

## 3.0A Step-Down Switching Regulator

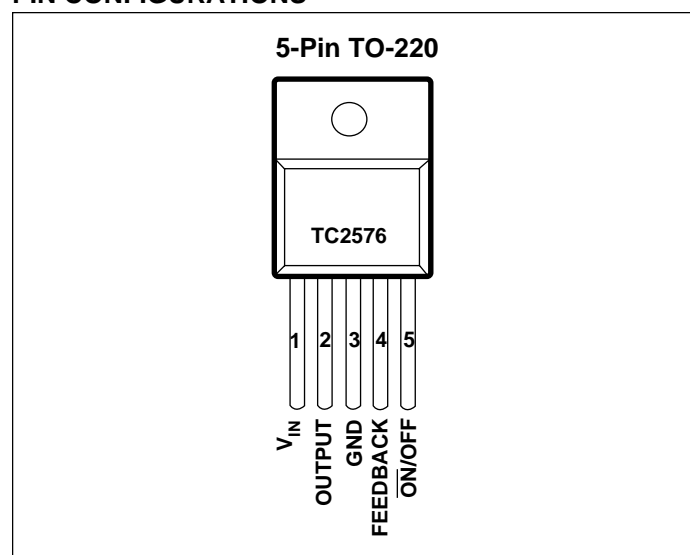
### FEATURES

- 3.3V, 5.0V, 12V and Adjustable Output Versions
- Adjustable Version Output Voltage Range: 1.23 to 37V  $\pm 4\%$  Max. Over Line and Load Conditions
- Guaranteed 3.0A Output Current
- Wide Input Voltage Range
- Requires Only 4 External Components
- 52kHz Fixed Frequency Internal Oscillator
- TTL Shutdown Capability, Low Power Standby Mode
- High Efficiency
- Uses Readily Available Standard Inductors
- Thermal Shutdown and Current Limit Protection

### APPLICATIONS

- Simple and High-Efficiency Step-Down (Buck) Regulator
- Efficient Pre-Regulator for Linear Regulators
- On-Card Switching Regulators
- Positive to Negative Converters (Buck-Boost)
- Negative Step-Up Converters
- Power Supply for Battery Chargers

### PIN CONFIGURATIONS



### GENERAL DESCRIPTION

The TC2576 series of regulators are monolithic integrated circuits ideally suited for easy and convenient design of a step-down switching regulator (buck converter). All circuits of this series are capable of driving a 3.0A load with excellent line and load regulation. These devices are available in fixed output voltages of 3.3V, 5.0V, 12.0V and an adjustable output version.

These regulators were designed to minimize the number of external components to simplify the power supply design. Standard series of inductors optimized for use with the TC2576 are offered by several different inductor manufacturers.

Since the TC2576 converter is a switch-mode power supply, its efficiency is significantly higher in comparison with popular three-terminal linear regulators, especially with higher input voltages. In many cases, the power dissipated is so low, that no heatsinking is required or its size can be reduced dramatically.

A standard series of inductors optimized for use with the TC2576 are available from several different manufacturers. This feature greatly simplifies the design of switch-mode power supplies.

The TC2576 features include a guaranteed  $\pm 4\%$  tolerance on output voltage within specified input voltages and output load conditions, and  $\pm 10\%$  on the oscillator frequency ( $\pm 2\%$  over  $0^\circ\text{C}$  to  $+125^\circ\text{C}$ ). External shutdown is included, featuring 80 $\mu\text{A}$  (typical) standby current. The output switch includes cycle-by-cycle current limiting, as well as thermal shutdown for full protection under fault conditions.

### ORDERING INFORMATION

Part Number	Package	Temperature Range
TC2576-3.3VAT	5-Pin TO-220	-40 to +125°C
TC2576-5.0VAT	5-Pin TO-220	-40 to +125°C
TC2576-12.0VAT	5-Pin TO-220	-40 to +125°C
TC2576VAT*	5-Pin TO-220	-40 to +125°C

Note: \*ADJ = 1.23 To 37V.

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### TC2576

#### ABSOLUTE MAXIMUM RATINGS\*

Maximum Supply Voltage .....  $V_{IN} = 45V$   
 ON/OFF Pin Input Voltage .....  $-0.3V \leq V \leq +V_{IN}$   
 Output Voltage to Ground (Steady State) .....  $-1.0V$   
 Max Power Dissipation (TO-220) ..... (Internally Limited)  
     Thermal Resistance, Junction-to-Ambient .....  $65^{\circ}C/W$   
     Thermal Resistance, Junction-to-Case .....  $5.0^{\circ}C/W$   
 Storage Temperature Range .....  $-65^{\circ}C$  to  $+150^{\circ}C$   
 Minimum ESD Rating ..... 2.0  
 (Human Body Model:  $C = 100\text{ pF}$ ,  $R = 1.5\text{ k}\Omega$ )

Lead Temperature (Soldering, 10 seconds) .....  $260^{\circ}C$   
 Maximum Junction Temperature .....  $150^{\circ}C$   
 Operating Junction Temperature Range ....  $-40$  to  $+125^{\circ}C$   
 Supply Voltage ..... 40V

\*This is a stress rating only, and functional operation of the device at these or any other conditions beyond those indicated in the operation section of the specifications is not implied. Exposure to absolute maximum ratings conditions for extended periods of time may affect device reliability.

**ELECTRICAL CHARACTERISTICS:** Unless otherwise specified,  $V_{IN} = 12V$  for the 3.3V, 5.0V, and Adjustable version,  $V_{IN} = 25V$  for the 12V version.  $I_{LOAD} = 500mA$ . For typical values  $T_J = 25^{\circ}C$ , for min/max values  $T_J$  is the operating junction temperature range that applies [Note 2], unless otherwise noted.

Symbol	Parameter	Test Conditions	Min	Typ	Max	Units
<b>TC2576-3.3 [(Note 1) Test Circuit Figure 2]</b>						
$V_{OUT}$	Output Voltage	$V_{IN} = 12V$ , $I_{LOAD} = 0.5A$ , $T_J = 25^{\circ}C$ $6.0V \leq V_{IN} \leq 40V$ , $0.5A \leq I_{LOAD} \leq 3.0A$ $T_J = 25^{\circ}C$ $T_J = -40^{\circ}C$ to $+125^{\circ}$	3.234 3.168 3.135	3.3 3.3 —	3.366 3.432 3.465	V
$\eta$	Efficiency	$V_{IN} = 12V$ , $I_{LOAD} = 3.0A$	—	75	—	%
<b>TC2576-5 [(Note 1) Test Circuit Figure 2]</b>						
$V_{OUT}$	Output Voltage	$V_{IN} = 12V$ , $I_{LOAD} = 0.5A$ , $T_J = 25^{\circ}C$ $8.0V \leq V_{IN} \leq 40V$ , $0.5A \leq I_{LOAD} \leq 3.0A$ $T_J = 25^{\circ}C$ $T_J = -40^{\circ}C$ to $+125^{\circ}C$	4.9 4.8 4.75	5.0 5.0 —	5.1 5.2 5.25	V
$\eta$	Efficiency	$V_{IN} = 12V$ , $I_{LOAD} = 3.0A$	—	77	—	%
<b>TC2576-12 [(Note 1) Test Circuit Figure 2]</b>						
$V_{OUT}$	Output Voltage	$V_{IN} = 25V$ , $I_{LOAD} = 0.5A$ , $T_J = 25^{\circ}C$ $15V \leq V_{IN} \leq 40V$ , $0.5A \leq I_{LOAD} \leq 3.0A$ $T_J = 25^{\circ}C$ $T_J = -40^{\circ}C$ to $+125^{\circ}C$	11.76 11.52 11.4	10 12 —	12.24 12.48 12.6	V
$\eta$	Efficiency	$V_{IN} = 15V$ , $I_{LOAD} = 3.0A$	—	88	—	%
<b>TC2576-Adjustable Version [(Note 1) Test Circuit Figure 2]</b>						
$V_{OUT}$	Feedback Voltage	$V_{IN} = 12V$ , $I_{LOAD} = 0.5A$ , $V_{OUT} = 5.0V$ , $T_J = 25^{\circ}C$	1.217	1.23	1.243	V
$V_{FBT}$	Feedback Voltage	$8.0V \leq V_{IN} \leq 40V$ , $0.5A \leq I_{LOAD} \leq 3.0A$ $V_{OUT} = 5.0V$ $T_J = 25^{\circ}C$ $T_J = -40^{\circ}C$ to $+125^{\circ}C$	1.193 1.18	1.23 —	1.267 1.28	
$\eta$	Efficiency	$V_{IN} = 12V$ , $I_{LOAD} = 3.0A$ , $V_{OUT} = 5.0V$	—	77	—	%

- NOTES:** 1. External components such as the catch diode, inductor, input and output capacitors can affect the switching regulator system performance. When the TC2576 is used as shown in the Figure 2 test circuit, the system performance will be as shown in the system parameters section of the Electrical Characteristics.  
 2. Tested junction temperature range for the TC2576:  $T_{LOW} = -40^{\circ}C$   $T_{HIGH} = +125^{\circ}C$

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**ELECTRICAL CHARACTERISTICS:** Unless otherwise specified,  $V_{IN} = 12V$  for the 3.3V, 5.0V, and Adjustable version,  $V_{IN} = 25V$  for the 12V version.  $I_{LOAD} = 500mA$ . For typical values  $T_J = 25^\circ C$ , for min/max values  $T_J$  is the operating junction temperature range that applies [Note 2], unless otherwise noted.

Symbol	Parameter	Test Conditions	Min	Typ	Max	Units
<b>TC2576-ALL OUTPUT VOLTAGE VERSIONS</b>						
$I_b$	Feedback Bias Current	$V_{OUT} = 5.0V$ (Adjustable Version Only) $T_J = 25^\circ C$ $T_J = -40^\circ C$ to $+125^\circ C$	— —	25 —	100 200	nA
$f_{OSC}$	Oscillator Frequency (Note 3)	$T_J = 25^\circ C$ $T_J = 0$ to $+125^\circ C$ $T_J = -40$ to $+125^\circ C$	— 47 42	52 52 —	— 58 63	kHz
$V_{SAT}$	Saturation Voltage	$I_{OUT} = 0.5 A$ , (Note 4) $T_J = 25^\circ C$ $T_J = -40$ to $+125^\circ C$	— —	1.5 —	1.8 2.0	V
DC	Max Duty Cycle ("on") [Note 5]		94	98	—	%
$I_{CL}$	Current Limit Peak Current (Notes 3 and 4)	$T_J = 25^\circ C$ $T_J = -40$ to $+125^\circ C$	4.2 3.5	5.8 —	6.9 7.5	A
$I_L$	Output Leakage Current (Notes 6 and 7), $T_J = 25^\circ C$	Output = 0 V Output = - 1.0 V	— —	0.8 6.0	2.0 20	mA
$I_Q$	Quiescent Current (Note 6)	$T_J = 25^\circ C$ $T_J = -40$ to $+125^\circ C$	— —	5.0 —	9.0 11	mA
$I_{STBY}$	Standby Quiescent Current, $\overline{ON}/OFF$ Pin = 5.0V ("off")	$T_J = 25^\circ C$ $T_J = -40$ to $+125^\circ C$	— —	80 —	200 400	$\mu A$
$V_{IH}$	$\overline{ON}/OFF$ Pin Logic Input Level (Test Figure 2)	$V_{OUT} = 0V$ $T_J = 25^\circ C$ $T_J = -40$ to $+125^\circ C$	2.2 2.4	1.4 —	— —	V
$V_{IL}$	Nominal Output Voltage	$T_J = 25^\circ C$ $T_J = -40$ to $+125^\circ C$	— —	1.2 —	1.0 0.8	V
$I_{IH}$	$\overline{ON}/OFF$ Pin Input Current (Test Figure 2)	$\overline{ON}/OFF$ Pin = 5.0V ("off"), $T_J = 25^\circ C$	—	15	30	$\mu A$
$I_{IL}$	$\overline{ON}/OFF$ Pin Input Current	$\overline{ON}/OFF$ Pin = 0V ("on"), $T_J = 25^\circ C$	—	0	5.0	$\mu A$

- NOTES:**
- The oscillator frequency reduces to approximately 18kHz in the event of an output short or an overload which causes the regulated output voltage to drop approximately 40% from the nominal output voltage. This self protection feature lowers the average power dissipation of the IC by lowering the minimum duty cycle from 5% down to approximately 2%.
  - Output (Pin 2) sourcing current. No diode, inductor or capacitor connected to the output pin.
  - Feedback (Pin 4) removed from output and connected to 0V.
  - Feedback (Pin 4) removed from output and connected to +12V for the Adjustable, 3.3V, and 5.0V versions, and 25V for the 12V versions, to force the output transistor "OFF".
  - $V_{IN} = 40 V$ .

