stable voltage suitable for use as a reference. The temperature coefficient of analog common is 20ppm/ $^{\circ}C$  typically.

### 8.3 Analog Common (Pin 32)

The analog common pin is set at a voltage potential approximately 3.0V below  $V+$ . The potential is between 2.7V and 3.35V below  $V+$ . Analog common is tied internally to the N channel FET capable of sinking 20mA. This FET will hold the common line at 3.0V should an external load attempt to pull the common line toward  $V+$ . Analog common source current is limited to 10 $\mu$ A. Analog common is, therefore, easily pulled to a more negative voltage (i.e., below  $V+ - 3.0V$ ).

The TC7106A connects the internal  $V_{IN+}$  and  $V_{IN-}$  inputs to analog common during the auto-zero cycle. During the reference integrate phase,  $V_{IN-}$  is connected to analog common. If  $V_{IN-}$  is not externally connected to analog common, a Common mode voltage exists. This is rejected by the converter's 86dB Common mode rejection ratio. In battery operation, analog common and  $V_{IN-}$  are usually connected, removing Common mode voltage concerns. In systems where  $V-$  is connected to the power supply ground, or to a given voltage, analog common should be connected to  $V_{IN-}$ .



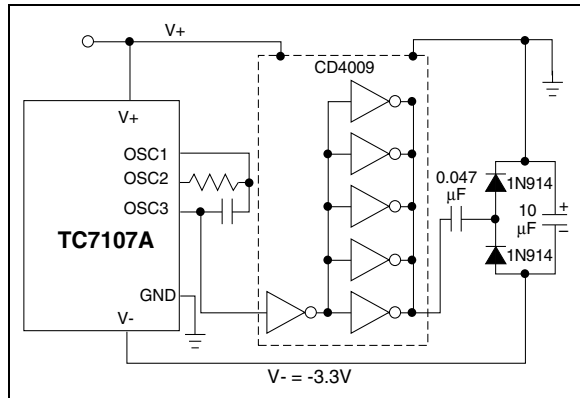


# TC7106/A/TC7107/A

## 9.0 POWER SUPPLIES

The TC7107A is designed to work from  $\pm 5V$  supplies. However, if a negative supply is not available, it can be generated from the clock output with two diodes, two capacitors, and an inexpensive IC (Figure 9-1).

**FIGURE 9-1: GENERATING NEGATIVE SUPPLY FROM +5V**

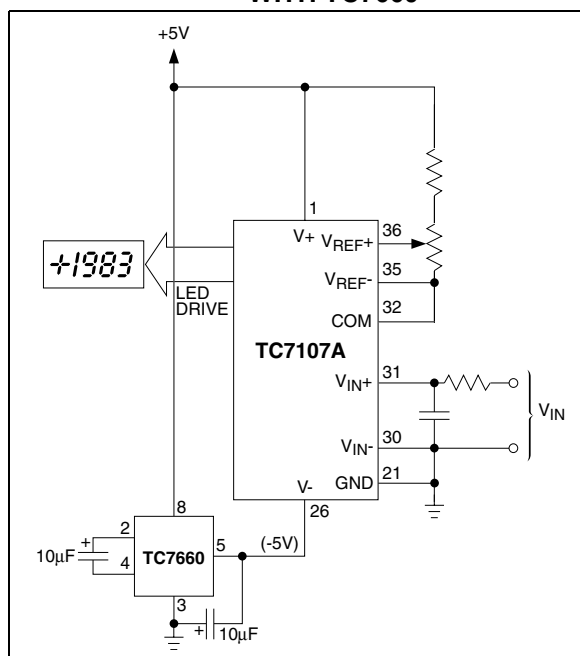


In selected applications a negative supply is not required. The conditions to use a single +5V supply are:

- The input signal can be referenced to the center of the Common mode range of the converter.
- The signal is less than  $\pm 1.5V$ .
- An external reference is used.

The TSC7660 DC to DC converter may be used to generate -5V from +5V (Figure 9-2).

**FIGURE 9-2: NEGATIVE POWER SUPPLY GENERATION WITH TC7660**

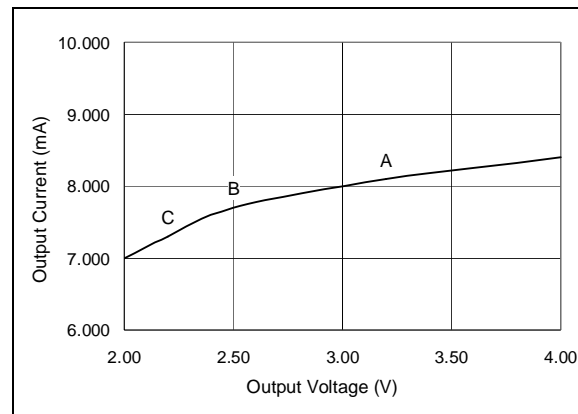


## 9.1 TC7107 Power Dissipation Reduction

The TC7107A sinks the LED display current and this causes heat to build up in the IC package. If the internal voltage reference is used, the changing chip temperature can cause the display to change reading. By reducing the LED common anode voltage, the TC7107A package power dissipation is reduced.

