16M LVTTL interface SGRAM 125 MHz/100 MHz/83 MHz 256-kword × 32-bit × 2-bank

HITACHI

ADE-203-678E (Z) Rev. 2.0 Oct. 2, 1998

Description

All inputs and outputs signals refers to the rising edge of the clock input. The HM5216326 provides 2 banks to realize better performance. 8 column block write function and write per bit function are provided for graphic applications.

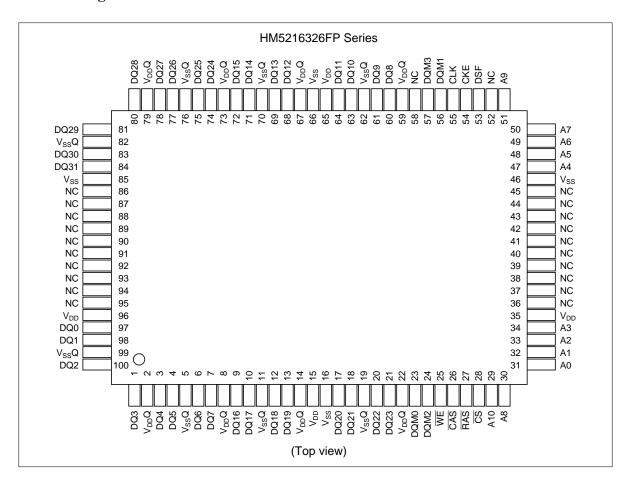
Features

- 3.3V Power supply
- Clock frequency: 125 MHz/100 MHz/83 MHz (max)
- LVTTL interface
- 2 banks can operates simultaneously and independently
- Burst read/write operation and burst read/ single write operation capability
- Programmable burst length: 1/2/4/8/full page
- 2 variations of burst sequence
 - Sequential (BL = 1/2/4/8/full page)
 - Interleave (BL = 1/2/4/8)
- Programmable CAS latency: 1/2/3
- Byte control by DQM
- 8 column block write function with column address mask
- Write per bit function (old mask)
- Refresh cycles: 2048 refresh cycle/32 ms
- 2 variations of refresh
 - Auto refresh
 - Self refresh

Ordering Information

Type No.	Frequency	Package
HM5216326FP-8	125 MHz	100-pin plastic TQFP (TFP-100H)
HM5216326FP-10	100 MHz	
HM5216326FP-12	83 MHz	

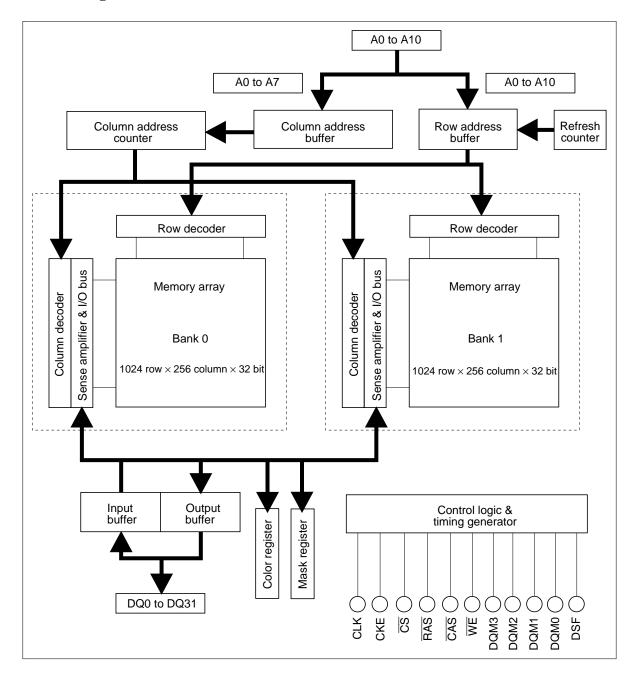
Pin Arrangement



Pin Description

Pin name	Function		
A0 to A10	Address input		
	Row address A0 to A9		
	Column address A0 to A7		
	Bank select address (BS) A10		
DQ0 to DQ31	Data-input/output		
CS	Chip select		
RAS	Row address asserted bank enable		
CAS	Column address asserted		
WE	Write enable		
DQM0 to DQM3	Byte input/output mask		
CLK	Clock input		
CKE	Clock enable		
V_{DD}	Power for internal circuit		
$\overline{V_{ss}}$	Ground for internal circuit		
$\overline{V_{DD}Q}$	Power for DQ internal circuit		
V _{ss} Q	Ground for DQ internal circuit		
DSF	Special function input flag		
NC	No connection		

Block Diagram



Pin Functions

CLK (**input pin**): CLK is the master clock input pin. The other input signals are referred at CLK rising edge.

 $\overline{\text{CS}}$ (input pin): When $\overline{\text{CS}}$ is Low, the command input cycle becomes valid. When $\overline{\text{CS}}$ is High, all inputs are ignored. However, internal operations (bank active, burst operations, etc.) are held.

 \overline{RAS} , \overline{CAS} , and \overline{WE} (input pins): These pins define operation commands (read, write, etc.) depending on the combination of their voltage levels. For details, refer to the command operation section.

DSF (**input pin**): DSF is a part of inputs of graphic commands of the HM5216326. If DSF is LOW, the HM5216326 operates as standard synchronous DRAM.

A0 to A9 (input pins): Row address (AX0 to AX9) is determined by A0 to A9 pins at the CLK rising edge when a bank active command is input. Column address (AY0 to AY7) is determined by levels on A0 to A7 pins at the CLK rising edge when a read or write command is input. A9 determines precharge mode. When A9 is low, only the bank selected by A10 (BS) is precharged by a precharge command. When A9 is high, both banks are precharged by a precharge command.

A10 (input pin): A10 is the bank select signal (BS). The memory array of the HM5216326 is divided into the bank 0 and the bank 1, both contain $1024 \text{ row} \times 256 \text{ column} \times 32 \text{ bits}$. If A10 is Low, the bank 0 is selected, and if A10 is High, the bank 1 is selected.

CKE (input pin): By referring low level on CKE pin, HM5216326 determines to go into clock suspend modes or power down modes. When refresh command is input, low level on this pin is also referred to turn on self refresh process.

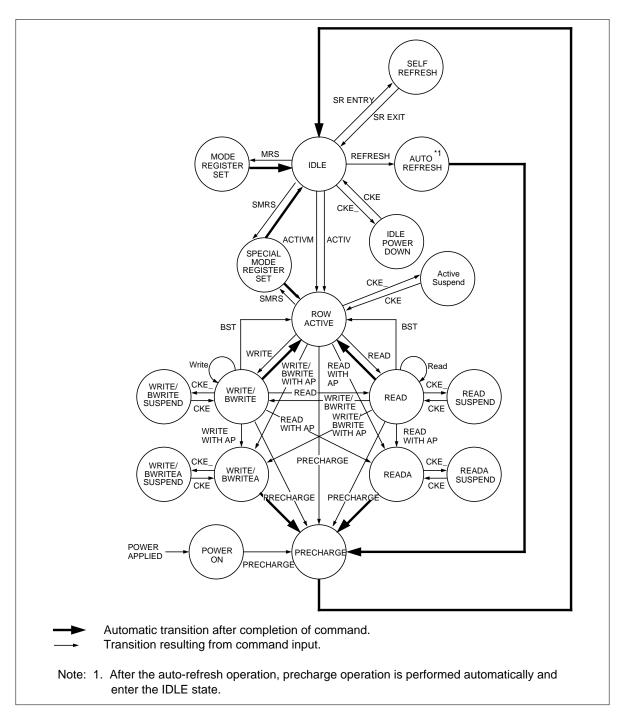
DQM0, DQM1, DQM2 and DQM3 (input pins): DQM0 applies to DQ0 to DQ7. DQM1 applies to DQ8 to DQ15. DQM2 applies to DQ16 to DQ23. DQM3 applies to DQ24 to DQ31. In read mode, referring high level on DQM pins, HM5216326 floats related DQ pins. In write mode, referring high level on DQM pins, HM5216326 ignores input data through related DQ pins.

DQ0 to DQ31 (input/output): These are the data line for the HM5216326.

 V_{DD} and $V_{DD}Q$ (power supply pins): 3.3 V is applied. (V_{DD} is for the internal circuit and $V_{DD}Q$ is power supply pin for DQ output buffer.)

 V_{ss} and $V_{ss}Q$ (power supply pins): Ground is connected. (V_{ss} is for the internal circuit and $V_{ss}Q$ is for DQ output buffer.)

Simplified State Diagram



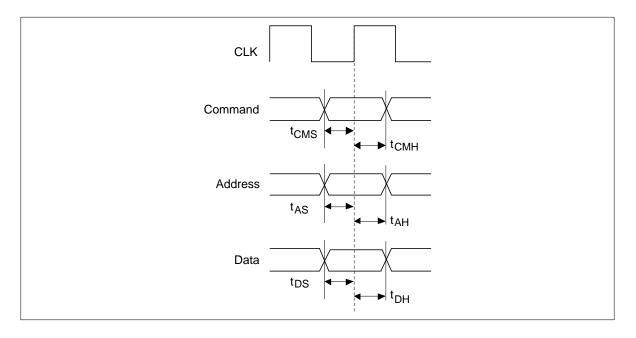
Commands Operation

Commands Explanation

Every operations of HM5216326 are executed by input commands. A command is input, at the rising edge of CLK, by setting the levels on $\overline{\text{CS}}$, $\overline{\text{RAS}}$, $\overline{\text{CAS}}$, $\overline{\text{WE}}$, A9 (precharge control) and DSF pins, HIGH (V_{II}) or LOW (V_{IL}).

Note: The setup and hold condition should be obeyed when command, address or data is input.

Setup and Hold Condition of Command, Address and Data Input



Precharge command [PRE, PALL]: At the CLK rising edge, by setting

 $\overline{\text{CS}}$, $\overline{\text{RAS}}$, $\overline{\text{WE}}$, DSF are LOW,

CAS is HIGH

bank can be precharged to idle state.

A9 = LOW: the bank selected by A10 is precharged.

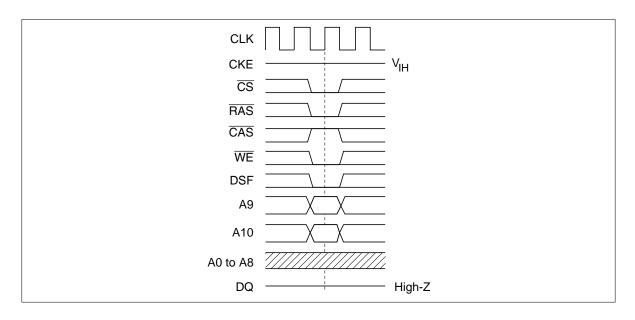
A9 = HIGH: both banks are precharged.

[State transition]

power on — (precharge) -> Idle

Row active — (precharge) -> Idle

Precharge Command



Mode register set command [MRS]: If both banks have been precharged or are in idle state, at the CLK rising edge, by setting

 $\overline{\text{CS}}$, $\overline{\text{RAS}}$, $\overline{\text{CAS}}$, $\overline{\text{WE}}$, DSF; LOW

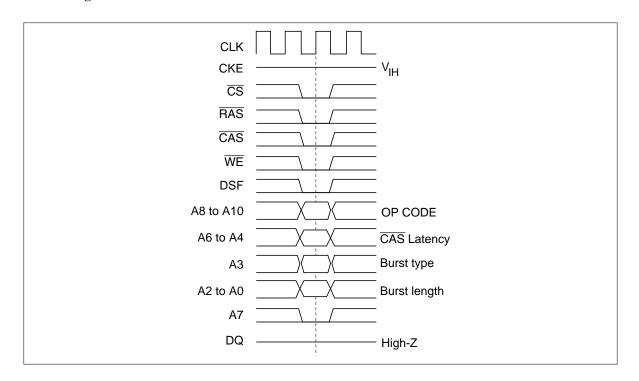
an internal register (the mode register; MRS) are set.

The data through address pins, at the cycle when this command is input, are stored in the mode register. A8, A9, A10 bits determine burst write or single write. A4 to A6 bits determine $\overline{\text{CAS}}$ latency. A3 bit determines burst type, sequential or interleave. A0 to A2 bits determine burst length. A7 bit should be set to low. See table below for details.

[State transition]

Idle — (Mode resister set) ->Idle

Mode Register Set Command



Mode Register Configuration

A10	A9	A8	Operation CODE
0	0	0	Burst read and burst write
×	0	1	R
0	1	0	Burst read and single write
×	1	1	R

A6	A5	A4	CAS latency
0	0	0	R
0	0	1	1
0	1	0	2
0	1	1	3
1	×	×	R

A3	Burst type
0	Sequential
1	Interleave

			Burst length			
A2	A 1	Α0	BT = 0	BT = 1		
0	0	0	1	1		
0	0	1	2	2		
0	1	0	4	4		
0	1	1	8	8		
1	0	0	R	R		
1	0	1	R	R		
1	1	0	R	R		
1	1	1	Full page	R		

Note: R: Reserved

Bank and row active command [ACTV, ACTVM]: If a bank has been precharged or is in idle state. At the CLK rising edge, by setting

 \overline{CS} , \overline{RAS} ; LOW,

CAS, WE: HIGH

a row of the bank is activated. The bank is selected by setting the level on A10 pin HIGH (bank 1) or LOW (bank 0) at this timing. A0 to A9 determine the row address.

[Option]

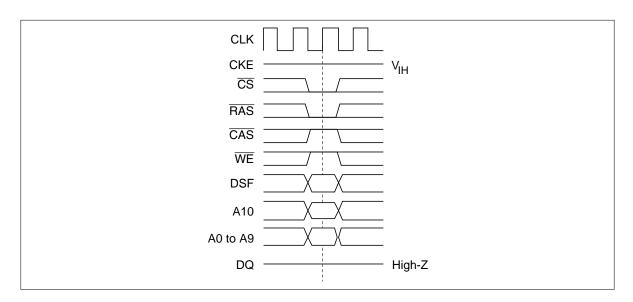
DSF = LOW; write per bit function disable (ACTV)

DSF = HIGH; write per bit function enable (ACTVM)

[State transition]

Idle — (row active) ->Row active

Bank and Row Active Command



Column address and read command: For a row of one of two banks activated by ACTV or ACTVM, at the CLK rising edge, by setting

 \overline{CS} , \overline{CAS} , DSF; LOW,

RAS, WE; HIGH,

data is output through DQ pins.