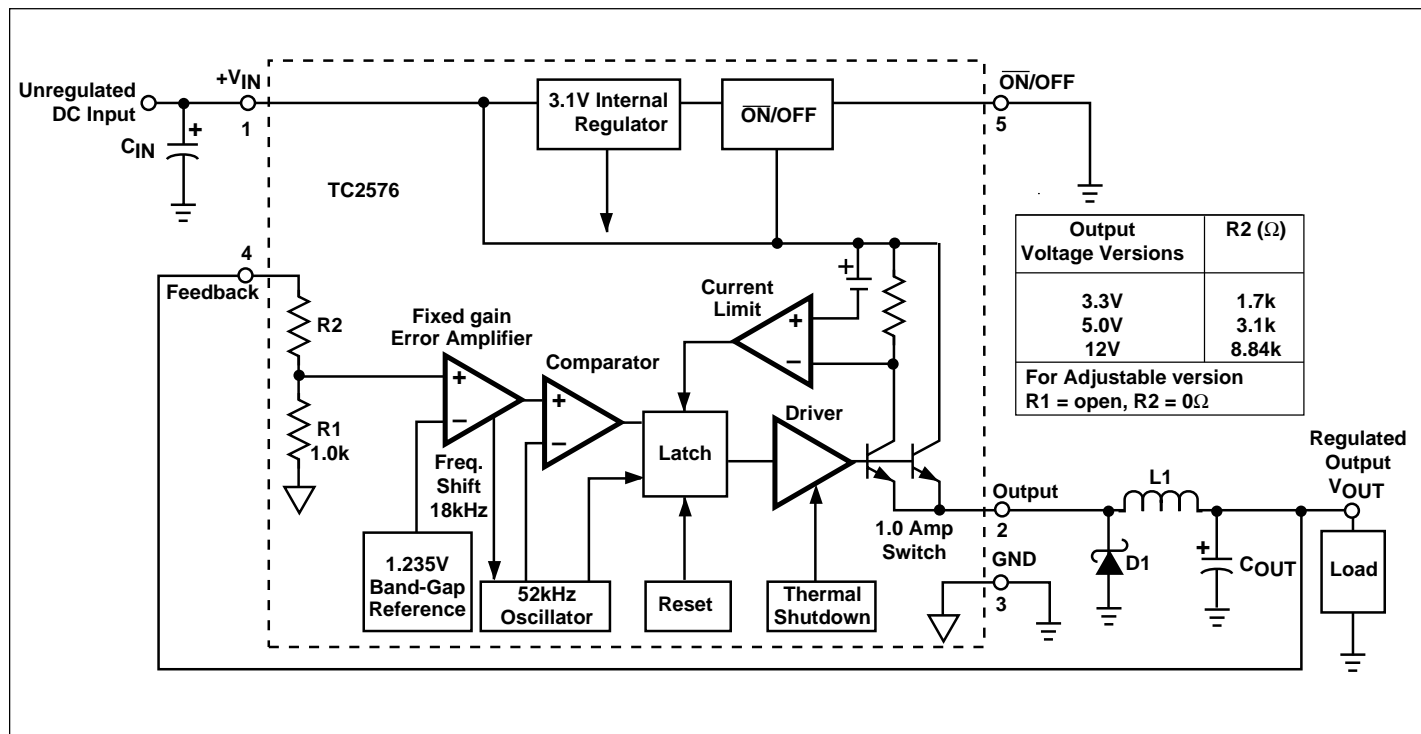
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### PIN DESCRIPTION

Pin No. 5-Pin TO-220	Symbol	Description
1	$V_{IN}$	This pin is the positive input supply for the TC2576 step-down switching regulator. In order to minimize voltage transients and to supply the switching currents needed by the regulator, a suitable input bypass capacitor must be present ( $C_{IN}$ in Figure 1).
2	Output	This is the emitter of the internal switch. The saturation voltage $V_{SAT}$ of this output switch is typically 1.5V. It should be kept in mind that the PCB area connected to this pin should be kept to a minimum in order to minimize coupling to sensitive circuitry.
3	GND	Circuit ground pin. See the information about the printed circuit board layout.
4	Feedback	This pin senses regulated output voltage to complete the feedback loop. The signal is divided by the internal resistor divider network R2, R1 and applied to the non-inverting input of the internal error amplifier. In the adjustable version of the TC2576 switching regulator this pin is the direct input of the error amplifier and the resistor network R2, R1 is connected externally to allow programming of the output voltage.
5	ON/OFF	It allows the switching regulator circuit to be shut down using logic level signals, thus dropping the total input supply current to approximately 80 $\mu$ A. The threshold voltage is typically 1.4V. Applying a voltage above this value (up to $+V_{IN}$ ) shuts the regulator off. If the voltage applied to this pin is lower than 1.4V or if this pin is left open, the regulator will be in the "on" condition.

### REPRESENTATIVE BLOCK DIAGRAM AND TYPICAL APPLICATION



### 3.0A Step-Down Switching Regulator

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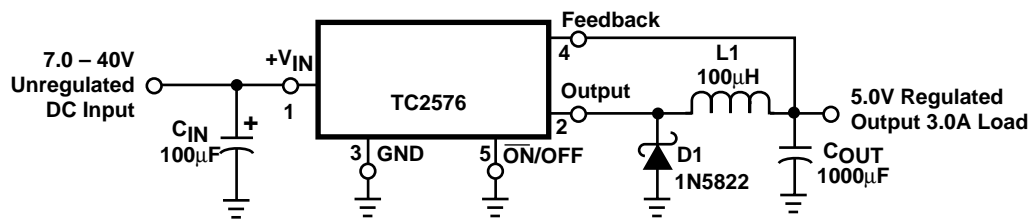


Figure 1. Block Diagram and Typical Application: Fixed Output Voltage Versions

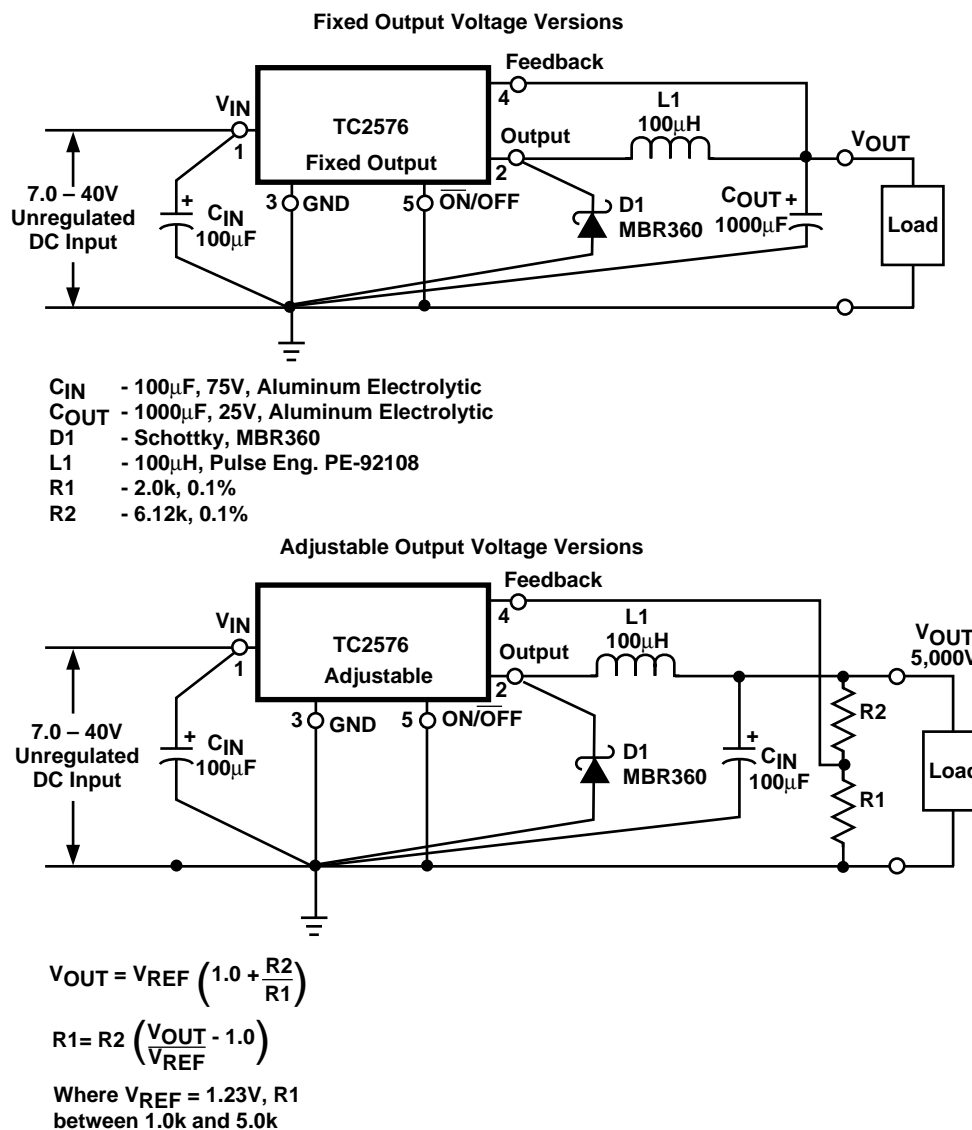


Figure 2. Typical Test Circuit

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### PCB LAYOUT GUIDELINES

As in any switching regulator, the layout of the printed circuit board is very important. Rapidly switching currents associated with wiring inductance, stray capacitance and parasitic inductance of the printed circuit board traces can generate voltage transients which can generate electromagnetic interferences (EMI) and affect the desired operation. As indicated in the Figure 2, to minimize inductance and ground loops, the length of the leads indicated by heavy lines should be kept as short as possible.

For best results, single-point grounding (as indicated) or ground plane construction should be used.

On the other hand, the PCB area connected to the Pin 2 (emitter of the internal switch) of the TC2576 should be kept to a minimum in order to minimize coupling to sensitive circuitry.

Another sensitive part of the circuit is the feedback. It is important to keep the sensitive feedback wiring short. To assure this, physically locate the programming resistors near to the regulator, when using the adjustable version of the TC2576 regulator.

### DESIGN PROCEDURE

#### Buck Converter Basics

The TC2576 is a "Buck" or Step-Down Converter which is the most elementary forward-mode converter. Its basic schematic can be seen in Figure 3.

The operation of this regulator topology has two distinct time periods. The first one occurs when the series switch is on, the input voltage is connected to the input of the inductor.

The output of the inductor is the output voltage, and the rectifier (or catch diode) is reverse biased. During this period, since there is a constant voltage source connected across the inductor, the inductor current begins to linearly ramp upwards, as described by the following equation:

$$I_{L(ON)} = \frac{(V_{IN} - V_{OUT}) t_{ON}}{L}$$

During this "on" period, energy is stored within the core material in the form of magnetic flux. If the inductor is properly designed, there is sufficient energy stored to carry the requirements of the load during the "off" period.

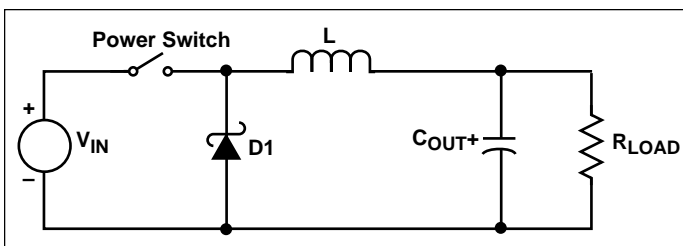


Figure 3. Basic Buck Converter

The next period is the "off" period of the power switch. When the power switch turns off, the voltage across the inductor reverses its polarity and is clamped at one diode voltage drop below ground by the catch diode. The current now flows through the catch diode thus maintaining the load current loop. This removes the stored energy from the inductor. The inductor current during this time is:

$$I_{L(OFF)} = \frac{(V_{OUT} - V_D) t_{OFF}}{L}$$

This period ends when the power switch is once again turned on. Regulation of the converter is accomplished by varying the duty cycle of the power switch. It is possible to describe the duty cycle as follows:

$$d = \frac{t_{ON}}{T}, \text{ where } T \text{ is the period of switching.}$$

For the buck converter with ideal components, the duty cycle can also be described as:

$$d = \frac{V_{OUT}}{V_{IN}}$$

Figure 4 shows the buck converter idealized waveforms of the catch diode voltage and the inductor current.

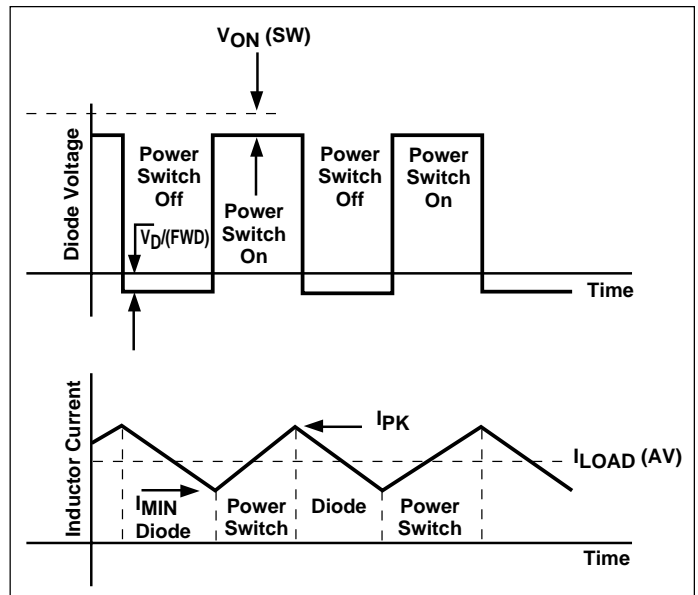


Figure 4. Buck Converter Idealized Waveforms

## 3.0A Step-Down Switching Regulator

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### Procedure (Fixed Output Voltage Version)

In order to simplify the switching regulator design, a step-by-step design procedure and some examples are provided.