Figure 9-3 is a curve tracer display showing the relationship between output current and output voltage for a typical TC7107CPL. Since a typical LED has 1.8 volts across it at 7mA, and its common anode is connected to +5V, the TC7107A output is at 3.2V (point A on Figure 9-3). Maximum power dissipation is  $8.1mA \times 3.2V \times 24 \text{ segments} = 622mW$ .

**FIGURE 9-3: TC7107 OUTPUT CURRENT VS. OUTPUT VOLTAGE**



Notice, however, that once the TC7107A output voltage is above two volts, the LED current is essentially constant as output voltage increases. Reducing the output voltage by 0.7V (point B in Figure 9-3) results in 7.7mA of LED current, only a 5 percent reduction. Maximum power dissipation is only  $7.7mA \times 2.5V \times 24 = 462mW$ , a reduction of 26%. An output voltage reduction of 1 volt (point C) reduces LED current by 10% (7.3mA) but power dissipation by 38% ( $7.3mA \times 2.2V \times 24 = 385mW$ ).

Reduced power dissipation is very easy to obtain. Figure 9-4 shows two ways: either a 5.1 ohm, 1/4 watt resistor or a 1 Amp diode placed in series with the display (but not in series with the TC7107A). The resistor will reduce the TC7107A output voltage, when all 24 segments are "ON," to point "C" of Figure 9-4. When segments turn off, the output voltage will increase. The diode, on the other hand, will result in a relatively steady output voltage, around point "B."

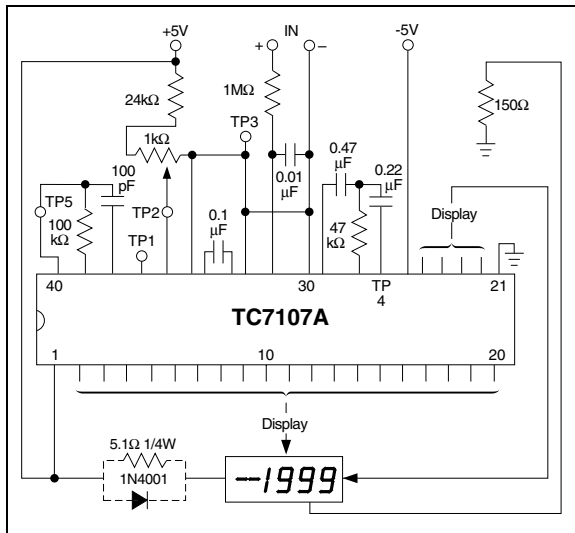
In addition to limiting maximum power dissipation, the resistor reduces the change in power dissipation as the display changes. This effect is caused by the fact that, as fewer segments are "ON," each "ON" output drops more voltage and current. For the best case of six seg-



ments (a "111" display) to worst case (a "1888" display), the resistor will change about 230mW, while a circuit without the resistor will change about 470mW. Therefore, the resistor will reduce the effect of display dissipation on reference voltage drift by about 50%.

The change in LED brightness caused by the resistor is almost unnoticeable as more segments turn off. If display brightness remaining steady is very important to the designer, a diode may be used instead of the resistor.

**FIGURE 9-4: DIODE OR RESISTOR LIMITS PACKAGE POWER DISSIPATION**



## 10.0 TYPICAL APPLICATIONS

### 10.1 Liquid Crystal Display Sources

Several manufacturers supply standard LCDs to interface with the TC7106A 3-1/2 digit analog-to-digital converter.

Manufacturer	Address/Phone	Representative Part Numbers*
Crystaloid Electronics	5282 Hudson Dr. Hudson, OH 44236 216-655-2429	C5335, H5535, T5135, SX440
AND	720 Palomar Ave. Sunnyvale, CA 94086 408-523-8200	FE 0201, 0701 FE 0203, 0701 FE 0501
Epson	3415 Kashikawa st. Torrance, CA 90505 213-534-0360	LD-B709BZ LD-H7992AZ
Hamlin, Inc.	612 E. Lake St. Lake Mills, WI 53551 414-648-236100	3902, 3933, 3903

**Note:** Contact LCD manufacturer for full product listing and specifications.

### 10.2 Light Emitting Diode Display Sources

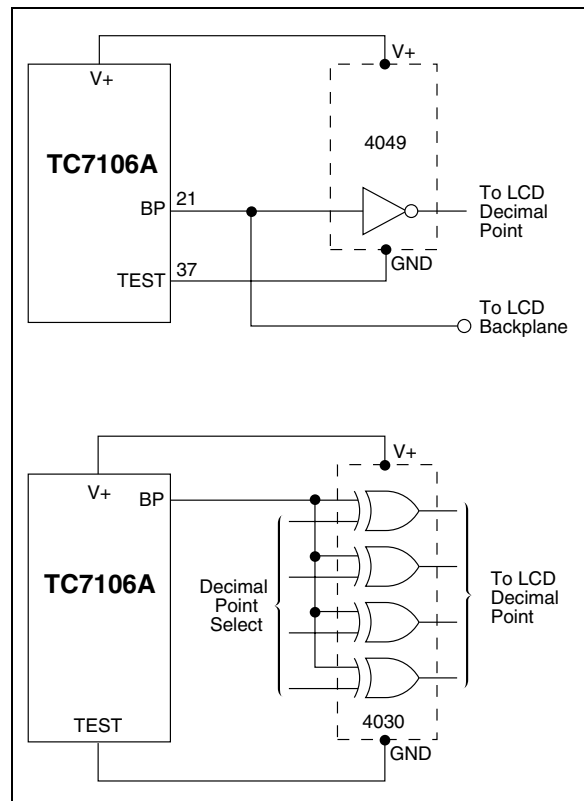
Several LED manufacturers supply seven segment digits with and without decimal point annunciators for the TC7107A.