A10 determines the bank address.

A0 to A7 determine the column address.

CAS latency stored in MRS determines the timing when data are driven.

In case, $CL(\overline{CAS} | \text{latency}) = 1$, 1 clock cycle after the command input, data start to be output.

In case CL = 2, 2 clock cycle after the command input, data start to be output.

In case CL = 3, 3 clock cycle after the command input, data start to be output.

Burst Length (BL) stored in MRS determines data length of output.

[Option]

A9 = HIGH; auto precharge mode or execute precharge automatically after finishing data output.

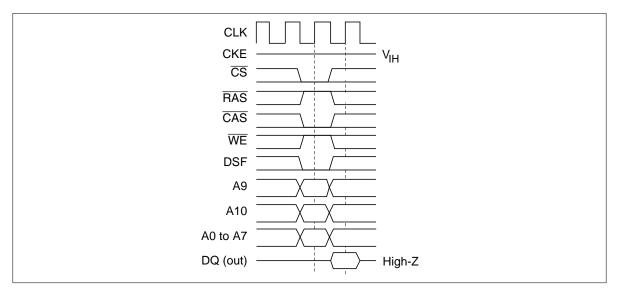
A9 = LOW; Read mode without auto precharge.

[State transition]

Row active — (Column address and read command) ->Row active

Row active — (Column address and read command) ->Idle (auto precharge)

Column Address and Read Command (CL = 1, BL = 1)



Column address and write command: For a row of one of two banks activated by ACTV or ACTVM, at the CLK rising edge, by setting

 \overline{CS} , \overline{CAS} , DSF, \overline{WE} ; LOW,

RAS; HIGH,

the data on DQ pins are input.

A10 determines the bank address.

A0 to A7 determine the column address.

For write, data should start to be input at the same cycle of the command input.

Burst length stored in MRS determines the expected data length to be input.

If the bank, for which command is input, is activated by ACTVM, then I/O bit mask function or write per bit is available.

[Option]

A9 = HIGH; auto precharge mode or execute precharge automatically after finishing data input.

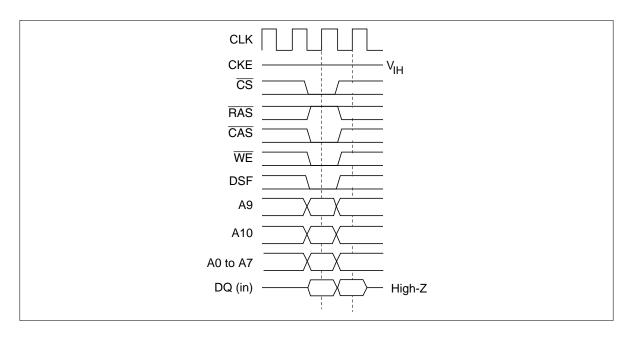
A9 = LOW; write mode without auto precharge.

[State transition]

Row active — (Column address and write command) ->Row active

Row active — (Column address and write command) ->Idle (auto precharge case)

Column Address and Write Command (BL = 2)



Burst stop command (BST): At the CLK rising edge, by setting

 $\overline{\text{CS}}$, $\overline{\text{WE}}$, DSF: LOW,

 \overline{RAS} , \overline{CAS} ; HIGH,

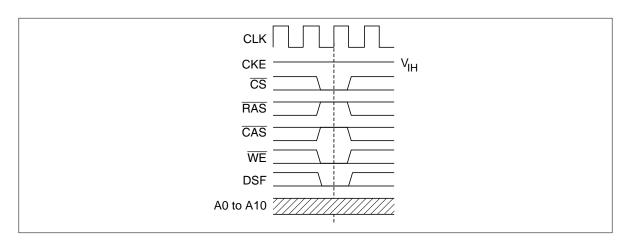
full page burst (BL = 256) read/write is interrupted.

If BL is set to 1, 2, 4, 8, to try to execute this command is illegal.

[State transition]

Row active — (Burst stop command) -> Row active

Burst Stop Command



Auto refresh command (REF): If both banks are in idle state, at the CLK rising edge, by setting

 $\overline{\text{CS}}$, $\overline{\text{RAS}}$, $\overline{\text{CAS}}$, DSF; LOW,

WE; HIGH,

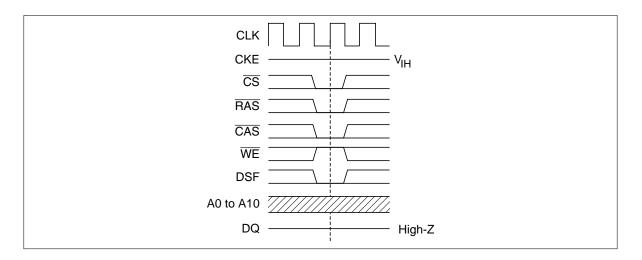
the HM5216326 starts auto-refresh (CBR type) operation. Refresh address is internally generated.

No precharge commands are required after autorefresh, since precharge is automatically performed for both banks.

[State transition]

Idle — (Auto refresh command) -> Idle

Auto Refresh Command



Self refresh command (REF): If both banks are in idle state, at the CLK rising edge, by setting

 $\overline{\text{CS}}$, $\overline{\text{RAS}}$, $\overline{\text{CAS}}$, DSF; LOW,

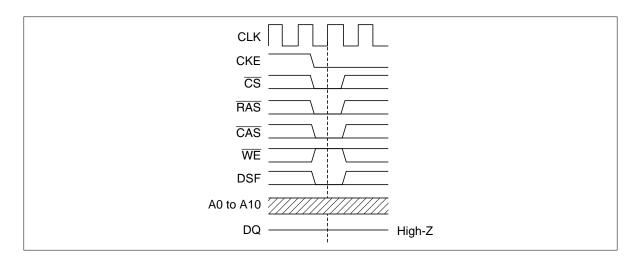
WE; HIGH,

and if CKE's falling edge is detected, the HM5216326 starts self-refresh operation. Self-refresh operation is kept while CKE is LOW.

[State transition]

Idle — (Self refresh command) -> Self refresh mode

Self Refresh Command



No operation command (NOP): At the CLK rising edge, by setting

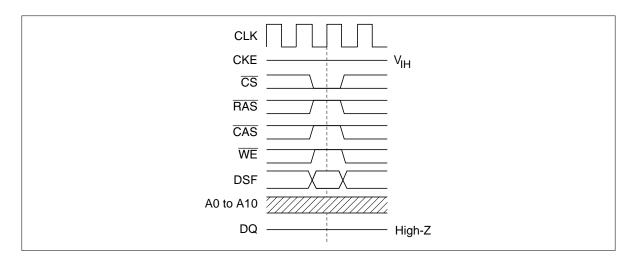
 $\overline{\text{CS}}$; LOW,

 $\overline{\text{WE}}$, $\overline{\text{RAS}}$, $\overline{\text{CAS}}$; HIGH,

[State transition]

No transition

No Operation Command



Ignore command (DESL): At the CLK rising edge, by setting

 $\overline{\text{CS}}$; HIGH, any input is ignored.

Graphic Commands

Special mode register set command (SMRS): If each banks is in idle state or activated, at the CLK rising edge, by setting

 \overline{CS} , \overline{RAS} , \overline{CAS} , \overline{WE} ; LOW,

DSF; HIGH,

an internal register (the special mode register; SMRS) are set.

The data through address pins, at the cycle when this command is input, are stored in the special mode register.

A0 to A4: reserved. should be LOW when SMRS is issued.

A5: determines whether loading mask data or not when SMRS is issued.

A6: determines whether loading color data or not when SMRS is issued.

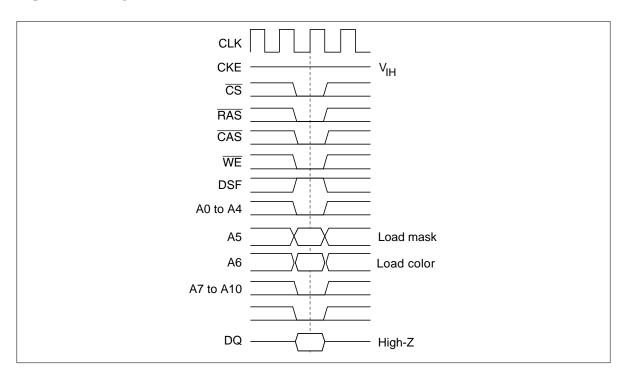
A7 to A10: reserved. should be set LOW when SMRS is issued.

In case A5 bit of the mode register = HIGH, the data through DQ pins, at the cycle this command is issued, are stored in the MASK register (32 bits). If write per bit function is available*, and DQi (i = 0,...,31)bit of the MASK register = LOW, DQi data path to memory array is masked.

In case A6 bit of the mode register HIGH, the data through DQ pins, at the cycle when this command is issued, are stored in the COLOR register (32 bits). This specific data is written to 8 columns in one clock cycle by block write command.

Note: When bank active command is issued and DSF set to HIGH, write per bit function is enabled.

Special Mode Register Set Command



Special Mode Register Configuration

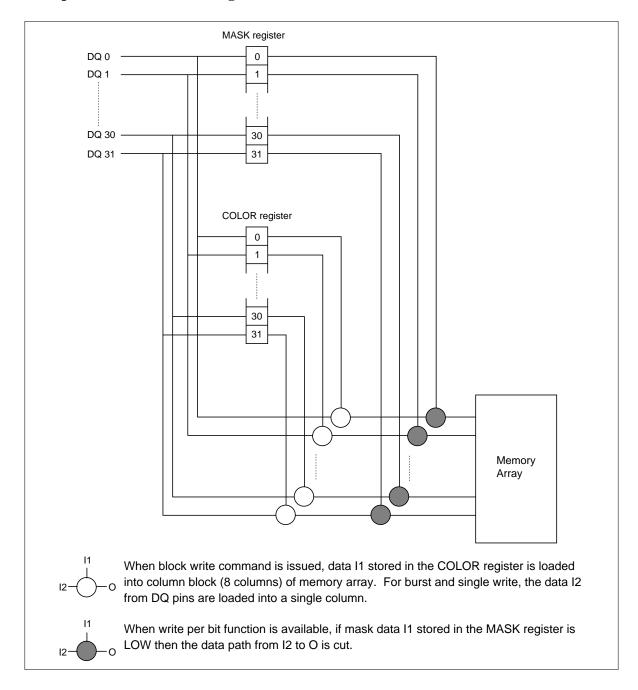
A5	A6	Function	
0	×	Disable	Load Mask
1	0	Enable	
×	0	Disable	Load Color
0	1	Enable	
1	1	ILLEGAL	

Note: ×: V_{IH} or V_{IL}

Reserved Bits

Α0	A1	A2	A3	A4	A7	A8	A9	A10
0	0	0	0	0	0	0	0	0

Graphic Function Block Diagram



Column address and block write command: For a row of one of two banks activated by ACTV or ACTVM, at the CLK rising edge, by setting

 \overline{CS} , \overline{CAS} , \overline{WE} ; LOW,

RAS, DSF; HIGH,

a block write *2 is executed.

A10 determines the bank address.

A0 to A2 HIGH or LOW (ignored).

A3 to A7 determine the column block address.

The data through DQ pins, at the cycle when the block write command input, are referred to stop the color data to be written onto the specific column. (Column mask)

[Option]

A9 = HIGH; Auto precharge mode or execute precharge automatically after finishing a block write execution.

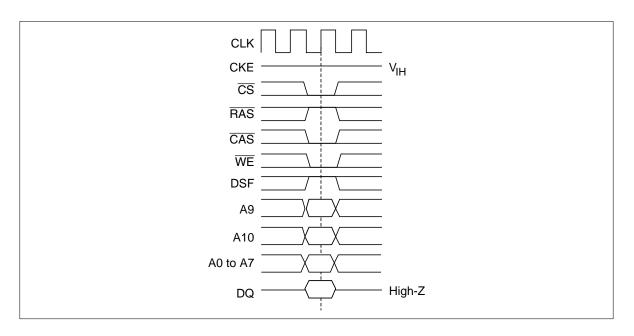
A9 = LOW; Write mode without auto precharge.

[State transition]

Row active — (Block write command) ->Row active

Row active — (Block write command) ->Idle(auto precharge case)

Column Address and Block Write Command



Column Block

Column location			Column	Column block location					
A0	A1	A2	А3	A4	A5	A6	A7		
0	0	0	аЗ	a4	а5	a6	a7		
1	0	0	аЗ	a4	a5	a6	a7		
0	1	0	а3	a4	a5	a6	a7		
1	1	0	аЗ	a4	а5	a6	a7		
0	0	1	аЗ	a4	a5	a6	a7		
1	0	1	a3	a4	a5	a6	a7		
0	1	1	аЗ	a4	а5	a6	a7		
1	1	1	a3	a4	а5	a6	a7		

Note: 1. a3, a4, a5, a6, a7; V_{IH} or V_{IL}.