Procedure	Example
<b>Given Parameters:</b> $V_{OUT}$ = Regulated Output Voltage (3.3V, 5.0V, 12V or 15V) $V_{IN(max)}$ = Maximum Input Voltage $I_{LOAD(max)}$ = Maximum Load Current <b>1. Controller IC Selection</b> According to the required input voltage, output voltage and current select the appropriate type of the controller IC output voltage version. <b>2. Input Capacitor Selection (<math>C_{IN}</math>)</b> To prevent large voltage transients from appearing at the input and for stable operation of the converter, an aluminum or tantalum electrolytic bypass capacitor is needed between the input pin + $V_{IN}$ and ground pin GND. This capacitor should be located close to the IC using short leads. This capacitor should have a low ESR (Equivalent Series Resistance) value. <b>3. Catch Diode Selection (D1)</b> <b>A.</b> Since the diode maximum peak current exceeds the regulator maximum load current, the catch diode current rating must be at least 1.2 times greater than the maximum load current. For a robust design the diode should have a current rating equal to the maximum current limit of the TC2576 to be able to withstand a continuous output short. <b>B.</b> The reverse voltage rating of the diode should be at least 1.25 times the maximum input voltage. <b>4. Inductor Selection (L1)</b> <b>A.</b> According to the required working conditions, select the correct inductor value using the selection guide from Figures 36 to 38. <b>B.</b> From the appropriate inductor selection guide, identify the inductance region intersected by the Maximum Input Voltage line and the Maximum Load Current line. Each region is identified by an inductance value and an inductor code. <b>C.</b> Select an appropriate inductor from the several different manufacturers part numbers listed in Table 2. The designer must realize that the inductor current rating must be higher than the maximum peak current flowing through the inductor. This maximum peak current can be calculated as follows: $I_P(max) = I_{LOAD(max)} + \frac{(V_{IN} - V_{OUT}) t_{ON}}{2L}$ where $t_{ON}$ is the "on" time of the power switch and $t_{ON} = \frac{V_{OUT}}{V_{IN}} \times \frac{1.0}{f_{OSC}}$ For additional information about the inductor, see the inductor section in the "APPLICATION HINTS" section of this datasheet.	<b>Given Parameters:</b> $V_{OUT} = 5.0V$ $V_{IN(max)} = 15V$ $I_{LOAD(max)} = 3.0A$ <b>1. Controller IC Selection</b> According to the required input voltage, output voltage, polarity and current value, use the TC2576-5 controller IC. <b>2. Input Capacitor Selection (<math>C_{IN}</math>)</b> A 100 $\mu$ F, 25V aluminium electrolytic capacitor located near to the input and ground pins provides sufficient bypassing. <b>3. Catch Diode Selection (D1)</b> <b>A.</b> For this example the current rating of the diode is 3.0A <b>B.</b> Use a 20V 1N5820 Schottky diode, or any of the suggested fast recovery diodes shown in Table 1. <b>4. Inductor Selection (L1)</b> <b>A.</b> Use the inductor selection guide shown in Figure 37. <b>B.</b> From the selection guide, the inductance area intersected by the 15V line and 3.0A line is L100. <b>C.</b> Inductor value required is 100 $\mu$ H. From Table 2, choose an inductor from any of the listed manufacturers.



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### Procedure (Fixed Output Voltage Version) (Continued)

In order to simplify the switching regulator design, a step-by-step design procedure and examples are provided.

Procedure	Example
<b>5. Output Capacitor Selection (<math>C_{OUT}</math>)</b> <b>A.</b> Since the TC2576 is a forward-mode switching regulator with voltage mode control, its open loop 2-pole-1-zero frequency characteristic has the dominant pole-pair determined by the output capacitor and inductor values. For stable operation and an acceptable ripple voltage, (approximately 1% of the output voltage) a value between 680 $\mu$ F and 2000 $\mu$ F is recommended. <b>B.</b> Due to the fact that the higher voltage electrolytic capacitors generally have lower ESR (Equivalent Series Resistance) numbers, the output capacitor's voltage rating should be at least 1.5 times greater than the output voltage. For a 5.0V regulator, a rating at least 8.0V is appropriate, and a 10V or 16V rating is recommended.	<b>5. Output Capacitor Selection (<math>C_{OUT}</math>)</b> <b>A.</b> $C_{OUT}$ = 680 $\mu$ F to 2000 $\mu$ F standard aluminium electrolytic.  <b>B.</b> Capacitor voltage rating = 20V.

### Procedure (Adjustable Output Version: TC2576-ADJ)

Procedure	Example
<b>Given Parameters:</b> $V_{OUT}$ = Regulated Output Voltage $V_{IN}$ (max) = Maximum DC Input Voltage $I_{LOAD}$ (max) = Maximum Load Current	<b>Given Parameters:</b> $V_{OUT}$ = 8.0V $V_{IN}$ (max) = 2.5V $I_{LOAD}$ (max) = 2.5V
<b>1. Programming Output Voltage</b> To select the right programming resistor R1 and R2 value (see Figure 2) use the following formula:  $V_{OUT} = V_{REF} \left( 1.0 + \frac{R2}{R1} \right) \text{ where } V_{REF} = 1.23V$  Resistor R1 can be between 1.0k $\Omega$ and 5.0k $\Omega$ . (For best temperature coefficient and stability with time, use 1% metal film resistors).  $R2 = R1 \left( \frac{V_{OUT}}{V_{REF}} - 1.0 \right)$	<b>1. Programming Output Voltage (selecting R1 and R2)</b> Select R1 and R2 $V_{OUT} = 1.23 \left( 1.0 + \frac{R2}{R1} \right) \text{ Select } R1 = 1.8k\Omega$  $R2 = R1 \left( \frac{V_{OUT}}{V_{REF}} - 1.0 \right) = 1.08k \left( \frac{8.0V}{1.23V} - 1.0 \right)$  $R1 = 9.91k\Omega$ , choose a 9.88k $\Omega$ metal film resistor.
<b>2. Input Capacitor Selection (<math>C_{IN}</math>)</b> To prevent large voltage transients from appearing at the input and for stable operation of the converter, an aluminium or tantalum electrolytic bypass capacitor is needed between the input pin + $V_{IN}$ and ground pin GND. This capacitor should be located close to the IC using short leads. This capacitor should have a low ESR (Equivalent Series Resistance) value. For additional information see input capacitor section in the "APPLICATION HINTS" section of this data sheet.	<b>2. Input Capacitor Selection (<math>C_{IN}</math>)</b> A 100 $\mu$ F, 150V aluminium electrolytic capacitor located near the input and ground pin provides sufficient bypassing.



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#### Procedure (Adjustable Output Version: TC2576-ADJ) (Continued)

Procedure	Example
<p><b>3. Catch Diode Selection (D1)</b></p> <p>A. Since the diode maximum peak current exceeds the regulator maximum load current the catch diode current rating must be at least 1.2 times greater than the maximum load current. For a robust design, the diode should have a current rating equal to the maximum current limit of the TC2576 to be able to with stand a continuous output short.</p> <p>B. The reverse voltage rating of the diode should be at least 1.25 times the maximum input voltage.</p>	<p><b>3. Catch Diode Selection (D1)</b></p> <p>A. For this example, a 3.0A current rating is adequate.</p> <p>B. Use a 30V IN5821 Schottky diode or any suggested fast recovery diodes in Table 1.</p>
<p><b>4. Inductor Selection (L1)</b></p> <p>A. Use the following formula to calculate the inductor Volt x microsecond [V x <math>\mu</math>s] constant:</p> $E \times T = (V_{IN} - V_{OUT}) \frac{V_{OUT}}{V_{IN}} \times \frac{10^6}{F[Hz]} [V \times \mu sec]$ <p>B. Match the calculated E x T value with the corresponding number on the vertical axis of the Inductor Value Selection Guide shown in Figure 37. This E x T constant is a measure of the energy handling capability of an inductor and is dependent upon the type of core, the core area, the number of turns, and the duty cycle.</p> <p>C. Next step is to identify the inductance region intersected by the E x T value and the maximum load current value on the horizontal axis shown in Figure 7.</p> <p>D. From the inductor code, identify the inductor value. Then select an appropriate inductor from Table 2. The inductor chosen must be rated for a switching frequency of 52kHz and for a current rating of <math>1.15 \times I_{LOAD}</math>. The inductor current rating can also be determined by calculating the inductor peak current:</p> $I_{P(max)} = I_{LOAD(max)} + \frac{(V_{IN} - V_{OUT}) t_{ON}}{2L}$ <p>where <math>t_{ON}</math> is the "on" time of the power switch and</p> $t_{ON} = \frac{(V_{OUT}}{V_{IN}} \times \frac{1.0}{f_{OSC}})$ <p>For additional information about the inductor, see the inductor section in the "External Components" section of this data sheet.</p>	<p><b>4. Inductor Selection (L1)</b></p> <p>A. Calculate E x T [V x <math>\mu</math>sec] constant:</p> $E \times T = (25 - 8.0) \times \frac{8.0}{25} \times \frac{1000}{52} = 80 [V \times \mu sec]$ <p>B. E x T = 80 [V x <math>\mu</math>sec]</p> <p>C. <math>I_{LOAD(max)} = 2.5 A</math> Inductance Region = H150</p> <p>D. Proper inductor value = 150<math>\mu</math>H Choose the inductor from Table 2.</p>

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### Procedure (Adjustable Output Version: TC2576-ADJ) (Continued)

Procedure	Example
<p><b>5. Output Capacitor Selection (<math>C_{OUT}</math>)</b></p> <p>A. Since the TC2576 is a forward-mode switching regulator with voltage mode control, its open loop 2-pole-1-zero frequency characteristic has the dominant pole-pair determined by the output capacitor and inductor values.</p> <p>For stable operation, the capacitor must satisfy the following requirement:</p> $C_{OUT} \geq 13,000 \frac{V_{IN(max)}}{V_{OUT} \times L} [\mu F]$ <p>B. Capacitor values between 10<math>\mu</math>F and 2000<math>\mu</math>F will satisfy the loop requirements for stable operation. To achieve an acceptable output ripple voltage and transient response, the output capacitor may need to be several times larger than the above formula yields.</p> <p>C. Due to the fact that the higher voltage electrolytic capacitors generally have lower ESR (Equivalent Series Resistance) numbers, the output capacitor's voltage rating should be at least 1.5 times greater than the output voltage. For a 5.0V regulator, a rating of at least 8.0V is appropriate, and a 10V or 16V rating is recommended.</p>	<p><b>5. Output Capacitor Selection (<math>C_{OUT}</math>)</b></p> <p>A. <math>C_{OUT} \geq 13,000 \frac{25}{8 \times 150} = 332.5\mu F</math></p> <p>To achieve an acceptable ripple voltage, select <math>C_{OUT}</math> 680<math>\mu</math>F electrolytic capacitor.</p>

**Table 1. Diode Selection Guide**

$V_R$	Schottky				Fast Recovery			
	3.0A		4.0-6.0A		3.0A		4.0-6.0A	
	Through Hole	Surface Mount	Through Hole	Surface Mount	Through Hole	Surface Mount	Through Hole	Surface Mount
20V	1N5820 MBR320P SR302	SK32	1N5823 SR502 SB520		MUR320 31DF1 HER302  (all diodes rated to at least 100V)	MURS320T3 MURD320 30WF10  (all diodes rated to at least 100V)	MUR420 HER602  (all diodes rated to at least 100V)	MURD620CT 50WF10  (all diodes rated to at least 100V)
30V	1N5821 MBR330 SR303 31DQ03	SK33 30WQ03	1N5824 SR503 SB530	50WQ03				
40V	1N5822 MBR340 SR304 31DQ04	SK34 30WQ04 MBRS340T3 MBRD340	1N5825 SR504 SB540	MBRD640CT 50WQ04				
50V	MBR350 31DQ05 SR305	SK35 30WQ05	SB550	50WQ05				
60V	MBR360 DQ06 SR306	MBRS360T3 MBRD360	50SQ080	MBRD660CT				

### 3.0A Step-Down Switching Regulator

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**Table 2. Inductor Selection Guide by Manufacturer's Part Number**

Inductor Code	Inductor Value	Tech 89	Schott Corp.	Pulse Eng.	Renco
L47	47 $\mu$ H	77 212	671 26980	PE-53112	RL2442
L68	68 $\mu$ H	77 262	671 26990	PE-92114	RL2443
L100	100 $\mu$ H	77 312	671 27000	PE-92108	RL2444
L150	150 $\mu$ H	77 360	671 27010	PE-53113	RL1954
L220	220 $\mu$ H	77 408	671 27020	PE-52626	RL1953
L330	330 $\mu$ H	77 456	671 27030	PE-52627	RL1952
L470	470 $\mu$ H	*	671 27040	PE-53114	RL1951
L680	680 $\mu$ H	77 506	671 27050	PE-52629	RL1950
H150	150 $\mu$ H	77 362	671 27060	PE-53115	RL2445
H220	220 $\mu$ H	77 412	671 27070	PE-53116	RL2446
H330	330 $\mu$ H	77 462	671 27080	PE-53117	RL2447
H470	470 $\mu$ H	*	671 27090	PE-53118	RL1961
H680	680 $\mu$ H	77 508	671 27100	PE-53119	RL1960
H1000	1000 $\mu$ H	77 556	671 27110	PE-53120	RL1959
H1500	1500 $\mu$ H	*	671 27120	PE-53121	RL1958
H2200	2200 $\mu$ H	*	671 27130	PE-53122	RL2448

**Note:** \*Contact Manufacturer

**Table 3. Example of Several Inductor Manufacturers Phone/Fax Numbers**

<b>Pulse Engineering Inc.</b>	Phone Fax	+ 1-619-674-8100 + 1-619-674-8262
<b>Pulse Engineering Inc. Europe</b>	Phone Fax	+ 353-9324-107 + 353-9324-459
<b>Renco Electronics Inc.</b>	Phone Fax	+ 1-516-645-5828 + 1-516-586-5562
<b>Tech 39</b>	Phone Fax	+ 33-1-4115-1681 + 33-1-4709-5051
<b>Schott Corp.</b>	Phone Fax	+ 1-612-475-1173 + 1-612-475-1786

### TC2576

#### EXTERNAL COMPONENTS

##### Input Capacitor ( $C_{IN}$ )

###### The Input Capacitor Should Have a Low ESR

For stable operation of the switch mode converter a low ESR (Equivalent Series Resistance) aluminium or solid tantalum bypass capacitor is needed between the input pin and the ground pin, to prevent large voltage transients from appearing at the input. It must be located near the regulator and use short leads. With most electrolytic capacitors, the capacitance value decreases and the ESR increases with lower temperatures. For reliable operation in temperatures below  $-25^{\circ}\text{C}$  larger values of the input capacitor may be needed. Also paralleling a ceramic or solid tantalum capacitor will increase the regulator stability at cold temperatures.