Manufacturer	Address/Phone	Display
Hewlett-Packard Components	640 Page Mill Rd. Palo Alto, CA 94304	LED
AND	720 Palomar Ave. Sunnyvale, CA 94086 408-523-8200	LED

### 10.3 Decimal Point and Annunciator Drive

The TEST pin is connected to the internally generated digital logic supply ground through a 500Ω resistor. The TEST pin may be used as the negative supply for external CMOS gate segment drivers. LCD display annunciators for decimal points, low battery indication, or function indication may be added without adding an additional supply. No more than 1mA should be supplied by the TEST pin; its potential is approximately 5V below V+ (see Figure 10-1).

**FIGURE 10-1: DECIMAL POINT DRIVE USING TEST AS LOGIC GROUND**



# TC7106/A/TC7107/A

## 10.4 Ratiometric Resistance Measurements

The true differential input and differential reference make ratiometric reading possible. Typically in a ratiometric operation, an unknown resistance is measured, with respect to a known standard resistance. No accurately defined reference voltage is needed.

The unknown resistance is put in series with a known standard and a current passed through the pair. The voltage developed across the unknown is applied to the input and the voltage across the known resistor is applied to the reference input. If the unknown equals the standard, the display will read 1000.

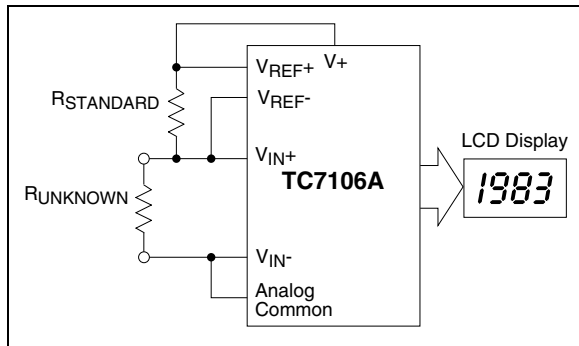
The displayed reading can be determined from the following expression:

$$\text{Displayed(Reading)} = \frac{R_{\text{Unknown}}}{R_{\text{Standard}}} \times 1000$$

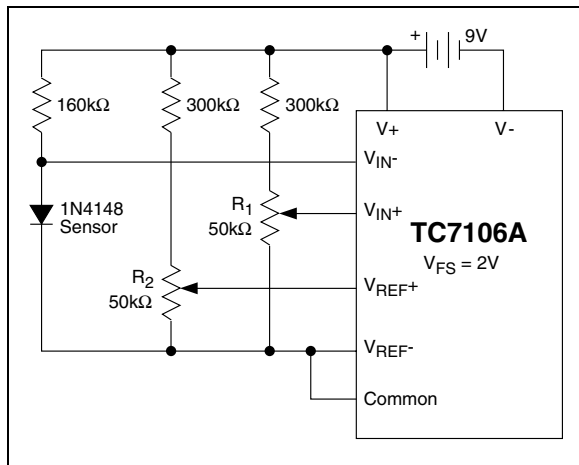
The display will over range for:

$$R_{\text{UNKNOWN}} \geq 2 \times R_{\text{STANDARD}}$$

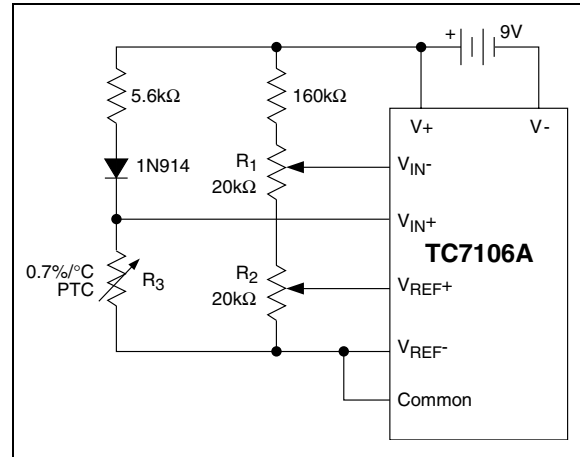
**FIGURE 10-2: LOW PARTS COUNT RATIOMETRIC RESISTANCE MEASUREMENT**



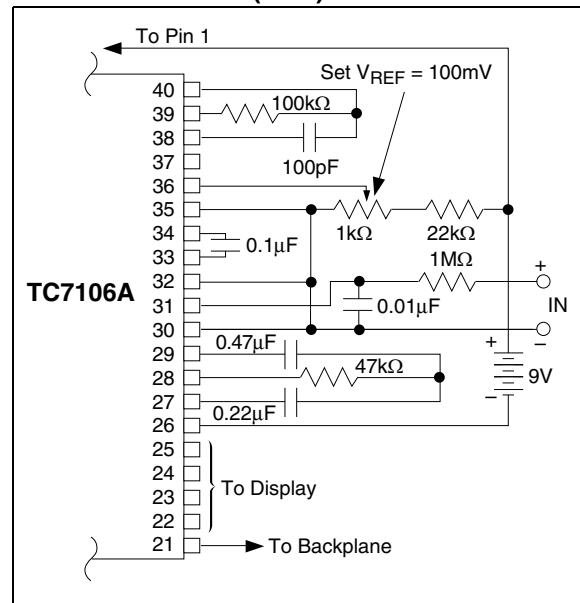
**FIGURE 10-3: TEMPERATURE SENSOR**



**FIGURE 10-4: POSITIVE TEMPERATURE COEFFICIENT RESISTOR TEMPERATURE SENSOR**

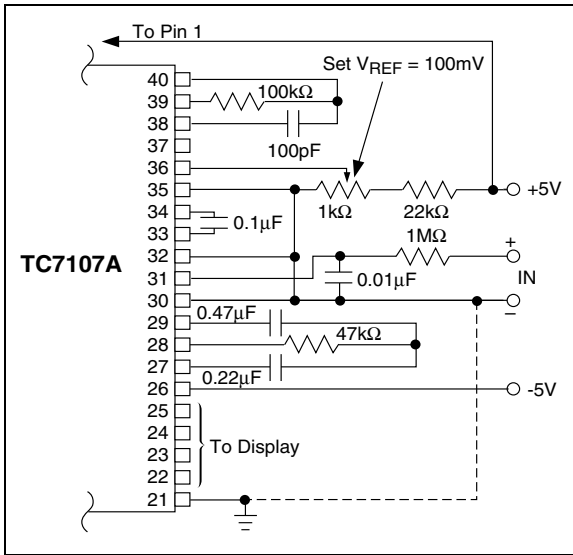


**FIGURE 10-5: TC7106A, USING THE INTERNAL REFERENCE: 200mV FULL SCALE, 3 READINGS-PER-SECOND (RPS)**

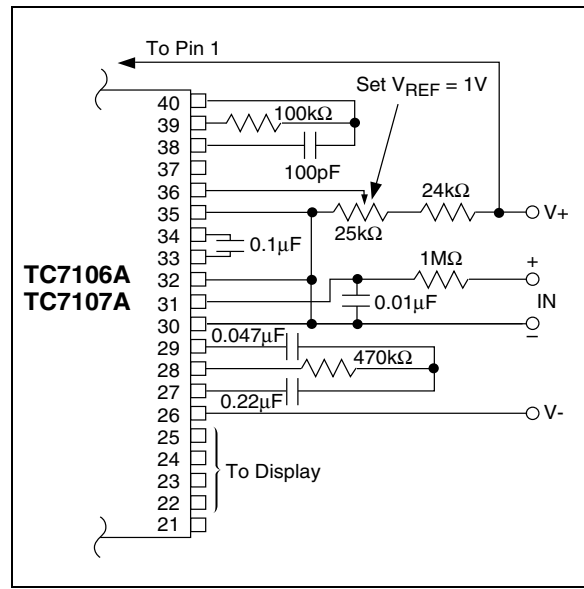


# TC7106/A/TC7107/A

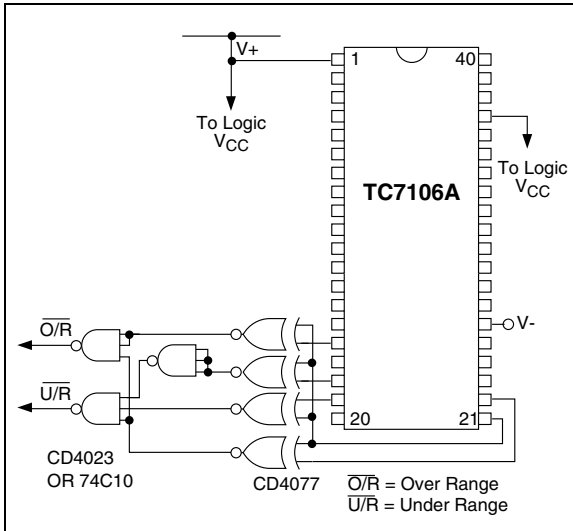
**FIGURE 10-6: TC7107 INTERNAL REFERENCE: 200mV FULL SCALE, 3RPS,  $V_{IN-}$  TIED TO GND FOR SINGLE ENDED INPUTS**



