(Low-Power Dot-Matrix Liquid Crystal Display Controller/Driver with Key Scan Function)

# **HITACHI**

### **Description**

The HD66727, dot-matrix liquid crystal display controller and driver LSI incorporating a key scan function, displays alphanumerics, katakana, hiragana, and symbols. It can be configured to drive a dot-matrix liquid crystal display and control key scan functions under the control of an I<sup>2</sup>C bus or a clock-synchronized serial microprocessor. A single HD66727 is capable of displaying up to four 12-character lines, 40 segments, and 12 annunciators, and controlling up to a 4-by-8 key matrix, and driving three LED. The HD66727 incorporates all the functions required for driving a dot-matrix liquid crystal display such as display RAM, character generator, and liquid crystal drivers, and it also incorporates a booster for the LCD power supply and key scan functions.

The HD66727 provides various functions to reduce the power consumption of an LCD system such as low-voltage operation of 2.4V or less, a booster for generating a maximum of triple LCD drive voltage from the supplied voltage, and voltage-followers for decreasing the direct current flow in the LCD drive bleeder-resistors. Combining these hardware functions with software functions such as standby and sleep modes allows a fine power control. The HD66727, with the above functions, is suitable for any portable battery-driven product requiring long-term driving capabilities and small size.

#### **Features**

- Control and drive of a dot-matrix LCD with built-in key scan functions
- Four 12-character lines, 40 segments, and 12 annunciators
- Control of up to a 4 × 8-key matrix, 3 LED ports and 3 general ports
- Low-power operation support:
  - 2.4 to 5.5V (low voltage)
  - Double or triple booster for liquid crystal drive voltage
  - Contrast adjuster and voltage followers for decreasing the direct current flow in the LCD drive bleeder-resistors
  - Standby mode and sleep mode
  - Displays up to 12 static annunciators
- I<sup>2</sup>C bus or clock-synchronized serial interface
- 60 × 8-bit display data RAM (60 characters max)

- 11,520-bit character generator ROM
  - 240 characters ( $6 \times 8$  dots)
- 32 × 6-bit character generator RAM
  - -4 characters (6  $\times$  8 dots)
- 8 × 6-bit segment RAM
  - 40 segment-icons and marks max
- 60-segment × 34-common liquid crystal display driver
- Programmable display sizes and duty ratios (see Table 1)
- Vertical smooth scroll
- Vertical double-height display of all character fonts
- Horizontal double display with dedicated character fonts (6-dot font width used)
- Wide range of instruction functions:
  - Clear display, display on/off control, icon and mark control, character blink, white-black inverting blinking cursor, icon and mark blink, return home, cursor on/off, white-black inverting raster-row
- Internal oscillation with an external resistor
- Hardware reset
- Wide range of LCD drive voltages
  - 3.0V to 13.0V
- Slim chip with bumps for chip-on-glass (COG) mounting, slim chip without bumps for chip-on-board (COB) mounting, and tape carrier package (TCP) (under development)

Table 1 Programmable Display Sizes and Duty Ratios

Display Size	Duty Ratio	Oscillation Frequency	Current Consumption	Multi- plexed- Drive Segments	Static- Drive Annu- nciators	Scanned Keys	LED Drive	General Port
1 line × 12 characters	1/10	40 kHz	8 μΑ	40	12	32 (4 × 8)	3	3
2 lines × 12 characters	1/18	80 kHz	15 μΑ	40	12	32 (4 × 8)	3	3
3 lines × 12 characters	1/26	120 kHz	23 μΑ	40	12	32 (4 × 8)	3	3
4 lines × 12 characters	1/34	160 kHz	30 μΑ	40	12	32 (4 × 8)	3	3

Note: Current consumption excludes that for LCD power supply source;  $V_{cc} = 3V$ .

## Type Name

External Dimension	Operation Voltage	Internal Font
TCP	2.4V to 5.5V	Japanese and European fonts
Bare chip	_	
Au-bumped chip	_	
TCP	2.4V to 5.5V	PHS & Pager fonts
Bare chip	_	
Au-bumped chip	_	
	Dimension TCP Bare chip Au-bumped chip TCP Bare chip	Dimension Operation Voltage  TCP 2.4V to 5.5V  Bare chip  Au-bumped chip  TCP 2.4V to 5.5V  Bare chip

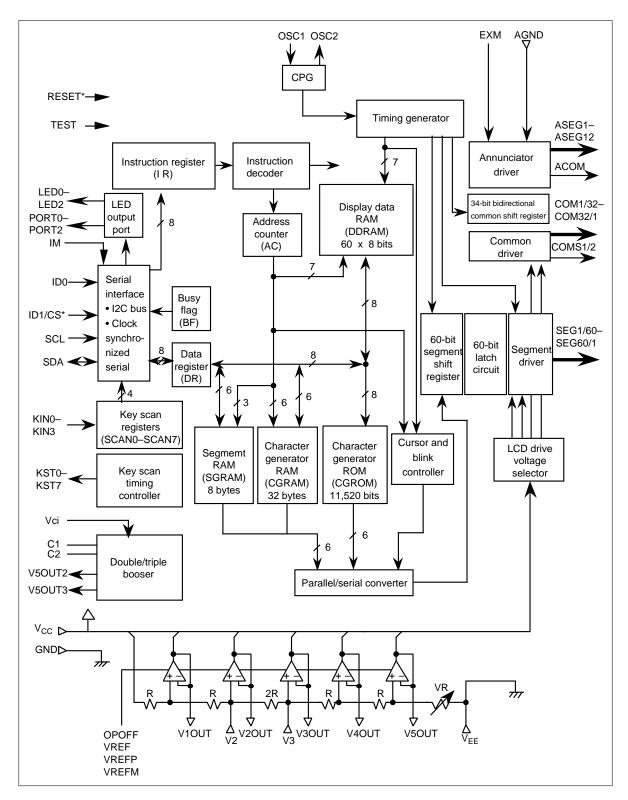
## **LCD-II Family Comparison**

Item	LCD-II (HD44780U)	HD66702R	HD66710	HD66712U
Power supply voltage	2.7V to 5.5V	5V ± 10% (standard) 2.7 V to 5.5V (low voltage)	2.7V to 5.5V	2.7V to 5.5V
Liquid crystal drive voltage	3.0 to 11.0V	3.0V to 8.3V	3.0 to 13.0V	2.7 to 11.0V
Maximum display - characters per chip	8 characters × 2 lines	20 characters × 2 lines	16 characters × 2 lines/ 8 characters × 4 lines	24 characters × 2 lines/ 12 characters × 4 lines
Segment display	None	None	40	60 (extended to 80)
Display duty ratio	1/8, 1/11, and 1/16	1/8, 1/11, and 1/16	1/17 and 1/33	1/17 and 1/33
CGROM	9,920 bits (208 5-x-8 dot characters and 32 5-x-10 dot characters)	7,200 bits (160 5-x-7 dot characters and 32 5-x-10 dot characters)	9,600 bits (240 5-x-8 dot characters)	9,600 bits (240 5-x-8 dot characters)
CGRAM	64 bytes	64 bytes	64 bytes	64 bytes
DDRAM	80 bytes	80 bytes	80 bytes	80 bytes
SEGRAM	None	None	8 bytes	16 bytes
Segment signals	40	100	40	60
Common signals	16	16	33	34
Liquid crystal drive waveform	Α	В	В	В
Clock source	External resistor or external clock	External resistor or external clock	External resistor or external clock	External resistor or external clock
Rf oscillation frequency	270 kHz ± 30%	320 kHz ± 30%	270 kHz ± 30%	270 kHz ± 30%
Liquid crystal voltage booster circuit	None	None	Double or triple booster circuit	Double or triple booster circuit
Liquid crystal drive operational amplifier	None	None	None	None
Bleeder-resistor for liquid crystal drive	External	External	External	External
Liquid crystal contrast adjuster	None	None	None	None
Key scan circuit	None	None	None	None
Extension driver control signal	Independent control signal	Independent control signal	Used in common with a driver output pin	Independent control signal
Reset function	Internal reset circuit	Internal reset circuit	Internal reset circuit	Internal reset circuit or reset input
Horizontal smooth scroll	Impossible	Impossible	Dot unit	Dot unit and line unit
Vertical smooth scroll	Impossible	Impossible	Impossible	Impossible
Number of displayed lines	1 or 2	1 or 2	1, 2, or 4	1, 2, or 4
Low power control	None	None	Low power mode	Low power mode
Bus interface	4 or 8 bits	4 or 8 bits	4 or 8 bits	Serial, 4, or 8 bits
Package	80-pin QFP1420 80-pin TQFP1414 80-pin bare chip	144-pin FQFP2020 144-pin bare chip	100-pin QFP1420 100-pin TQFP1414 100-pin bare chip	128-pin TCP 128-pin bare chip

## **LCD-II Family Comparison (cont)**

Item	HD66720	HD66717	HD66727
Power supply voltage	2.7V to 5.5V	2.4V to 5.5V	2.4V to 5.5V
Liquid crystal drive voltage	3.0 to 11.0V	3.0 to 13.0V	3.0 to 13.0V
Maximum display characters per chip	10 characters × 1 line/ 8 characters × 2 lines	12 characters × 1 line/2 lines/3 lines/4 lines	12 characters × 1 line/2 lines/3 lines/4 lines
Segment display	42 (extended to 80)	40 (and 10 annunciators)	40 (and 12 annunciators)
Display duty ratio	1/9 and 1/17	1/10, 1/18, 1/26, and 1/34	1/10, 1/18, 1/26, and 1/34
CGROM	9,600 bits (240 5-x-8 dot characters)	9,600 bits (240 5-x-8 dot characters)	11,520 bits (240 6-x-8 dot characters)
CGRAM	64 bytes	32 bytes	32 bytes
DDRAM	40 bytes	60 bytes	60 bytes
SEGRAM	16 bytes	8 bytes	8 bytes
Segment signals	42	60	60
Common signals	17	34	34
Liquid crystal drive waveform	В	В	В
Clock source	External resistor or external clock	External resistor or external clock	External resistor or external clock
Rf oscillation frequency	160 kHz ± 30%	1-line mode: 40 kHz ± 30% 2-line mode: 80 kHz ± 30% 3-line mode: 120 kHz ± 30% 4-line mode: 160 kHz ± 30%	1-line mode: 40 kHz $\pm$ 30% 2-line mode: 80 kHz $\pm$ 30% 3-line mode: 120 kHz $\pm$ 30% 4-line mode: 160 kHz $\pm$ 30%
Liquid crystal voltage booster circuit	Double or triple booster circuit	Double or triple booster circuit	Double or triple booster circuit
Liquid crystal drive operational amplifier	None	Built-in for each V1 to V5	Built-in for each V1 to V5
Bleeder-resistor for liquid crystal drive	External	Internal 1/4 and 1/6 bias resistors	Internal 1/4 and 1/6 bias resistors
Liquid crystal contrast adjuster	None	Incorporated	Incorporated
Key scan circuit	$5 \times 6 = 30 \text{ keys}$	None	$4 \times 8 = 32 \text{ keys}$
Extension driver control signal	Independent control signal	None	None
Reset function	Internal reset circuit or reset input	Reset input	Reset input
Horizontal smooth scroll	Dot unit and line unit	Impossible	Impossible
Vertical smooth scroll	Impossible	Dot (raster-row) unit	Dot (raster-row) unit
Number of displayed lines	1 or 2	1, 2, 3, or 4	1, 2, 3, or 4
Low power control	Low power mode and sleep mode	Standby mode and sleep mode	Standby mode and sleep mode
Bus interface	Serial	I <sup>2</sup> C, serial, 4, or 8 bits	I <sup>2</sup> C or clock-synchronized serial
Package	100-pin QFP1420 100-pin TQFP1414 100-pin bare chip	Slim chip with/without bumps TCP	Slim chip with/without bumps TCP