###### RMS Current Rating of $C_{IN}$

The important parameter of the input capacitor is the RMS current rating. Capacitors that are physically large and have large surface area will typically have higher RMS current ratings. For a given capacitor value, a higher voltage electrolytic capacitor will be physically larger than a lower voltage capacitor, and thus be able to dissipate more heat to the surrounding air, and therefore will have a higher RMS current rating. The consequences of operating an electrolytic capacitor beyond the RMS current rating is a shortened operating life. In order to assure maximum capacitor operating lifetime, the capacitor's RMS ripple current rating should be:

$$I_{RMS} > 1.2 \times d \times I_{LOAD}$$

where  $d$  is the duty cycle, for a buck regulator

$$d = \frac{t_{ON}}{T} = \frac{V_{OUT}}{V_{IN}}$$

$$\text{and } d = \frac{t_{ON}}{T} = \frac{|V_{OUT}|}{|V_{OUT}| + V_{IN}} \text{ for a buck-boost regulator.}$$

##### Output Capacitor ( $C_{OUT}$ )

For low output ripple voltage and good stability, low ESR output capacitors are recommended. An output capacitor has two main functions: it filters the output and provides regulator loop stability. The ESR of the output capacitor and the peak-to-peak value of the inductor ripple current are the main factors contributing to the output ripple voltage value. Standard aluminium electrolytics could be adequate for some applications but for quality design, low ESR types are recommended.

An aluminium electrolytic capacitor's ESR value is related to many factors, such as the capacitance value, the

voltage rating, the physical size and the type of construction. In most cases, the higher voltage electrolytic capacitors have lower ESR value. Often capacitors with much higher voltage ratings may be needed to provide low ESR values, that are required for low output ripple voltage.

###### The Output Capacitor Requires an ESR Value that has an Upper and Lower Limit

As mentioned above, a low ESR value is needed for low output ripple voltage, typically 1% to 2% of the output voltage. But if the selected capacitor's ESR is extremely low (below  $0.05 \Omega$ ), there is a possibility of an unstable feedback loop, resulting in oscillation at the output. This situation can occur when a tantalum capacitor, that can have a very low ESR, is used as the only output capacitor.

###### At Low Temperatures, Put in Parallel Aluminium Electrolytic Capacitors with Tantalum Capacitors

Electrolytic capacitors are not recommended for temperatures below  $-25^{\circ}\text{C}$ . The ESR rises dramatically at cold temperatures and typically rises 3 times at  $-25^{\circ}\text{C}$  and as much as 10 times at  $-40^{\circ}\text{C}$ . Solid tantalum capacitors have much better ESR spec at cold temperatures and are recommended for temperatures below  $-25^{\circ}\text{C}$ . They can be also used in parallel with aluminium electrolytics. The value of the tantalum capacitor should be about 10% or 20% of the total capacitance. The output capacitor should have at least 50% higher RMS ripple current rating at 52kHz than the peak-to-peak inductor ripple current.

##### Catch Diode

###### Locate the Catch Diode Close to the TC2576

The TC2576 is a step-down buck converter, it requires a fast diode to provide a return path for the inductor current when the switch turns off. This diode must be located close to the TC2576 using short leads and short printed circuit traces to avoid EMI problems.

###### Use a Schottky or a Soft Switching Ultra-Fast Recovery Diode

Since the rectifier diodes are very significant source of losses within switching power supplies, choosing the rectifier that best fits into the converter design is an important process. Schottky diodes provide the best performance because of their fast switching speed and low forward voltage drop.

They provide the best efficiency especially in low output voltage applications (5.0 V and lower). Another choice could be Fast-Recovery, or Ultra-Fast Recovery diodes. It has to be noted, that some types of these diodes with an abrupt turnoff characteristic may cause instability or EMI troubles.

A fast-recovery diode with soft recovery characteristics

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can better fulfill some quality, low noise design requirements. Table 1 provides a list of suitable diodes for the TC2576 regulator. Standard 50/60Hz rectifier diodes, such as the 1N4001 series or 1N5400 series are NOT suitable.

### Inductor

The magnetic components are the cornerstone of all switching power supply designs. The style of the core and the winding technique used in the magnetic component's design have a great influence on the reliability of the overall power supply.

Using an improper or poorly designed inductor can cause high voltage spikes generated by the rate of transitions in current within the switching power supply, and the possibility of core saturation can arise during an abnormal operational mode. Voltage spikes can cause the semiconductors to enter avalanche breakdown and the part can instantly fail if enough energy is applied. It can also cause significant RFI (Radio Frequency Interference) and EMI (Electro-Magnetic Interference) problems.

### Continuous and Discontinuous Mode of Operation.

The TC2576 step-down converter can operate in both the continuous and the discontinuous modes of operation. The regulator works in the continuous mode when loads are relatively heavy, the current flows through the inductor continuously and never falls to zero. Under light load conditions, the circuit will be forced to the discontinuous mode when inductor current falls to zero for certain period of time (see Figure 5 and Figure 6). Each mode has distinctively different operating characteristics, which can affect the regulator performance and requirements. In many cases the preferred mode of operation is the continuous mode. It offers greater output power, lower peak currents in the switch,

inductor and diode, and can have a lower output ripple voltage. On the other hand it does require larger inductor values to keep the inductor current flowing continuously, especially at low output load currents and/or high input voltages.

To simplify the inductor selection process, an inductor selection guide for the TC2576 regulator was added to this data sheet (Figures 36 through 40). This guide assumes that the regulator is operating in the continuous mode, and selects an inductor that will allow a peak-to-peak inductor ripple current to be a certain percentage of the maximum design load current. This percentage is allowed to change as different design load currents are selected. For light loads (less than approximately 300mA) it may be desirable to operate the regulator in the discontinuous mode, because the inductor value and size can be kept relatively low. Consequently, the percentage of inductor peak-to-peak current increases. This discontinuous mode of operation is perfectly acceptable for this type of switching converter. Any buck regulator will be forced to enter discontinuous mode if the load current is light enough.

### Selecting the Right Inductor Style

Some important considerations when selecting a core type are core material, cost, the output power of the power supply, the physical volume the inductor must fit within, and the amount of EMI (Electro-Magnetic Interference) shielding that the core must provide. The inductor selection guide covers different styles of inductors such as pot core, E-core, toroid and bobbin core, as well as different core materials such as ferrites and powdered iron from different manufacturers.

For high quality design regulators the toroid core seems to be the best choice. Since the magnetic flux is contained within the core, it generates less EMI, reducing noise prob-

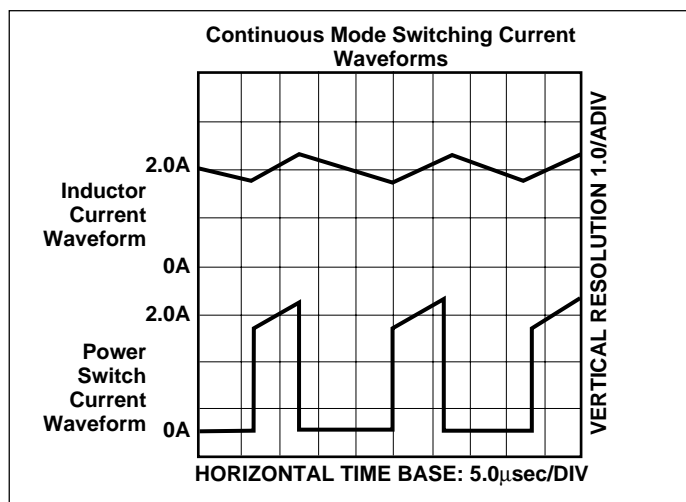


Figure 5. Continuous Mode Switching Current Waveforms

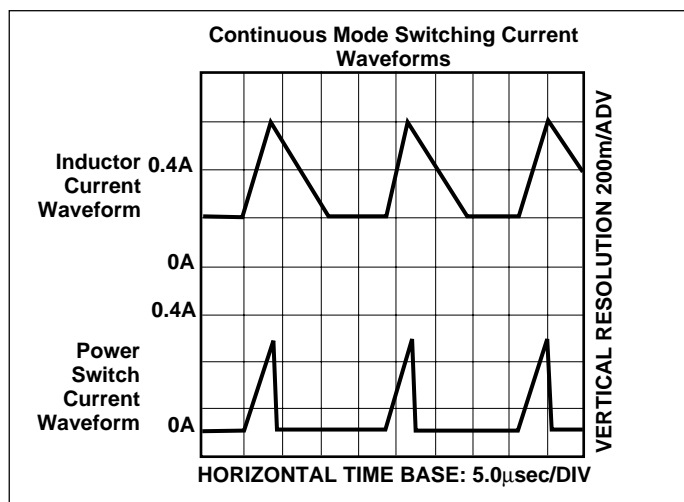


Figure 6. Discontinuous Mode Switching Current Waveforms

### TC2576

lems in sensitive circuits. The least expensive is the bobbin core type, which consists of wire wound on a ferrite rod core. This type of inductor generates more EMI due to the fact that its core is open, and the magnetic flux is not contained within the core.

When multiple switching regulators are located on the same printed circuit board, open core magnetics can cause interference between two or more of the regulator circuits, especially at high currents due to mutual coupling. A toroid, pot core or E-core (closed magnetic structure) should be used in such applications.

### Do Not Operate an Inductor Beyond its Maximum Rated Current

Exceeding an inductor's maximum current rating may cause the inductor to overheat because of the copper wire losses, or the core may saturate. Core saturation occurs when the flux density is too high and consequently the cross sectional area of the core can no longer support additional lines of magnetic flux.

This causes the permeability of the core to drop, the inductance value decreases rapidly and the inductor begins to look mainly resistive. It has only the DC resistance of the winding. This can cause the switch current to rise very rapidly and force the TC2576 internal switch into cycle-by-cycle current limit, thus reducing the DC output load current. This can also result in overheating of the inductor and/or the TC2576. Different inductor types have different saturation characteristics, and this should be kept in mind when selecting an inductor.

## GENERAL RECOMMENDATIONS

### Output Voltage Ripple and Transients Source of the Output Ripple

Since the TC2576 is a switch mode power supply regulator, its output voltage, if left unfiltered, will contain a sawtooth ripple voltage at the switching frequency. The output ripple voltage value ranges from 0.5% to 3% of the output voltage. It is caused mainly by the inductor sawtooth ripple current multiplied by the ESR of the output capacitor.

### Short Voltage Spikes and How to Reduce Them

The regulator output voltage may also contain short voltage spikes at the peaks of the sawtooth waveform (see Figure 7). These voltage spikes are present because of the fast switching action of the output switch, and the parasitic inductance of the output filter capacitor. There are some other important factors such as wiring inductance, stray capacitance, as well as the scope probe used to evaluate these transients, all these contribute to the amplitude of

these spikes. To minimize these voltage spikes, low inductance capacitors should be used, and their lead lengths must be kept short. The importance of quality printed circuit board layout design should also be highlighted.

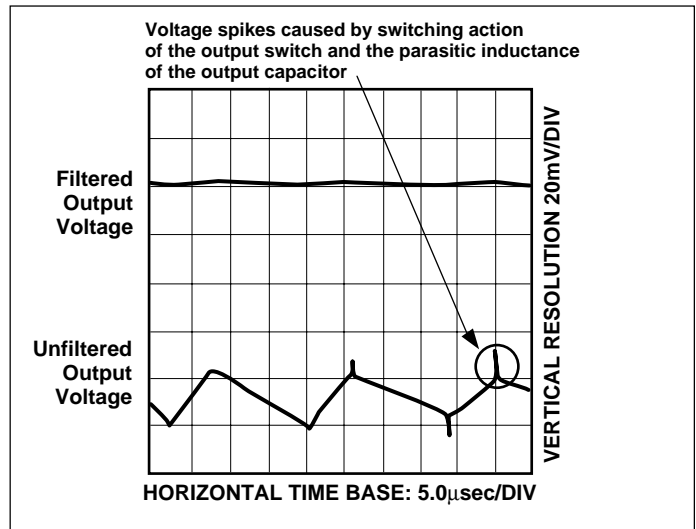


Figure 7. Output Ripple Voltage Waveforms

### Minimizing the Output Ripple

In order to minimize the output ripple voltage it is possible to enlarge the inductance value of the inductor L1 and/or to use a larger value output capacitor. There is also another way to smooth the output by means of an additional LC filter (20 $\mu$ H, 100 $\mu$ F), that can be added to the output (see Figure 16) to further reduce the amount of output ripple and transients. With such a filter it is possible to reduce the output ripple voltage transients 10 times or more. Figure 7 shows the difference between filtered and unfiltered output waveforms of the regulator shown in Figure 16.