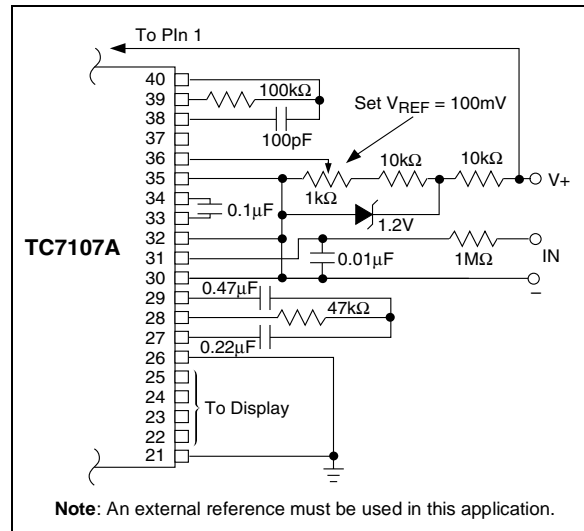
**FIGURE 10-8: TC7106/TC7107: RECOMMENDED COMPONENT VALUES FOR 2.00V FULL SCALE**



**FIGURE 10-7: CIRCUIT FOR DEVELOPING UNDER RANGE AND OVER RANGE SIGNALS FROM TC7106A OUTPUTS**



**FIGURE 10-9: TC7107 OPERATED FROM SINGLE +5V SUPPLY**



# TC7106/A/TC7107/A

FIGURE 10-10: 3-1/2 DIGIT TRUE RMS AC DMM

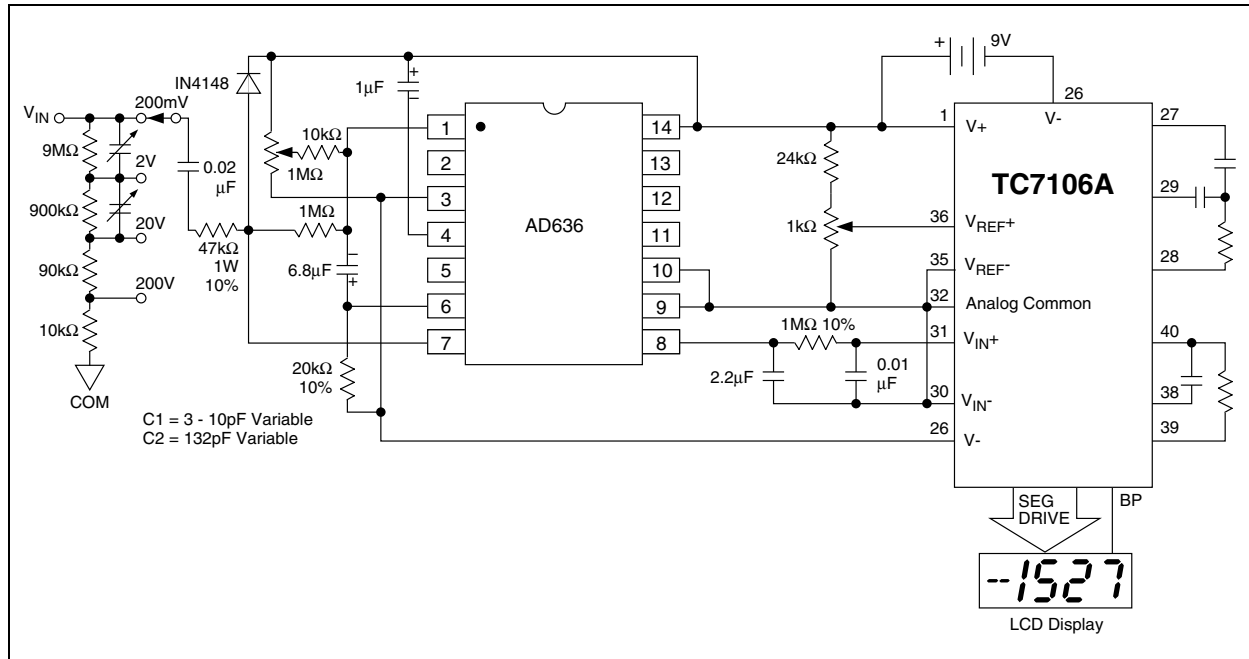
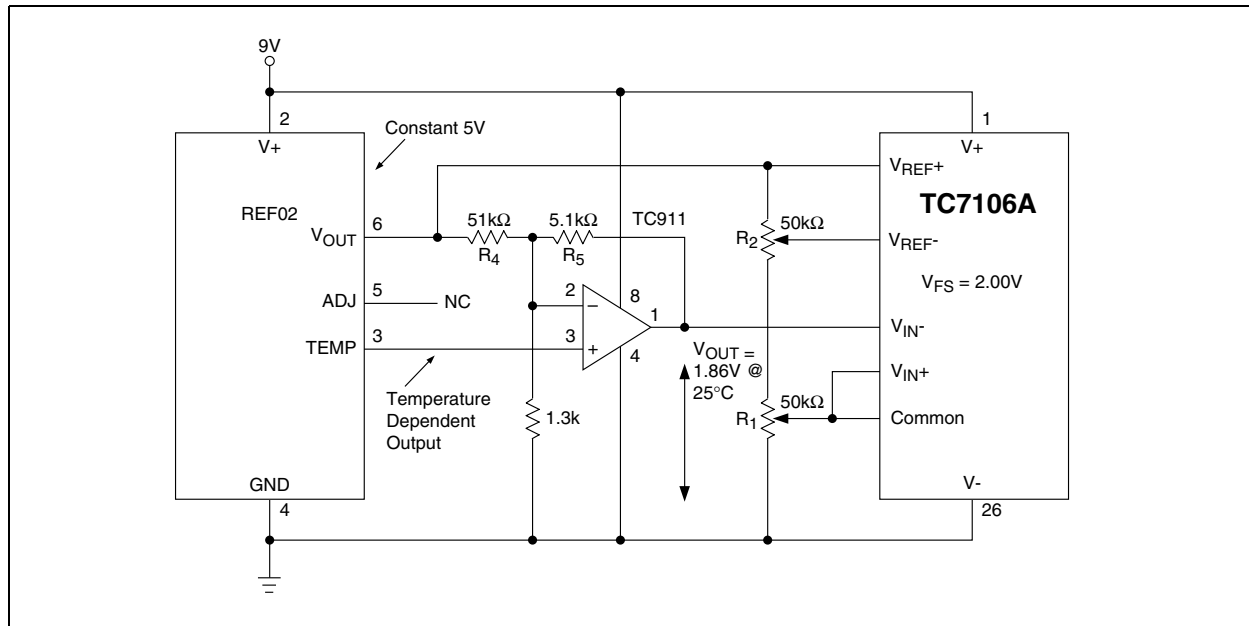