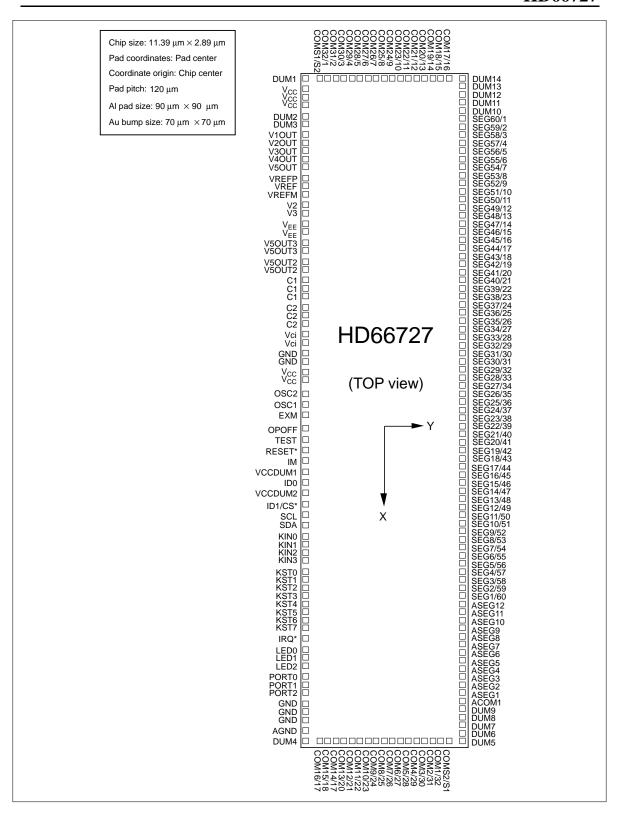
## **HD66727 Block Diagram**



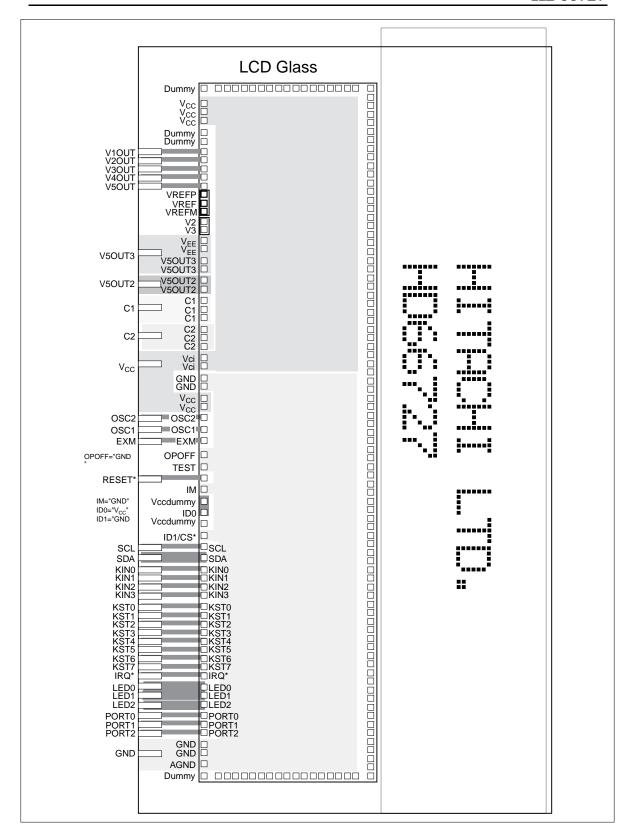
## **HD66727 Pad Coordinates**

Pad Name	х	Υ	Pad Name	lx	Υ	Pad Name	x	Υ	Pad Name	х	Υ
DUM1	-5446	-1244	KIN1	1737	-1173	ASEG3	4212	1191	SEG39/22	-1905	1196
$V_{CC}$	-5146	-1244	KIN2	1904	-1173	ASEG4	4088	1191	SEG40/21	-2029	1196
V <sub>CC</sub>	-5022	-1244	KIN3	2071	-1173	ASEG5	3963	1191	SEG41/20	-2153	1196
V <sub>CC</sub>	-4898	-1244	KST0	2261	-1173	ASEG6	3839	1191	SEG42/19	-2278	1196
DUM2	-4648	-1244		2421	-1173	ASEG7	3714	1191	SEG43/18	-2402	1196
DUM3	-4524	-1244	KST2	2581	-1173	ASEG8	3590	1191	SEG44/17	-2527	1196
V1OUT	-4336	-1169		2740		ASEG9	3465	1191	SEG45/16	-2651	1196
V2OUT	-4216	-1169		2900		ASEG10	3341	1191	SEG46/15	-2776	1196
V3OUT	-4095	-1169	KST5	3060	1173	ASEG11	3217	1191	SEG47/14	-2900	1196
V4OUT	-3975	-1169		3220	-1173	ASEG12	3092	1191	SEG48/13	-3024	1196
V5OUT	-3855	-1169		3380	-1173		2824	1196	SEG49/12	-3149	1196
VREFP	-3734	-1169	IRQ*	3539	-1173		2700	1196	SEG50/11	-3273	1196
VREF	-3614	-1169	LED0	3716	-1173	SEG3/58	2575	1196	SEG51/10	-3398	1196
VREFM	-3494	-1169	LED1	3876	-1173	SEG4/57	2451	1196	SEG52/9	-3522	1196
V2	-3373	-1169	LED2	4036	-1173	SEG5/56	2326	1196	SEG53/8	-3647	1196
V3	-3253	-1169	PORT0	4228	-1173	SEG6/55	2202	1196	SEG54/7	-3771	1196
$V_{FF}$	-3106	-1168	PORT1	4403	-1173	SEG7/54	2078	1196	SEG55/6	-3896	1196
V <sub>EE</sub>	2985	-1168	PORT2	4578	-1173	SEG8/53	1953	1196	SEG56/5	-4020	1196
V5OUT3	-2829	-1168	GND	4735	-1201		1829	1196	SEG57/4	-4144	1196
V5OUT3	-2708	-1168	GND	4855	-1201	SEG10/51	1704	1196	SEG58/3	-4269	1196
V5OUT2	-2528	-1168	GND	5054	-1201	SEG11/50	1580	1196	SEG59/2	-4393	1196
V5OUT2	-2407	-1168	AGND	5263	-1201	SEG12/49	1455	1196	SEG60/1	-4518	1196
C1	-2216	-1168	DUM4	5446	-1201	SEG13/48	1331	1196	DUM10	-4773	1260
C1	-2095	-1168	COM16/17	5446	-1020	SEG14/47	1206	1196	DUM11	-4898	1260
C1	-1975	-1168	COM15/18	5446	-896	SEG15/46	1082	1196	DUM12	-5022	1260
C2	-1822	-1168	COM14/19	5446	-772	SEG16/45	958	1196	DUM13	-5146	1260
C2	-1701	-1168	COM13/20	5446	-647	SEG17/44	833	1196	DUM14	-5446	1260
C2	-1580	-1168	COM12/21	5446	-523	SEG18/43	709	1196	COM17/16	-5446	970
VCI	-1389	-1168	COM11/22	5446	-398	SEG19/42	584	1196	COM18/15	-5446	845
VCI	-1268	-1168	COM10/23	5446	-274	SEG20/41	460	1196	COM19/14	-5446	721
GND	-1083	-1168	COM9/24	5446	-149	SEG21/40	335	1196	COM20/13	-5446	596
GND	-962	-1168	COM8/25	5446	-25	SEG22/39	211	1196	COM21/12	-5446	472
V <sub>cc</sub>	-792	-1168	COM7/26	5446	100	SEG23/38	87	1196	COM22/11	-5446	348
V <sub>CC</sub>	-672	-1168	COM6/27	5446	224	SEG24/37	-38	1196	COM23/10	-5446	223
OSC2	-459	-1173	COM5/28	5446	348	SEG25/36	-162	1196	COM24/9	-5446	99
OSC1	-315	-1173	COM4/29	5446	473	SEG26/35	-287	1196	COM25/8	-5446	-26
EXM	-148	-1173	COM3/30	5446	597	SEG27/34	-411	1196	COM26/7	-5446	-150
OPOFF	19	-1173	COM2/31	5446	722	SEG28/33	-536	1196	COM27/6	-5446	-275
TEST	185	-1173	COM1/32	5446	846	SEG29/32	-660	1196	COM28/5	-5446	-399
RESET*	352	-1173	COMS2/S1	5446	971	SEG30/31	-785	1196	COM29/4	-5446	-524
IM	519	-1173	DUM5	5446	1246	SEG31/30	-909	1196	COM30/3	-5446	-648
VCCDUM1	666	-1173	DUM6	5194	1246	SEG32/29	-1033	1196	COM31/2	-5446	-772
ID0	789	-1173	DUM7	5070	1246	SEG33/28	-1158	1196	COM32/1	-5446	-897
VCCDUM2	937	-1173	DUM8	4945		SEG34/27	-1282	1196	COMS1/S2	-5446	-1021
ID1	1059	-1173		4821		SEG35/26	-1407				
SCL	1226		ACOM1	4585		SEG36/25	-1531	1196			
SDA	1392		ASEG1	4461		SEG37/24	-1656				
KIN0	1571	-1173	ASEG2	4337		SEG38/23	-1780	1196			

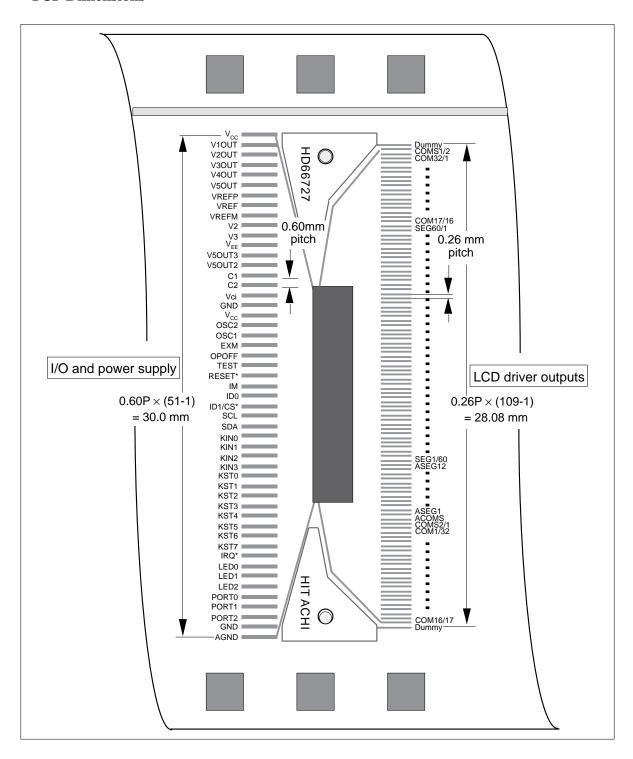
**HD66727 Pad Arrangement** 



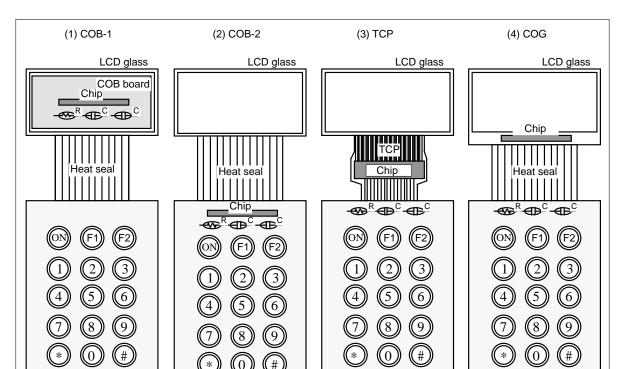
**Chip-on-Glass (COG) Mounting and Routing Examples** 



## **TCP Dimensions**



Key-matrix board



## **HD66727** Mounting Variations and Key-Matrix Configurations

Key-matrix board

Figure 1 HD66727 Mounting Variations

Key-matrix board

Key-matrix board

Table 2 Configurations of LCD Modules (LCM) with Key Scan Function for Different Mounting Methods

Parts	Chip-on-Board (COB) Mounting 1	Chip-on-Board (COB) Mounting 2	Tape-Carrier- Package (TCP) Mounting	Chip-on-Glass (COG) Mounting
LCD glass	Necessary	Necessary	Necessary	Necessary
LCM (COB) substrate	Necessary	Not necessary	Not necessary	Not necessary
HD66727 package	Bare chip	Bare chip	TCP	Bumped chip
Heat seal	Necessary	Necessary	Optional	Necessary
Key matrix substrate	Necessary	Necessary	Necessary	Necessary

## **Pin Functions**

 Table 3
 Pin Functional Description

Signal	Number of Pins	I/O	Connected to	Function
IM	1	I	V <sub>cc</sub> or GND	Selects the MPU interface mode: Low: I <sup>2</sup> C bus mode High: Clock-synchronized serial mode
ID1/CS*	1	I	ID1: V <sub>cc</sub> or GND CS*: MPU	Inputs the HD66727's identification code (ID1) in the I <sup>2</sup> C bus mode.  Selects the HD66727 in the clock-synchronized serial mode:  Low: HD66727 is selected and can be accessed  High: HD66727 is not selected and cannot be accessed
SDA	1	I/O	MPU	Inputs/outputs serial (receive/transmit) data and outputs the acknowledge bit in the I <sup>2</sup> C bus mode. Inputs/outputs serial (receive/transmit) data in the clock-synchronized serial mode.
SCL	1	I	MPU	Inputs serial clock pulses. Serial data is latched at the rising edge of each clock pulse.
ID0	1	I	V <sub>cc</sub> or GND	Inputs the HD66727's identification code in both interface modes; must be fixed to high or low.
IRQ*	1	0	MPU	Generates the key scan interrupt signal.
KST0- KST7	8	0	Key matrix	Generates strobe signals for latching scanned data from the key matrix at specific time interval.
KIN0-KIN3	4	1	Key matrix	Samples key state from key matrix synchronously with strobe signals.
LED0- LED2	3	0	LED back light	Output ports for control of LED or back light. Can draw 2 mA–3 mA sink current. Also used as general ports.
PORT0- PORT2	3	0	General output	General output ports. These ports cannot drive current such as LED control.
COMS1/2, COMS2/1	2	0	LCD	Common output signals for segment-icon display.
COM1/32- COM32/1	32	O	LCD	Common output signals for character display: COM1 to COM8 for the first line; COM9 to COM16 for the second line, COM17 to COM24 for the third line, and COM25 to COM32 for the fourth line. All the unused pins output deselection waveforms. In the sleep mode (SLP = 1) or standby mode (STB = 1), all pins output $V_{\rm CC}$ level. The CMS bit can change the shift direction of the common signal. For example, if CMS = 0, COM1/32 is COM1. If CMS = 1, COM1/32 is COM32.

Table 3 Pin Functional Description (cont)

	Number of								
Signal	Pins	I/O	Connected to	Function					
SEG1/60- SEG60/1	60	0	LCD	Segment output signals for segment-icon display and character display. In the sleep mode (SLP = 1) or standby mode (STB = 1), all pins output $V_{\rm cc}$ level. The SGS bit can change the shift direction of the segment signal. For example, if SGS = 0, SEG1/60 is SEG1. If SGS = 1, SEG1/60 is SEG60.					
ACOM	1	0	LCD	display statically between \	annunciator display; can drive $\gamma_{\rm cc}$ and AGND levels; outputs display is turned off (DA = 0).				
ASEG1- ASEG12	12	0	LCD	Segment output signals for annunciator display; can drive display statically between $V_{\rm CC}$ and AGND levels; output $V_{\rm CC}$ level while annunciator display is turned off (DA = 0).					
V2, V3	2	I	Open or short- circuited	V2 and V3 are voltage levels for the internal operational amplifiers; can drive LCD with 1/4 bias when V2 and V3 are short-circuited and with 1/6 bias when they are left disconnected.					
VREFP, VREF, VREFM	3	I	Open or short- circuited	Adjusts the driving capability of the internal operational amplifiers according to the LCD power suppoly voltage.					
				LCD Power Supply Voltage (V <sub>CC</sub> -V <sub>EE</sub> )	Pin Settings VREF, VREFP, and VREFM				
				$V_{CC}-V_{EE}$ : $3V-5V$	Only VREF and VREFP shorted				
				$V_{CC}-V_{EE}$ : $4V-6V$	All pins open				
				$V_{CC}-V_{EE}$ : 5V-8V	All pins shorted				
				$V_{cc}$ – $V_{EE}$ : 7V or more	Only VREF and VREFM shorted				
V1OUT- V5OUT	5	I or O	Open or external bleeder-resistor	Used for output from the internal operational amplifiers when they are used (OPOFF = GND); when amplifiers'					
$V_{EE}$	2	_	Power supply	GND power supply for LCD	drive. $V_{CC} - V_{EE} \le 13V$ .				
$V_{\rm cc}$ , GND	8	_	Power supply	V <sub>cc</sub> : +2.4V to +5.5V; GND (	logic): 0V				
AGND	1	_	Power supply	Low level power supply for adjust contrast of annuncia					
OSC1, OSC2	2	_	Oscillation- resistor or clock	For R-C oscillation, connect external clock supply, input					

Table 3 Pin Functional Description (cont)

Signal	Number of Pins	I/O	Connected to	Function
Vci	2	I	Power supply	Inputs a reference voltage and supplies power to the booster; generates the liquid crystal display drive voltage from the operating voltage. Vci = $1.0V$ to $5.0V \le V_{\rm CC}$
V5OUT2	3	0	V <sub>EE</sub> pin/booster capacitance	Voltage input to the Vci pin is boosted twice and output. When the voltage is boosted three times, the same capacitance as that of C1–C2 should be connected here.
V5OUT3	2	0	V <sub>EE</sub> pin	Voltage input to the Vci pin is boosted three times and output.
C1, C2	6	_	Booster capacitance	External capacitance should be connected here when using the booster.
RESET*	1	1	MPU or external R-C circuit	Reset pin. Initializes the LSI when low. Be sure to input this signal after power-on.
EXM	1	I	MPU	External alternating signal used for annunciator display in the standby mode. If annunciator display is not used, EXM must be fixed to $V_{\rm cc}$ or GND.
OPOFF	1	I	V <sub>cc</sub> or GND	Turns the internal operational amplifier off when OPOFF = $V_{CC}$ , and turns it on when OPOFF = GND. If the amplifier is turned off (OPOFF = $V_{CC}$ ), V1 to V5 must be supplied to the V1OUT to V5OUT pins.
V <sub>cc</sub> dummy	2	0	Input pad	Outputs $V_{\text{cc}}$ supply level; can fix the input pads to $V_{\text{cc}}$ level.
TEST	1	I	GND	Test pin. Must be fixed at GND level.

### **Block Function Description**

#### **System Interface**

The HD66727 has two types of system interfaces: I<sup>2</sup>C bus and clock-synchronized serial. The interface mode is selected by the IM pin.

The HD66727 has two 8-bit registers: an instruction register (IR) and a data register (DR).

The IR stores instruction codes, such as clear display, return home, and display control, and address information for display data RAM (DDRAM), character generator RAM (CGRAM), and segment RAM (SEGRAM). The IR can only be written to by MPU and cannot be read from.

The DR temporarily stores data to be written into DDRAM, CGRAM, SEGRAM, or annunciator. Data written into the DR from the MPU is automatically written into DDRAM, CGRAM, SEGRAM, or annunciator by an internal operation. The DR is also used for data storage when reading data from DDRAM, CGRAM, or SEGRAM. When address information is written into the IR, data is read and then stored into the DR from DDRAM, CGRAM, or SEGRAM by an internal operation. Data transfer between the MPU is then completed when the MPU reads the DR. After the read, data in DDRAM, CGRAM, or SEGRAM at the next address is sent to the DR for the next read from the MPU.

These two registers and the operations can be selected by the register select bit (RS) and the read/write bit (R/W) as listed in Table 4. For details, see the Serial Data Transfer section.

Table 4 Register Selection by RS and R/W Bits

RS Bit	R/W Bit	Operation
0	0	IR write as an internal operation
0	1	Read busy flag (DB7) and key scan data (DB3 to DB0)
1	0	DR write as an internal operation (DR to DDRAM, CGRAM, SEGRAM, or annunciator)
1	1	DR read as an internal operation (DDRAM, CGRAM, or SEGRAM to DR)

#### **Busy Flag (BF)**

When the busy flag is 1, the HD66727 is in the internal operation mode, and the next instruction will not be accepted. When RS = 0 and R/W = 1, the busy flag is output from DB7. The next instruction must be written after ensuring that the busy flag is 0, or data must be transferred in appropriate timing considering instruction execution times.

#### **Key Scan Registers (SCAN0 to SCAN7)**

The key matrix scanner senses and holds the key states at each rising edge of the key strobe signals that are output by the HD66727. The key strobe signals are output as time-multiplexed signals from KST0 to KST7. After passing through the key matrix, these strobe signals are used to sample the key status on four inputs KIN0 to KIN3, enabling up to 32 keys to be scanned.

The states of inputs KIN0 to KIN3 are sampled by key strobe signal KST0 and latched into register SCAN0. Similarly, the data sampled by strobe signals KST1 to KST7 is latched into registers SCAN1 to SCAN7, respectively.

#### Address Counter (AC)

The address counter (AC) assigns addresses to DDRAM, CGRAM, or SEGRAM. When the address set instruction is written into the IR, the address information is sent from the IR to the AC. Selection of DDRAM, CGRAM, and SEGRAM is also determined concurrently by the instruction. Figure 2 shows the address counter and a sample DDRAM address setting to the address counter.

After writing into (reading from) DDRAM, CGRAM, or SEGRAM, the AC is automatically incremented by 1 (or decremented by 1).

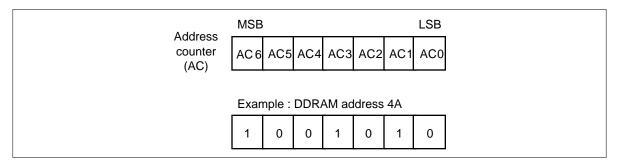


Figure 2 Address Counter and Sample DDRAM Address Setting

#### **Display Data RAM (DDRAM)**

Display data RAM (DDRAM) stores display data represented in 8-bit character codes. Its capacity is  $60 \times 8$  bits, or 60 characters, which is equivalent to an area of 12 characters  $\times 5$  lines. Any number of display lines (LCD drive duty ratio) from 1 to 4 can be selected by software. Here, assignment of DDRAM addresses is the same for all display modes (Table 5). The line to be displayed at the top of the display (display-start line) can also be selected by register settings. See Table 6.

Table 5 DDRAM Addresses and Display Positions

Display Line	1st Char.	2nd Char.	3rd Char.	4th Char.	5th Char.	6th Char.	7th Char.	8th Char.	9th Char.	10th Char.	11th Char.	12th Char.
1st	00	01	02	03	04	05	06	07	08	09	0A	0B
2nd	10	11	12	13	14	15	16	17	18	19	1A	1B
3rd	20	21	22	23	24	25	26	27	28	29	2A	2B
4th	30	31	32	33	34	35	36	37	38	39	3A	3B
5th	40	41	42	43	44	45	46	47	48	49	4A	4B

Note: Char. indicates character position.