DQ Input at the Block Write Cycle and Column Mask Location

		Column lo	cation	Column ma	Column mask		
DQ pin NO.	DQ group*1	A0	A1	A2	No mask	Mask	
DQ0	00	0	0	0	High	Low	
DQ1	00	1	0	0	High	Low	
DQ2	00	0	1	0	High	Low	
DQ3	00	1	1	0	High	Low	
DQ4	00	0	0	1	High	Low	
DQ5	00	1	0	1	High	Low	
DQ6	00	0	1	1	High	Low	
DQ7	00	1	1	1	High	Low	
DQ8	01	0	0	0	High	Low	
DQ9	01	1	0	0	High	Low	
DQ10	01	0	1	0	High	Low	
DQ11	01	1	1	0	High	Low	
DQ12	01	0	0	1	High	Low	
DQ13	01	1	0	1	High	Low	
DQ14	01	0	1	1	High	Low	
DQ15	01	1	1	1	High	Low	
DQ16	10	0	0	0	High	Low	
DQ17	10	1	0	0	High	Low	
DQ18	10	0	1	0	High	Low	
DQ19	10	1	1	0	High	Low	
DQ20	10	0	0	1	High	Low	
DQ21	10	1	0	1	High	Low	
DQ22	10	0	1	1	High	Low	
DQ23	10	1	1	1	High	Low	
DQ24	11	0	0	0	High	Low	
DQ25	11	1	0	0	High	Low	
DQ26	11	0	1	0	High	Low	
DQ27	11	1	1	0	High	Low	
DQ28	11	0	0	1	High	Low	
DQ29	11	1	0	1	High	Low	
DQ30	11	0	1	1	High	Low	
DQ31	11	1	1	1	High	Low	

Note: DQ group: 00; DQ0 to DQ7, 01; DQ8 to DQ15, 10; DQ16 to DQ23, 11; DQ24 to DQ31

Command Truth Table

The HM5216326 recognizes the following commands specified by the \overline{CS} , \overline{RAS} , \overline{CAS} , \overline{WE} , DSF and address pins. All other combinations than those in the table bellow are illegal.

		CKE									
Function	Symbol	n – 1	n	CS	RAS	CAS	WE	DSF	A10	Α9	A0 to A8
Ignore command	DESL*2	Н	×	Н	×	×	×	×	×	×	×
No operation	NOP	Н	×	L	Н	Н	Н	×	×	×	×
Burst stop in full page	BST*3	Н	×	L	Н	Н	L	L	×	×	×
Column address and read command	READ	Н	×	L	Н	L	Н	L	V	L	V
Read with auto precharge	READ A	Н	×	L	Н	L	Н	L	V	Н	V
Column address and write command	WRIT	Н	×	L	Н	L	L	L	V	L	V
Write with auto precharge	WRIT A	Н	×	L	Н	L	L	L	V	Н	V
Row address strobe and bank active	ACTV	Н	×	L	L	Н	Н	L	V	V	V
Precharge select bank	PRE	Н	×	L	L	Н	L	L	V	L	×
Precharge all bank	PALL	Н	×	L	L	Н	L	L	×	Н	×
Refresh (auto, self)	REF, SELF	Н	×	L	L	L	Н	L	×	×	×
Mode register set	MRS	Н	×	L	L	L	L	L	V	V	V
Row address strobe and bank active and Masked write enable	ACTVM	Н	×	L	L	Н	Н	Н	V	V	V
Column address and block write command	BWRIT	Н	×	L	Н	L	L	Н	V	L	V
Block write with auto precharge	BWRITA	Н	×	L	Н	L	L	Н	V	Н	V
Special mode register set	SMRS	Н	×	L	L	L	L	Н	L	L	V

Notes: 1. H: V_{IH} . L: V_{IL} . \times : V_{IH} or V_{IL} . V: Valid address input.

^{2.} When $\overline{\text{CS}}$ is high, the HM5216326 ignores command input. Internal operation is held.

^{3.} Illegal if the burst length is 1, 2, 4 or 8.

DQM Truth Table

CKE DQM i **Function Symbol** n – 1 n Ith byte write enable/output enable ENB i Н L × MASK i Ith byte write input/output disable Н Н \times

Note: H: V_{IH} . L: V_{IL} . \times : V_{IH} or V_{IL} . i = 0, 1, 2, 3.

DQM0 for DQ0 to DQ7, DQM1 for DQ8 to DQ15, DQM2 for DQ16 to DQ23, DQM3 for DQ24 to

DQ31

CKE Truth Table

CKE **Current state Function** n – 1 $\overline{\mathsf{CS}}$ RAS CAS WE DSF **Address** n Н Active Clock suspend mode entry L × × × × × × Any Clock suspend L L \times × × \times × \times Clock suspend Clock suspend mode exit L Н \times × \times \times × \times Idle Auto refresh command REF Н Н L L L Н L × Self refresh entry SELF Idle Η L L L L Н L × Idle Н Power down entry L × \times × × × Self refresh Self refresh exit L Н L Н Н Н × L Η Η Power down L Power down exit Н L Η Н Н × L Н Н ×

Note: H: V_{IH} . L: V_{II} . \times : V_{IH} or V_{II} .

Function Truth Table

The following tables show how each command works and what command can be executed in the state given.

Current state	CS	RAS	CAS	WE	DSF	Address	Command	Operation
Precharge	Н	×	×	×	×	×	DESL	NOP -> Idle after t _{RP}
	L	Н	Н	Н	×	×	NOP	NOP -> Idle after t _{RP}
	L	Н	Н	L	L	×	BST	ILLEGAL*2, *6
	L	Н	L	Н	L	BA, CA, A9	READ/READ A	ILLEGAL*2
	L	Н	L	L	L	BA, CA, A9	WRIT/WRIT A	ILLEGAL*2
	L	L	Н	Н	L	BA, RA	ACTV	ILLEGAL*2
	L	L	Н	L	L	BA, A9	PRE, PALL	NOP*3
	L	L	L	×	×	×		ILLEGAL
	L	L	Н	Н	Н	BA, RA	ACTVM	ILLEGAL*2
	L	Н	L	L	Н	BA, CA, A9	BWRIT/BWRIT A	ILLEGAL*2
Idle	Н	×	×	×	×	×	DESL	NOP
	L	Н	Н	Н	×	×	NOP	NOP
	L	Н	Н	L	L	×	BST	NOP*6
	L	Н	L	Н	L	BA, CA, A9	READ/READ A	ILLEGAL*2
	L	Н	L	L	L	BA, CA, A9	WRIT/WRIT A	ILLEGAL*2
	L	L	Н	Н	L	BA, RA	ACTV	Bank and row active
	L	L	Н	L	L	BA, A9	PRE, PALL	NOP*3
	L	L	L	Н	L	×	REF, SELF	Auto self refresh*4
	L	L	L	L	L	MODE	MRS	Mode register set*4
	L	L	Н	Н	Н	BA, RA	ACTVM	Bank and row active and write per bit enable
	L	Н	L	L	Н	BA, CA, A9	BWRIT/BWRIT A	ILLEGAL*2
	L	L	L	L	Н	Special MODE	SMRS	Special mode register set*5

Current state	e CS	RAS	CAS	WE	DSF	Address	Command	Operation
Row active	Н	×	×	×	×	×	DESL	NOP
	L	Н	Н	Н	×	×	NOP	NOP
	L	Н	Н	L	L	×	BST	NOP*6
	L	Н	L	Н	L	BA, CA, A9	READ/READ A	Start read
	L	Н	L	L	L	BA, CA, A9	WRIT/WRIT A	Start write
	L	L	Н	Н	L	BA, RA	ACTV	ILLEGAL*2
	L	L	Н	L	L	BA, A9	PRE, PALL	Precharge
	L	L	L	×	L			ILLEGAL
	L	L	Н	Н	Н	BA, RA	ACTVM	ILLEGAL*2
	L	Н	L	L	Н	BA, CA, A9	BWRIT/BWRIT A	Start block write
	L	L	L	L	Н	Special MODE	SMRS	Special mode register set*5
Read	Н	×	×	×	×	×	DESL	NOP -> Burst end -> Row active
	L	Н	Н	Н	×	×	NOP	NOP -> Burst end -> Row active
	L	Н	Н	L	L	×	BST	Burst stop -> Row active*6
	L	Н	L	Н	L	BA, CA, A9	READ/READ A	Term burst -> Start new read
	L	Н	L	L	L	BA, CA, A9	WRIT/WRIT A	Term burst -> Start write
	L	L	Н	Н	L	BA, RA	ACTV	ILLEGAL*2
	L	L	Н	L	L	BA, A9	PRE, PALL	Term burst -> Precharge
	L	L	L	×	×	×		ILLEGAL
	L	L	Н	Н	Н	BA, RA	ACTVM	ILLEGAL*2
	L	Н	L	L	Н	BA, CA, A9	BWRIT/BWRIT A	Term burst -> Start block write
Read with auto precharge	Н	×	×	×	×	×	DESL	NOP -> Burst end -> Precharge
	L	Н	Н	Н	×	×	NOP	NOP -> Burst end -> Precharge
	L	Н	Н	L	L	×	BST	ILLEGAL
	L	Н	L	Н	L	BA, CA, A9	READ/READ A	ILLEGAL*2
	L	Н	L	L	L	BA, CA, A9	WRIT/WRIT A	ILLEGAL*2
	L	L	Н	Н	L	BA, RA	ACTV	ILLEGAL*2
	L	L	Н	L	L	BA, A9	PRE, PALL	ILLEGAL*2
	L	L	L	×	×	×		ILLEGAL
	L	L	Н	Н	Н	BA, RA	ACTVM	ILLEGAL*2
	L	Н	L	L	Н	BA, CA, A9	BWRIT/BWRIT A	ILLEGAL*2

Current state	cs CS	RA	S CAS	WE	DSF	Address	Command	Operation
Write/BWrite	Н	×	×	×	×	×	DESL	NOP -> Burst end -> Write recovering
	L	Н	Н	Н	×	×	NOP	NOP -> Burst end -> Write recovering
	L	Н	Н	L	L	×	BST	Burst stop -> Row active*6
	L	Н	L	Н	L	BA, CA, A9	READ/READ A	Term burst -> Start read
	L	Н	L	L	L	BA, CA, A9	WRIT/WRIT A	Term burst -> Start new write
	L	L	Н	Н	L	BA, RA	ACTV	ILLEGAL*2
	L	L	Н	L	L	BA, A9	PRE, PALL	Term burst -> Precharge
	L	L	L	×	×	×		ILLEGAL
	L	L	Н	Н	Н	BA, RA	ACTVM	ILLEGAL*2
	L	Н	L	L	Н	BA, CA, A9	BWRIT/BWRIT A	Term burst -> Start block write
Write/Bwrite with auto precharge	Н	×	×	×	×	×	DESL	NOP -> Burst end -> Write recovering with precharge
	L	Н	Н	Н	×	×	NOP	NOP -> Burst end -> Write recovering with precharge
	L	Н	Н	L	L	×	BST	ILLEGAL
	L	Н	L	Н	L	BA, CA, A9	READ/READ A	ILLEGAL*2
	L	Н	L	L	L	BA, CA, A9	WRIT/WRIT A	ILLEGAL*2
	L	L	Н	Н	L	BA, RA	ACTV	ILLEGAL*2
	L	L	Н	L	L	BA, A9	PRE, PALL	ILLEGAL*2
	L	L	L	×	×	×		ILLEGAL
	L	L	Н	Н	Н	BA, RA	ACTVM	ILLEGAL*2
	L	Н	L	L	Н	BA, CA, A9	BWRIT/BWRIT A	ILLEGAL*2
Write/Bwrite recovering	Н	×	×	×	×	×	DESL	NOP -> Row active after $t_{\mbox{\tiny WR}}/t_{\mbox{\tiny BWR}}$
	L	Н	Н	Н	×	×	NOP	NOP -> Row active after t _{wR} /t _{BWR}
	L	Н	Н	L	L	×	BST	NOP -> Row active after t_{WR}/t_{BWR}^{*6}
	L	Н	L	Н	L	BA, CA, A9	READ/READ A	Start read*2
			L	BA, CA, A9	WRIT/WRIT A	Start new write*2		
	 		BA, RA	ACTV	ILLEGAL*2			
	L L H L BA, A9		BA, A9	PRE, PALL	ILLEGAL*2			
	L		L	×	×	×		ILLEGAL
	L	L	Н	Н	Н	BA, RA	ACTVM	ILLEGAL*2
	L	Н	L	L	Н	BA, CA, A9	BWRIT/BWRIT A	ILLEGAL*2

HM5216326	Series
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Current state	CS	RAS	S CAS	WE	DSF	Address	Command	Operation
Write/Bwrite recovering with precharge	Н	×	×	×	×	×	DESL	NOP -> Precharge after t_{WR}/t_{BWR}
	L	Н	Н	Н	×	×	NOP	NOP -> Precharge after t_{WR}/t_{BWR}
	L	Н	Н	L	L	×	BST	ILLEGAL
	L	Н	L	Н	L	BA, CA, A9	READ/READ A	ILLEGAL*2
	L	Н	L	L	L	BA, CA, A9	WRIT/WRIT A	ILLEGAL*2
	L	L	Н	Н	L	BA, RA	ACTV	ILLEGAL*2
	L	L	Н	L	L	BA, A9	PRE, PALL	ILLEGAL*2
	L	L	L	¥	¥	¥		ILLEGAL
	L	L	Н	Н	Н	BA, RA	ACTVM	ILLEGAL*2
	L	Н	L	L	Н	BA, CA, A9	BWRIT/BWRIT A	ILLEGAL*2
Row activating	Н	×	×	×	×	×	DESL	NOP -> Row active after t _{RCD}
	L	Н	Н	Н	×	×	NOP	NOP -> Row active after t _{RCD}
	L	Н	Н	L	L	×	BST	NOP -> Row active after t _{RCD} *6
	L	Н	L	Н	L	BA, CA, A9	READ/READ A	ILLEGAL*2
	L	Н	L	L	L	BA, CA, A9	WRIT/WRIT A	ILLEGAL*2
	L	L	Н	Н	L	BA, RA	ACTV	ILLEGAL*2
	L	L	Н	L	L	BA, A9	PRE, PALL	ILLEGAL*2
	L	L	L	×	×	×		ILLEGAL
	L	L	Н	Н	Н	BA, RA	ACTVM	ILLEGAL*2
	L	Н	L	L	Н	BA, CA, A9	BWRIT/BWRIT A	ILLEGAL*2
Refresh (auto precharge)	Н	×	×	×	×	×	DESL	NOP -> Idle after t _{RC}
	L	Н	Н	Н	×	×	NOP	NOP -> Idle after t _{RC}
	L	Н	Н	L	L	×	BST	NOP -> Idle after t _{RC} *6
	L	Н	L	×	×	BA, CA, A9		ILLEGAL
	L	L	×	×	×	×		ILLEGAL
Mode register set	Н	×	×	×	×	×	DESL	NOP -> Idle after t _{RSC}
	L	Н	Н	Н	×	×	NOP	NOP -> Idle after t _{RSC}
	L	Н	Н	L	L	×	BST	ILLEGAL
	L	Н	L	×	×	BA, CA, A9		ILLEGAL
	L	L	×	×	×	×		ILLEGAL

Current state	CS	RAS	CAS	WE	DSF	Address	Command	Operation
Special Mode register set	Н	×	×	×	×	×	DESL	NOP -> Idle after $t_{\mbox{\scriptsize RSC}}$ or row active after $t_{\mbox{\scriptsize SBW}}$
	L	Н	Н	Н	×	×	NOP	NOP -> Idle after $t_{\mbox{\scriptsize RSC}}$ or row active after $t_{\mbox{\scriptsize SBW}}$
	L	Н	Н	L	L	×	BST	ILLEGAL
	L	Н	L	×	×	BA, CA, A9		ILLEGAL
	L	L	×	×	×	×		ILLEGAL

Notes: 1. H: V_{IH} . L: V_{IL} . \times : V_{IH} or V_{IL} .