FIGURE 10-11: INTEGRATED CIRCUIT TEMPERATURE SENSOR



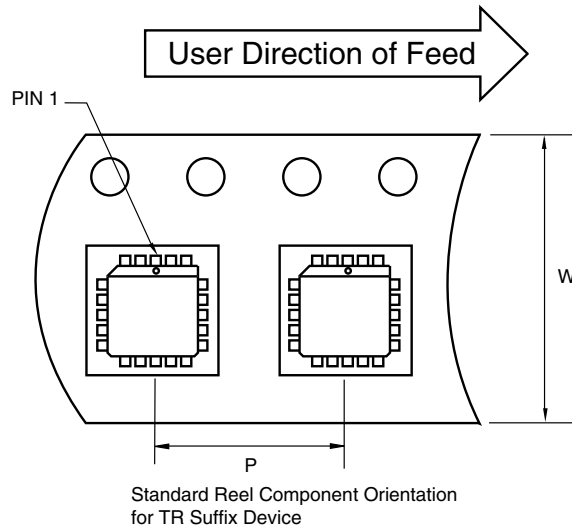
## 11.0 PACKAGING INFORMATION

### 11.1 Package Marking Information

Package marking data not available at this time.

### 11.2 Taping Form

#### Component Taping Orientation for 44-Pin PLCC Devices

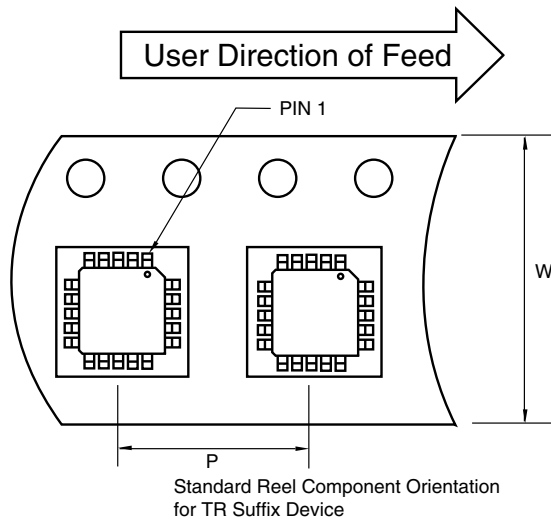


#### Carrier Tape, Number of Components Per Reel and Reel Size

Package	Carrier Width (W)	Pitch (P)	Part Per Full Reel	Reel Size
44-Pin PLCC	32 mm	24 mm	500	13 in