 Table 6
 Display-Line Modes, Display-Start Line, and DDRAM Addresses

**Display-Start Lines** 

					spiay Otait Li		
Display- Line Mode	Duty Ratio	Common Pins	1st Line (SN = 000)	2nd Line (SN = 001)	3rd Line (SN = 010)	4th Line (SN = 011)	5th Line (SN = 100)
1-line (NL = 00)	1/10	COM1- COM8	"00"H–"0B"H	"10"H–"1B"H	"20"H–"2B"H	"30"H–"3B"H	"40"H–"4B"H
2-line (NL = 01)	1/18	COM1- COM8	"00"H–"0B"H	"10"H–"1B"H	"20"H–"2B"H	"30"H–"3B"H	"40"H–"4B"H
		COM9- COM16	"10"H–"1B"H	"20"H–"2B"H	"30"H–"3B"H	"40"H–"4B"H	"00"H–"0B"H
3-line (NL = 10)	1/26	COM1- COM8	"00"H–"0B"H	"10"H–"1B"H	"20"H–"2B"H	"30"H–"3B"H	"40"H–"4B"H
		COM9- COM16	"10"H–"1B"H	"20"H–"2B"H	"30"H–"3B"H	"40"H–"4B"H	"00"H–"0B"H
		COM17- COM24	"20"H–"2B"H	"30"H–"3B"H	"40"H–"4B"H	"00"H–"0B"H	"10"H–"1B"H
4-line (NL = 11)	1/34	COM1- COM8	"00"H–"0B"H	"10"H–"1B"H	"20"H–"2B"H	"30"H–"3B"H	"40"H–"4B"H
		COM9- COM16	"10"H–"1B"H	"20"H–"2B"H	"30"H–"3B"H	"40"H–"4B"H	"00"H–"0B"H
		COM17- COM24	"20"H–"2B"H	"30"H–"3B"H	"40"H–"4B"H	"00"H–"0B"H	"10"H–"1B"H
		COM25- COM32	"30"H–"3B"H	"40"H–"4B"H	"00"H–"0B"H	"10"H–"1B"H	"20"H–"2B"H

#### **Character Generator ROM (CGROM)**

Character generator ROM (CGROM) generates  $6 \times 8$ -dot character patterns from 8-bit character codes. It can generate 240  $6 \times 8$ -dot character patterns. Table 7 illustrates the relation between character codes and character patterns for the Hitachi standard CGROM. User-defined character patterns are also available using a mask-programmed ROM (see the Modifying Character Patterns section).

 Table 7
 Relation between Character Codes and Character Patterns (ROM code: A03)

Upper		2004	2010		0400	0404	2442	0444	4000	4004	1010	4044	1100	4404	4440	
Lower bits bits	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011	1100	1101	1110	1111
xxxx 0000	CG RAM (1)					····	•••	••••••••••••••••••••••••••••••••••••••	•	 		•••••	.::	•••	<b>:::</b> :	<b>!:::</b> :
xxxx 0001	CG RAM (2)		•	;	•••••		••••	•:::			<b>:::</b>	•••••	•••••	·;	••••	* <del>*</del>
xxxx 0010	CG RAM (3)		* *	•••••	:; :;	•••••••••••••••••••••••••••••••••••••••	<u>::</u>	••••	••••		•	•	•••	<b>:</b>	; ;	::::
xxxx 0011	CG RAM (4)	••		••••	••••	*****	<b>:</b> .	•••••	:::	;;		•••	••••	••••	•	::-::
xxxx 0100	CG RAM (1)	::	:#:	:-	:.·:	•••••	:::	***	••••	::	•••	•••••	•••	•••••	<u>.</u> :	3. 3.
xxxx 0101	CG RAM (2)	•.••	** .*	••••	••••	<b>!!</b>	;; ;;	<b>!!</b>		::	**	·•••	••••	•••	:::	: :::
xxxx 0110	CG RAM (3)	;·:		 	•••••	•••	•	•••	•:::	: <u>`</u> .;	•••••	<b>;</b> ;;	•••	•••••	••••••••••••••••••••••••••••••••••••••	3 3
xxxx 0111	CG RAM (4)	÷	**	****	:		•••• ••••	<b>i</b> i	:	: <u>.</u> .i	••••	•••••	••••	••••	:;	<b>.::</b>
xxxx 1000	CG RAM (1)	••••	•••			****	<b>!</b> ;	•••	:::	: <u>;</u>	•••		•••••	•••	•.•	••••
xxxx 1001	CG RAM (2)	::	•••	••••	••••••	<b>!!</b>	:	••	• • • •••• ••••	;;	***;	•	•••••	<b>!!</b> .:	•• ‡	•;
xxxx 1010	CG RAM (3)	••	: <b>‡</b> :	## ##		•••••	.;	•••••	••••• •••••	:_:	••••		••		•	••••••
xxxx 1011	CG RAM (4)	****	•••••	## <b>#</b>	<b>!</b> :	:	<b>!</b> ::	••••	:	: <u>:</u> :.	•••••	••••	••••	•••••	<b>::</b>	;:-;
xxxx 1100	CG RAM (1)	•••••	;:	•••	•	:3;3: •••••	:	•	**	<b>:</b> :	· <b>!·</b> ::	••••••	••••	<b>:</b>	:‡.	ļ:
xxxx 1101	CG RAM (2)	i	••••	•••••	<b>:</b> ::		<b>;</b> ;;	<b>:</b>	:	•••••	•••	••••;	••••	••	÷	••••
xxxx 1110	CG RAM (3)	•	22	•••	•••	•••,	•••• ••••	••••••	:;		••••	· <u>†··</u> ;	••••	•••	••••	
xxxx 1111	CG RAM (4)	***	.•••	••••		•••••	::	<b>::</b> ··	::: :::		:::	••	••••	<b>:::</b>		

 Table 7
 Relation between Character Codes and Character Patterns (ROM code: A04)

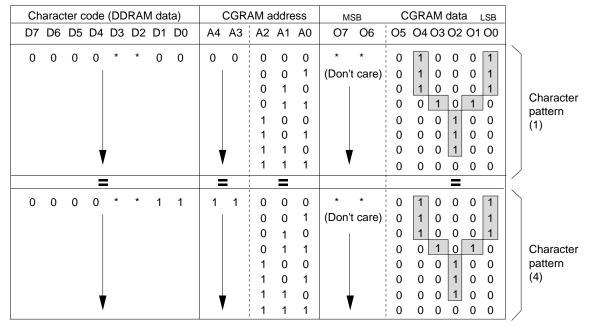
Upper Lower bits	0000	0004	0040	0044	0400	04.04	0440	0444	4000	4004	4040	4044	4400	4404	4440	4444
bits bits	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011	1100	1101	1110	1111
xxxx 0000	CG RAM (1)					•••••• ••••••	•••	<b>::::</b> ·	3.	 		•••••	••••	•••,	:.:.	<b>;:</b> :
xxxx 0001	CG RAM (2)		•	ઋનનું	•••••		••••	•:::	·i	•••••	<b>:::</b>	•••••	•••••	i;	••••	:::4
xxxx 0010	CG RAM (3)	.:: <u>.</u>	* *	•••••	::::;	;··;	i;		.:. :::	:::-: ::::-:	•	••••••	•	.:·:	;; ;;	::::
xxxx 0011	CG RAM (4)	***		••••	•••••	*****	:	•••••	:::	::		•••	••••	••••	••••	::::
xxxx 0100	CG RAM (1)	::::	·#·	:-:	••••	•••••	::	••••	••••	::	•••	•••••	•••	<b>:</b> :::	•••	:::
xxxx 0101	CG RAM (2)	•••	****	•••••		<b>ii</b>	;;	<b>ii</b>	i	::::	**	••••	•••••• •••••		:::	ii
xxxx 0110	CG RAM (3)	÷:		••••	: :	i.,i	*	••		···	•••••	<b>:</b>	••••	•••••	•••	2000 2000
xxxx 0111	CG RAM (4)	:::	.3	****	••••		****	<b>i</b> i	:	·	•••••	•••••	•••••	•••	:;	JI.
xxxx 1000	CG RAM (1)	•••••	<b>3.</b>		<u></u>	••••	••••	•••	::::	• • ••••	•••		•••••• •••••	<b>!.!</b>	•.•	••••
xxxx 1001	CG RAM (2)	::	•	••••	::	i.,:	• 3•••\$	••	: ::	::	****;	•••••	•••••	ij	•• •	·
xxxx 1010	CG RAM (3)	••	: <b>:</b> :	**		••••		••••	;;	: <b>:</b>	•••••	•••••	•	<b>i.</b> .·	• •••••••	•••••
xxxx 1011	CG RAM (4)	****	•••••	#	***	:	••••	***	::	:‡:	***	***	3 3	<b>!</b> !	<b>:</b>	;;;
xxxx 1100	CG RAM (1)	••••	;3	•••	•	::::: :::::	<b>3</b>	•••••	2;•	••••	••••••	••••••	•••••	•••	***	
xxxx 1101	CG RAM (2)	•	••••	•••••	<b>:</b> ::		***	•••	:	•••••• ••••••	•••	•••••	••••	••	••••	•
xxxx 1110	CG RAM (3)	**:	<b>33</b>	•••	<b>!</b> !	••••	••••	••••	:;	::: <u>.</u> :	••••		••••	•,••	••• ••••	
xxxx 1111	CG RAM (4)	:::•	.•••	••••	:::	•••••	::	•••••	::: :::	<b>į</b>	*::	·i	••••	<b>:::</b>	::::	

#### **Character Generator RAM (CGRAM)**

Character generator RAM (CGRAM) of  $32 \times 6$  bits allows the user to redefine the character patterns. In the case of  $6 \times 8$ -dot characters, up to four characters may be redefined.

Write the character codes at addresses "00"H to "03"H into DDRAM to display the character patterns stored in CGRAM (Table 8).

Table 8 Example of Relationships between Character Code (DDRAM) and Character Pattern (CGRAM Data)



Notes: 1. The lower 2 bits of the character code correspond to the upper two bits of the CGRAM address (2 bits: 4 types).

- 2. CGRAM address bits 0 to 2 designate the character pattern raster-row position. The 8th raster-row is the cursor position and its display is formed by a logical OR with the cursor.
- 3. In the 5-dot font width, the higher three bits of the CGRAM data are invalid; use the lower five bits (O4 to O0). In the 6-dot font width, the higher two bits are invalid.
- 4. When the upper four bits (bits 7 to 4) of the character code are 0, CGRAM is selected.

  Bits 3 and 2 of the character code are invalid (\*). Therefore, for example, the character codes 00H and 08H correspond to the same CGRAM address.
- 5. A set bit in the CGRAM data corresponds to display selection, and 0 to non-selection.

#### Segment RAM (SEGRAM)

Segment RAM (SEGRAM) is used to enable control of segments such as icons and marks by the user program. Segments and characters are driven by a multiplexing drive method.

SEGRAM has a capacity of  $8 \times 6$  bits, for controlling the display of a maximum of 40 (48 in the 6-dot font width) icons and marks. While COMS1 and COMS2 outputs are being selected, SEGRAM is read and

segments (icons and marks) are displayed by a multiplexing drive method (20 segments each during COMS1 and COMS2 selection).

Bits in SEGRAM corresponding to segments to be displayed are directly set by the MPU, regardless of the contents of DDRAM and CGRAM.

Tables 9 and 10 illustrate the correspondence between SEGRAM addresses and driver signals.

Table 9 Correspondence between Segment Display SEGRAM Addresses (ASEG) and Driver Signals in the 5-Dot Font Width

ASE	ASEG Address			Segment Signals									
MSI	В		LSB	D7	D6	D5	D4	D3	D2	D1	D0	Signal	
1	0	0	0	*	*	*	SEG1, SEG21, SEG41	SEG2, SEG22, SEG42	SEG3, SEG23, SEG43	SEG4, SEG24, SEG44	SEG5, SEG25, SEG45	COMS1	
1	0	0	1	*	*	*	SEG6, SEG26, SEG46	SEG7, SEG27, SEG47	SEG8, SEG28, SEG48	SEG9, SEG29, SEG49	SEG10, SEG30, SEG50	COMS1	
1	0	1	0	*	*	*	SEG11, SEG31, SEG51	SEG12, SEG32, SEG52	SEG13, SEG33, SEG53	SEG14, SEG34, SEG54	SEG15, SEG35, SEG55	COMS1	
1	0	1	1	*	*	*	SEG16, SEG36, SEG56	SEG17, SEG37, SEG57	SEG18, SEG38, SEG58	SEG19, SEG39, SEG59	SEG20, SEG40, SEG60	COMS1	
1	1	0	0	*	*	*	SEG1, SEG21, SEG41	SEG2, SEG22, SEG42	SEG3, SEG23, SEG43	SEG4, SEG24, SEG44	SEG5, SEG25, SEG45	COMS2	
1	1	0	1	*	*	*	SEG6, SEG26, SEG46	SEG7, SEG27, SEG47	SEG8, SEG28, SEG48	SEG9, SEG29, SEG49	SEG10, SEG30, SEG50	COMS2	
1	1	1	0	*	*	*	SEG11, SEG31, SEG51	SEG12, SEG32, SEG52	SEG13, SEG33, SEG53	SEG14, SEG34, SEG54	SEG15, SEG35, SEG55	COMS2	
1	1	1	1	*	*	*	SEG16, SEG36, SEG56	SEG17, SEG37, SEG57	SEG18, SEG38, SEG58	SEG19, SEG39, SEG59	SEG20, SEG40, SEG60	COMS2	

Notes: 1. When the SFT pin is grounded, the SEG1 pin output is connected to the far left of the LCD panel, and when the SFT pin is high, the SEG60 pin output is connected to the far left.

<sup>2.</sup> SEG1 to SEG20 data is identical to SEG21 to SEG40 and SEG41 to SEG60 data.

<sup>3.</sup> The lower five bits (D4 to D0) of SEGRAM data determine on or off display of each segment. A segment is selected (turned on) when the corresponding data is 1, and is deselected (turned off) when the corresponding data is 0. The upper three bits (D7 to D5) are invalid.

Table 10 Correspondence between Segment Display SEGRAM Addresses (ASEG) and Driver Signals in the 6-Dot Font Width

A	SEG	Addre	ess				Se	gment Sig	nals			Common
MSB			LSB	D7	D6	D5	D4	D3	D2	D1	D0	Signal
1	0	0	0	*	*	SEG1, SEG25, SEG49	SEG2, SEG26, SEG50	SEG3, SEG27, SEG51	SEG4, SEG28, SEG52	SEG5, SEG29, SEG53	SEG6, SEG30, SEG54	COMS1
1	0	0	1	*	*	SEG7, SEG31, SEG55	SEG8, SEG32, SEG56	SEG9, SEG33, SEG57	SEG10, SEG34, SEG58	SEG11, SEG35, SEG59	SEG12, SEG36, SEG60	COMS1
1	0	1	0	*	*	SEG13, SEG37	SEG14, SEG38	SEG15, SEG39	SEG16, SEG40	SEG17, SEG41	SEG18, SEG42	COMS1
1	0	1	1	*	*	SEG19, SEG43	SEG20, SEG44	SEG21, SEG45	SEG22, SEG46	SEG23, SEG47	SEG24, SEG48	COMS1
1	1	0	0	*	*	SEG1, SEG25, SEG49	SEG2, SEG26, SEG50	SEG3, SEG27, SEG51	SEG4, SEG28, SEG52	SEG5, SEG29, SEG53	SEG6, SEG30, SEG54	COMS2
1	1	0	1	*	*	SEG7, SEG31, SEG55	SEG8, SEG32, SEG56	SEG9, SEG33, SEG57	SEG10, SEG34, SEG58	SEG11, SEG35, SEG59	SEG12, SEG36, SEG60	COMS2
1	1	1	0	*	*	SEG13, SEG37	SEG14, SEG38	SEG15, SEG39	SEG16, SEG40	SEG17, SEG41	SEG18, SEG42	COMS2
1	1	1	1	*	*	SEG19, SEG43	SEG20, SEG44	SEG21, SEG45	SEG22, SEG46	SEG23, SEG47	SEG24, SEG48	COMS2

Notes: 1. When the SFT pin is grounded, the SEG1 pin output is connected to the far left of the LCD panel, and when the SFT pin is high, the SEG60 pin output is connected to the far left.

- 2. SEG1 to SEG24 data are identical to SEG25 to SEG48 and SEG49 to SEG60 data.
- 3. The lower six bits (D5 to D0) of SEGRAM data determine on or off display for each segment. A segment is selected (turned on) when the corresponding bit is 1, and is deselected (turned off) when the corresponding bit is 0. The upper two bits (D7 to D6) are invalid.

#### **Timing Generation Circuit**

The timing generation circuit generates timing signals for the operation of internal circuits such as DDRAM, CGROM, CGRAM, and SEGRAM. RAM read timing for display and internal operation timing by MPU access are generated separately to avoid interfering with each other. Therefore, when writing data to DDRAM, for example, there will be no undesirable interferences, such as flickering, in areas other than the display area.

#### **Cursor/Blink Control Circuit**

The cursor/blink (or white-black inversion) control is used to produce a cursor or a flashing area on the display at a position corresponding to the location stored in the address counter (AC).

For example (Figure 3), when the address counter is 08H, a cursor is displayed at a position corresponding to DDRAM address "08"H.