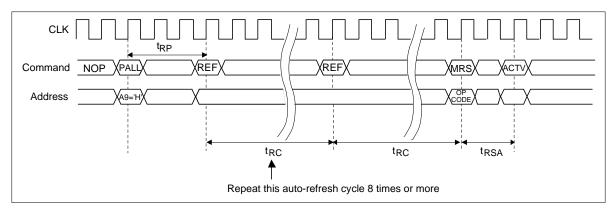
- 2. To execute this command for the current bank is illegal. However this command can be executed for another bank depends on the state of another bank.
- 3. NOP for the current bank or the bank in idle state. Precharge for the bank in other state.
- 4. Illegal, if both banks are not in idle state.
- 5. Illegal, if another bank is not in active or idle state.
- 6. In burst read/write, if BL is set to 1, 2, 4, 8, to try to execute BST command is illegal.

Operations of HM5216326 Series

Power on sequence: In order to get rid of data contention of I/O bus when power on, the following power on sequence recommended to be performed before any operation.

- 1. Apply power and start clock. Keep a NOP condition.
- 2. Maintain stable power, stable clock, and NOP condition for 200 μs.
- 3. Execute precharge command (PALL: A9 = HIGH).
- 4. Execute 8 or more auto refresh commands (REF) t_{RP} after the precharge command as dummy. An interval t_{RC} is necessary between two consecutive auto refresh commands.
- 5. Execute a mode register set command (MRS) t_{RC} after the last auto refresh command input.

Power on Sequence

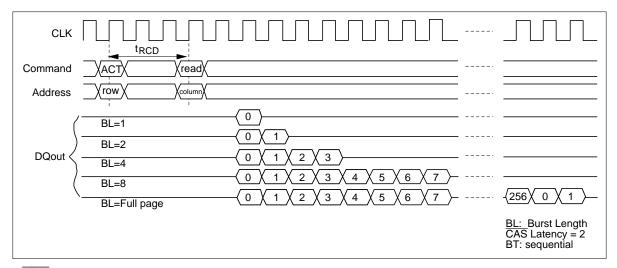


Read/Write Operations

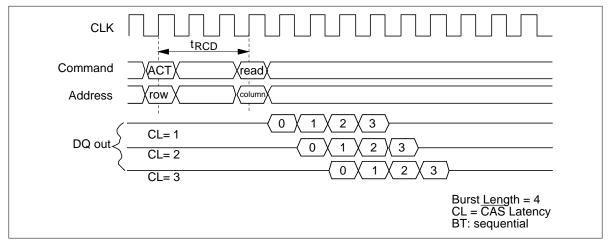
Bank active: A read/write operation begins with a bank active command (ACTV or ACTVM). The bank active command determines a bank (A10) and a row address (AX0 to AX9). For the bank and the row, a read/write command can be applied. An interval not less than t_{RCD} , after an ACTV/ ACTVM command to a read/write command, is required.

Read operation: Burst length (BL), \overline{CAS} latency (CL) and burst type (BT) of the mode register are referred when read command is executed. Burst length (BL) determines the length of a sequential data by a single read command, which can be set to 1, 2, 4, 8 or 256 (full-page). Starting address of a burst data is defined by column address (AY0 to AY7) and bank select address (A10) loaded through A0 to A9 in the cycle when the read command is issued. \overline{CAS} latency (CL) determines the delay of data output after read command input. When burst length is 1, 2, 4 or 8, DQ buffers automatically become High-Z at the next cycle after completion of burst read. When burst length is full-page (256), data are repeatedly output until a burst stop command, a read/write command or a precharge command is input.

Burst Length



CAS Latency



Burst operation (on read or write): One burst data output/input by one read/write command are included in a column block determined by A1 to A7 in case BL (Burst Length) = 2, by A2 to A7 in case BL = 4 and by A3 to A7 in case BL = 8. Burst type (BT) determines the order how data of the column block are output/input. There are two burst types, sequential (wrap around) or interleave. The order of the burst data depends also on the start column location of the burst data. See tables below for details.

Column Block

BL = 2

Colum	n location	Column	block location	on				
A0	A1	A2	А3	A4	A5	A6	A7	
0	a1	a2	a3	a4	a5	a6	a7	
1	a1	a2	a3	a4	a5	a6	a7	

Note: a1, a2, a3, a4, a5, a6, a7; V_{IH} or V_{IL}.

BL = 4

Column	location	Column	block location	on				
A0	A1	A2	А3	A4	A5	A6	A7	
0	0	a2	a3	a4	a5	a6	a7	
1	0	a2	a3	a4	a5	a6	a7	
0	1	a2	a3	a4	a5	a6	a7	
1	1	a2	a3	a4	a5	a6	a7	

Note: a2, a3, a4, a5, a6, a7; V_{IH} or V_{IL}.

BL = 8

Column	location		Column	block location	on			
A0	A1	A2	А3	A4	A5	A6	A7	
0	0	0	a3	a4	a5	a6	a7	
1	0	0	a3	a4	a5	a6	a7	
0	1	0	a3	a4	a5	a6	a7	
1	1	0	a3	a4	a5	a6	a7	
0	0	1	a3	a4	a5	a6	a7	
1	0	1	a3	a4	a5	a6	a7	
0	1	1	a3	a4	а5	a6	а7	
1	1	1	a3	a4	a5	a6	a7	

Note: a3, a4, a5, a6, a7; V_{IH} or V_{IL}.

The Order of Burst Operation

BL = 2

Start column location	Order in decimal BL = 2								
A0	Sequentia	al	Interleave						
0	0	1	0	1					
1	1	0	1	0					

BL = 4

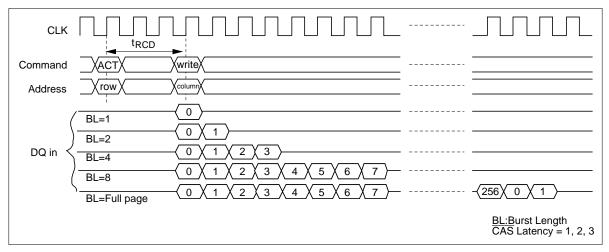
Start col	umn location	Orde	r in decir	nal BL =	4						
A0	A1	Sequ	ential		Interleave						
0	0	0	1	2	3	0	1	2	3		
1	0	1	2	3	0	1	0	3	2		
0	1	2	3	0	1	2	3	0	1		
1	1	3	0	1	2	3	2	1	0		

BL = 8

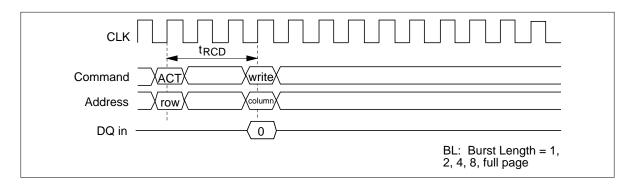
Start	column l	ocation	Or	der II	n dec	ımaı	BL :	= 8										
A0	A1	A2	Se	quen	tial						Inte	erlea	ve					
0	0	0	0	1	2	3	4	5	6	7	0	1	2	3	4	5	6	7
1	0	0	1	2	3	4	5	6	7	0	1	0	3	2	5	4	7	6
0	1	0	2	3	4	5	6	7	0	1	2	3	0	1	6	7	4	5
1	1	0	3	4	5	6	7	0	1	2	3	2	1	0	7	6	5	4
0	0	1	4	5	6	7	0	1	2	3	4	5	6	7	0	1	2	3
1	0	1	5	6	7	0	1	2	3	4	5	4	7	6	1	0	3	2
0	1	1	6	7	0	1	2	3	4	5	6	7	4	5	2	3	0	1
1	1	1	7	0	1	2	3	4	5	6	7	6	5	4	3	2	1	0

Write operation: OPCODE (A10, A9, A8) of the mode register is referred when a write command is executed as well as BL (Burst Length) and BT (Burst Type). CL (CAS Latency) is ignored and CL is fixed to 0 for write operation, that is, write data input starts on the same cycle when the write command is issued.

Burst write: Before executing a burst write operation, OPCODE (A10, A9, A8) should be set to (0, 0, 0). Burst length (BL) determines the length of a sequential data by the burst write command, which can be set to 1, 2, 4, 8 or 256 (full-page). Starting address of a burst data is defined by column address (AY0 to AY7) and bank select address (A10) loaded through A0 to A10 in the cycle when the burst write command is issued.



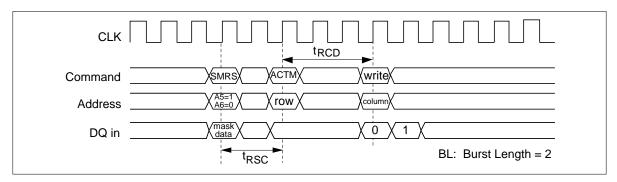
Single write: Before executing a single write operation, OPCODE (A10, A9, A8) should be set to (0, 1, 0). In the single write operation, data are only written to the single column defined by the column address and the bank select address loaded at the write command set cycle regardless of the defined burst length. (The latency of data input is 0).



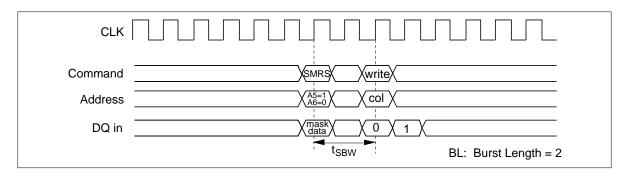
Write per bit: To use write per bit function,

- Set mask data in advance, which define DQ paths to be masked, to the MASK register by SMRS command. An interval not less than t_{RSC} after a SMRS command to an ACTVM command is necessary.
- 2. Use ACTVM command to activate the bank for which write per bit operation is performed. An interval not less than t_{RCD} , after an ACTVM command to a write or a block write command, is necessary.
- 3. Execute a write or a block write command. In this write operation, DQ paths defined by mask register are masked to preserve the previous data. (See the example below)

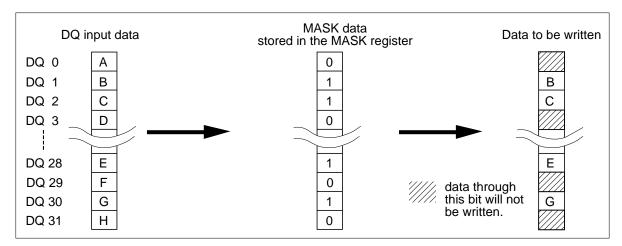
Special Mode Register Set (Load Mask) in Idle State and Write Per Bit



Special Mode Register Set (Load Mask) in Active State and Write Per Bit

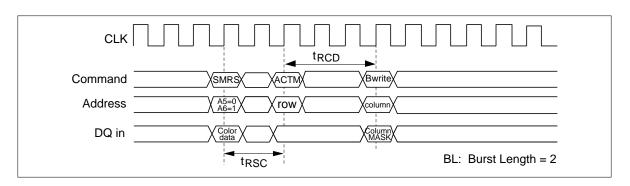


Write Per Bit Example

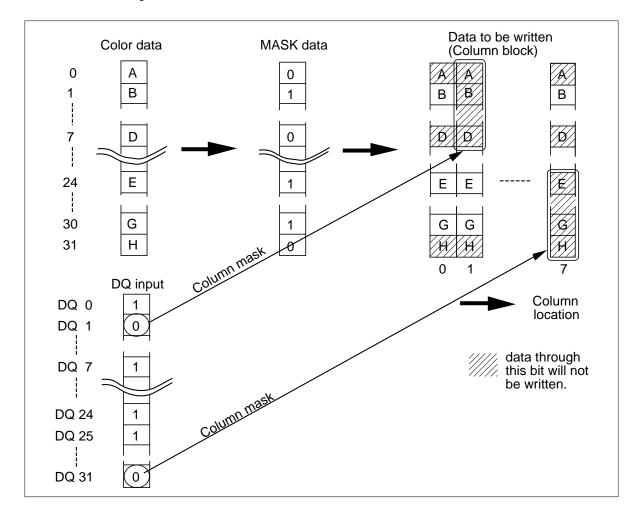


Block write: Before executing a block write command, a color data (32 bit) should be set in advance, which is allowed to be written in 8 columns at one write cycle, to the color register by SMRS command. An interval not less than t_{RSC} after a SMRS command to an ACTVM command is necessary. If a SMRS command is executed in active state to set the color register, an interval not less than t_{SBW} is required before executing a block write command after the SMRS command. If a block write command is applied to the bank which is activated by ACTVM command, write per bit function is also available. DQ inputs at the cycle, when a block write command is executed, are referred to mask the specific columns. See the example below.