The upper waveform is from the normal unfiltered output of the converter, while the lower waveform shows the output ripple voltage filtered by an additional LC filter.

## Heatsinking and Thermal Considerations

### The Through-Hole-Package

The TC2576 is available in a 5-Pin TO-220 package. Although the TO-220 packages need a heatsink under most conditions, there are some applications that require no heatsink to keep the TC2576 junction temperature within the allowed operating range. Higher ambient temperatures require some heat sinking, either to the printed circuit (PC) board or an external heatsink.



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### Thermal Analysis and Design

The following procedure must be performed to determine whether or not a heatsink will be required. First determine:

1.  $P_{D(max)}$  – maximum regulator power dissipation in the application.
2.  $T_{A(max)}$  – maximum ambient temperature in the application.
3.  $T_{J(max)}$  – maximum allowed junction temperature (125°C for the TC2576). For a conservative design, the maximum junction temperature should not exceed 110°C to assure safe operation. For every additional +10°C temperature rise that the junction must withstand, the estimated operating lifetime of the component is halved.
4.  $\Theta_{JC}$  – package thermal resistance junction–case.
5.  $\Theta_{JA}$  – package thermal resistance junction–ambient.

(Refer to Absolute Maximum Ratings on page 2 of this data sheet or  $\Theta_{JC}$  and  $\Theta_{JA}$  values).

The following formula is to calculate the approximate total power dissipated by the TC2576:

$$P_D = (V_{IN} \times I_Q) + d \times I_{LOAD} \times V_{SAT}$$

where d is the duty cycle and for buck converter

$$d = \frac{t_{ON}}{T} = \frac{V_O}{V_{IN}}$$

$I_Q$  (quiescent current) and  $V_{SAT}$  can be found in the TC2576 data sheet,

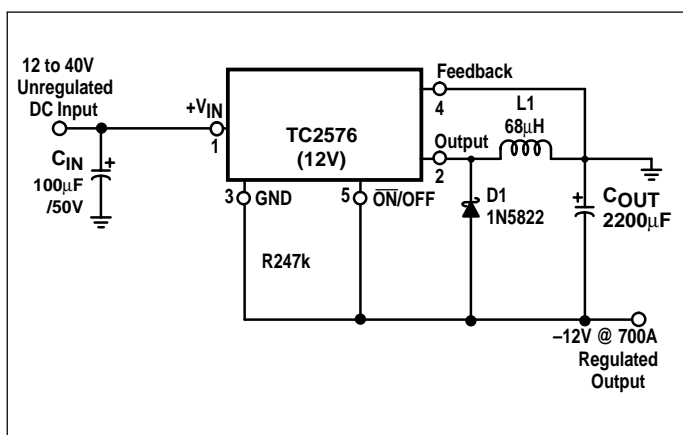


Figure 8. Inverting Buck-Boost Develops (12V)

$V_{IN}$  is minimum input voltage applied,  
 $V_O$  is the regulator output voltage,  
 $I_{LOAD}$  is the load current.

The dynamic switching losses during turn–on and turn–off can be neglected if a proper type catch diode is used.

### Packages (Free–Standing)

For a free-standing application when no heatsink is used, the junction temperature can be determined by the following expression:

$$T_J = (\Theta_{JA}) (P_D) + T_A$$

where  $(\Theta_{JA}) (P_D)$  represents the junction temperature rise caused by the dissipated power and  $T_A$  is the maximum ambient temperature.

### Some Aspects That can Influence Thermal Design

It should be noted that the package thermal resistance and the junction temperature rise numbers are all approximate, and there are many factors that will affect these numbers, such as PC board size, shape, thickness, physical position, location, board temperature, as well as whether the surrounding air is moving or still.

Other factors are trace width, total printed circuit copper area, copper thickness, single– or double–sided, multilayer board, the amount of solder on the board or even color of the traces.

The size, quantity and spacing of other components on the board can also influence its effectiveness to dissipate the heat.

## ADDITIONAL APPLICATIONS

### Inverting Regulator

An inverting buck–boost regulator using the TC2576 (12V) is shown in Figure 8. This circuit converts a positive input voltage to a negative output voltage with a common ground by bootstrapping the regulators ground to the negative output voltage. By grounding the feedback pin, the regulator senses the inverted output voltage and regulates it.

In this example the TC2576 (12V) is used to generate a –12V output. The maximum input voltage in this case cannot exceed 28V because the maximum voltage appearing across the regulator is the absolute sum of the input and output voltages and this must be limited to a maximum of 40V.



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This circuit configuration is able to deliver approximately 0.7 A to the output when the input voltage is 12V or higher. At lighter loads the minimum input voltage required drops to approximately 4.7V, because the buck-boost regulator topology can produce an output voltage that, in its absolute value, is either greater or less than the input voltage.

Since the switch currents in this buck-boost configuration are higher than in the standard buck converter topology, the available output current is lower.

This type of buck-boost inverting regulator can also require a larger amount of startup input current, even for light loads. This may overload an input power source with a current limit less than 5.0A.

Such an amount of input start-up current is needed for at least 2.0msec or more. The actual time depends on the output voltage and size of the output capacitor.

Because of the relatively high startup currents required by this inverting regulator topology, the use of a delayed startup or an undervoltage lockout circuit is recommended.

Using a delayed startup arrangement, the input capacitor can charge up to a higher voltage before the switch-mode regulator begins to operate.

The high input current needed for startup is now partially supplied by the input capacitor  $C_{IN}$ .

It has been already mentioned above, that in some situations, the delayed start-up or the undervoltage lockout features could be very useful. A delayed start-up circuit applied to a buck-boost converter is shown in Figure 9, Figure 15 in the "Undervoltage Lockout" section describes an undervoltage lockout feature for the same converter topology.

## Design Recommendations

The inverting regulator operates in a different manner than the buck converter and so a different design procedure has to be used to select the inductor  $L1$  or the output capacitor  $C_{OUT}$ .

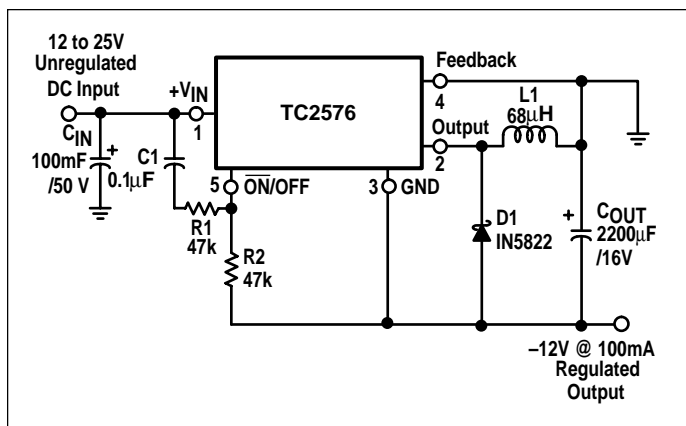


Figure 9. Inverting Buck-Boost Regulator with Delayed Startup

The output capacitor values must be larger than what is normally required for buck converter designs. Low input voltages or high output currents require a large value output capacitor (in the range of thousands of  $\mu F$ ).

The recommended range of inductor values for the inverting converter design is between 68 $\mu H$  and 220  $\mu H$ . To select an inductor with an appropriate current rating, the inductor peak current has to be calculated.

The following formula is used to obtain the peak inductor current:

$$I_{PEAK} \approx \frac{I_{LOAD} (V_{IN} - |V_{OUT}|)}{V_{IN}} + \frac{V_{IN} \times t_{ON}}{2L_1}$$

where  $t_{ON} \approx \frac{|V_{OUT}|}{V_{IN} + |V_{OUT}|} \times \frac{1.0}{f_{OSC}}$ , and  $f_{OSC} = 52kHz$ .

Under normal continuous inductor current operating conditions, the worst case occurs when  $V_{IN}$  is minimal.

With the inverting configuration, the use of the  $\overline{ON/OFF}$  pin requires some level shifting techniques. This is caused by the fact, that the ground pin of the converter IC is no longer at ground. Now, the  $\overline{ON/OFF}$  pin threshold voltage (1.3V approximately) has to be related to the negative output voltage level. There are many different possible shutdown methods, two of them are shown in Figures 10 and 11.

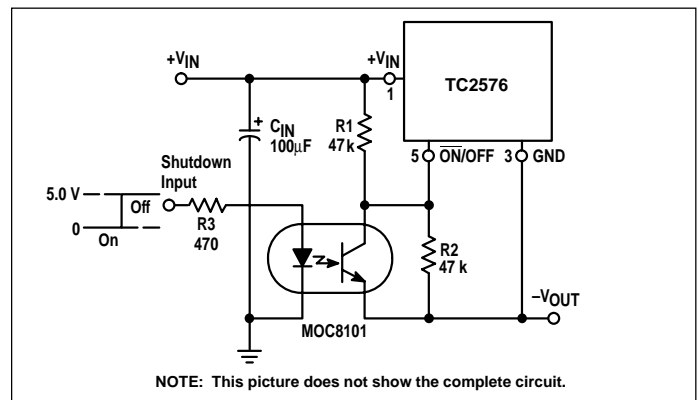


Figure 10. Inverting Buck-Boost Regulator Shutdown Circuit Using an Optocoupler

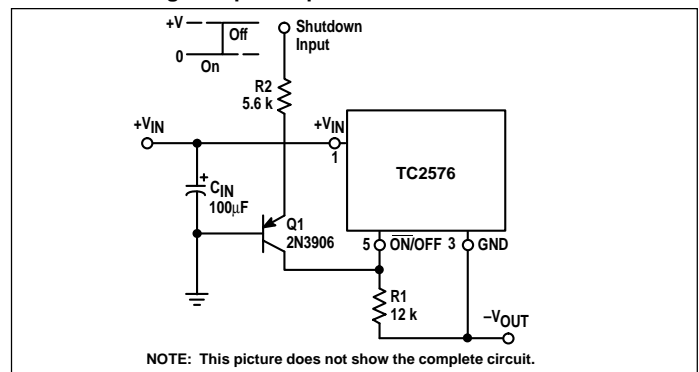


Figure 11. Inverting Buck-Boost Regulator Shutdown Circuit Using a PNP Transistor

## 3.0A Step-Down Switching Regulator

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### Negative Boost Regulator

This example is a variation of the buck–boost topology and it is called negative boost regulator. This regulator experiences relatively high switch current, especially at low input voltages. The internal switch current limiting results in lower output load current capability.

The circuit in Figure 12 shows the negative boost configuration. The input voltage in this application ranges from  $-5.0$  to  $-12\text{V}$  and provides a regulated  $-12\text{V}$  output. If the input voltage is greater than  $-12\text{V}$ , the output will rise above  $-12\text{V}$  accordingly, but will not damage the regulator.

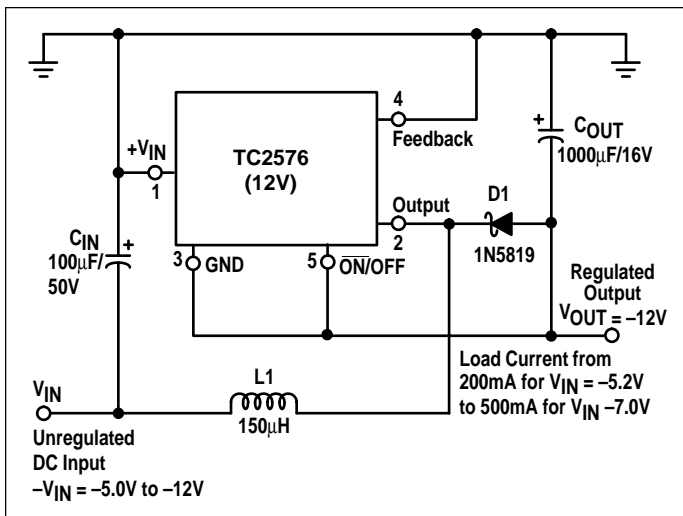


Figure 12. Negative Boost Regulator

### Design Recommendations

The same design rules as for the previous inverting buck–boost converter can be applied. The output capacitor  $C_{OUT}$  must be chosen larger than what would be required for a standard buck converter. Low input voltages or high output currents require a large value output capacitor (in the range of thousands of  $\mu\text{F}$ ). The recommended range of inductor values for the negative boost regulator is the same as for inverting converter design.

Another important point is that these negative boost converters cannot provide any current limiting load protection in the event of a short in the output so some other means, such as a fuse, may be necessary to provide the load protection.

### Delayed Startup

There are some applications, like the inverting regulator already mentioned above, which require a higher amount of start-up current. In such cases, if the input power source is limited, this delayed start-up feature becomes very useful.

To provide a time delay between the time when the input

voltage is applied and the time when the output voltage comes up, the circuit in Figure 13 can be used. As the input voltage is applied, the capacitor  $C_1$  charges up, and the voltage across the resistor  $R_2$  falls down. When the voltage on the ON/OFF pin falls below the threshold value  $1.3\text{V}$ , the regulator starts up. Resistor  $R_1$  is included to limit the maximum voltage applied to the ON/OFF pin. It reduces the power supply noise sensitivity, and also limits the capacitor  $C_1$  discharge current, but its use is not mandatory.