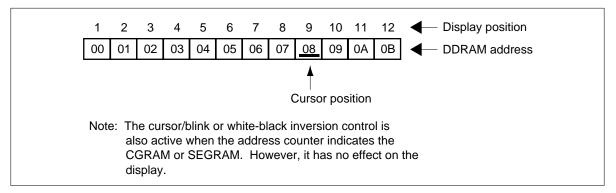


Figure 3 Cursor Position and DDRAM Address

#### **Multiplexing Liquid Crystal Display Driver Circuit**

The multiplexing liquid crystal display driver circuit consists of 34 common signal drivers (COM1 to COM32, COMS1, COMS2) and 60 segment signal drivers (SEG1 to SEG60). When the number of lines are selected by a program, the required common signal drivers automatically output drive waveforms, while the other common signal drivers continue to output deselection waveforms.

Character pattern data is sent serially through a 60-bit shift register and latched when all needed data has arrived. The latched data then enables the segment signal drivers to generate drive waveform outputs.

The shift direction of 60-bit data can be changed by the SGS bit. The shift direction of the common driver can also be changed by the CMS bit; select the direction appropriate for the device mounting configuration.

When multiplexing drive is not used, or during the standby or sleep mode, all the above common and segment signal drivers output the  $V_{\text{CC}}$  level, halting display.

#### **Annunciator Driver Circuit**

The static annunciator drivers, which are specially used for displaying icons and marks, consists of 1 common signal driver (ACOM) and 12 segment signal drivers (ASEG1 to ASEG12). Since this driver circuit operates at the logic operating voltage ( $V_{\rm CC}$  to AGND), the LCD drive power supply circuit is not necessary, and low-power consumption can be achieved. It is suitable for mark indication during system standby because of its drive capability during the standby and sleep modes. When multiplexing drive is not used, or during the standby or sleep mode, all the above common and segment signal drivers output the  $V_{\rm CC}$  level, halting display.

Tables 11 to 13 illustratate the correspondence between the annunciator addresses (AAN) and driver signals.

Table 11 Correspondence between Annunciator Display Addresses (AAN) and Driver Signals

AAI	N Add	Iress		Annun	Innunciator Segment Signals							
MS	В		LSB	D7	D6	D5	D4	D3	D2	D1	D0	Signal
0	0	0	0	Α	SEG1	A	SEG2	Α	SEG3	A	SEG4	ACOM
0	0	0	0	Blink	Data	Blink	Data	Blink	Data	Blink	Data	ACOM
0	0	0	1	A	SEG5	A	SEG6	Α	SEG7	A	SEG8	ACOM
0	0	0	1	Blink	Data	Blink	Data	Blink	Data	Blink	Data	ACOM
0	0	1	0	A	SEG9	AS	SEG10	AS	SEG11	AS	EG12	ACOM
0	0	1	0	Blink	Data	Blink	Data	Blink	Data	Blink	Data	ACOM

Notes: 1. The annunciator is turned on when the corresponding even bit (data) is 1, and is turned off when 0.

The turned-on annunciator blinks when the corresponding odd bit (blink) is 1. Blinking is provided by repeatedly turning on the annunciator for 32 frames and then turning it off for the next 32 frames.

Table 12 Correspondence between LED Driving Port Addresses (AAN) and Driver Signals

AA	N Add	lress		LED D	riving and	General O	utput Port					
MS	В		LSB	D7	D6	D5	D4	D3	D2	D1	D0	
0	0	1	1	*	*	Port2	Port1	Port0	LED2	LED1	LED0	
					Genera	l output po	rt	LED driving port				

Notes: 1. The LED bits are inverted and output from each LED pin. If 0 is set, the V<sub>cc</sub> level is output from the LED pin. If 1 is set, the GND level is output from the LED pin.

- 2. The port bits output from each port pin. If 0 is set, the GND level is output from the PORT pin. If 1 is set, the  $V_{cc}$  level is output from the PORT pin.
- Current cannot be driven for outputs of the V<sub>cc</sub> level in LED2–LED0 and the V<sub>cc</sub> and GND levels in PORT2–PORT0.
- 4. The upper two bits (D7 and D6) are invalid.

Table 13 Correspondence between SEG/COM Addresses (AAN) and Driver Signals

AAN	Addr	ess		Shift I	Direction o	f SEG/CO	M Driver					
MSB	3		LSE	B D7	D6	D5	D4	D3	D2	D1	D0	
0	1	0	0	*	*	*	*	*	*	CMS	SGS	

Notes: 1. If CMS = 0, COM1/32 is the first line of the first column, and COM32/1 is the 8th line of the fourth column. If CMS = 1, COM1/32 is the 8th line of the fourth column, and COM32/1 is the first line of the first column. If CMS = 0, COMS1/2 is COMS1, and COMS2/1 is COM2.

- 2. If SGS = 0, SEG1/60 is SEG1 in the left of the display, and SEG60/1 is SEG60 in the right of the display. If SGS = 1, the shift direction of the SEG is reversed.
- 3. The upper six bits (D7-D2) are invalid.

#### **LED Output Port**

The HD66727 includes three LED/back-light driving output ports and three general output ports. These ports can control the LED from the microcomputer through the serial interface.

#### **Booster (DC-DC Converter)**

The booster doubles or triples a voltage input to the Vci pin. With this function, both the internal logic units and LCD drivers can be controlled with a single power supply.

#### Oscillator (OSC)

The HD66727 can provide R-C oscillation simply by adding an external oscillation-resistor between the OSC1 and OSC2 pins. The appropriate oscillation frequency for operating voltage, display size, and frame frequency can be obtained by adjusting the external-resistor value. Clock pulses can also be supplied externally. Since R-C oscillation is halted during the standby mode, current consumption can be reduced.

#### V-Pin Voltage Followers

A voltage follower for each voltage level (V1 to V5) reduces current consumption by the LCD drive power supply circuit. No external resistors are required because of the internal bleeder-resistor, which generates different levels of LCD drive voltage. The voltage followers can be turned off while multiplexing drive is not being used.

#### Contrast Adjuster

The contrast adjuster can adjust LCD contrast by varying LCD drive voltage by software. This function is suitable for selecting appropriate brightness of the LCD or for temperature compensation.

## **Modifying Character Patterns**

### Character pattern development procedure

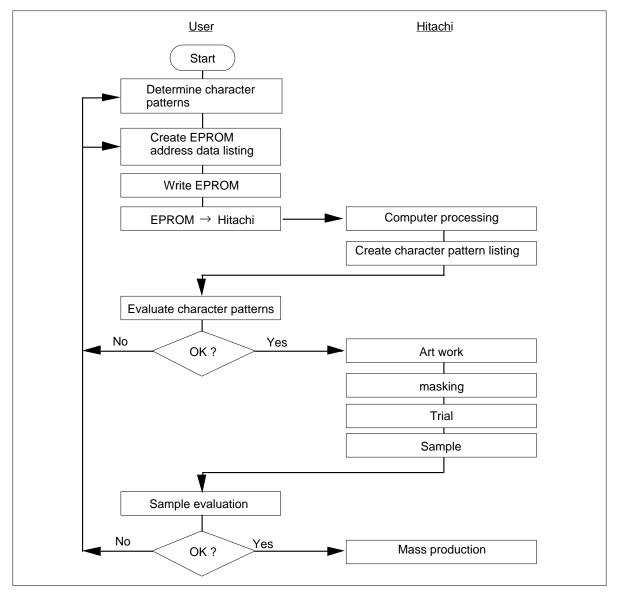


Figure 4 Character Pattern Development Procedure

The following operations correspond to the numbers listed in Figure 4:

- 1. Determine the correspondence between character codes and character patterns.
- 2. Create a listing indicating the correspondence between EPROM addresses and data.
- 3. Program the character patterns into an EPROM.
- 4. Send the EPROM to Hitachi.

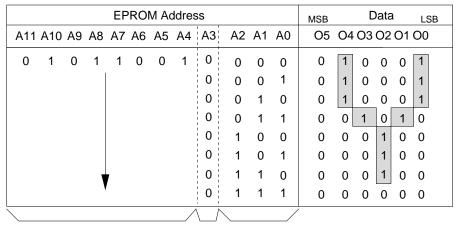
- 5. Computer processing of the EPROM is performed at Hitachi to create a character pattern listing, which is sent to the user.
- 6. If there are no problems within the character pattern listing, a trial LSI is created at Hitachi and samples are sent to the user for evaluation. When it is confirmed by the user that the character patterns are correctly written, mass production of the LSI will proceed at Hitachi.

#### **Programming Character Patterns**

This section explains the correspondence between addresses and data used to program character patterns in EPROM.

**Programming to EPROM:** The HD66727 character generator ROM can generate  $240.6 \times 8$ -dot character patterns. Table 14 shows correspondence between the EPROM address, data, and the character pattern.

Table 14 Example of Correspondence between EPROM Address, Data, and Character Pattern (6 × 8 Dots)



Character code

0 Line position

Notes: 1. EPROM address bits A11 to A4 correspond to a character code.

- 2. EPROM address bits A2 to A0 specify the line position of the character pattern. EPROM address bit A3 must be set to 0.
- 3. EPROM data bits O5 to O0 correspond to character pattern data.
- 4. Areas which are lit (indicated by shading) are stored as 1, and unlit areas as 0.
- 5. The eighth raster-row is also stored in the CGROM, and must also be programmed. If the eighth raster-row is used for a cursor, this data must all be set to zero.
- 6. EPROM data bits O7 to O6 are invalid. 0 must be written in all bits.

#### **Handling Unused Character Patterns:**

- EPROM data outside the character pattern area: This is ignored by character generator ROM for display operation so any data is acceptable.
- 2. EPROM data in CGRAM area: Always fill with zeros.
- 3. Treatment of unused user patterns in the HD66727 EPROM: According to the user application, these are handled in either of two ways:
  - a. When unused character patterns are not programmed: If an unused character code is written into DDRAM, all its dots are lit, because the EPROM is filled with 1s after it is erased.
  - b. When unused character patterns are programmed as 0s: Nothing is displayed even if unused character codes are written into DDRAM. (This is equivalent to a space.)

#### **Instructions**

#### **Outline**

Only the instruction register (IR) and the data register (DR) of the HD66727 can be controlled by the MPU. Before starting internal operation of the HD66727, control information is temporarily stored in these registers to allow interfacing with various peripheral control devices or MPUs which operate at different speeds. The internal operation of the HD66727 is determined by signals sent from the MPU. These signals, which include register selection bit (RS), read/write bit (R/W), and the data bus (DB0 to DB7), make up the HD66727 instructions. There are four categories of instructions that:

- Control display
- · Control key scan
- Control power management
- Set internal RAM addresses
- Perform data transfer with internal RAM

Normally, instructions that perform data transfer with internal RAM are used the most. However, auto-incrementation by 1 (or auto-decrementation by 1) of internal HD66727 RAM addresses after each data write can lighten the program load of the MPU.

While an instruction is being executed for internal operation, or during reset, no instruction other than the busy flag/key scan read instruction can be executed.

Because the busy flag is set to 1 while an instruction is being executed, check it to make sure it is 0 before sending another instruction from the MPU. If an instruction is sent without checking the busy flag, the time between the first instruction issue and next instruction issue must be longer than the instruction execution time itself. Refer to Table 23 for the list of each instruction execution cycles (clock pulses). The execution time depends on the operating clock frequency (oscillation frequency).

### **Instruction Description**

#### Busy Flag/Key Scan Read

The busy flag/key scan read instruction (Figure 5) reads scan data SD3 to SD0 latched into scan registers SCAN0 to SCAN7, scan cycle state SF1 and SF0, and transfer flag TF, sequentially. It also reads the busy flag (BF) indicating that the system is now internally operating on a previously received instruction. If BF is 1, the internal operation is in progress. The next instruction will not be accepted until BF is cleared to 0. Adjust the data transfer rate so that the last bit of the next instruction is received after BF is cleared to 0.

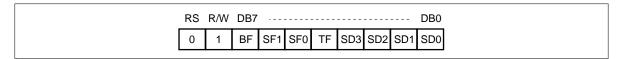


Figure 5 Busy Flag/Key Scan Read Instruction

#### **Clear Display**

The clear display instruction (Figure 6) writes space code 20H (character pattern for character code 20H must be a blank pattern) into all DDRAM addresses. It then sets DDRAM address 0 into the address counter. It also sets I/D to 1 (increment mode) in the entry mode set instruction.

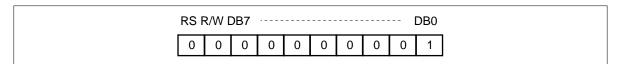
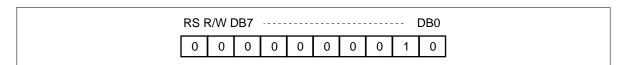


Figure 6 Clear Display Instruction

#### **Return Home**

The return home instruction (Figure 7) sets DDRAM address 0 into the address counter. The DDRAM contents do not change. The cursor or blinking goes to the top left of the display.



**Figure 7 Return Home Instruction** 

#### **Start Oscillator**

The start oscillator instruction (Figure 8) re-starts the oscillator from a halt state in the standby mode. After issuing this instruction, wait at least 10 ms for oscillation to become stable before issuing the next instruction. (Refer to the Standby Mode section.)

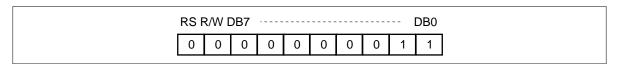


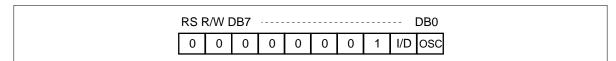
Figure 8 Start Oscillator Instruction

#### **Entry Mode Set**

The entry mode set instruction (Figure 9) includes the I/D and OSC bits.

**I/D:** Increments (I/D = 1) or decrements (I/D = 0) the DDRAM address by 1 when a character code is written into or read from DDRAM. The cursor or blinking moves to the right when incremented by 1 and to the left when decremented by 1. The same applies to writing and reading of CGRAM and SEGRAM.

**OSC:** Divides the external clock frequency by four (OSC = 1) and uses the resulting clock as an operating clock for all internal operations. The execution time for this instruction and subsequent ones is therefore quadrupled. The execution time of clearing this bit (OSC = 0) is also quadrupled. Note that, the key scan cycle is affected. For details, refer to the Partial-Display-Off Function section.



**Figure 9 Entry Mode Set Instruction** 

#### **Cursor Control**

The cursor control instruction (Figure 10) includes the B/W, C, and B bits.

**B/W**: When B/W is 1, the character at the cursor position is cyclically (every 32 frames) displayed with black-white inversion.

C: The cursor is displayed on the 8th raster-row when C is 1. The cursor is displayed using 5 dots in the 8th raster-row for  $5 \times 8$ -dot character font, or 6 dots in the 8th raster-row for  $6 \times 8$  dot character font.

**B:** The character indicated by the cursor blinks when B is 1. The blinking is displayed as switching between all black dots and displayed characters every 32 frames. The cursor and blinking can be set to display simultaneously. When LC and B = 1, the blinking is displayed as switching between all white dots and displayed characters.

Figure 11 shows cursor control examples.

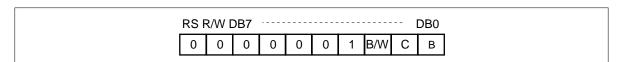


Figure 10 Cursor Control Instruction

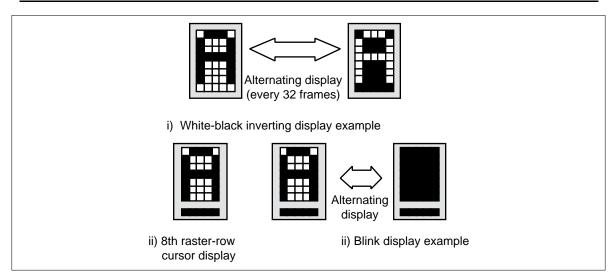


Figure 11 Cursor Control Examples

#### **Display On/Off Control**

The display on/off control instruction (Figure 12) includes the D, FW, and LC bits.

**D:** The character display and the segment display for multiplexing icon are on when D is 1. When off, the display data remains in DDRAM or SEGRAM, and can be displayed instantly by setting D to 1. When D is 0, multiplexing LCD drive halts and the display is off with the SEG1 to SEG60 outputs, COM1 to COM32 outputs, and COMS1/2 output set to  $V_{\rm CC}$  level and off. Because of this, the HD66727 can control charging current for the LCD with driving.

**FW:** When FW = 0, the font width is 5 dots. When FW = 1, the font width is 6 dots.

**LC:** When LC = 1, a cursor attribute is assigned to the line that contains the address counter (AC) value. Cursor mode can be selected with the B/W, C, and B bits. Refer to the Line-Cursor Display section.

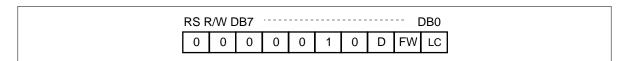


Figure 12 Display On/Off Control Instruction

#### **Power Control**

The power control instruction (Figure 13) includes the AMP, SLP, and STB bits.

**AMP:** When AMP = 1, each voltage follower for V1 to V5 pins and the booster are turned on. When AMP = 0, current consumption can be reduced while character or segment display controlled by the multiplexing drive method is not being used.

**SLP:** When SLP = 1, the HD66727 enters the sleep mode, where all the internal operations are halted except for the annunciator display function, key scan function, and the R-C oscillator, thus reducing current

consumption. For details, refer to the Sleep Mode section. Only the following instructions can be executed during the sleep mode.

- 1. Annunciator address (AAN) set
- 2. Annunciator data write
- 3. LED drive/general output port data write
- 4. Annunciator display on or off (DA = 1 or 0)
- 5. Voltage follower on or off (AMP = 1 or 0)
- 6. Standby mode set (STB = 1)
- 7. Sleep mode cancel (SLP = 0)
- 8. Key scan data (SD) read
- 9. Key scan interrupt generation enable/disable (IRE = 1 or 0)
- 10. Key scan cycle (KF) set

During the sleep mode, the other RAM data and instructions cannot be updated but they are retained.