Special Mode Register Set (Load Mask) in Idle State and Block Write



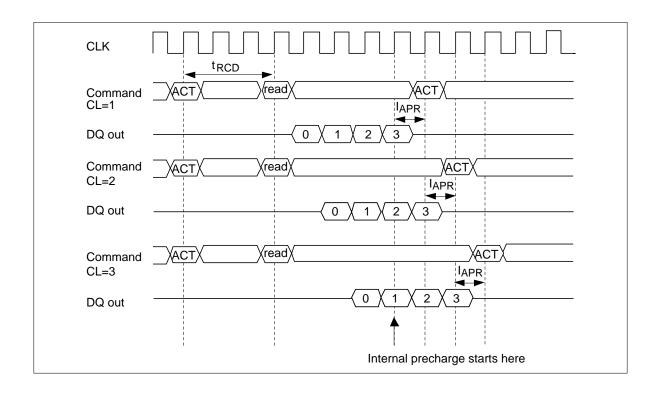
Block Write Example with Write Per Bit



Auto Precharge

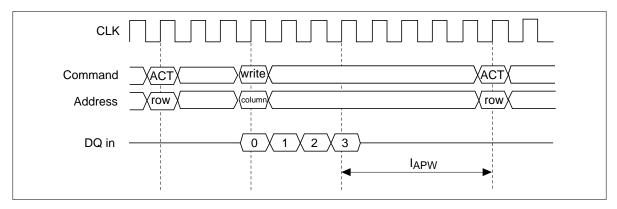
Read with auto precharge: In this operation, since precharge is automatically performed after completing a read operation, so no precharge commands are necessary after each read operation. The command next to this command must be a bank active (ACTV, ACTVM) command. In addition, an interval defined by l_{APR} is required prior to the next command.

CAS latency		Precharge start cycle
3	2	cycle before the last data out
2	1	cycle before the last data out
1	0	cycle before the last data out

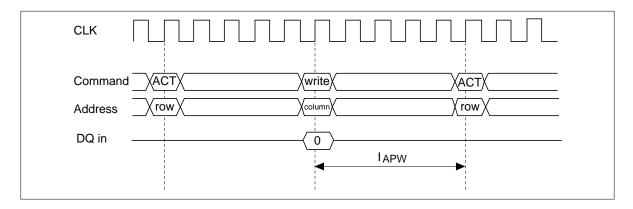


Write with auto precharge: In this operation, since precharge is automatically performed after completion of a burst write or a single write operation, so no precharge commands are necessary after the write operation. The command next to this command must be a bank active command (ACTV, ACTVM). In addition, an interval of l_{APW} is required between the last valid data and the following command.

Burst Write (Burst Length = 4)

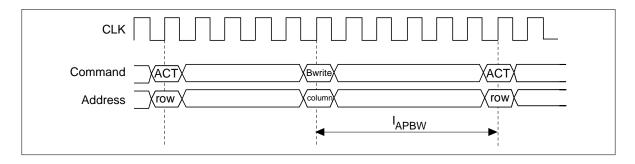


Single Write



Block write with auto-precharge: In this operation, since precharge is automatically performed after completion of a block write operation, so no need to execute precharge command. The following command must be a bank active command (ACTV, ACTVM). In addition, an interval of l_{APBW} is required between the last valid data input and the following command.

Block Write with Auto Precharge

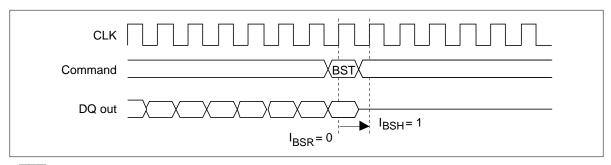


Full Page Burst Stop

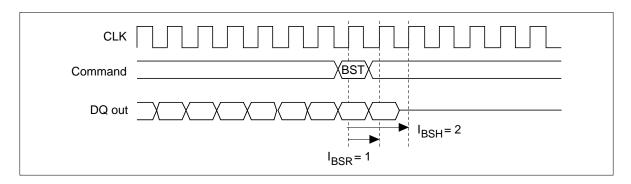
Burst stop command during burst read: Burst stop command is used to stop data output during a full-page burst read. This command sets the output buffer to High-Z and stops the full-page burst read. The timing, from command input to the last data, depends on $\overline{\text{CAS}}$ latency. BST command is legitimate only in case full page burst mode, and is illegal in case burst length 1, 2, 4 or 8.

CAS latency	BST to valid data	BST to high impedance
1	0	1
2	1	2
3	2	3

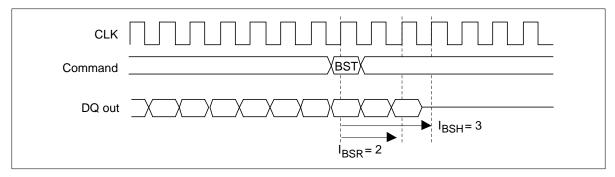
CAS Latency = 1, Burst Length = Full Page



CAS Latency = 2, Burst Length = Full Page

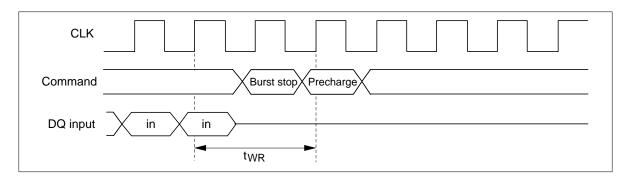


CAS Latency = 3, Burst Length = Full Page



Burst stop command at burst write: For full page burst write cycle, when a burst stop command is issued, the write data at that cycle and the following write data input are ignored. The BST command is legitimate only in case full page burst mode, and is illegal for burst length 1, 2, 4 or 8.

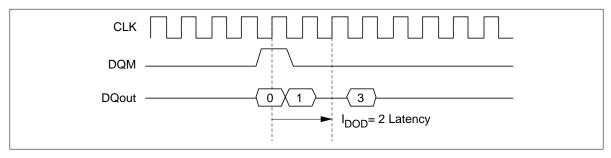
Burst Length = Full Page



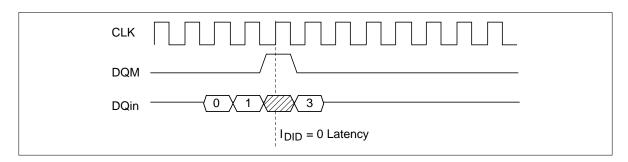
DQM Control

The DQM i (i=0, 1, 2, 3) controls the ith byte of DQ data. DQM control operation for read and for write are different in terms of latency.

Reading: When data are read, output buffer can be controlled by DQMi. By setting DQMi to LOW, the corresponding DQ output buffers become active. By setting DQMi to HIGH, the corresponding DQ output buffers are made floated so that the ith byte of data are not driven out. The latency of DQM operation for read operation is 2.



Writing: Input data can be controlled by DQMi. While DQMi is LOW, data is driven into the HM5216326. By setting DQMi to HIGH, corresponding ith byte of DQ input data are kept from being written to the HM5216326 and the previous data are protected. The latency of DQM control operation is 0.



Refresh

Auto Refresh: All the banks must be precharged before executing an auto-refresh command. Auto refresh command increments the internal counter every time when it is executed. This command also determines the row to be refreshed. Therefore external address specification is not necessary. Refresh cycle is 2048 cycles/32 ms. (2048 cycles are required to refresh all the row addresses.) All output buffers become High-Z after auto-refresh start. No prechrage commands are necessary after this operation.

Self Refresh: When issuing a self refresh command, by changing the level on CKE pin from HIGH to LOW simultaneously, a self refresh operation starts and is kept while CKE is LOW. During the self-refresh operation, all data schedule to be refreshed internally. This operation managed by an internal refresh timer. After exiting from the self refresh, since the last row refreshed cannot be determined, auto-refresh commands should immediately be performed for all addresses. Change the level on the CKE pin from LOW to HIGH to exit from Self refresh mode.

Others

Power Down Mode: Power down mode is a state in which all input buffers except the CKE input buffer are made inactive and clock signal is masked to cut power dissipation. To enter into power down mode, CKE should be set to low. Power down mode is kept as long as CKE is low. Change the level on the CKE pin from LOW to HIGH to exit from Power down mode. In this mode, internal refresh is not performed.

Clock Suspend: The HM5216326 enters into clock suspend mode from active mode by setting CKE to low. There are several types of clock suspend mode depends on the state when CKE level is changed from HIGH to LOW.

ACTIVE clock suspend: If CKE-transition (1 to 0) happens during a bank active state, the bank active status is kept. Any input signals are ignored during this mode.

READ and READ A suspend: If CKE transition (1 to 0) happens during a read operation, the read operation is kept or DQ output data is driven out until completion. Any input signals are ignored during this mode.

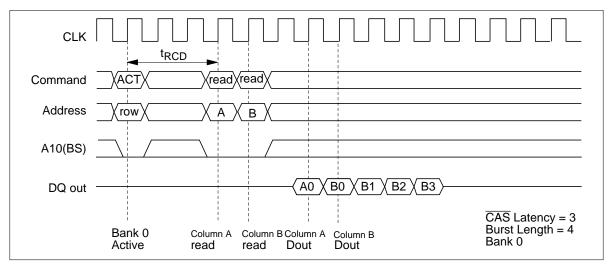
WRITE (BLOCK WRITE) and WRITE A (BLOCK WRITE A) suspend: If CKE-transition (1 to 0) happens during a write operation, though any input signals include DQ input data ignored, the write operation is kept until completion. Any input signals are ignored during this mode.

Change the level on the CKE pin from LOW to HIGH to exit from Clock suspend mode.

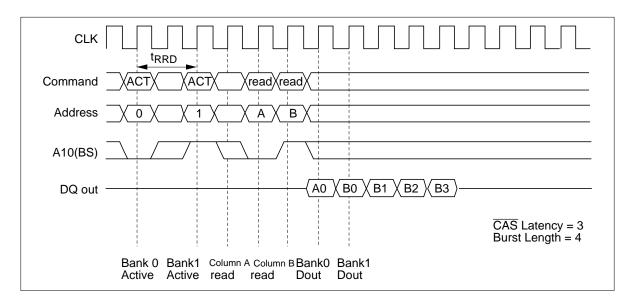
Command Intervals

Read Command Interval:

1. Operation for a column in the same row: Read command can be issued every cycle. Note that the latest read command has the priority to the preceding read command, that is, any read command can interrupt the preceding burst read operation to get valid data aimed by this interruption.

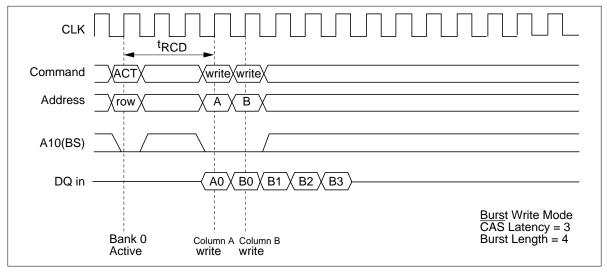


- 2. Operation for a column in other row of the same bank: It is necessary to execute a precharge command and a bank-active command before executing the new read command.
- 3. Operation for another bank: For another bank in active state, the new read command can be executed in the next cycle after the preceding read command is issued. If another bank is in idle state, a bank active command should be executed before executing the new read command.

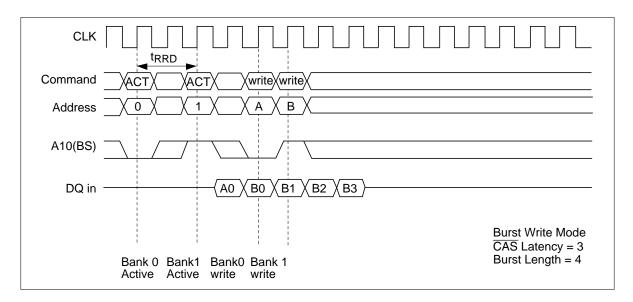


Write Command Interval:

1. Operation for a column in the same row: Write command can be issued every cycle. Note that the latest write command has the priority to the preceding write command, that is, any write command can interrupt the preceding burst write operation to get valid data

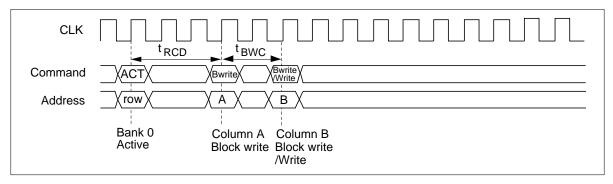


- 2. Operation for a column in other row of the same bank: It is necessary to execute a precharge command and a bank active command before executing the following write command.
- 3. Operation for another bank: For another bank in active state, the following burst write command can be executed in the next cycle after the preceding write command is issued. If another bank is in the idle state, bank active command should be executed.

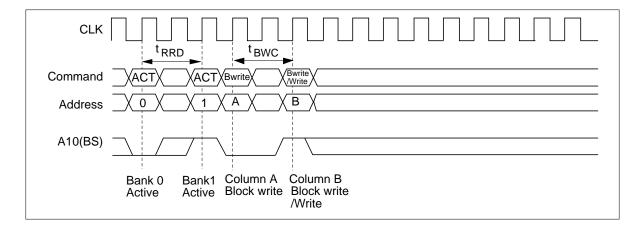


Block Write Command to Write or Block Write Command Interval:

1. Operation for a column in the same row: It is necessary to take no less than t_{BWC} internal between a block write and another block write or the following write. If t_{CK} is less than t_{BWC} , NOP command should be issued for the cycle between a block write command and the following write or another block write command.

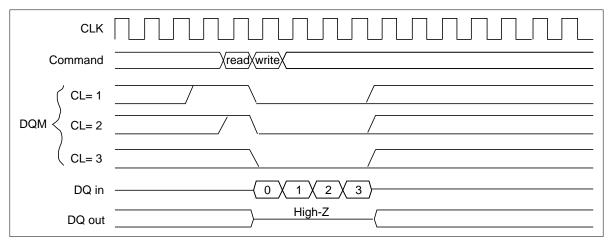


- 2. Operation for a column in other row of the same bank: It is necessary to execute a precharge command and a bank active command before the following write or another block write operation.
- 3. Operation for another bank: To execute the following write command or another block write command for another bank in active state, t_{BWC} interval to the next command is necessary. If another bank is in the idle state, bank active command should be executed. If t_{CK} is less than t_{BWC} , NOP command should be issued for the cycle between block write command and the following write or another block write command.



Read Command to Write or Block Write Command Interval:

1. Operation for a column in the same row: The write or the block write command following the preceding read command can be performed after an interval of no less than 1 cycle. To set DQ output High-Z when data are driven in, DQM must be used depending on \overline{CAS} latency as the timing shown below. Note that the latest write or block write command has the priority to the preceding read command, that is, any write or block write command can interrupt the preceding burst read operation to get valid data.