When a high  $50\text{Hz}$  or  $60\text{Hz}$  ( $100\text{Hz}$  or  $120\text{Hz}$  respectively) ripple voltage exists, a long delay time can cause some problems by coupling the ripple into the ON/OFF pin, the regulator could be switched periodically on and off with the line (or double) frequency.

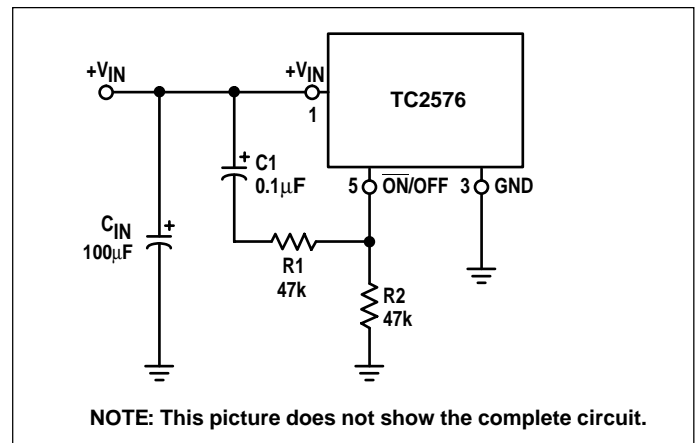


Figure 13. Delayed Startup Circuitry

### Undervoltage Lockout

Some applications require the regulator to remain off until the input voltage reaches a certain threshold level. Figure 14 shows an undervoltage lockout circuit applied to a buck regulator. A version of this circuit for buck–boost converter is shown in Figure 15. Resistor  $R_3$  pulls the ON/OFF pin high and keeps the regulator off until the input voltage reaches a predetermined threshold level, with respect to the ground Pin 3, which is determined by the following expression:

$$V_{TH} \approx V_{Z1} + \left(1.0 + \frac{R_2}{R_1}\right) V_{BE} (Q1)$$

The following formula is used to obtain the peak inductor current:

$$I_{PEAK} \approx \frac{I_{LOAD} (V_{IN} + |V_{OUT}|)}{V_{IN}} + \frac{V_{IN} \times t_{ON}}{2L_1}$$

$$\text{where } t_{ON} \approx \frac{|V_{OUT}|}{V_{IN} + |V_{OUT}|} \times \frac{1.0}{f_{OSC}}, \text{ and } f_{OSC} = 52\text{kHz}.$$

## TC2576

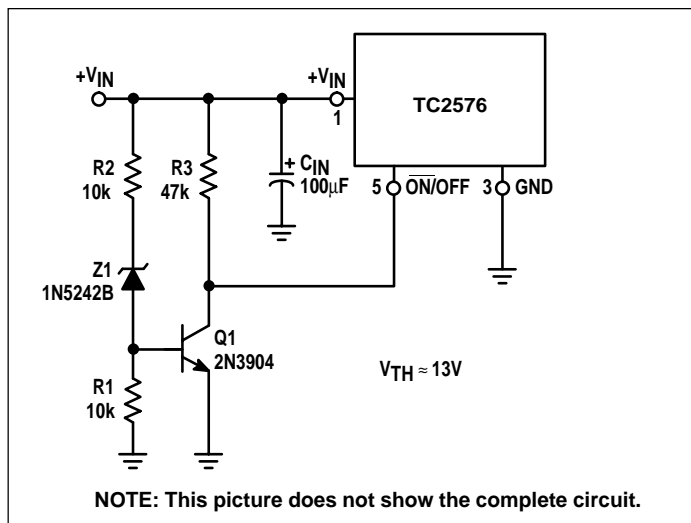


Figure 14. Undervoltage Lockout Circuit for Buck Converter

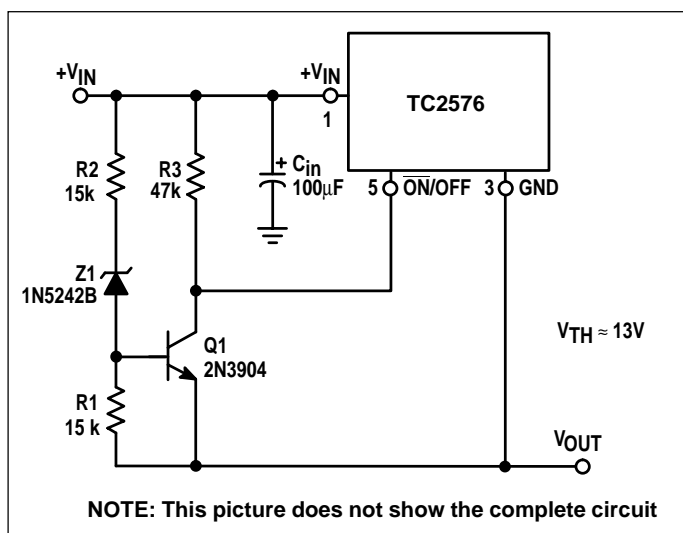


Figure 15. Undervoltage Lockout Circuit for Buck-Boost Converter

## Adjustable Output, Low-Ripple Power Supply

A 3.0 A output current capability power supply that features an adjustable output voltage is shown in Figure 16. This regulator delivers 3.0A into 1.2 to 35V output. The input voltage ranges from roughly 3.0 to 40V. In order to achieve a 10 or more times reduction of output ripple, an additional L-C filter is included in this circuit.

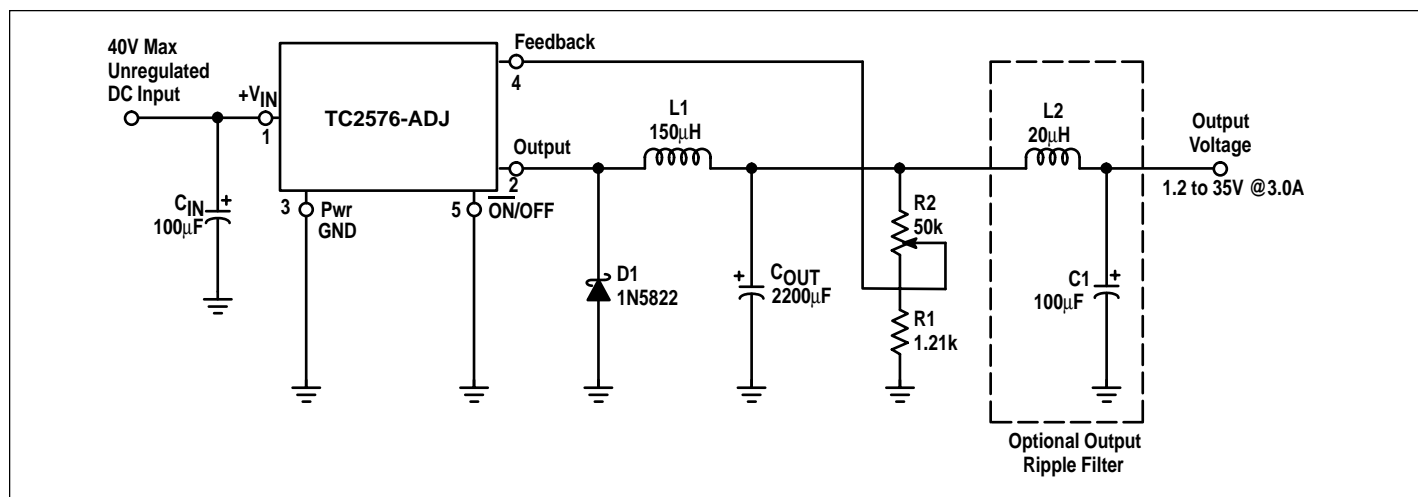


Figure 16. 1.2 to 35V Adjustable 3.0A Power Supply with Low Output Ripple

### 3.0A Step-Down Switching Regulator

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The TC2576 Step-Down Voltage Regulator with 5.0V @ 3.0A Output Power Capability.  
Typical Application with Through-Hole PC Board Layout

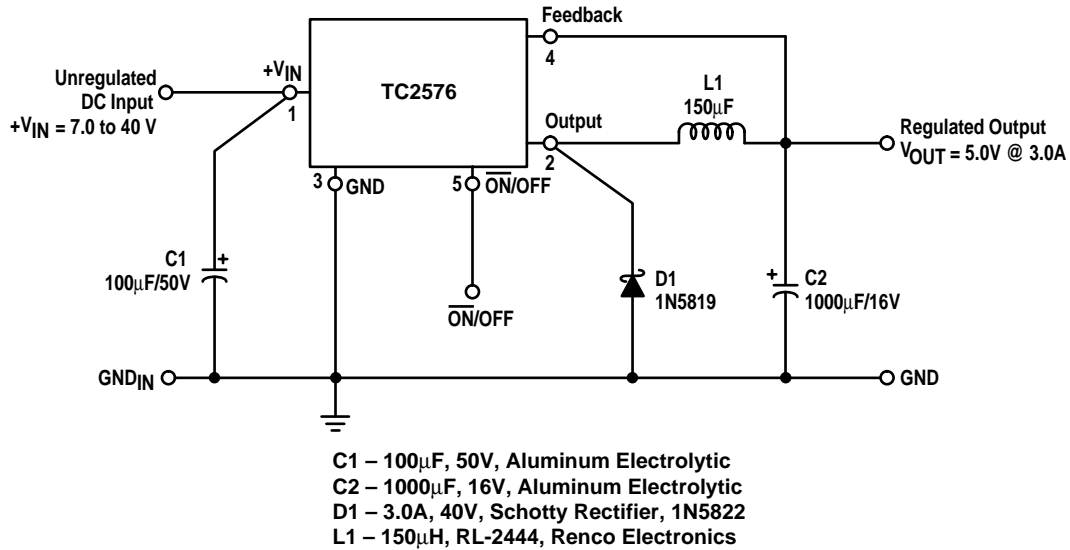


Figure 17. Schematic Diagram of the TC2576 (5V) Step-Down Converter

The TC2576-ADJ Step-Down Voltage Regulator with 8.0V @ 1.0A Output Power Capability.  
Typical Application with Through-Hole PC Board Layout

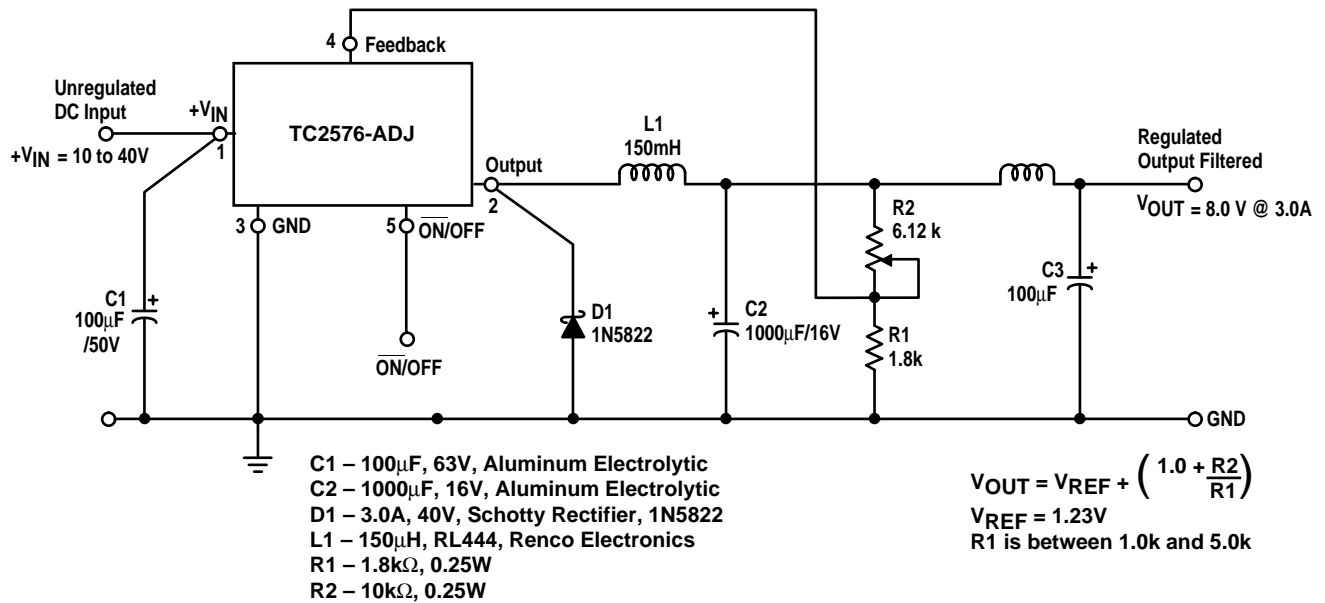


Figure 18. Schematic Diagram of the 8.0V @ 3.0A Step-Down Converter Using the TC2576-ADJ