STB: When STB = 1, the HD66727 enters the standby mode, where the device completely stops, halting all the internal operations including the internal R-C oscillator and no external clock pulses are supplied. However, annunciator display alone is available when the alternating signal for annunciator-driving signals is supplied to the EXM pin. When the annunciator display is not needed, make sure to turn off display (DA = 0). Normal key scanning is also halted in the standby mode. However, the HD66727 can detect four key inputs connected with strobe signal KST0, thus generating the key scan interrupt (IRQ\*). For details, refer to the Standby Mode section and the Key Scan Interrupt section. Only the following instructions can be executed during the standby mode.

- 1. Annunciator address (AAN) set
- 2. Annunciator data write
- 3. LED drive/general output port data write
- 4. Annunciator display on or off (DA = 1 or 0)
- 5. Voltage follower on or off (AMP = 1 or 0)
- 6. Start oscillator
- 7. Standby mode cancel (STB = 0)
- 8. Key scan interrupt generation enable/disable (IRE = 1 or 0)

During the standby mode, the other RAM data and instructions may be lost; they must be set again after the standby mode is canceled.

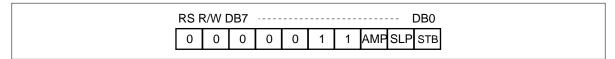


Figure 13 Power Control Instruction

#### **Display Control**

The display control instruction (Figure 14) includes the NL and DL bits.

**NL1, NL0:** Designates the number of display lines. This value determines the LCD drive multiplexing duty ratio (Table 15). The address assignment is the same for all display line modes.

**DL3–DL1:** Doubles the height of characters on a specified line. The first, second, or third line is doubled in height when DL1, DL2, or DL3 = 1, respectively. Two lines can be simultaneously doubled in a 4-line display. Refer to the Double-Height Display section.

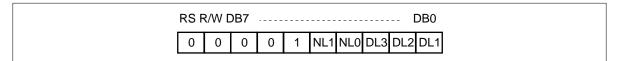


Figure 14 Display Control Instruction

Table 15 NL Bits and Display Lines

NL1	NL0	Number of Display Lines	LCD Drive Multiplexing Duty Ratio
0	0	1	1/10
0	1	2	1/18
1	0	3	1/26
1	1	4	1/34
	•	•	.,,,,

#### **Contrast Control**

The contrast control instruction (Figure 15) includes the SN and CT bits.

**SN2:** Combined with the SN1 and SN0 bits described in the Scroll Control section to select the top line to be scrolled (display-start line).

**CT3–CT0:** Controls the LCD drive voltage (potential difference between  $V_{CC}$  and V5) to adjust contrast (Figure 16 and Table 16). For details, refer to the Contrast Adjuster section.

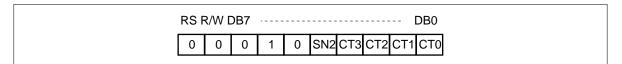


Figure 15 Contrast Control Instruction

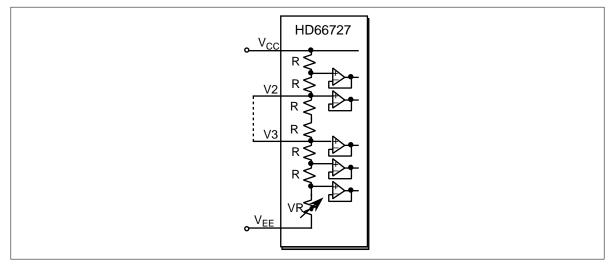


Figure 16 Contrast Adjuster

Table 16 CT Bits and Variable Resistor Value of Contrast Adjuster

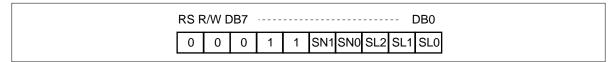
СТЗ	CT2	CT1	СТ0	Variable Resistor Value (VR)
0	0	0	0	6.4 x R
0	0	0	1	6.0 x R
0	0	1	0	5.6 x R
0	0	1	1	5.2 x R
0	1	0	0	4.8 x R
0	1	0	1	4.4 x R
0	1	1	0	4.0 x R
0	1	1	1	3.6 x R
1	0	0	0	3.2 x R
1	0	0	1	2.8 x R
1	0	1	0	2.4 x R
1	0	1	1	2.0 x R
1	1	0	0	1.6 x R
1	1	0	1	1.2 x R
1	1	1	0	0.8 x R
1	1	1	1	0.4 x R

## **Scroll Control**

The scroll control instruction (Figure 17) includes the SN and SL bits.

**SN1, SN0:** Combined with the SN2 bit described in the Contrast Control section to select the top line to be displayed (display-start line) through the data output from the COM1 pin (Table 17). After first five lines are displayed from the top line, the cycle is repeated and scrolling continues.

**SL2–SL0:** Selects the top raster-row to be displayed (display-start raster-row) in the display-start line specified by SN2 to SN0. Any raster-row from the first to eighth can be selected (Table 18). This function is used to perform vertical smooth scroll together with SN2 to SN0. For details, refer to the Vertical Smooth Scroll section.



**Figure 17 Scroll Control Instruction** 

Table 17 SN Bits and Display-Start Lines

SN2	SN1	SN0	Display-Start Line
0	0	0	1st line
0	0	1	2nd line
0	1	0	3rd line
0	1	1	4th line
1	0/1	0/1	5th line

Table 18 SN Bits and Display-Start Raster-Rows

SL2	SL1	SL0	Display-Start Raster-Row
0	0	0	1st raster-row
0	0	1	2nd raster-row
0	1	0	3rd raster-row
0	1	1	4th raster-row
1	0	0	5th raster-row
1	0	1	6th raster-row
1	1	0	7th raster-row
1	1	1	8th raster-row

#### Annunciator/SEGRAM Address Set

The annunciator/SEGRAM address set instruction (Figure 18) includes the DA and A (AAN/ASEG) bits.

**DA:** Turns annunciator display on or off. When DA = 1, annunciator display is turned on and driven statically. When DA = 0, annunciator display is turned off with ASEG1 to ASEG10 and ACOM pins held to  $V_{\rm CC}$  level.

The internal operating clock supply is halted during the standby mode; make sure to turn off display (DA = 0) if the external alternating signal is not supplied. For details, refer to the Segment Display and Annunciator Display section and the Standby Mode section.

**AAAA:** Used for setting the SEGRAM address into the address counter (AC) or for directly setting the annunciator address. The SEGRAM addresses range from 1000H to 1111H (8 addresses), while the annunciator addresses range from 0000H to 0010H (3 addresses).

The annunciator address is directly set without using the address counter, and consequently must be updated for each access. The annunciator address can be set even during the sleep and standby modes.

Once the SEGRAM address is set, data in the SEGRAM can be accessed consecutively since the address counter is automatically incremented or decremented by one according to the I/D bit setting after each access. The SEGRAM address cannot be set during the sleep or standby mode.

AAAA is the address for setting the 0011 LED/general port data; 0100 is the address for setting the SEG/COM shift direction. See 'Annunciator Driver Circuit' for details.

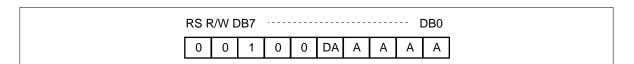


Figure 18 Annunciator/SEGRAM Address Set Instruction

Table 19 Annunciator/LED/SEG/COM Shift Direction/SEGRAM Address Set

Address	Α	Α	Α	Α	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0		
Annunciator	0	0	0	0	ASEG1		ASEG2		ASEG3		ASEG4	ļ		
address	0	0	0	1	ASEG5		ASEG6		ASEG7		ASEG8	3		
	0	0	1	0	ASEG9		ASEG1	0	ASEG1	1	ASEG1	2		
LED port address	0	0	1	1	*	*	PORT2	PORT1	PORT0	LED2	LED1	LED0		
SEG/COM shift direction address	0	1	0	0	*	*	*	*	*	*	CMS	SGS		
SEGRAM	1	0	0	0	*	*	SEGRAM data in COMS1 side							
address	1	0	0	1	*	*	_							
	1	0	1	0	*	*	_							
	1	0	1	1	*	*	_							
	1	1	0	0	*	* SEGI	SEGRAM data in COMS2 side							
	1	1	0	1	*		-							
	1	1	1	0	*	*	<del></del>							
	1	1	1	1	*	*								

## **CGRAM Address Set**

The CGRAM address set instruction (Figure 19) includes the A (ACG) bits.

**AAAAA:** Used for setting the CGRAM address into the address counter (AC). The CGRAM addresses range from 00H to 1FH (32 addresses) (Table 19).

Once the CGRAM address is set, data in the CGRAM can be accessed consecutively since the address counter is automatically incremented or decremented according to the I/D bit setting after each access. The CGRAM address cannot be set during the sleep or standby mode.

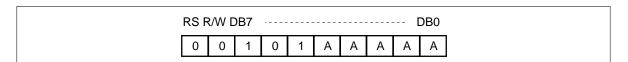


Figure 19 CGRAM Address Set Instruction

Table 20 CGRAM Addresses and Character Codes

Displayed Character	CGRAM Address	Character Codes	
1st character	"00"H to "07"H	"00"H	
2nd character	"08"H to "0F"H	"01"H	
3rd character	"10"H to "17"H	"02"H	
4th character	"18"H to "1F"H	"03"H	

## **DDRAM Address Set**

The DDRAM address set instruction (Figure 20) includes the A (ADD), IRE, and KF bits.

**AAAAAA:** Used for setting the DDRAM address into the address counter (AC). The DDRAM addresses range from "00"H to "4B"H (60 addresses) (Table 21).

Once the DDRAM address is set, data in the DDRAM can be accessed consecutively since the address counter is automatically incremented or decremented according to the I/D bit setting after each access. Here, invalid addresses are automatically skipped. The DDRAM address cannot be set during the sleep or standby mode.

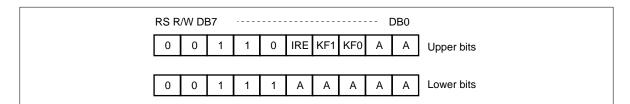


Figure 20 DDRAM Address Set Instruction

Table 21 DDRAM Addresses and Invalid Addresses

Displayed Line	DDRAM Address	Invalid Addresses
1st line	"00"H to "0B"H	"0C"H to "0F"H
2nd line	"10"H to "1B"H	"1C"H to "1F"H
3rd line	"20"H to "2B"H	"2C"H to "2F"H
4th line	"30"H to "3B"H	"3C"H to "3F"H
5th line	"40"H to "4B"H	"4C"H and subsequent addresses

**IRE:** When IRE is 1, the key scan interrupt (IRQ\*) generation is enabled. When a key is pressed, the IRQ\* pin outputs a low level signal.

**KF1, KF0:** Used for specifying the key scan cycle. Set these bits according to the mechanical characteristics of the keys and the oscillation frequency (Table 22).

Table 22 KF Bits and Key Scan Cycles

NL1	KF1	KF0	Key Scan Cycle	Key Strobe Width
1 or 2 display lines (NL1=0)	0	0	160/fosc	20/fosc
1 or 2 display lines (NL1=0)	0	1	320/fosc	40/fosc
1 or 2 display lines (NL1=0)	1	0	640/fosc	80/fosc
1 or 2 display lines (NL1=0)	1	1	1,280/fosc	160/fosc
3 or 4 display lines (NL1=1)	0	0	320/fosc	40/fosc
3 or 4 display lines (NL1=1)	0	1	640/fosc	80/fosc
3 or 4 display lines (NL1=1)	1	0	1,280/fosc	160/fosc
3 or 4 display lines (NL1=1)	1	1	2,560/fosc	320/fosc

Note: fosc is the oscillation frequency or external clock frequency.

### Write Data to RAM

The write data to RAM instruction (Figure 21) writes 8-bit data to annunciator or DDRAM, lower 6-bit data to LED port, SEGRAM or CGRAM, or lower two bits to shift direction change bits of SEG/COM that is selected by the previous specification of the address set instruction (annunciator/LED/SEGRAM address set, CGRAM address set, or DDRAM address set).

After a write, the address is automatically incremented or decremented by 1 according to the I/D bit setting in the entry mode set instruction. The annunciator or LED port address is not automatically updated; it must be specifically updated to write data to a different address. During the sleep and standby modes, DDRAM, CGRAM, or SEGRAM cannot be accessed.

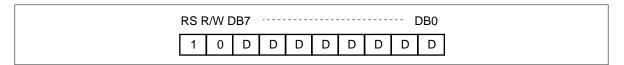


Figure 21 Write Data to RAM Instruction

### Read Data from RAM

The read data from RAM instruction (Figure 22), reads 8-bit data from DDRAM, or 5-bit data from CGRAM or SEGRAM that is selected by the previous specification of the address set instruction (SEGRAM address set, CGRAM address set, or DDRAM address set). The unused upper three bits of CGRAM or SEGRAM data are read as 000; annunciator data cannot be read. If no address is specified by the address set instruction just before this instruction, the first data read will be invalid. When executing consecutive read instructions, the next data is normally read from the next address.

After a read, the address is automatically incremented or decremented by 1 according to the I/D bit setting in the entry mode set instruction.

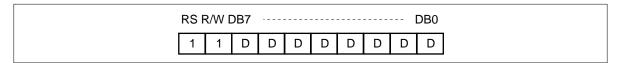


Figure 22 Read Data from RAM Instruction

**Table 23** Instruction List

	Code									Execution			
No.	Instruction	R/W	RS	DB7	DB	6 DB5	DB4	DB3	DB2	DB1	DB0	Description	Cycle *1
KS	Busy flag/key scan read	1	0	BF		SF	TF		\$	SD		Reads busy flag (BF), key- scan state (SF and TF), and data in key scan registers (SD).	0
CL	Clear display	0	0	0	0	0	0	0	0	0	1	Clears entire display and sets address 0 into the address counter.	310
СН	Return home	0	0	0	0	0	0	0	0	1	0	Sets DDRAM address 0 into the address counter.	5
OS	Start oscillator	0	0	0	0	0	0	0	0	1	1	Starts the oscillation standby mode.	_
EM	Entry mode set	0	0	0	0	0	0	0	1	I/D	OSC	Sets the address update direction after RAM access (I/D), and system clock division (OSC).	5
CR	Cursor control	0	0	0	0	0	0	1	B/W	С	В	Sets black-white inverting cursor (B/W), 8th raster-row cursor (C), and blink cursor (B).	5
DO	Display on/off control	0	0	0	0	0	1	0	D	FW	LC	Sets character/segment display on (D), font width (FW), and line-cursor display (LC).	5
PW	Power control	0	0	0	0	0	1	1	AMP	SLP	STB	Turns on LCD power supply (AMP), and sets the sleep mode (SLP) and standby mode (STB).	5
DC	Display control	0	0	0	0	1	NL1	NL0	DL3	DL2	DL1	Sets the number of display lines (NL) and the lines to be doubled in height.	5
CN	Contrast control	0	0	0	1	0	SN2		(	СТ		Sets the display-start line (SN2) and contrast-adjusting value (CT).	5
SC	Scroll control	0	0	0	1	1	SN1	SN0		SL		Sets the display-start line (SN) and display-start raster-row (SL).	5
AS	Annunciator/ SEGRAM address set	0	0	1	0	0	DA		AAN	'ASEG	}	Turns on the annunciator display (DA) and sets annunciator/SEGRAM address.	5
CA	CGRAM address set	0	0	1	0	1			ACG			Sets the initial CGRAM address to the address counter.	5
DA	DDRAM address set (upper bits)	0	0	1	1	0	IRE	KF1	KF0	(up	DD per its)	Sets the initial higher DDRAM address to the address counter, and key scan cycle.	5
DA	DDRAM address set	0	0	1	1	1		ADD	(lowe	r bits)		Sets the initial lower DDRAM address to the	5

					C	ode			Execution			
No.	Instruction	R/W	RS	DB7 DB6	DB5	DB4	DB3	DB2	DB1	DB0	Description	Cycle *1
	(lower bits)										address counter.	
WD	Write data to RAM	0	1			Write	e data				Writes data to DDRAM, CGRAM, SEGRAM, annunciator/LED/general I port, or SEG/COM shift direction.	
RD	Read data from RAM	1	1			Read	d data				Reads data from DDRAM, CGRAM, or SEGRAM.	5

Note: 1. Represented by the number of operating clock pulses; the execution time depends on the supplied clock frequency or the internal oscillation frequency.