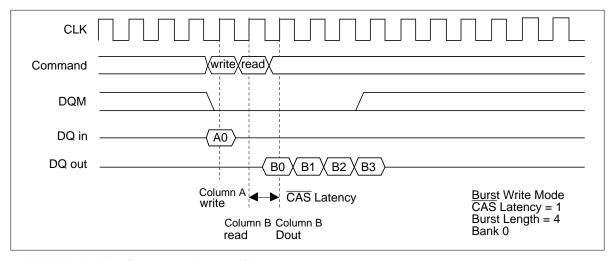


- 2. Operation for a column in other row of the same bank: It is necessary to execute a precharge command and a bank active command before executing the next write or another block write command.
- 3. Operation for another bank: For another bank in active state, the following write or block write command can be executed from the next cycle after the preceding write command is issued. If another bank is in idle state, bank active command should be executed, prior to execute the following write or block write command.

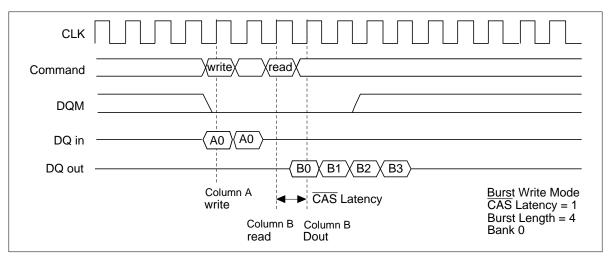
Write Command to Read Command Interval:

1. Operation for a column in the same row: The read command following the preceding write command can be performed after an interval of no less than 1cycle. Note that the latest read command has the priority to the preceding writing command, that is, any read command can interrupt the preceding write operation to get valid data.

WRITE to READ Command Interval (1)



WRITE to READ Command Interval (2)

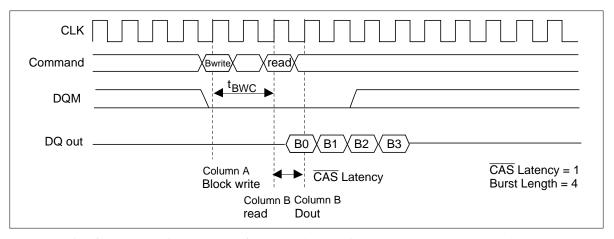


- 2. Operation for a column in other row of the same bank: To execute the following read command, it is necessary to execute a precharge command and a bank active command.
- 3. Operation for another bank: For another bank in active state, the following read command can be executed from the next cycle after the preceding write command is issued. If another bank is in idle state, a bank active command should be executed prior to execute the following read command.

Block Write Command to Read Command Interval:

1. Operation for a column in the same row : Within the same row, it is necessary to take no less than t_{BWC} between a block write and the following read command. If t_{CK} is less than t_{BWC} , NOP command should be issued for the cycle between a block write command and the following read command.

Block Write Command to Read Command Interval

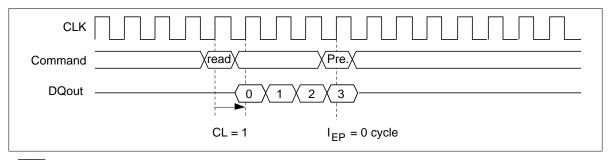


- 2. Operation for a column in other row of the same bank: It is necessary to execute a precharge command and a bank active command before the following write or another block write operation.
- 3. Operation for another bank: To execute a read command for another bank in active state, t_{BWC} interval to the next command is necessary. If another bank is in idle state, bank active command should be executed. If t_{CK} is less than t_{BWC} NOP command should be issued for the cycle between a block write command and the following read command.

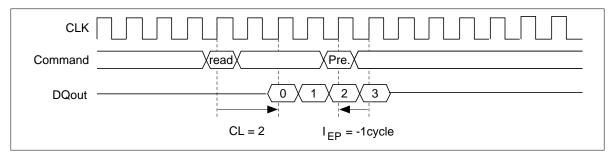
Read Command to Precharge Command: The minimum interval between read command and precharge command is one cycle. However, since the output buffer then becomes High-Z after the cycles defined by l_{HZP} , there is a possibility that burst read data output will be interrupted, if the precharge command is input during burst read. To read all data by burst read, the cycles defined by l_{EP} must be assured as an interval from the final data output to precharge command execution.

READ to PRECHARGE Command Interval (Same Bank): Output All Data

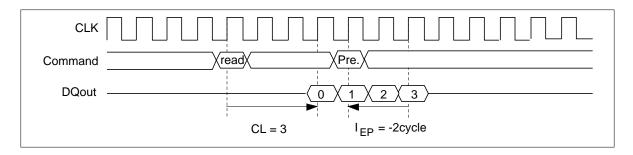
$\overline{\text{CAS}}$ Latency = 1, Burst Length = 4



 $\overline{\text{CAS}}$ Latency = 2, Burst Length = 4

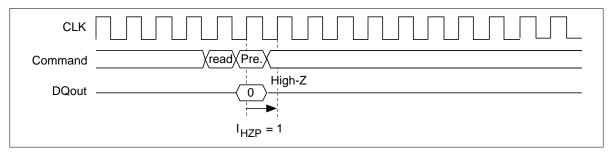


 $\overline{\text{CAS}}$ Latency = 3, Burst Length = 4

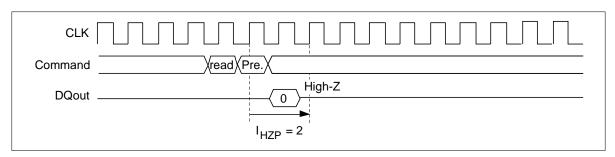


READ to PRECHARGE Command Interval (Same Bank): Stop Output Data

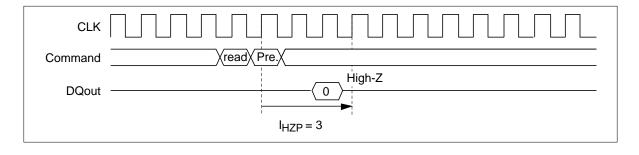
CAS Latency = 1, Burst Length = 4



CAS Latency = 2, Burst Length = 4



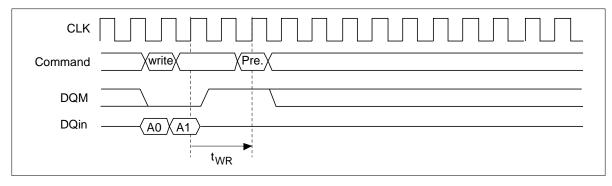
 $\overline{\text{CAS}}$ Latency = 3, Burst Length = 4



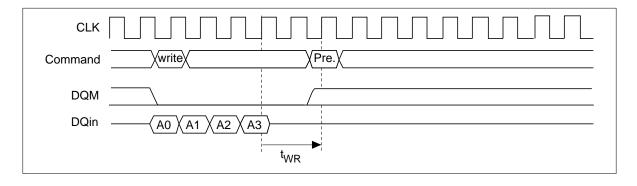
Write Command to Precharge Command: The minimum interval between a write command and the following precharge command is 1 cycle. However, if the burst write operation is not finished, input must be masked by means of DQM for the cycle defined by t_{WR} , for assurance.

WRITE to Precharge Command Interval (Same Bank)

Burst Length = 4 (To Stop Write Operation)

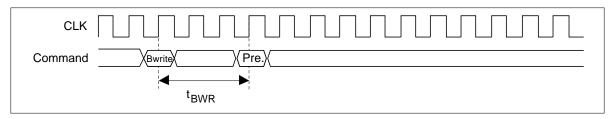


Burst Length = 4 (To Write All Data)



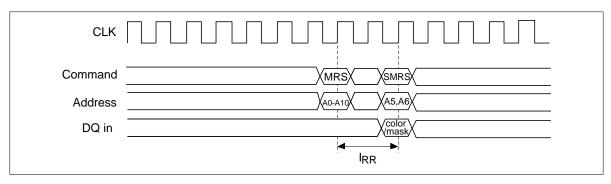
Block Write Command to Precharge Command Interval: The minimum interval between block write command and the following precharge command is t_{BWR} .

Block Write to Precharge Command Interval (Same Bank)



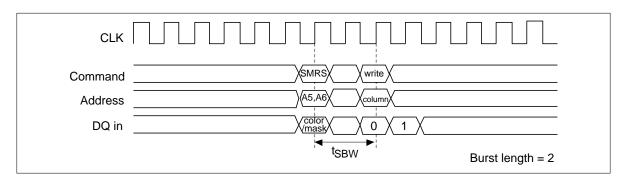
Register set to register set interval: The minimum interval between two successive register set commands (mode/special mode) is l_{RR} .

Mode register set to spacial mode register interval



Special Mode Register Set to Block Write/Write Interval: The minimum interval between a special mode register set and a block write/write is t_{SBW} .

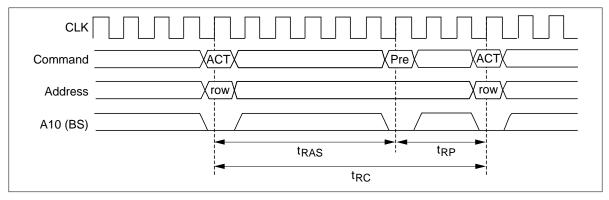
Special Mode Register Set to Burst Write Interval



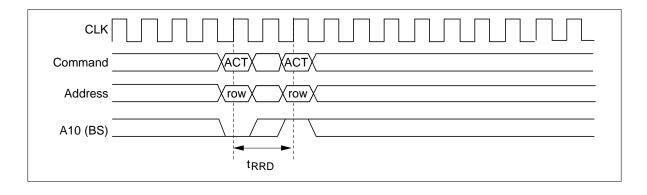
Bank Active Command Interval:

- 1. Operation for the same bank: The interval between two bank-active commands must be no less than t_{RC} .
- 2. Operation for another bank: The interval between two bank-active commands must be no less than t_{RRD} .

Bank Active to Bank Active for the Same Bank



Bank Active to Bank Active for Another Bank



Absolute Maximum Ratings

Parameter	Symbol	Value	Unit	Note
Voltage on any pin relative to V _{ss}	V _T	-1.0 to +4.6	V	1
Supply voltage relative to V _{ss}	V_{DD}	-1.0 to +4.6	V	
Short circuit output current	lout	50	mA	
Power dissipation	P _T	1.0	W	
Operating temperature	Topr	0 to +70	°C	
Storage temperature	Tstg	-55 to +125	°C	

Note: 1. V_{IH} (max) = 5.75 V for pulse width \leq 5 ns

Recommended DC Operating Conditions (Ta = 0 to +70°C)

Parameter	Symbol	Min	Max	Unit	Notes	
Supply voltage	V_{DD} , $V_{DD}Q$	3.0	3.6	V	1	
	V_{ss} , $V_{ss}Q$	0	0	V		
Input high voltage	V_{IH}	2.0	4.6	V	1, 2	
Input low voltage	V_{IL}	-0.3	0.8	V	1, 3	

Notes: 1. All voltage referred to V_{ss}

- 2. V_{IH} (max) = 5.5 V for pulse width \leq 5 ns
- 3. V_{IL} (min) = -1.0 V for pulse width $\leq 5 \text{ ns}$

DC Characteristics (Ta = 0 to 70°C, V_{DD} , $V_{DD}Q$ = 3.3 V \pm 0.3 V, V_{SS} , $V_{SS}Q$ = 0 V)

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Parameter Symbol Min Max Min			_		40		40		-		
Operating current I	Parameter	Symbol		May		May		May	- Unit	Test conditions	Note
$ \frac{t_{\text{RC}} = \min, \text{CL} = 3}{t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = \min, \text{CL} = 3}{t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = \min, \text{CL} = 3}{t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = \min, \text{CL} = 3}{t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = \min, \text{CK} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min} = \frac{t_{\text{RC}} = V_{\text{IL}}, t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = \min}{t_{\text{CK}} = min} = \frac{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = min}{t_{\text{CK}} = min} = \frac{t_{\text{CK}} = V_{\text{IL}}, t_{\text{CK}} = min}{t_{\text{CK}} = min} = \frac{t_{\text{CC}}, t_{\text{CK}} = v_{\text{IL}}, t_{\text{CK}} = min}{t_{\text{CK}} = min} = \frac{t_{\text{CC}}, t_{\text{CK}} = v_{\text{IL}}, t_{\text{CK}} = min}{t_{\text{CK}} = v_{\text{IL}}, t_{\text{CK}} = min} = \frac{t_{\text{CC}}, t_{\text{CK}} = min}{t_{\text{CK}} = v_{\text{IL}}, t_{\text{CK}} = min} = \frac{t_{\text{CC}}, t_{\text{CK}} = v_{\text{IL}}, t_{\text{CK}} $			IVIIII		IVIIII		IVIIII				
$(Bank \ Disable) \\ \hline (Bank \$	Operating current	I _{CC1}		210		180	_	150	mA	$t_{RC} = min, CL = 3$	1
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	-	I _{CC2}	_	5		5	_	5	mA	$CKE = V_{IL}, t_{CK} = min$	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			_	3		3	_	3	mA		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			_	95	_	75	_	60	mA	NOP command	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		I _{CC3}		15	_	10	_	10	mA		1
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$			_	100	_	80	_	65	mA	NOP command $t_{CK} = min$,	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Burst operating current										
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		I _{CC4}	_	220	_	170	_	140	mA	$t_{CK} = min, BL = 4$	1
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	(CL = 2)	I_{CC4}	_	280	_	240	_	200	mΑ	2 bank operation	
	(CL = 3)	I _{CC4}	_	330	_	280	_	240	mA		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Refresh current	I _{CC5}	_	190	_	150	_	120	mA		
current $ \begin{array}{ccccccccccccccccccccccccccccccccccc$	Self refresh current	I _{CC6}	_	3		3		3	mA		
Output leakage current I_{LO} -10 10 -10 10 10 μ A $0 \le Vout \le V_{DD}$ $DQ = disable$ Output high voltage V_{OH} 2.4 $ 2.4$ $ 0.4$ V $I_{OH} = -2$ mA	•	I _{CC7}	_	200	_	160	_	130	mA	1 bank operation,	
$ DQ = disable $ Output high voltage V_{OH} 2.4 — 2.4 — V $I_{OH} = -2 \text{ mA} $	Input leakage current	I _{LI}	-10	10	-10	10	-10	10	μΑ	$0 \le Vin \le V_{DD}$	
	Output leakage current	I _{LO}	-10	10	-10	10	-10	10	μΑ		
Output low voltage V_{OL} — 0.4 — 0.4 V I_{OL} = 2 mA	Output high voltage	V _{OH}	2.4		2.4		2.4		V	$I_{OH} = -2 \text{ mA}$	
	Output low voltage	V _{OL}		0.4		0.4		0.4	V	I _{OL} = 2 mA	

Note: 1. I_{cc} depends on output load condition when the device is selected. I_{cc} (max) is specified on condition that all output pins are floated.