TC2576

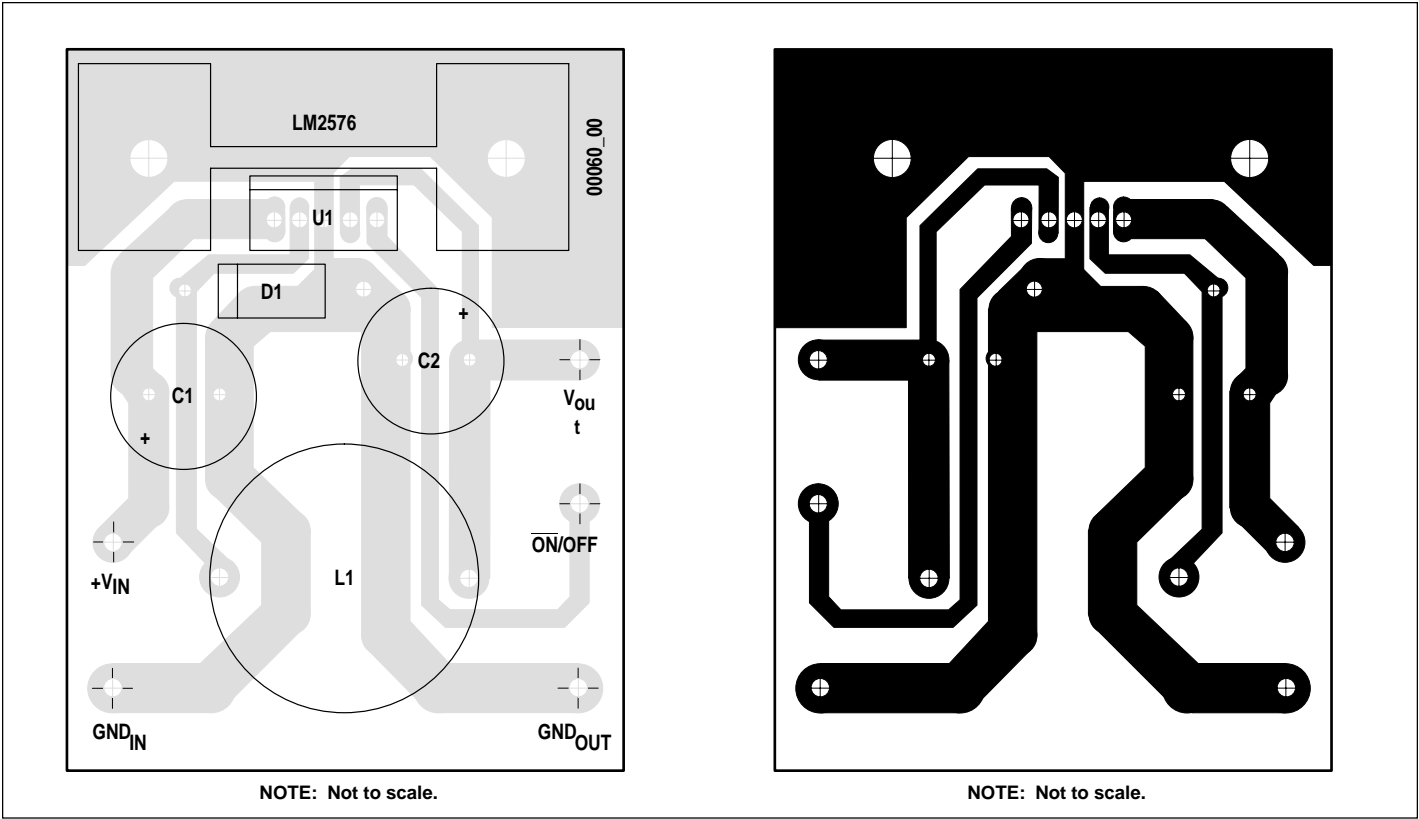


Figure 19. Printed Circuit Board Component Side

Figure 20. Circuit Board Copper Side

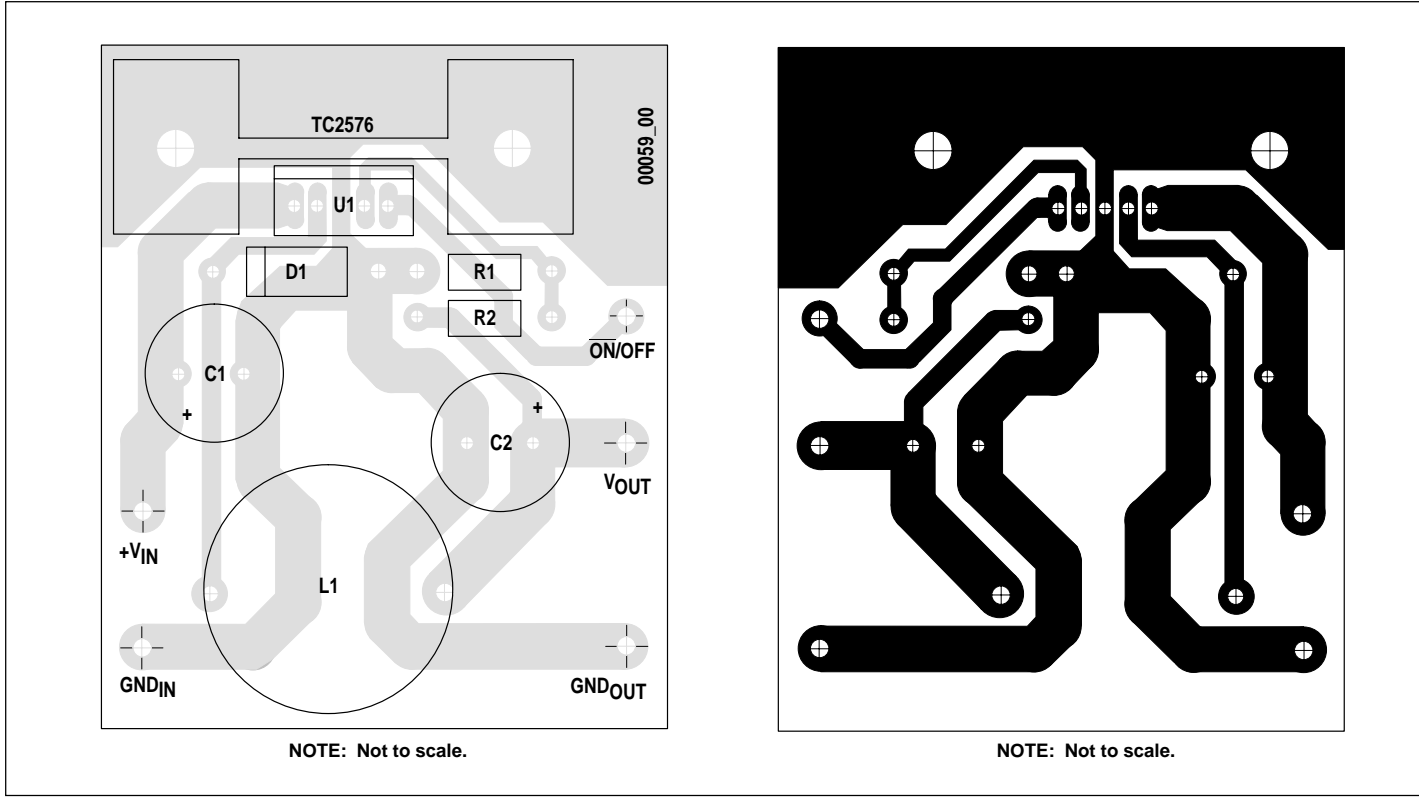


Figure 21. Printed Circuit Board Component Side

Figure 22. Circuit Board Copper Side

### 3.0A Step-Down Switching Regulator

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#### TYPICAL CHARACTERISTICS (Circuit of Figure 2)

Figure 23. Normalized Output Voltage

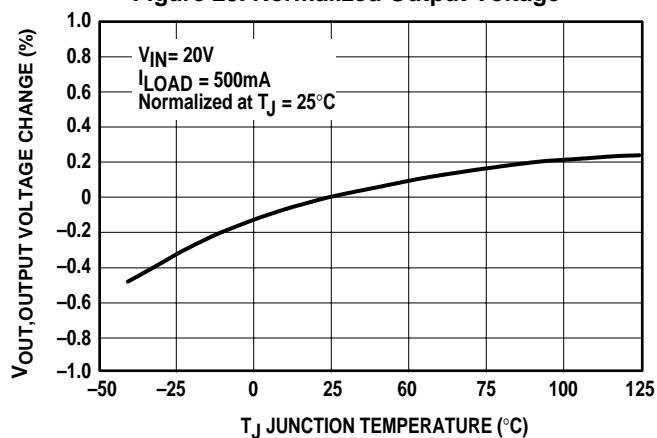


Figure 24. Line Regulation

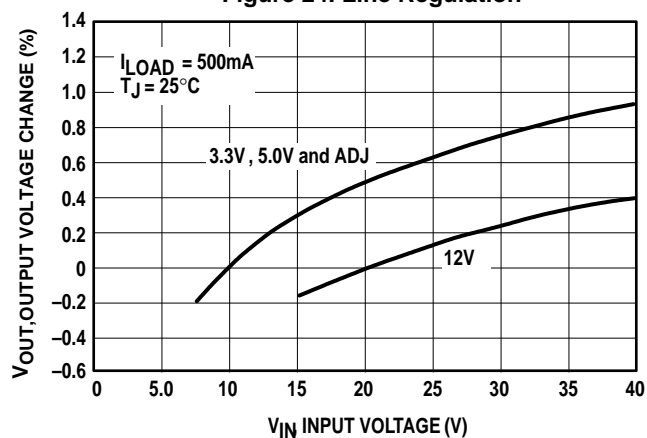


Figure 25. Dropout Voltage

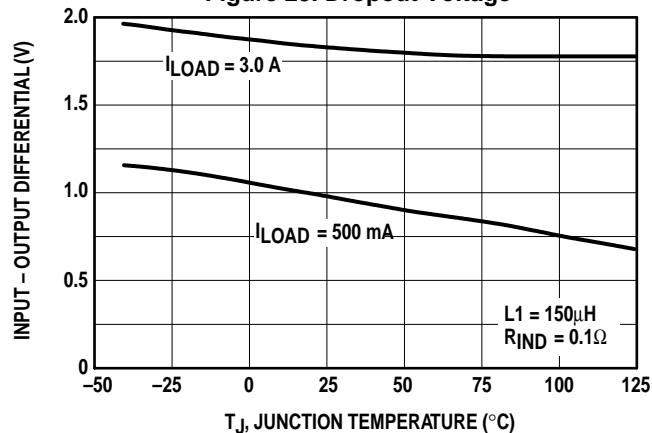


Figure 26. Current Limit

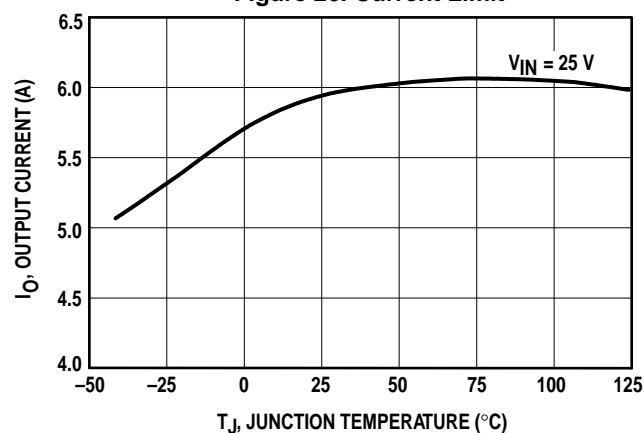


Figure 27. Quiescent Current

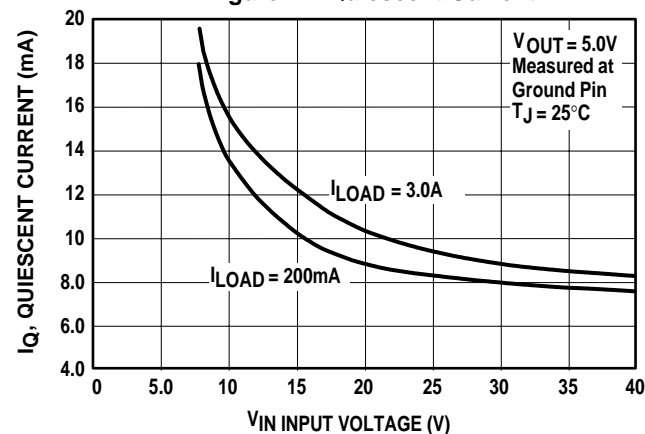
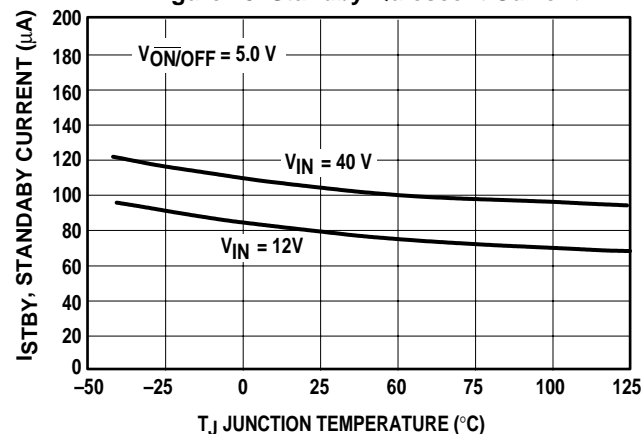