#### Bit definition:

BF = 1: Internally operating SF: Key-scan state

TF = 1: Key-scan internally operating

SD: Key-scanned data I/D = 1: Address increment I/D = 0: Address decrement

OSC = 1: System clock divided by four B/W = 1: Black-white inverting cursor on

C = 1: 8th raster-row cursor on

B = 1: Blink cursor on

D = 1: Character/segment display on

FW = 0: 5-dot font width FW = 1: 6-dot font width

LC = 1: Line containing AC given cursor attribute

AMP = 1: Voltage followers and booster on

SLP = 1: Sleep mode
STB = 1: Standby mode
CT: Contrast adjustment

NL1, NL0: Number of display lines [00: 1 line (1/10 duty ratio), 01: 2 lines (1/18 duty ratio), 10: 3 lines

(1/26 duty ratio), 11: 4 lines (1/34 duty ratio)]

DL3-DL1: Double-height lines (DL1 = 1: 1st line, DL2 = 1: 2nd line, DL3 = 1: 3rd line)

SN2-SN0: Display-start line (000: 1st line, 001: 2nd line, 010: 3rd line, 011: 4th line, 100: 5th line)

SL2-SL0: Display-start raster-row (000: 1st raster-row ... 111: 8th raster-row)

DA = 1: Annunciator display on

AAN/ASEG: Annunciator address (0000–0010), LED/general port address (PORT2–PORT0, LED2–LED0) (0011)

AAN/ASEG: SEG/COM shift change address (CMS, SGS) (0100), SEGRAM address (1000-1111)

ACG: CGRAM address (00000–11111)

ADD: DDRAM address (0000000–1001011)

IRE = 1: Key scan interrupt generation enabled

KF1, KF0: Key scan cycle set

## **Reset Function**

## **Initialization by Internal Reset Circuit**

The HD66727 is internally initialized by RESET\* input. During initialization, the system executes the instructions as described below. Here, the busy flag (BF) therefore indicates a busy state (BF = 1), accepting no instruction or RAM data access from the MPU. Here, reset input must be held at least 10 ms.

After releasing power-on reset, clear display instruction is operated. So wait for 1,000 clock-cycles or more.

Make sure to reset the HD66727 immediately after power-on.

### Initialization of Instruction Sets, RAM, and Pins

#### **Instruction set initialization:**

1. Clear display executed

Writes 20H to DDRAM after releasing reset.

2. Return home executed

Sets the address counter (AC) to 00H to select DDRAM

- 3. Start oscillator executed
- 4. Entry mode set

I/D = 1: Increment by 1

OSC = 0: Clock frequency not divided

5. Cursor control

B/W = 0: White-black inverting cursor off

C = 0: 8th raster-row cursor off

B = 0: Blink cursor off

6. Display on/off control

D = 0: Character/segment display off

FW = 0: 5-dot font width

LC = 0: Line-cursor off

7. Power control

AMP = 0: LCD power supply off

SLP = 0: Sleep mode off

STB = 0: Standby mode off

8. Display control

NL1, NL0 = 11: 4-line display (1/34 multiplexing duty ratio)

DL3–DL1 = 000: Double-height display off

9. Contrast adjust

CT = 0000: Weak contrast

### 10. Scroll control

SN2-SN0 = 000: First line displayed at the top

SL2-SL0 = 000: First raster-row displayed at the top of the first line

### 11. Annunciator control

DA = 0: Annunciator display off

### 12. Key scan control

IRE = 0: Key scan interrupt (IRQ\*) generation disabled

KF1, KF0 = 00: Key scan cycle set to 320 clock cycles

### 13. LED/general port

LED2/LED1/LED0 = 000: LED2/LED1/LED0 outputs =  $V_{CC}$  level

PORT2/ PORT1/ PORT0 = 000: PORT2/ PORT1/ PORT0 outputs = GND level

## 14. LCD driver output direction

CMS = 0: Starts shift from COM1/32

SGS = 0: Starts shift from SEG1/60

### **RAM data initialization:**

### 1. DDRAM

All addresses are initialized to 20H by the clear display instruction

### 2. CGRAM/SEGRAM

Not automatically initialized by reset input; must be initialized by software while display is off (D = 0)

3. Annunciator data

Not automatically initialized by reset input; must be initialized by software while display is off (DA=0)

### Output pin initialization:

- 1. LCD driver output pins (SEG/COM, ASEG/ACOM): Outputs  $V_{CC}$  level
- 2. Booster output pins (V5OUT2 and V5OUT3): Outputs GND level
- 3. Oscillator output pin (OSC2): Outputs oscillation signal
- 4. Key strobe pins (KST0 to KST7): Outputs strobe signals at a specified time interval
- 5. Key scan interrupt pin (IRQ\*): Outputs  $V_{CC}$  level
- 6. LED driving port (LED0–LED2): Outputs V<sub>CC</sub> level
- 7. General output port (PORT0-PORT2): Outputs GND level

## Serial Data Transfer

### I<sup>2</sup>C Bus Interface

Grounding the IM pin (interface mode pin) allows serial data transfer conforming to the  $I^2C$  bus interface using the serial data line (SDA) and serial transfer clock line (SCL). Here, the HD66727 operates in an transmit/receive slave mode.

The HD66727 initiates serial data transfer by transferring the first byte when a high SCL level at the falling edge of the SDA input is sampled; it ends serial data transfer when a high SCL level at the rising edge of the SDA input is sampled.

Table 24 illustrates the first bytes of I<sup>2</sup>C bus interface data and Figure 23 shows the I<sup>2</sup>C bus interface timing sequence.

The HD66727 is selected when the higher six bits of the 7-bit slave address in the first byte transferred from the master device match the 6-bit device identification code assigned to the HD66727. The HD66727, when selected, receives the subsequent data string. The lower bits of the identification code can be determined by the ID1 and ID0 pins; select an appropriate code that is not assigned to any other slave device. The upper four bits is fixed to 0111. Two different slave addresses must be assigned to a single HD66727 because the least significant bit (LSB) of the slave address is used as a register select bit (RS): when RS = 0, an instruction can be issued or key scan data can be read, and when RS = 1, data can be written to or read from RAM. Read or write is selected according to the eighth bit of the first byte (R/W bit) as shown in Table 25.

The ninth bit of the first byte is a receive-data acknowledge bit (ACK). When the received slave address matches the device ID code, the HD66727 pulls down the ACK bit to a low level. Therefore, the ACK output buffer is an open-drain structure, only allowing low-level output. However, the ACK bit is undetermined immediately after power-on; make sure to initialize the LSI using the RESET\* input.

After identifying the address in the first byte, the HD66727 receives the subsequent data as an HD66727 instruction or as RAM data, or transmits key scan data or RAM data. Having received or transmitted 8-bit data normally, the HD66727 pulls down the ninth bit (ACK) to a low level. Therefore, if the ACK is not returned, the data must be transferred again. Multiple bytes of data can be consecutively transferred until the transfer-end condition is satisfied. Here, when the serial data transfer rate is longer than the HD66727 instruction execution time, effective data transfer is possible without retransmission (see Table 23, Instruction List). Note that the display clear instruction alone requires longer execution time than the others.

Table 24 First Bytes of I<sup>2</sup>C Bus Interface Data

## **Transferred Bit String**

First Byte of	S	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7	Bit 8	Bit 9
I <sup>2</sup> C bus system * <sup>1</sup>	Transfer start	A6	A5	A4	А3	A2	A1	A0	R/W	ACK
HD66727 *2	Transfer start	0	1	1	1	ID1	ID0	RS	R/W	ACK

Notes: 1. Bits 1 to 7 of the first byte of the I<sup>2</sup>C bus system indicate the I<sup>2</sup>C slave address.

2. Bits 1 to 6 of the first byte of the HD66727 indicate the device ID code.

Table 25 RS and R/W Bit Function of I<sup>2</sup>C Bus Interface Data

RS	R/W	Function
0	0	Writes instruction
0	1	Reads key scan data and BF flag
1	0	Writes RAM data
1	1	Reads RAM data

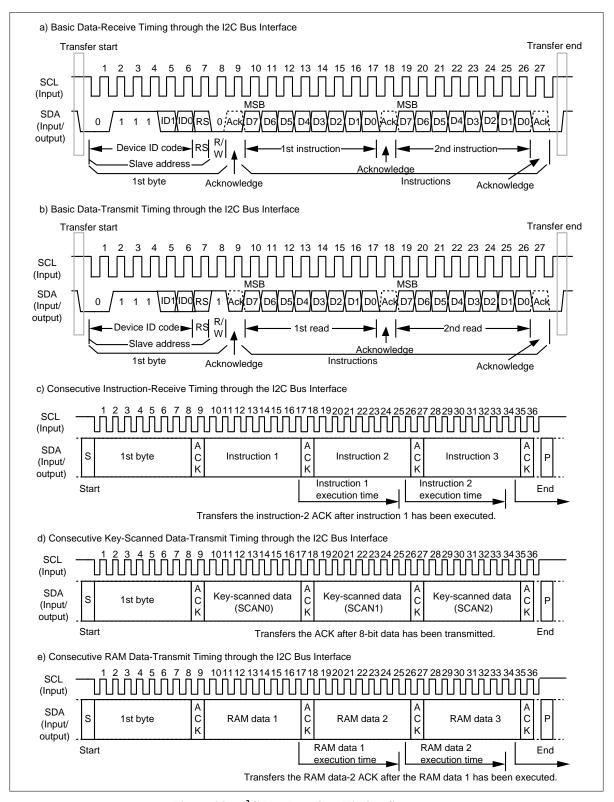


Figure 23 I<sup>2</sup>C Bus Interface Timing Sequence

### **Clock-Synchronized Serial Interface**

Setting the IM pin (interface mode pin) to the high level allows standard clock-synchronized serial data transfer, using the chip select line (CS\*), serial data line (SDA), and serial transfer clock line (SCL).

The HD66727 initiates serial data transfer by transferring the start byte at the falling edge of the CS\* input. It ends serial data transfer at the rising edge of the CS\* input.

Table 24 illustrates the first bytes of I<sup>2</sup>C bus interface data and Figure 24 shows the clock-synchronized serial interface timing sequence.

The HD66727 is selected when the 6-bit chip address in the start byte transferred from the transmitting device matches the 6-bit device identification code assigned to the HD66727. The HD66727, when selected, receives the subsequent data string. The least significant bit of the identification code can be determined by the ID0 pin. The upper five bits must be 01110. Two different chip addresses must be assigned to a single HD66727 because the seventh bit of the start byte is used as a register select bit (RS): when RS = 0, an instruction can be issued or key scan data can be read, and when RS = 1, data can be written to or read from RAM. Read or write is selected according to the eighth bit of the start byte (R/W bit) as shown in Table 27.

After receiving the start byte, the HD66727 receives or transmits the subsequent data byte-by-byte. Data is transferred with the MSB first. To transfer data consecutively, adjust the data transfer rate so that the HD66727 can complete the current instruction before the eighth bit of the next instruction is transferred (see Table 23, Instruction List). If the next instruction is transferred during execution of the current instruction, the next instruction will be ignored. Note that the display-clear instruction alone requires longer execution time than the others.

Table 26 Start Byte of Clock-Synchronized Serial Interface Data

S	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7	Bit 8
Transfer start	0	1	1	1	0	ID0	RS	R/W

Note: Bits 1 to 6 indicate the device ID code.

Table 27 RS and R/W Bit Function of Clock-Synchronized Serial Interface Data

RS	R/W	Function
0	0	Writes instruction
0	1	Reads key scan data and BF flag
1	0	Writes RAM data
1	1	Reads RAM data

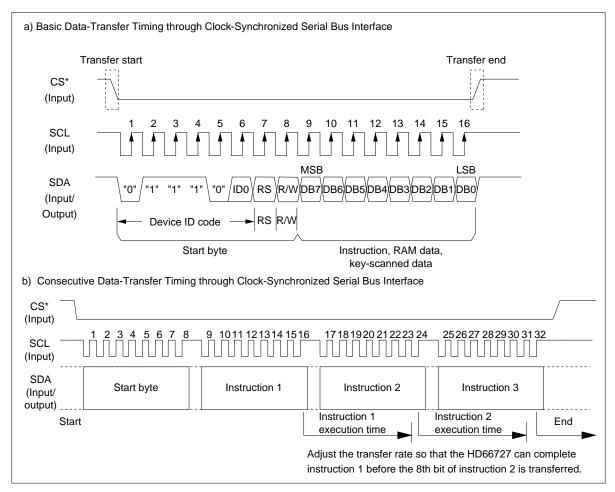


Figure 24 Clock-Synchronized Serial Interface Timing Sequence

## **Key Scan Control**

# **Key Scan Mechanism**

The key matrix scanner senses and holds the key states at each rising edge of the key strobe signals (KST) that are output by the HD66727. The key strobe signals are output as time-multiplexed signals from KST0 to KST7. After passing through the key matrix, these strobe signals are used to sample the key state on four inputs KIN0 to KIN3, enabling up to 32 keys to be scanned (Figure 25).

The states of inputs KIN0 to KIN3 are sampled by key strobe signal KST0 and latched into the SCAN0 register. Similarly, the data sampled by strobe signals KST1 to KST7 is latched into the SCAN1 to SCAN7 registers, respectively (Figure 26). Key pressing is stored as 1 in these registers.

The generation cycle and pulse width of the key strobe signals depend on the operating frequency (oscillation frequency) of the HD66727, the display line determined by the NL1 bit, and the key scan cycle determined by the KF0 and KF1 bits. For example, when the operating frequency is 160 kHz, NL1 is 1, and KF0 and KF1 are both 0, the generation cycle is 8.0 ms and the pulse width is 1.0 ms (Figure 27). When the operating frequency (oscillation frequency) is changed, the above generation cycle and the pulse width are also changed in inverse proportion (Table 28).

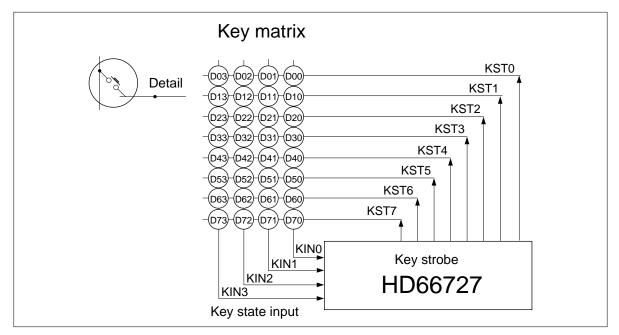


Figure 25 Key Scan Configuration

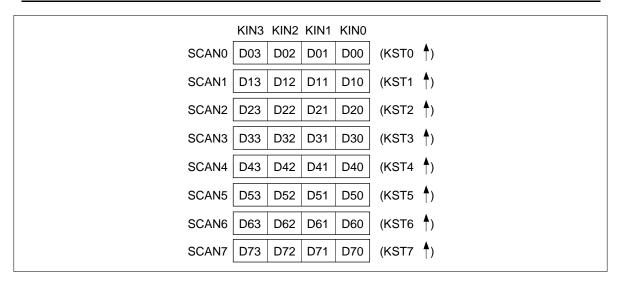


Figure 26 Key Scan Register Configuration

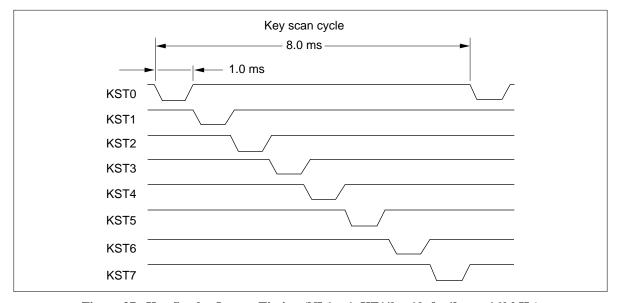


Figure 27 Key Strobe Output Timing (NL1 = 1, KF1/0 = 10, fcp/fosc = 160 kHz)

Table 28 Key Scan Cycles for Each Operating Frequency

Register **Key Scan Cycle** NL1 KF1 KF0 **Clock Cycle** 160 kHz 120 kHz 80 kHz 40 kHz 0 (1, 2 lines) 0 0 160  $(1.0 ms)^{*}$ (1.3 ms)\*2.0 ms 4.0 ms 0 (1, 2 lines) 0 1 320  $(2.0 \text{ ms})^{*}$  $(2.7 \text{ ms})^*$ 4.0 ms 8.0 ms 16.0 ms 0 (1, 2 lines) 1 0 640  $(4.0 \text{ ms})^*$  $(5.3 \text{ ms})^*$ 8.0 ms 0 (1, 2 lines) 1 1 1,280  $(8.0 ms)^*$ (10.7 ms)\* 16.0 ms 32.0 ms 320 1 (3, 4 lines) 0 0 2.0 ms 2.7 ms  $(4.0 \text{ ms})^*$ (8.0ms)\*1 (3, 4 lines) 640 (8.0ms)\*0 1 4.0 ms 5.3 ms  $(16.0ms)^*$ 10.7 ms 1 (3, 4 lines) 1 0 1,280 8.0 ms (32.0ms)\*(16.0 ms)\* 1 (3, 4 lines) 1 2,560 16.0 ms 21.3 ms (32.0 ms)\*(64.0ms)\*

Note: \* Reference value

In order to compensate for the mechanical features of the keys, such as chattering and noise and for the key-strobe generation cycle and the pulse width of the HD66727, software should read the scanned data two or three times in succession to obtain valid data. Multiple keypress combinations should also be processed in software. Up to three keys can be pressed simultaneously. Note, however, that if the third key is pressed on an intersection between the rows and columns of the first two keys pressed, incorrect data will be sampled. For three-key input, the third key must be on a separate column and row.

The input pins KIN0 to KIN3 are pulled up to  $V_{\rm CC}$  with internal MOS transistors (see the Electrical Characteristics section). External resistors may also be required to further pull up the voltages when the internal pull-ups are insufficient for the desired noise margins or for a large key matrix.