Capacitance (Ta = 25°C, V_{DD} , $V_{DD}Q = 3.3 \text{ V} \pm 0.3 \text{ V}$)

Parameter	Symbol	Тур	Max	Unit	Notes	
Input capacitance (Address)	C _{I1}	_	5	pF	1	
Input capacitance (Signals)	C _{I2}	_	5	pF	1	
Output capacitance (DQ)	Co	_	7	pF	1, 2	

Notes: 1. Capacitance measured with Boonton Meter or effective capacitance measuring method.

^{2.} $DQM = V_{IH}$ to disable Dout.

AC Characteristics (Ta = 0 to 70°C, V_{DD} , $V_{DD}Q = 3.3~V \pm 0.3~V$, V_{SS} , $V_{SS}Q = 0~V$)

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		-8		-10		-12		•	
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
System clock cycle time									
(CL = 1)	t _{CK}	24	_	30	_	36	_	ns	_1
(CL = 2)	t _{CK}	12		15		18		ns	_
(CL = 3)	t _{CK}	8		10		12		ns	
CLK high pulse width	t _{CH}	3	_	3	_	4	_	ns	1
CLK low pulse width	t _{CL}	3		3	_	4		ns	1
Access time from CLK (CL = 1)	t _{AC}	_	23	_	28	_	32	ns	1, 2
(CL = 2)	t _{AC}	_	11	_	13	_	15	ns	_
(CL = 3)	t _{AC}	_	7	_	7.5	_	10	ns	_
Data-out hold time	t _{oH}	3	_	3	_	3		ns	1
CLK to data-out low impedance	t _{LZ}	0		0	_	0		ns	1
CLK to data-out high impedance (CL = 1)	t _{HZ}	_	11	_	13	_	15	ns	1, 3
(CL = 2,3)	t _{HZ}	_	6	_	7	_	9	ns	
Data-in setup time	t _{DS}	2.5		3	_	3.5		ns	1
Data-in hold time	t _{DH}	1	_	1	_	1.5		ns	1
Address setup time	t _{AS}	2.5		3	_	3.5		ns	1
Address hold time	t _{AH}	1	_	1	_	1.5	_	ns	1
CKE setup time	t _{CKS}	2.5	_	3	_	3.5		ns	1, 4
CKE hold time	t _{CKH}	1	_	1	_	1.5	_	ns	1, 4
Command (CS, RAS, CAS, WE, DQM, DSF) setup time	t _{CMS}	2.5	_	3	_	3.5	_	ns	1
Command (CS, RAS, CAS, WE, DQM, DSF) hold time	t _{CMH}	1	_	1	_	1.5	_	ns	1
Refresh/active to refresh/active command period	t _{RC}	72		90	_	108	_	ns	1
Active to precharge on full page mode	t _{RASC}	_	120000	_	120000	_	120000	ns	1
Active to precharge command period	t _{RAS}	48	120000	60	120000	72	120000	ns	1
Active command to column command	t _{RCD}	24		30		36		ns	1
Precharge to active command period	t _{RP}	24	_	30	_	36	_	ns	1

AC Characteristics (Ta = 0 to 70°C, V_{DD} , $V_{DD}Q = 3.3 \text{ V} \pm 0.3 \text{ V}$, V_{SS} , $V_{SS}Q = 0 \text{ V}$) (cont)

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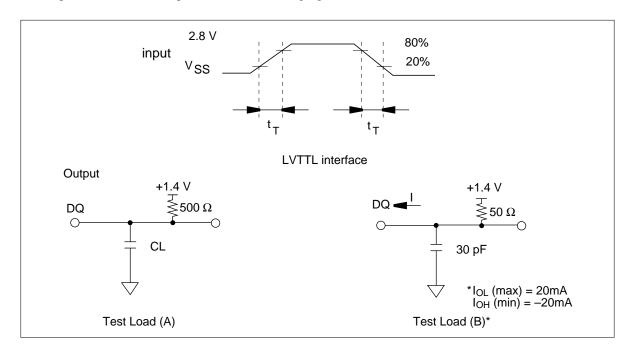
	HM52							
	-8		-10	-10		-12		
Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
t _{WR}	12	_	15	_	18		ns	_ 1
t _{WR}	12	_	15	_	18	_	ns	_
t _{WR}	16	_	20	_	24	_	ns	_
t_{BWR}	24	_	30	_	36	_	ns	1
t _{BWR}	24	_	30	_	36	_	ns	_
t _{BWR}	24	_	30	_	36	_	ns	
t _{RRD}	16	_	20	_	24	_	ns	1
t _{RSC}	16	_	20	_	24	_	ns	1
t _{BWC}	16	_	20	_	24	_	ns	1
t _{sbw}	16		20	_	24	_	ns	1
t _T	1	5	1	5	1	5	ns	_
t _{REF}		32	_	32	_	32	ms	_
	twR twR twR tbwR tbwR tbwR tbwR tbwR tbw	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Symbol Min Max t _{WR} 12 — t _{WR} 12 — t _{WR} 16 — t _{BWR} 24 — t _{BWR} 24 — t _{RRD} 16 — t _{RSC} 16 — t _{BWC} 16 — t _{SBW} 16 — t _T 1 5	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$				

Notes: 1. AC measurement assumes $t_T = 1$ ns. Reference level for timing of input signals is 1.4 V. Test load (A) is used with CL = 30 pF in general except fpr the measurement of access time (note2) and t_{HZ} (note3).

- 2. Access time is measured at 1.4 V. Test load (B) is used with current source.
- 3. t_{HZ} (max) defines the time at which the outputs achieves \pm 200 mV. Test load (A) is used with CL = 5 pF and with current source.
- 4. When Active Suspend Exit, Power Down Exit or Self Refresh Exit is executed. CKE should be kept "H" more than 1 cycle from these Exit cycles.

Test Conditions

- Input and output timing reference levels: 1.4 V
- Input waveform and output load: See following figures



Relationship Between Frequency and Minimum Latency

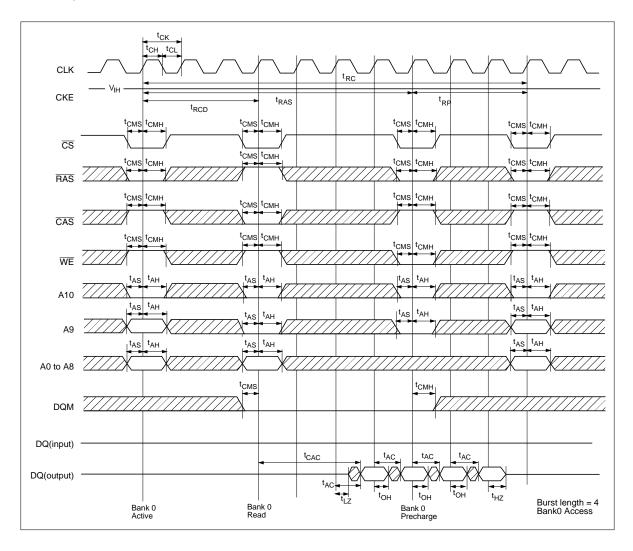
ŀ	1	N	15	2	!1	6	3	2	6

Parameter		-8			-10 ·			-12			_
CL	_	3	2	1	3	2	1	3	2	1	_
t _{ck} (ns)	Symbol	8	12	24	10	15	30	12	18	36	Notes
Last data in to active command (Auto precharge, same bank)	I _{APW}	5	3	2	5	3	2	5	3	2	
Block write to active command (Auto precharge, same bank)	I _{APBW}	6	4	2	6	4	2	6	4	2	
Precharge command to high impedance	I _{HZP}	3	2	1	3	2	1	3	2	1	
Last data out to active command (Auto precharge, same bank)	I _{APR}	1	1	1	1	1	1	1	1	1	
Last data out to precharge	I _{EP}	-2	-1	0	-2	-1	0	-2	-1	0	
Column command to column command	I _{CCD}	1	1	1	1	1	1	1	1	1	
Write command to data in latency	I _{wcD}	0	0	0	0	0	0	0	0	0	
DQM to data in	I _{DID}	0	0	0	0	0	0	0	0	0	
DQM to data out	I _{DOD}	2	2	2	2	2	2	2	2	2	
CKE to CLK disable	I _{CLE}	1	1	1	1	1	1	1	1	1	
Burst stop to output valid data hold	I _{BSR}	2	1	0	2	1	0	2	1	0	
Burst stop to output high impedance	I _{BSH}	3	2	1	3	2	1	3	2	1	
Burst stop to write data ignore	I _{BSW}	0	0	0	0	0	0	0	0	0	
MRS to data in latency	I _{MSD}	0	0	0	0	0	0	0	0	0	
SMRS to data in latency	I _{SSD}	0	0	0	0	0	0	0	0	0	
Register set to register set	I _{RR}	2	2	1	2	2	1	2	2	1	
Self refresh exit to command input	I _{SEC}	9	6	3	9	6	3	9	6	3	= [t _{RC}]
Self refresh exit time	I _{SREX}	2	2	2	2	2	2	2	2	2	1

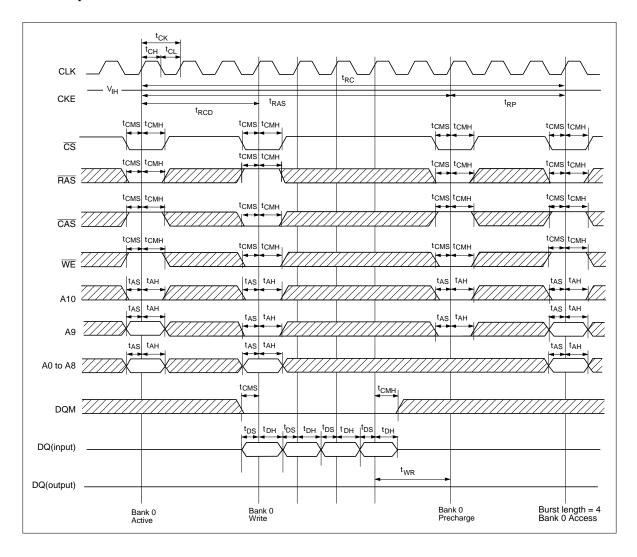
Note: 1. When self refresh exit is executed, CKE should be kept "H" for longer than I_{SREX} from exit cycle.