**Note:** Drawing does not represent total number of pins.

#### Component Taping Orientation for 44-Pin PQFP Devices



#### Carrier Tape, Number of Components Per Reel and Reel Size

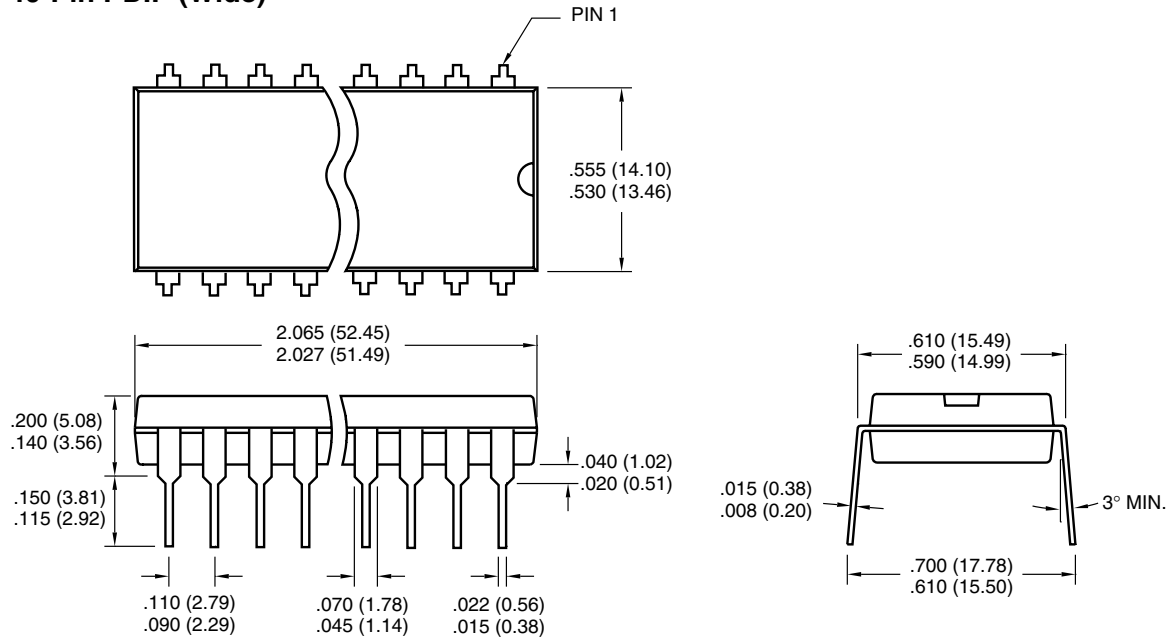
Package	Carrier Width (W)	Pitch (P)	Part Per Full Reel	Reel Size
44-Pin PQFP	24 mm	16 mm	500	13 in