## **Key Scan Data Transfer**

The key-scanned data can be read by an MPU via a serial interface as shown in Figure 28. First, a start byte should be transferred. After the HD66727 has received the start byte, the MPU reads scan data SD0 to SD3 from the SCAN0 register starting from the MSB. Similarly, the MPU reads data from SCAN1, SCAN2, SCAN3, SCAN4, SCAN5, SCAN6, and SCAN7 in that order. After reading SCAN7, the MPU starts at SCAN0 again. While reading the scanned data, the MPU also reads the scan flags (SF1 and SF0) and the transfer flag (TF). The scan flags reflect the value of the scan cycle counter, which automatically increments its value by one for each scan cycle from 00 to 11 (after 11, it is reset to 00). If the scan data is read more than once to be confirmed, and the corresponding scan counter values are the same, the scan data might have been erroneously latched into the scan register at the same timing; it should be reconfirmed as required. Also, if the transfer flag is read as 1, the HD66727 has been read out while it is latching scan data and is thus unstable; it should also be reconfirmed as required.

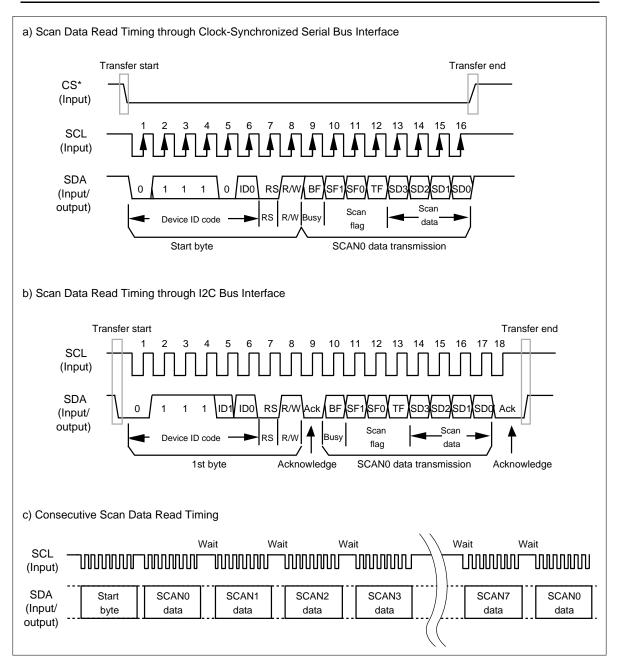


Figure 28 Scan Data Serial Transfer Timing

## **Key Scan Interrupt (Wake-Up Function)**

If the interrupt enable bit (IRE) is set to 1, the HD66727 sends an interrupt signal to the MPU on detecting that a key has been pressed in the key scan circuit by setting the IRQ\* output pin to a low level. An interrupt signal can be generated by pressing any key in a 32-key matrix. The interrupt level continues to be output during the key scan cycle in which the key is being pressed. See Figure 29.

Normal key scanning is performed and interrupts can occur in the HD66727 sleep mode (SLP = 1). Accordingly, power consumption can be minimized in the sleep mode, where only annunciators can be displayed, by triggering the MPU to read key states via the interrupt generated only when the HD66727 detects a key input from the 32-key matrix. For details, refer to the Sleep Mode section.

On the other hand, normal key scanning and the internal operating clock are halted in the standby mode (STB = 1). During this period, the KST0 output is kept low, so the HD66727 can always sense four key inputs D00 to D03, connected with KIN0 to KIN3, respectively. Therefore, if any of the four keys is pressed in the standby mode, an interrupt occurs. Accordingly, power consumption can be further minimized in the standby mode, where the whole system is inactive, by triggering the MPU via the interrupt generated only when the HD66727 detects a key input from the above four keys. Note that the interrupt generated in the standby mode automatically starts internal R-C oscillation. For details, refer to the Standby Mode section.

The IRQ\* output pin is pulled up to the  $V_{\rm CC}$  with an internal MOS resistor of approximately 50 k $\Omega$ ; additional external resistors may be required to obtain stronger pull-ups. Interrupts may occur if noise occurs in KIN input during key scanning. Interrupts must be inhibited if not needed by setting the interrupt enable bit (IRE) to 0.

Figure 30 shows key scan interrupt processing flow in sleep and standby modes.

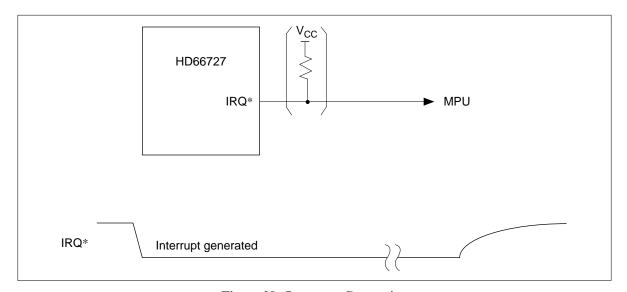


Figure 29 Interrupt Generation

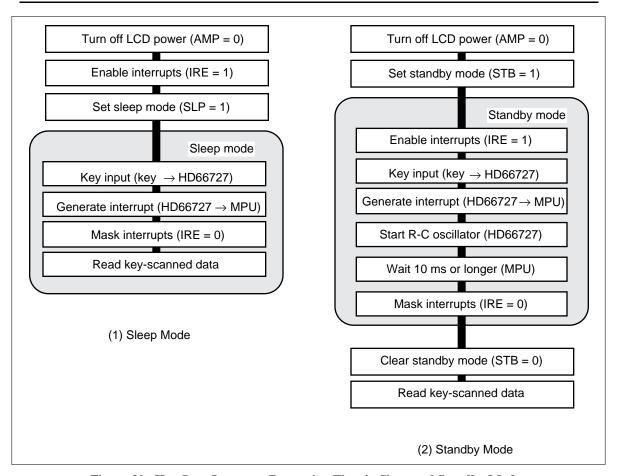


Figure 30 Key Scan Interrupt Processing Flow in Sleep and Standby Modes

## **Oscillator Circuit**

The HD66727 can either be supplied with operating clock pulses externally (external clock mode) or oscillate using an internal R-C oscillator and an external oscillator-resistor (internal oscillation mode), as shown in Figure 31. An appropriate oscillator-resistor must be used to obtain the optimum clock frequency according to the number of display lines (Table 29). Instruction execution times change in proportion to the operating clock frequency or R-C oscillation frequency; MPU data transfer rate must be appropriately adjusted (see Table 23, Instruction List). Figure 32 shows a sample LCD drive output waveform, where 4-lines are displayed with 1/34 multiplexing duty ratio.

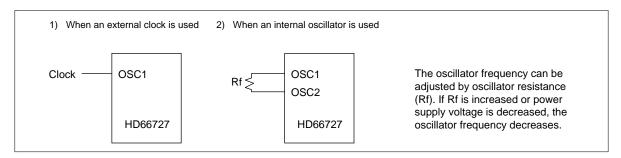


Figure 31 Oscillator Circuit

 Table 29
 Oscillation Frequency and LCD Frame Frequency

Item	1-Line Display (NL1, NL0 = 00)	2-Line Display (NL1, NL0 = 01)	3-Line Display (NL1, NL0 = 10)	4-Line Display (NL1, NL0 = 11)
Multiplexing duty ratio	1/10	1/18	1/26	1/34
R-C oscillation frequency (recommended value)	40 kHz	80 kHz	120 kHz	160 kHz
1-line drive frequency	0.66 kHz	1.3 kHz	2.0 kHz	2.7 kHz
Frame frequency	67 Hz	74 Hz	77 Hz	78 Hz

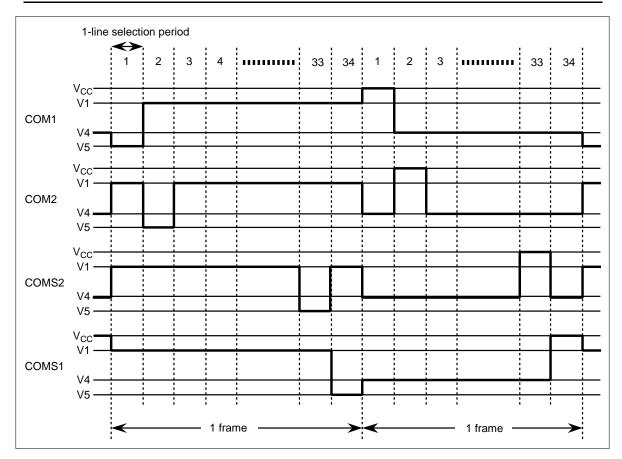


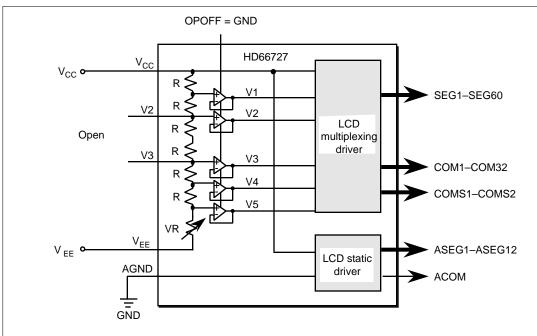
Figure 32 LCD Drive Output Waveform Example (4-line display with 1/34 multiplexing duty ratio)

# Power Supply for Liquid Crystal Display Drive

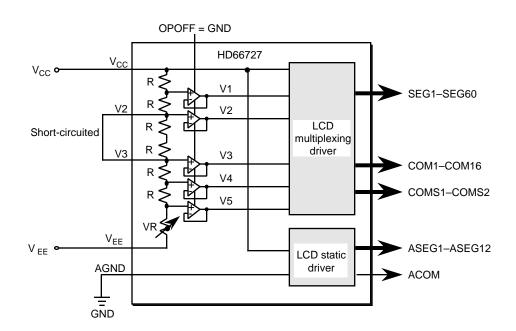
## When External Power Supply and Internal Operational Amplifiers are Used

To supply LCD drive voltage directly from the external power supply without using the internal booster, circuits should be connected as shown in Figure 33. Here, contrast can be adjusted through the CT bits of the contrast control instruction.

The HD66727 incorporates a voltage-follower operational amplifier for each of V1 to V5 to reduce current flowing through the internal bleeder-resistors, which generate different levels of liquid-crystal drive voltages. Thus, potential differences between  $V_{CC}$  and V1 and between  $V_{EE}$  and V5 must be 0.4V or greater. Note that the OPOFF pin must be grounded when using the operational amplifiers.



a) 3- or 4-line display with 1/6 bias



b) 1- or 2-line display with 1/4 bias

Notes: 1. Potential differences between  $V_{CC}$  and V1 and between V5 and  $V_{EE}$  must be 0.4V or greater, particularly for low-duty drive such as 1-line display.

2. When the internal operational amplifiers cannot fully drive the LCD panel used, an appropriate capacitor must be inserted between each output of V10UT to V50UT and  $V_{CC}$  to stabilize the operational amplifier output.

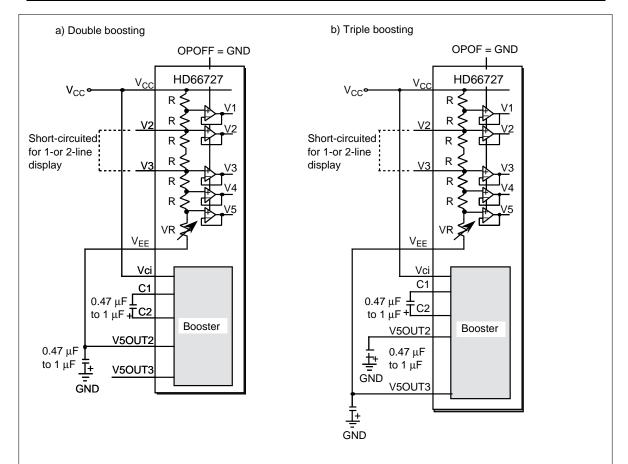
Figure 33 External Power Supply Circuit Example for LCD Drive Voltage Generation

### When an Internal Booster and Internal Operational Amplifiers are Used

To supply LCD drive voltage using the internal booster, circuits should be connected as shown in Figure 34. Here, contrast can be adjusted through the CT bits of the contrast control instruction. Temperature can be compensated either through the CT bits or by controlling the reference voltage for the booster (Vci pin) using a thermistor.

Note that Vci is both a reference voltage and power supply for the booster; the reference voltage must therefore be adjusted using an emitter-follower or a similar element so that sufficient current can be supplied. In this case, Vci must be equal to or smaller than the  $V_{\rm CC}$  level.

The HD66727 incorporates a voltage-follower operational amplifier for each of V1 to V5 to reduce current flowing through the internal bleeder-resistors, which generate different levels of liquid-crystal drive voltages. Thus, potential differences between  $V_{\rm CC}$  and V1 and between  $V_{\rm EE}$  and V5 must be 0.4V or greater. Note that the OPOFF pin must be grounded when using the operational amplifiers.



- Notes: 1. The reference voltage input (Vci) must be adjusted so that the output voltage after boosting will not exceed the absolute maximum rating of the liquid-crystal power supply voltage (15V). Particularly, Vci must be 5V or less for triple boosting.
  - 2. Vci is both a reference voltage and power supply for the booster; connect it to V<sub>CC</sub> directly or combine it with a transistor so that sufficient current can be obtained.
  - 3. Vci must be smaller than V<sub>CC</sub>.
  - 4. To operate the voltage-follower correctly, potential differences between V<sub>CC</sub> and V1 and between V5 and V<sub>EE</sub> must be 0.4V or greater, particularly for low-duty drive such as 1-line display.
  - 5. Polarized capacitors must be connected correclty.
  - 6. Circuits for temperature compensation should be designed based on the sample circuit shown in figure 35.
  - 7. The HD66727's internal operational amplifiers have a reduced drive current to save current consumption; when the internal operational amplifiers cannot fully drive the LCD panel used, an appropriate capacitor must be inserted between each output of V1OUT to V5OUT and V<sub>CC</sub> to stabilize the operational amplifier output (Figure 36).

Figure 34 Internal Power Supply Circuit Example for LCD Drive Voltage Generation

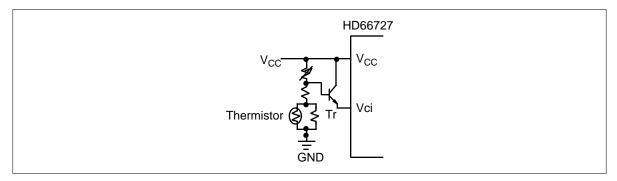


Figure 35 Temperature Compensation Circuit Example

## Example of Using Internal Operational Amplifier when Driving Large Size of LCD

The driving current of the internal operational amplifier in the HD66727 is reduced to control the consumption current. When load current is apparently large such as when driving large size of LCD panel, insert a capacitor between V10UT–V50UT outputs and  $V_{\rm CC}$  power supply, and stabilize the output level of the operational amplifier. Especially the capacitors for V10UT and V40UT must be inserted when 1/26 duty or 1/34 duty drives.

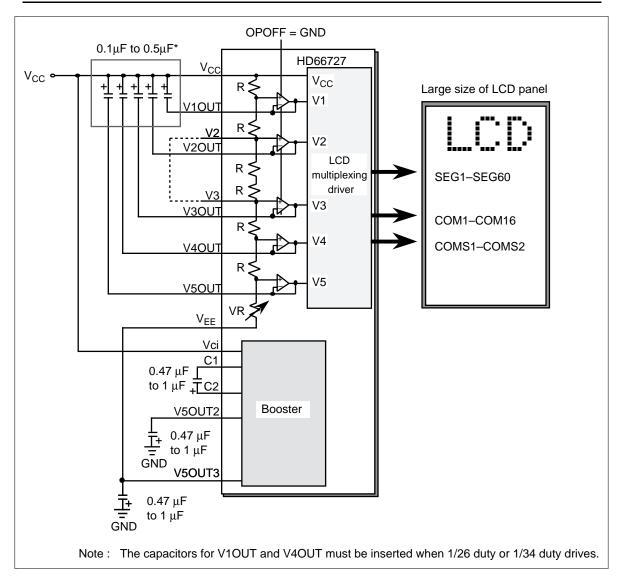
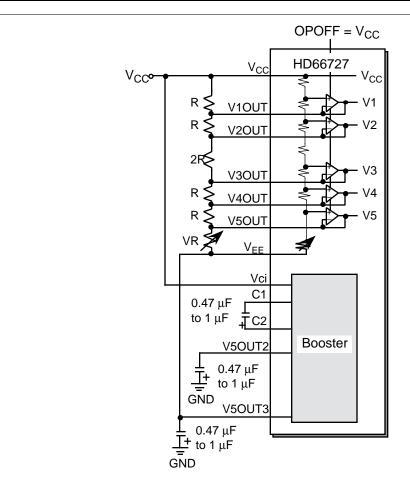


Figure 36 Operational Amplifier Output Stabilization Circuit Example when Driving Large Size of LCD Panel

## When an Internal Booster and External Bleeder-Resistors are Used

When the internal operational amplifiers cannot fully drive the LCD panel used, V1 to V5 voltages can be supplied through external bleeder-resistors (Figure 37). Here, the OPOFF pin must be set to the  $V_{CC}$  level to turn off the internal operational amplifiers. Since the internal contrast adjuster is disabled in this case, contrast must be adjusted externally. Double- and triple-boosters can be used as they are.



Notes: 1. Resistance of each external bleeder resistor should be 5 k $\Omega$  to 15 k $\Omega$ .

- 2. The bias current value for driving liquid-crystals can be varied by adjusting the resistance (2R) between the V2OUT and V3OUT pins.
- 3. The internal contrast-adjuster is disabled; contrast must be adjusted either by controlling the external variable resistor between  $V_{\text{EE}}$  and V5OUT or Vci for the booster.
- 4. Vci is both a reference voltage and power supply for the booster; connect it to V<sub>CC</sub> directly or combine it with a transistor so that sufficient current can be obtained.
- 5. Vci must be smaller than  $V_{CC}$ .