Figure 28. Standby Quiescent Current



## TC2576

### TYPICAL CHARACTERISTICS (Circuit of Figure 2 Cont.)

Figure 29. Standby Quiescent Current

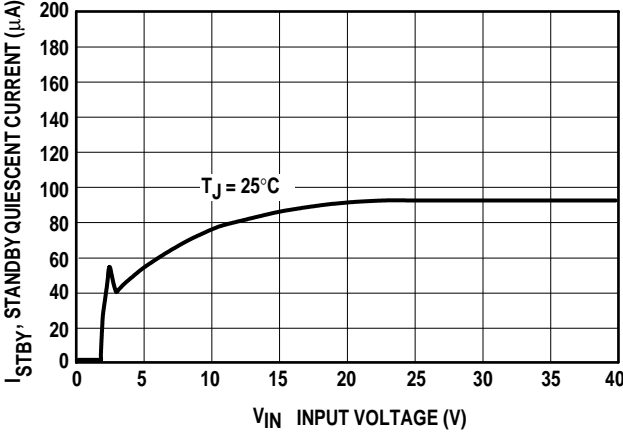


Figure 30. Switch Saturation Voltage

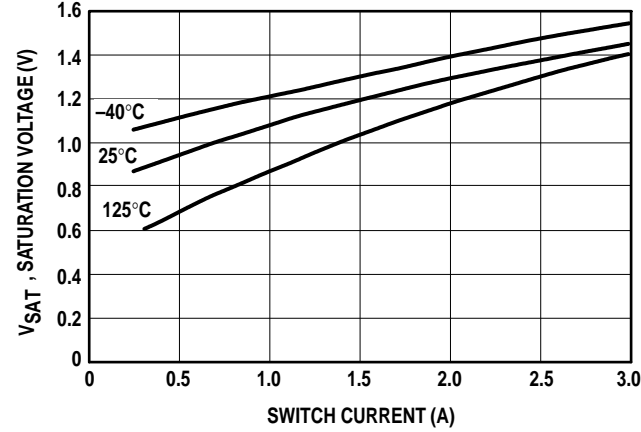


Figure 31. Oscillator Frequency

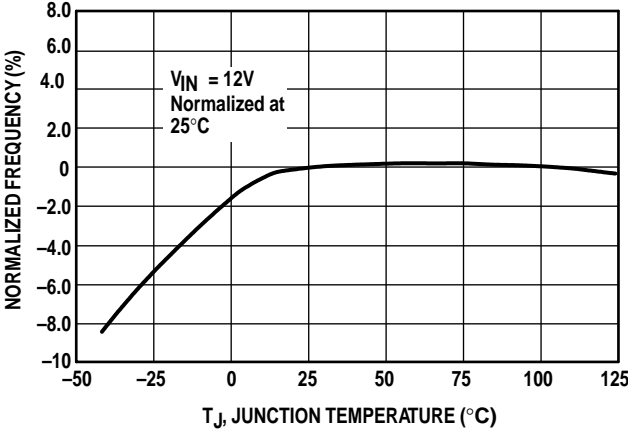


Figure 32. Minimum Operating Voltage

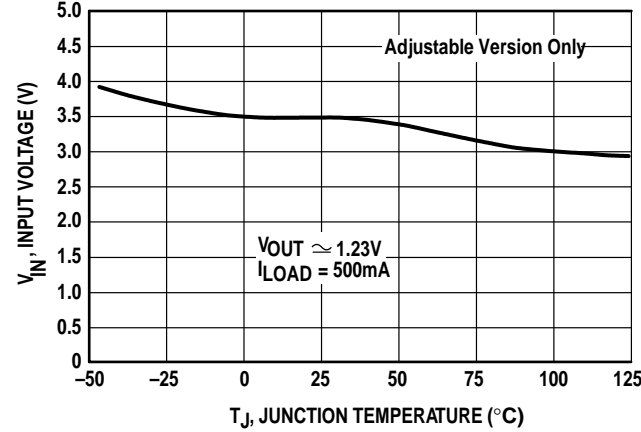
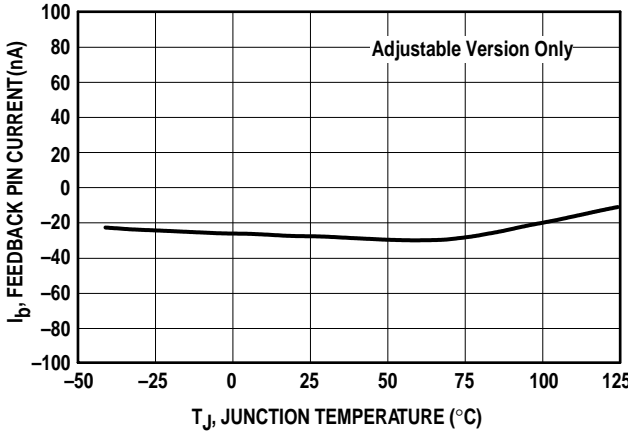


Figure 33. Feedback Pin Current

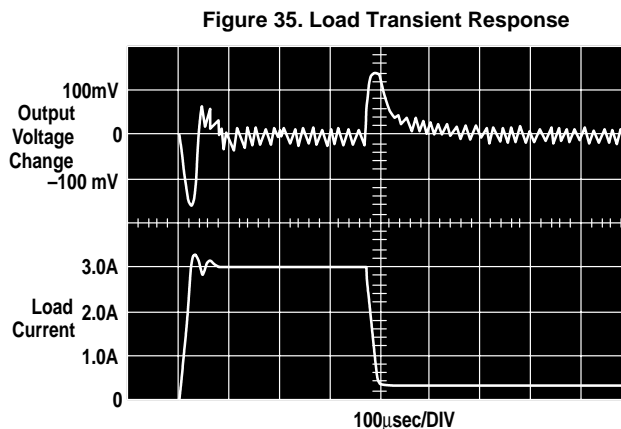
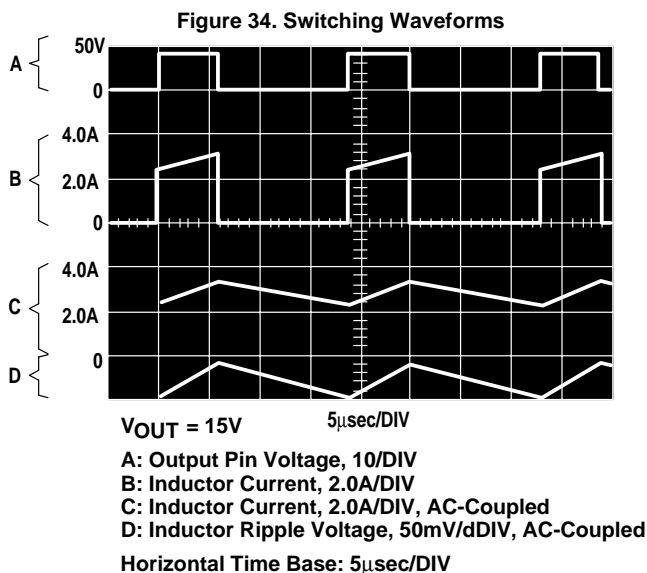




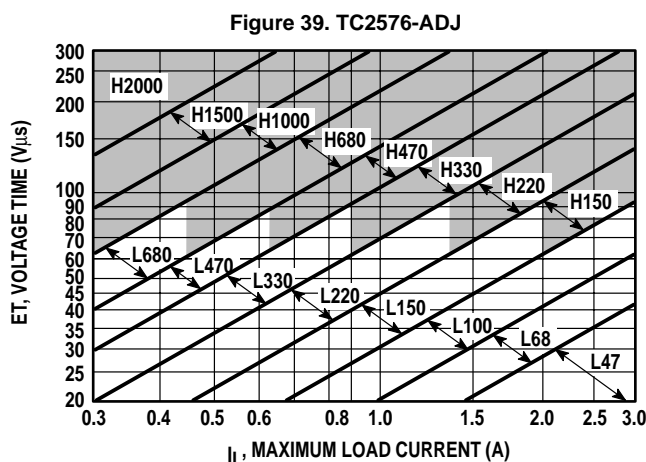
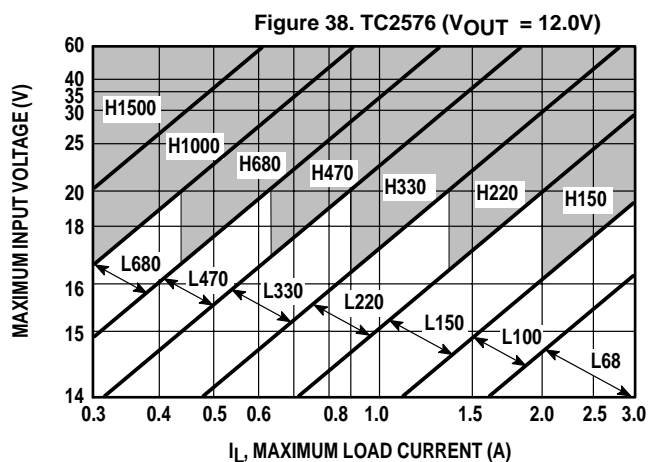
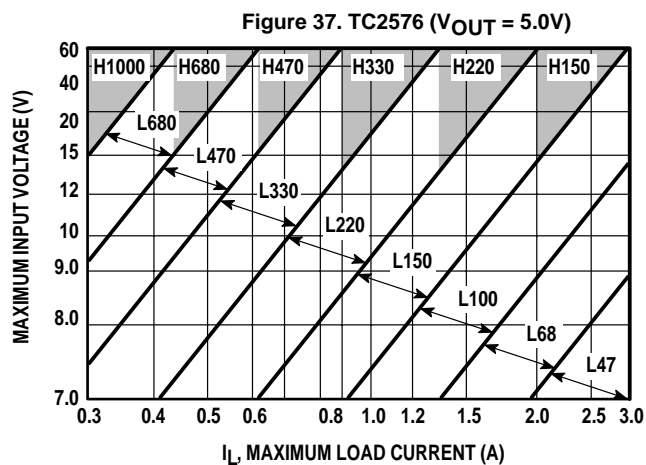
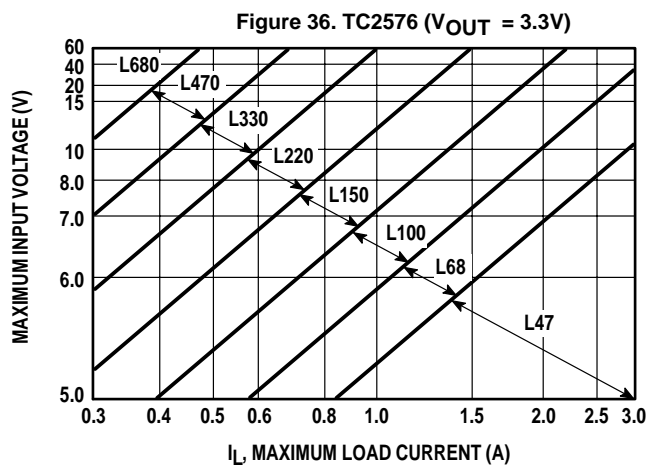
### 3.0A Step-Down Switching Regulator

TC2576

#### TYPICAL CHARACTERISTICS (Circuit of Figure 2 Cont.)



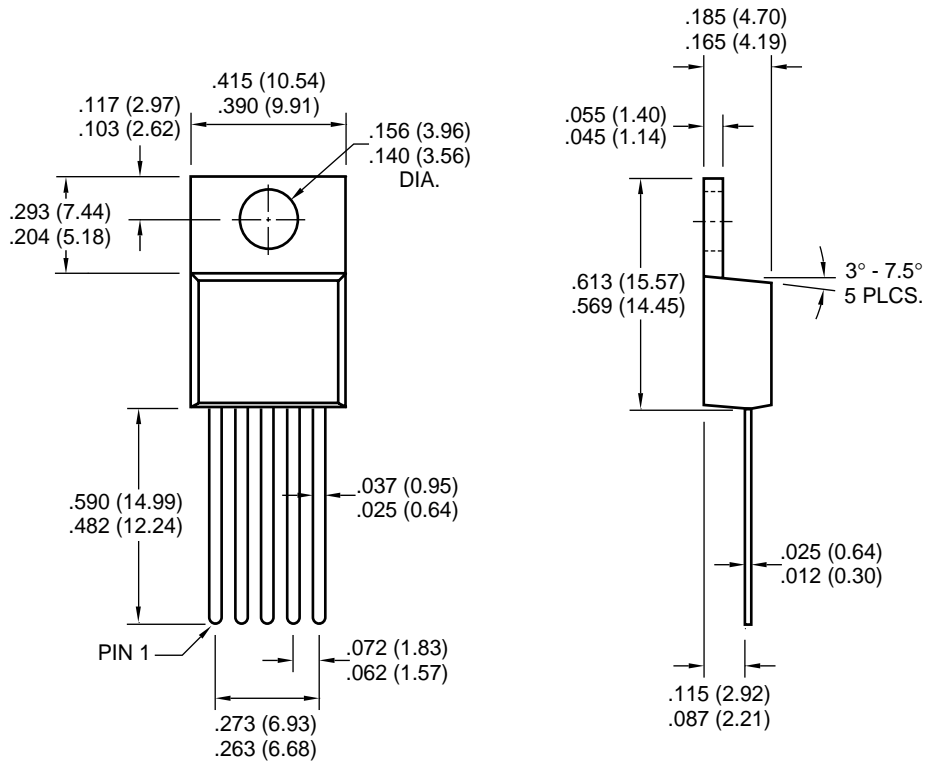
#### TC2576 Series Buck Regulator Design Procedures (Cont.) Indicator Value Selection Guide (For Continuous Mode Operation)



**TC2576**

## PACKAGE DIMENSIONS

## 5-Pin TO-220



Dimensions: inches (mm)



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