Timing Waveforms

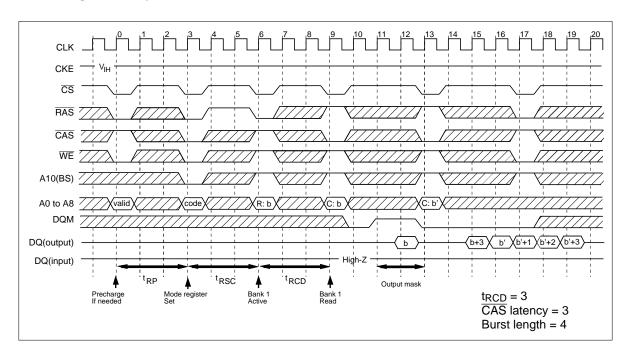
Read Cycle



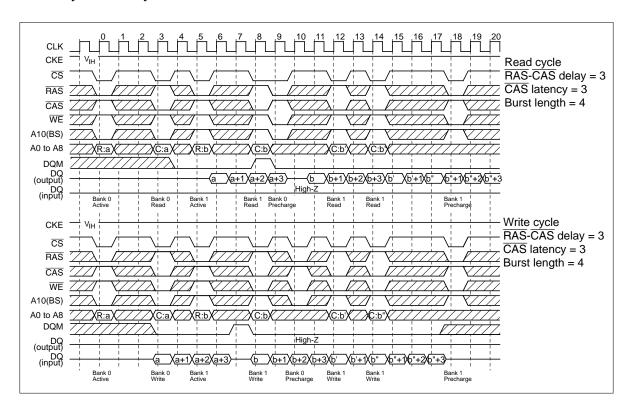
Write Cycle



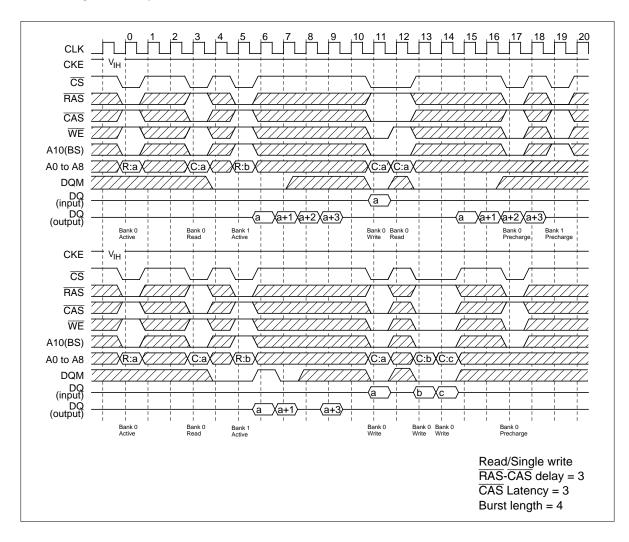
Mode Register Set Cycle



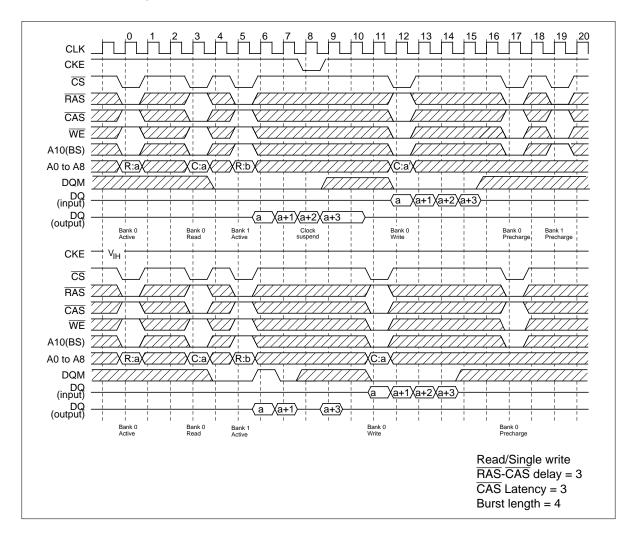
Read Cycle/Write Cycle



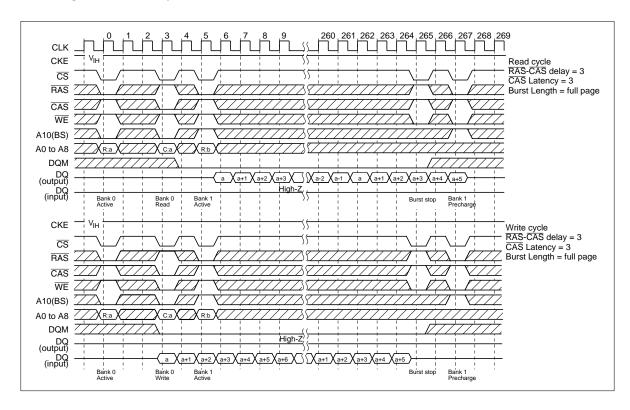
Read/Single Write Cycle



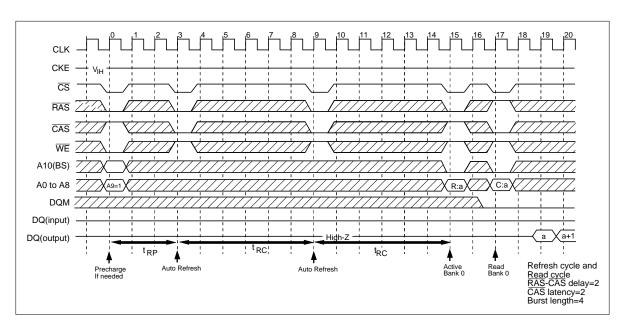
Read/Burst Write Cycle



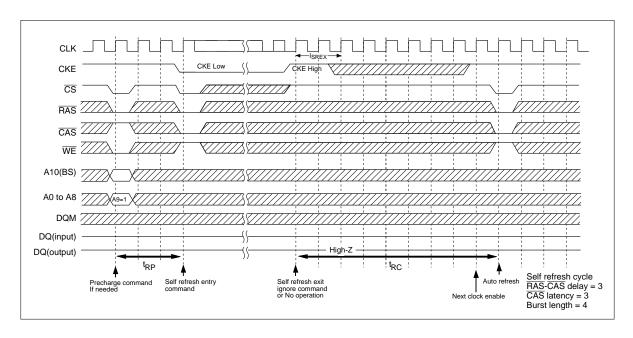
Full Page Read/Write Cycle



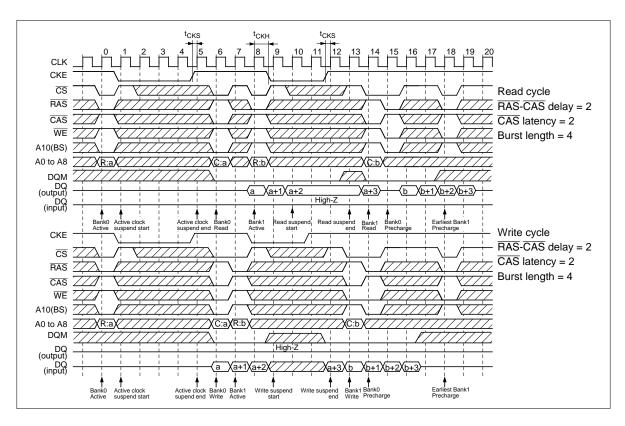
Auto Refresh Cycle



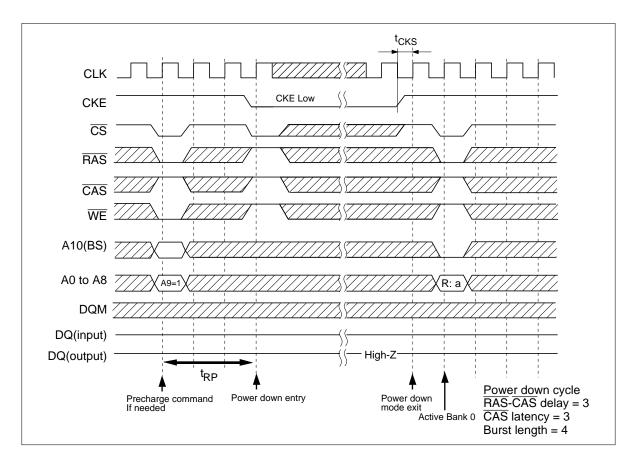
Self Refresh Cycle



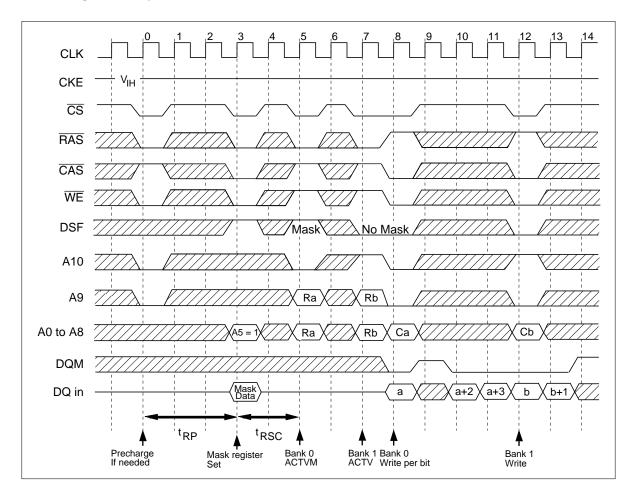
Clock Suspend Mode



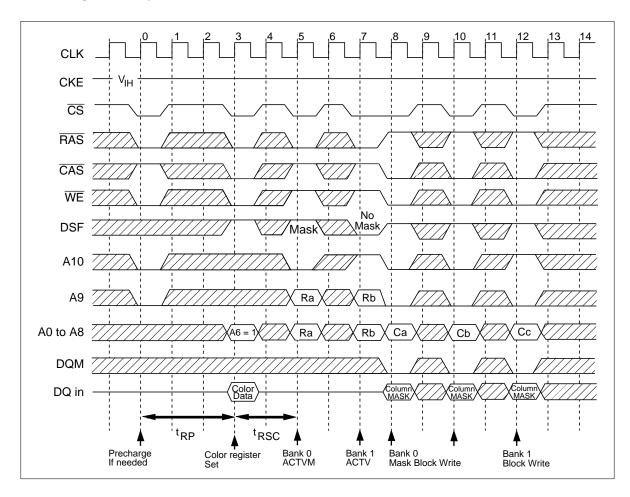
Power Down Mode



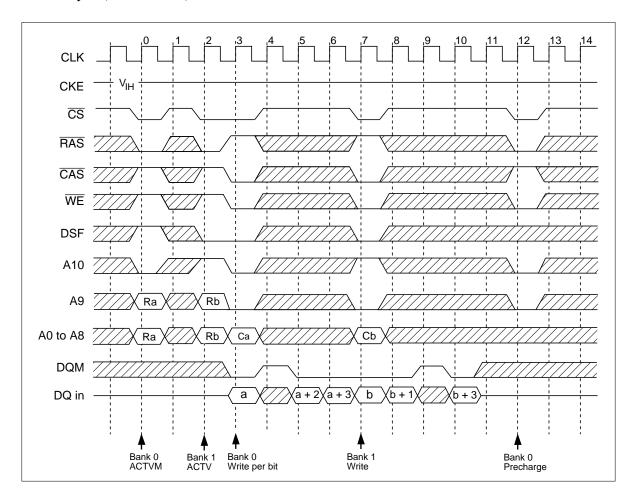
Mask Register Set Cycle



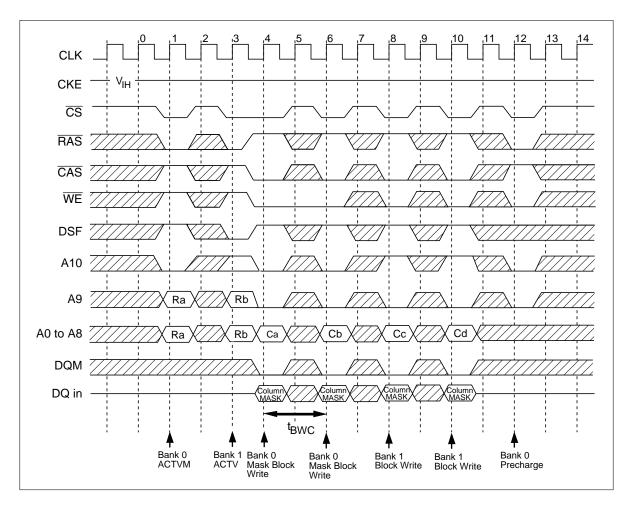
Color Register Set Cycle



Write Cycle (with I/O Mask)

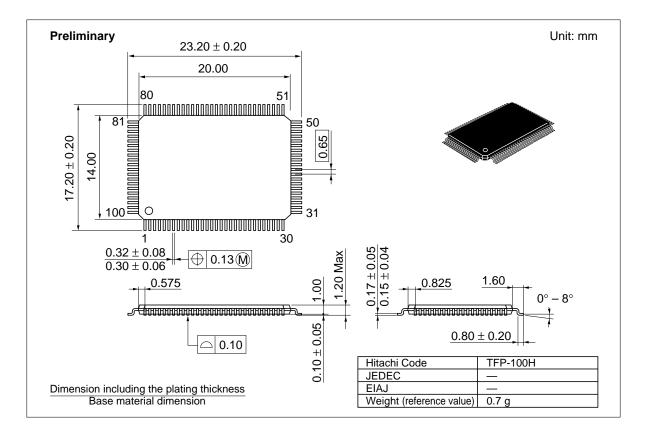


Block Write Cycle



Package Dimensions

HM5216326FP Series (TFP-100H)



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Revision Record

Rev.	Date	Contents of Modification	Drawn by	Approved by
0.0	Nov. 20, 1996	Initial issue	Y. Saiki	T. Kizaki
0.1	Jun. 9, 1997	Change of Package type: FP-100H to TFP-100H Change of CKE Truth Table AC Characteristics $t_{\text{CH}},t_{\text{CL}}\text{min: }2.5/3/4\text{ns to }3/3/4\text{ns}$ $t_{\text{AC}}(\text{CL}=2)\text{max: }10/11/12\text{ns to }11/13/15\text{ns}$ $t_{\text{OH}}\text{min: }2/3/3\text{ns to }3/3/3\text{ns}$ Timing Waveforms Change of Read/Single Write Cycle and Read/Burst Write Cycle	Y. Saiki	T. Kizaki
0.2	Nov. 21, 1997	Deletion of note for Auto precharge DC Characteristics I_{CC1} max: TBD/TBD/TBD mA to 210/180/150 mA I_{CC2} max: TBD/TBD/TBD mA to 5/5/5 mA I_{CC2} max: TBD/TBD/TBD mA to 5/5/5 mA I_{CC2} max: TBD/TBD/TBD mA to 3/3/3 mA I_{CC2} max: TBD/TBD/TBD mA to 95/75/60 mA I_{CC3} max: TBD/TBD/TBD mA to 15/10/10 mA I_{CC3} max: TBD/TBD/TBD mA to 100/80/65 mA I_{CC4} (CL=1) max: TBD/TBD/TBD mA to 220/170/140 mA I_{CC4} (CL=2) max: TBD/TBD/TBD mA to 280/240/200 mA I_{CC4} (CL=3) max: TBD/TBD/TBD mA to 330/280/240 mA I_{CC5} max: TBD/TBD/TBD mA to 190/150/120 mA I_{CC6} max: TBD/TBD/TBD mA to 1/1/1 mA I_{CC7} max: TBD/TBD/TBD mA to 200/160/130 mA AC Characteristics t_{AC} (CL = 1) max: 22/28/32 ns to 23/28/32 ns t_{AC} (CL = 3) max: 6.5/7.5/10 ns to 7/7.5/10 ns t_{DS} , t_{AS} , t_{CKS} , t_{CMS} min: 2/3/3.5 ns to 2.5/3/3.5 ns Change of Package dimension		K. Hayakawa
0.3	Jan. 14, 1998	Correct error DC Characteristics I _{CC6} max: 1/1/1 mA to 3/3/3 mA Relationship Between Frequency and Minimum Latency Addition of I _{SEC} : 9/6/3 Addition of I _{SREX} : 2/2/2 Addition of note1 Timing Waveforms: Change of Self refresh cycle	H. Suzuki	K. Hayakawa

Rev.	Date	Contents of Modification	Drawn by	Approved by
0.4	May. 19, 1998	Correct errors Change of figures for Column address and write command (BL = 2), Power on sequence, READ to PRECHARGE command interval: Output all data (CL = 2), Mode register set to special mode register set interval Bank active to bank active for the same bank Bank active to bank active for another bank Change of description for Graphic commands note Change of Simplified State Diagram Change of Timing waveforms for self refresh cycle Relationship Between Frequency and Minimum Latency: Change of note1 ("H" longer to "H" for longer) Timing Waveforms: in figures (A0 to A7) to (A0 to A8)	H. Suzuki	K. Hayakawa
1.0	Jul. 6, 1998	Deletion of Preliminary	H. Suzuki	K. Hayakawa
2.0	Oct. 2, 1998	Correct errors Column address and block write command: A0 to A1 HIGH or LOW to A0 to A2 HIGH or LOW CKE Truth Table Change of DSF (self refresh): L to ×		