**Note:** Drawing does not represent total number of pins.

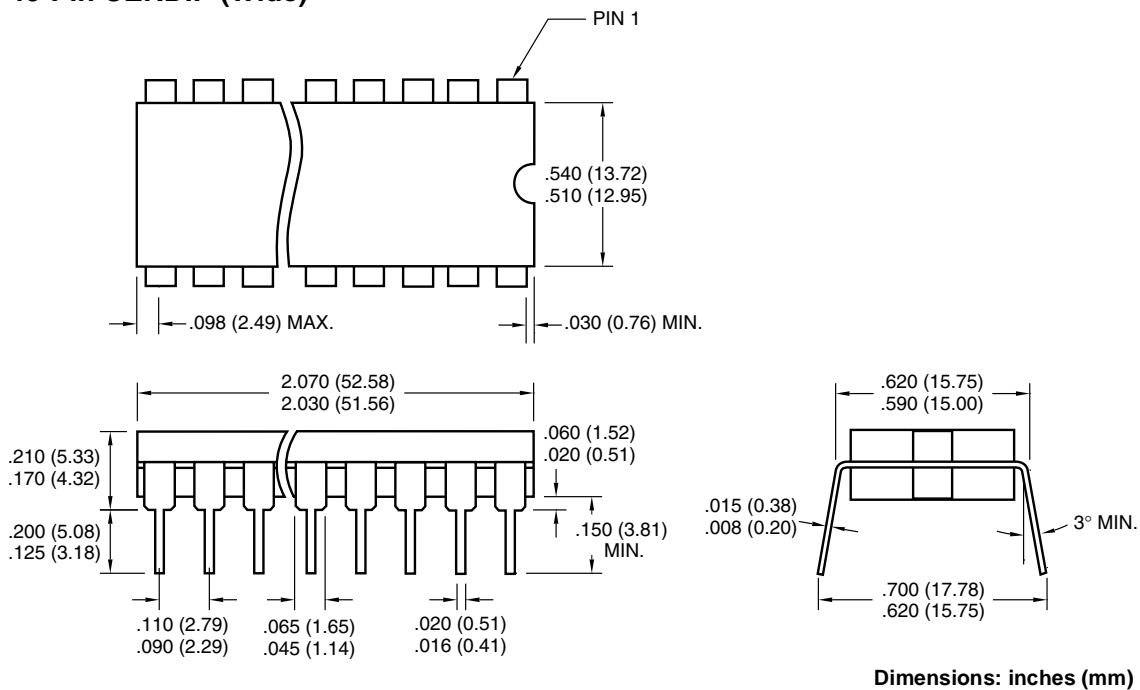
# TC7106/A/TC7107/A

## 11.3 Package Dimensions

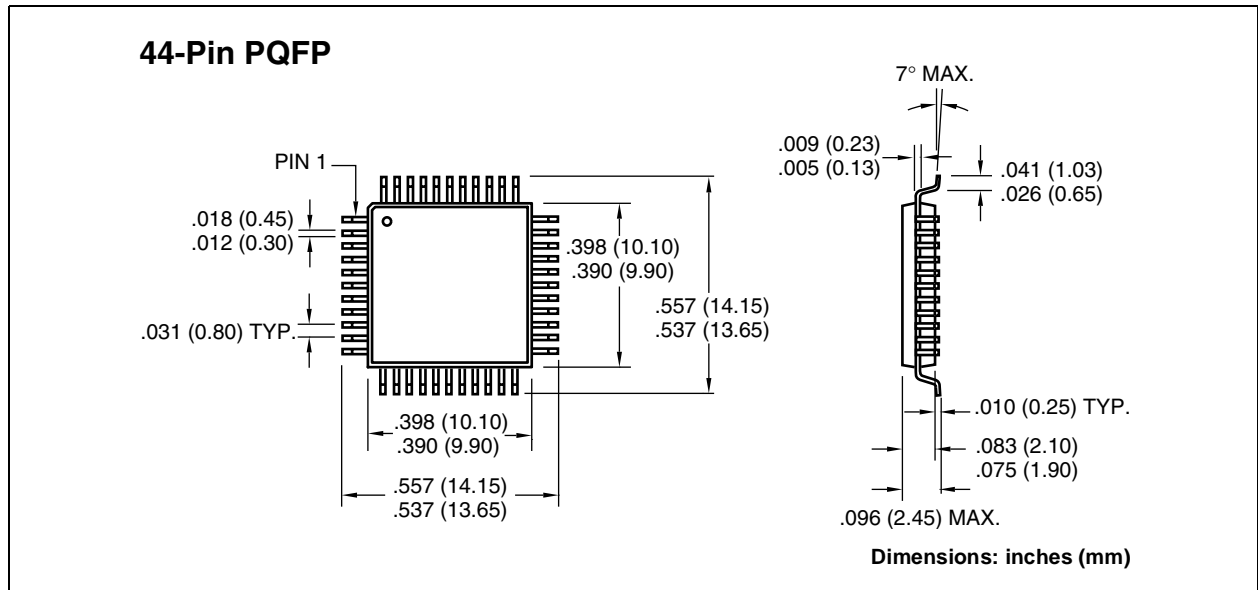
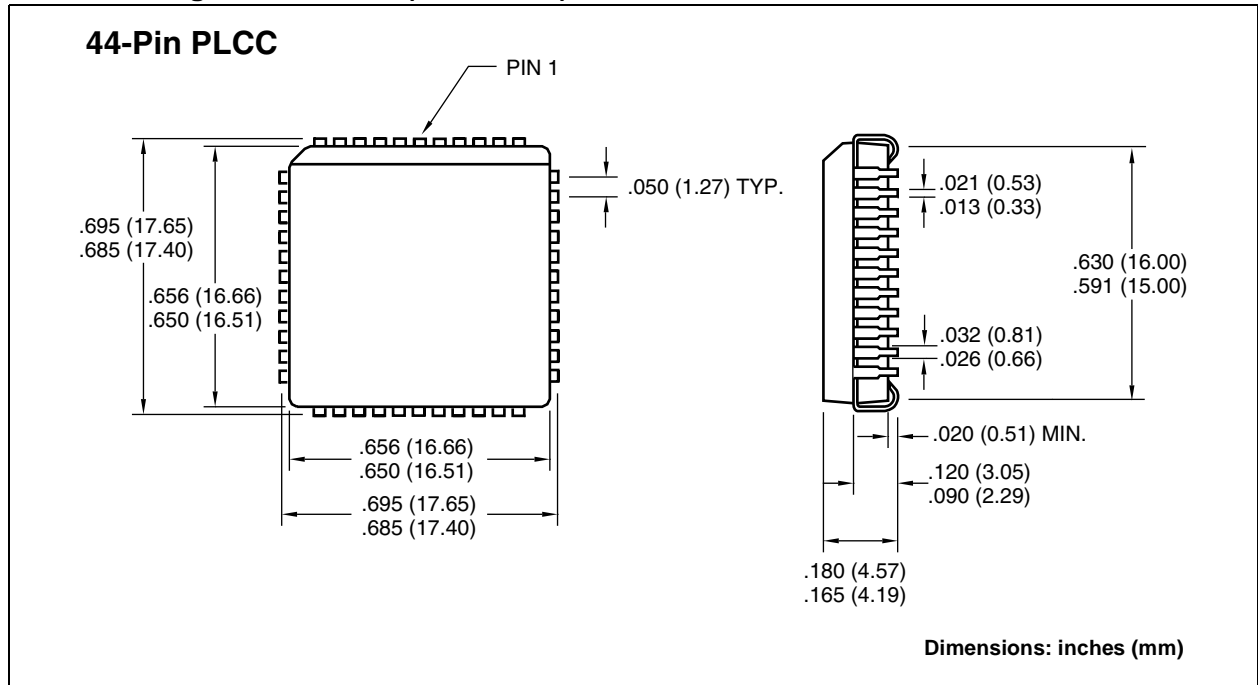
### 40-Pin PDIP (Wide)



### 40-Pin CERPDP (Wide)



## 11.3 Package Dimensions (Continued)



# TC7106/A/TC7107/A

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To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

<b>PART CODE</b>	<b>TC711</b>	<b>X</b>	<b>X</b>	<b>XXX</b>
6 = LCD } _____				
7 = LED } _____				
A or blank* _____				
R (reversed pins) or blank (CPL pkg only) _____				
* "A" parts have an improved reference TC				
Package Code (see below): _____				

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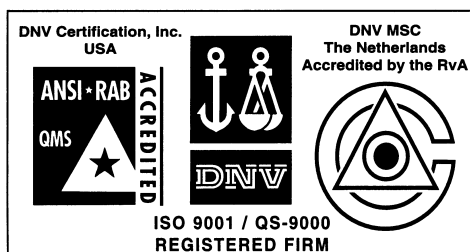
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