Figure 37 Power Supply Circuit Example Using External Bleeder-Resistor for LCD Drive Voltage Generation

## **Contrast Adjuster**

### **Multiplexing Drive System**

Contrast for an LCD controlled by the multiplexing drive method can be adjusted by varying the liquid-crystal drive voltage (potential difference between  $V_{\rm CC}$  and V5) through the CT bits of the contrast control instruction (electron volume function). See Figure 38 and Table 30. The value of a variable resistor (VR) can be adjusted within the range from 0.4 x R through 6.4 x R, where R is a reference resistance obtained by dividing the total resistance between  $V_{\rm CC}$  and V5.

The HD66727 incorporates a voltage-follower operational amplifier for each of V1 to V5 to reduce current flowing through the internal bleeder-resistors, which generate different levels of liquid-crystal drive voltages. Thus, potential differences between  $V_{CC}$  and V1 and between  $V_{EE}$  and V5 must be 0.4V or greater. Note that the OPOFF pin must be grounded when using the operational amplifiers.

### 1/6 bias (V2 and V3 pins left open):

LCD drive voltage VLCD:  $6R \times (V_{CC} - V_{EE})/(6R + VR)$  (VR = a value within the range from 0.4R to 6.4R)

VLCD adjustable range:  $0.484 \times (V_{CC} - V_{EE}) \le VLCD \le 0.938 \times (V_{CC} - V_{EE})$ 

Potential difference between  $V_{CC}$  and V1:  $R \times (V_{CC} - V_{EE})/(6R + VR) \ge 0.4$  (V)

Potential difference between V5 and  $V_{EE}$ :  $VR \times (V_{CC} - V_{EE})/(6R + VR) \ge 0.4$  (V)

## 1/4 bias (V2 and V3 pins short-circuited):

LCD drive voltage VLCD:  $4R \times (V_{cc} - V_{EE})/(4R + VR)$  (VR = a value within the range from 0.4R to 6.4R)

VLCD adjustable range:  $0.385 \times (V_{CC} - V_{EE}) \le VLCD \le 0.909 \times (V_{CC} - V_{EE})$ 

Potential difference between  $V_{CC}$  and V1:  $R \times (V_{CC} - V_{EE})/(4R + VR) \ge 0.4$  (V)

Potential difference between V5 and  $V_{EE}$ :  $VR \times (V_{CC} - V_{EE})/(4R + VR) \ge 0.4$  (V)

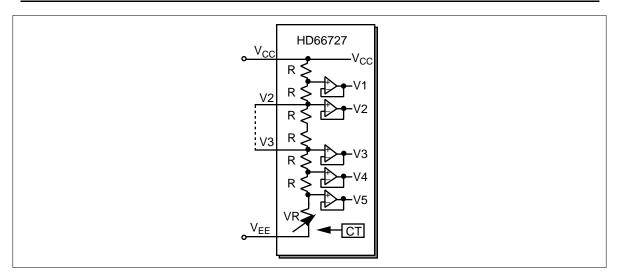


Figure 38 Contrast Adjuster

Table 30 Contrast-Adjust Bits (CT) and Variable Resistor Values

	CT1	СТ0	Variable Resistor Value (VR)
0	0	0	6.4 R
0	0	1	6.0 R
0	1	0	5.6 R
0	1	1	5.2 R
1	0	0	4.8 R
1	0	1	4.4 R
1	1	0	4.0 R
1	1	1	3.6 R
0	0	0	3.2 R
0	0	1	2.8 R
0	1	0	2.4 R
0	1	1	2.0 R
1	0	0	1.6 R
1	0	1	1.2 R
1	1	0	0.8 R
1	1	1	0.4 R
	0 0 0 1 1 1 1 0 0	0 0 0 0 0 1 0 1 1 1 1 1 1 0 0 0 1 1 1 1	0       0       1         0       1       0         0       1       1         1       0       0         1       1       0         1       1       1         0       0       0         0       0       1         0       1       0         0       1       1         1       0       0         1       0       0         1       0       1         1       0       1         1       0       1         1       0       1         1       0       1         1       0       1         1       0       1         1       0       1         1       0       1         1       0       1         1       0       0         1       0       0         1       0       0         1       0       0         1       0       0         1       0       0         1       0       0

## **Static Drive System**

Contrast for a statically-driven LCD, that is, annunciator display, can be adjusted through the AGND pin. The annunciators are driven statically by the potential difference between  $V_{\text{CC}}$  and AGND. The AGND pin level must be equal to or greater than the GND level.

## **LCD Panel Interface**

The HD66727 can change the shift direction of common drivers COM1–COM32 and COMS1 and COMS2 and segment drivers SEG1–SEG60 with the CMS and SGS bits. These bits can be selected according to the mounting method such as the chip arrangement or wire leading. However, the output position of annunciator drivers ASEG1–ASEG12 cannot be changed, so adjust it by software.

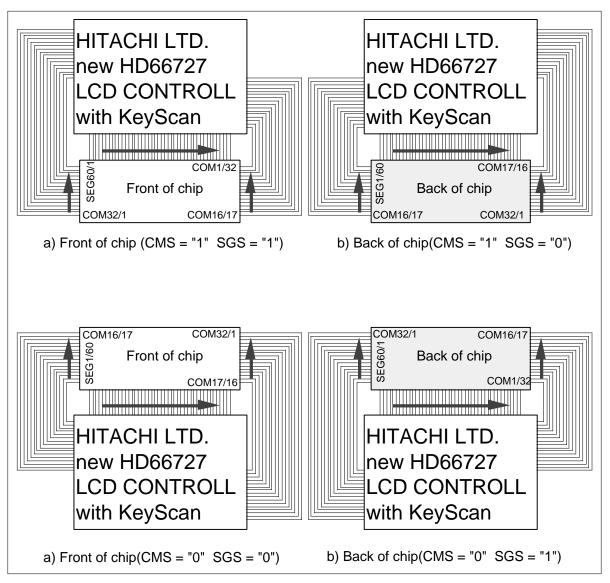


Figure 39 LCD Module Interface Examples

## **Segment Display and Annunciator Display**

The HD66727 provides both segment display, which is driven by the multiplexing method, and annunciator display, which is driven statically. Annunciator display is driven at a logic operating voltage ( $V_{CC}$  – AGND) and is thus also available while the LCD drive power supply is turned off. Accordingly,

annunciator display is suitable for displaying marks during system standby, when it is desirable to reduce current consumption. It is available in the sleep mode, where internal multiplexing operations for character or segment display are halted. If an alternating signal is supplied to the EXM pin, it is also available in the standby mode, where the internal R-C oscillator is halted. Here, AGND must be equal to or above the GND level.

Note that annunciator display cannot share character display drivers SEG and COM but require special drivers ASEG and ACOM that require long routing.

Tables 31 to 34 compare segment display to annunciator display. Figure 40 shows annunciator drive output waveforms in two modes.

Table 31 Comparison between Segment Display and Annunciator Display

Item	Segment Display	Annunciator Display
Number of driven elements	40 each by 5-dot font width	12
	48 each by 6-dot font width	
Blinking	Impossible	Possible
Segment drivers	SEG1-SEG60 (shared with character display)	ASEG1-ASEG12 (independent of character display)
Common drivers	COMS1, COMS2	ACOM
LCD power supply	V <sub>cc</sub> – V5 (LCD power supply necessary)	V <sub>cc</sub> – AGND (LCD power supply unnecessary)
Normal mode display	Possible together with character display by multiplexing drive	Possible by static drive
Sleep mode display	Impossible (SEG and COM output V <sub>cc</sub> )	Possible by static drive
Standby mode display (without oscillation)	Impossible (SEG and COM output V <sub>cc</sub> )	Possible by supplying alternating signal to the EXM pin

Table 32 Correspondence between Segment Display SEGRAM Addresses (ASEG) and Driver Signals when 5-Dot Font Width

ASEC	3 Addr	ess		Common	Segment Signal						
MSB LS		LSB	Signal	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0			
1	0	0	0	COMS1	SEG1/21/41	SEG2/22/42	SEG3/23/43	SEG4/24/44	SEG5/25/45		
1	0	0	1	COMS1	SEG6/26/46	SEG7/27/47	SEG8/28/48	SEG9/29/49	SEG10/30/50		
1	0	1	0	COMS1	SEG11/31/51	SEG12/32/52	SEG13/33/53	SEG14/34/54	SEG15/35/55		
1	0	1	1	COMS1	SEG16/36/56	SEG17/37/57	SEG18/38/58	SEG19/39/59	SEG20/40/60		
1	1	0	0	COMS2	SEG1/21/41	SEG2/22/42	SEG3/23/43	SEG4/24/44	SEG5/25/45		
1	1	0	1	COMS2	SEG6/26/46	SEG7/27/47	SEG8/28/48	SEG9/29/49	SEG10/30/50		
1	1	1	0	COMS2	SEG11/31/51	SEG12/32/52	SEG13/33/53	SEG14/34/54	SEG15/35/55		
1	1	1	1	COMS2	SEG16/36/56	SEG17/37/57	SEG18/38/58	SEG19/39/59	SEG20/40/60		

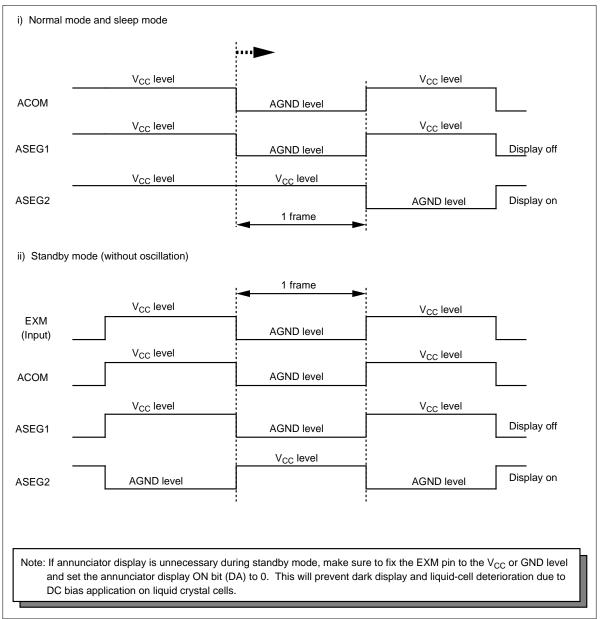
Table 33 Correspondence between Segment Display SEGRAM Addresses (ASEG) and Driver Signals when 6-Dot Font Width

ASEG Address				Common	Segment Signal							
MSB LS		LSB	Signal	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	
1	0	0	0	COMS1	*	*	SEG1/25/ 49	SEG2/26/ 50	SEG3/27/ 51	SEG4/28/ 52	SEG5/29/ 53	SEG6/30/ 54
1	0	0	1	COMS1	*	*	SEG7/31/ 55	SEG8/32/ 56	SEG9/33/ 57	SEG10/ 34/58	SEG11/ 35/59	SEG12/ 36/60
1	0	1	0	COMS1	*	*	SEG13/ 37	SEG14/ 38	SEG15/ 39	SEG16/ 40	SEG17/ 41	SEG18/ 42
1	0	1	1	COMS1	*	*	SEG19/ 43	SEG20/ 44	SEG21/ 45	SEG22/ 46	SEG23/ 47	SEG24/ 48
1	1	0	0	COMS2	*	*	SEG1/25/ 49	SEG2/26/ 50	SEG3/27/ 51	SEG4/28/ 52	SEG5/29/ 53	SEG6/30/ 54
1	1	0	1	COMS2	*	*	SEG7/31/ 55	SEG8/32/ 56	SEG9/33/ 57	SEG10/ 34/58	SEG11/ 35/59	SEG12/ 36/60
1	1	1	0	COMS2	*	*	SEG13/ 37	SEG14/ 38	SEG15/ 39	SEG16/ 40	SEG17/ 41	SEG18/ 42
1	1	1	1	COMS2	*	*	SEG19/ 43	SEG20/ 44	SEG21/ 45	SEG22/ 46	SEG23/ 47	SEG24/ 48

Table 34 Correspondence between Annunciator Display Addresses (AAN) and Driver Signals

**AAN Address Segment Signal** MSB LSB **Common Signal** Bits 7, 6 Bits 5, 4 Bits 3, 2 Bits 1, 0 ASEG1 ASEG2 ASEG4 0 0 0 ACOM ASEG3 0 0 ACOM ASEG5 ASEG6 ASEG7 ASEG8 0 1 0 0 ACOM ASEG9 ASEG10 ASEG11 0 1 ASEG12

Note: The annunciator is turned on when the corresponding even bit (bit 6, 4, 2, or 0) is 1, and the turned on annunciator blinks when the corresponding odd bit (bit 7, 5, 3, or 1) is 1.



#### Vertical Smooth Scroll

The HD66727 can scroll in the vertical direction in units of raster-rows. This function is achieved by writing character codes into DDRAM area that is not being used for display. In other words, since DDRAM corresponds to a 5-line × 12-character display, one of the lines can be used to achieve continuous smooth vertical scroll even in a 4-line display. Here, after the fifth line is displayed, the first line is displayed again. Specifically, this function is controlled by incrementing or decrementing the value in the display-start line bits (SL2 to SL0) and display-start raster-row bits (SN2 to SN0) by 1. For example, to smoothly scroll up, first set SN2 to SN0 to 000, and increment SL2 to SL0 by 1 from 000 to 111 to scroll seven raster-rows.

Figure 40 Annunciator Drive Output Waveforms

Then increment SN2 to SN0 to 001, and again increment SL2 to SL0 by 1 from 000 to 111. To start displaying and scrolling from the first raster-row of the second line, update the first line of DDRAM data as desired during its non-display period.

Figure 41 shows an example of vertical smooth scrolling and Figure 42 shows an example of setting instructions for vertically scrolling upward in a 4-line display (NL1 and NL0 = 11).

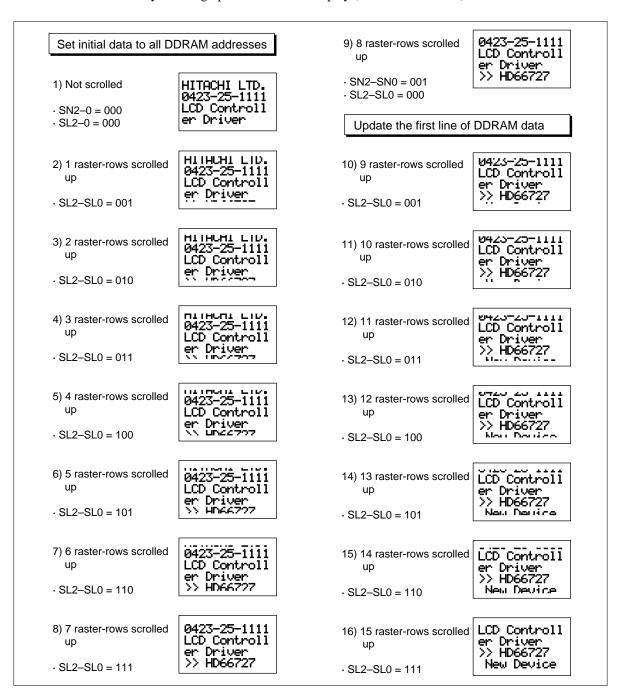


Figure 41 Example of Vertical Smooth Scrolling

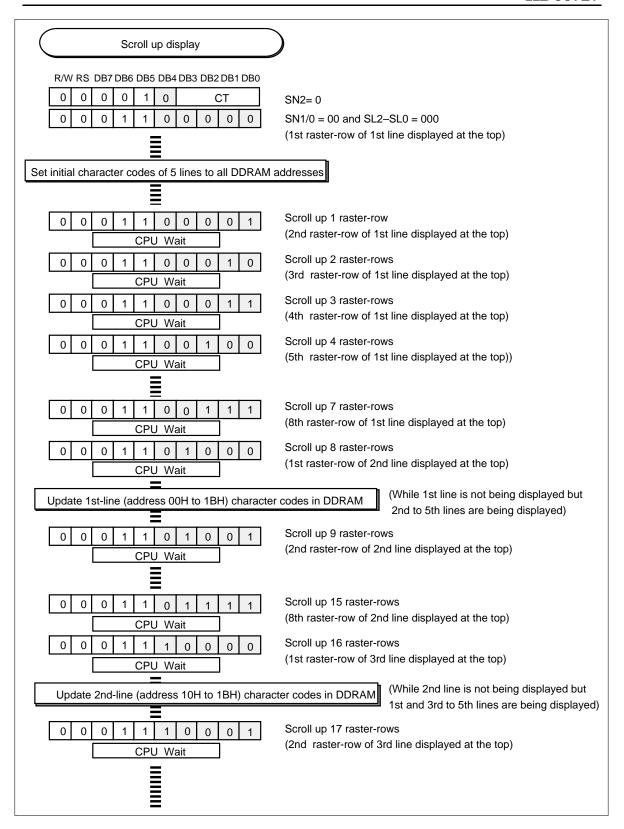


Figure 42 Example of Setting Instructions for Vertical Smooth Scroll (4-line display (NL1 and NL0 = 11))

### **Line-Cursor Display**

The HD66727 can assign a cursor attribute to an entire line corresponding to the address counter value by setting the LC bit to 1 (Table 35). One of three line-cursor modes can be selected: a black-white inverting blink cursor (B/W=1), an underline cursor (C=1), and a blink cursor (B=1). The blink cycle for a black-white inverting cursor and for a blink cursor is 32 frames. These line-cursors are suitable for highlighting an index and/or marker, and for indicating an item in a menu with a cursor or an underline.

Figures 43 to 45 show three line-cursor examples.

Table 35 Address Counter Value and Line-Cursor

Address Counter Value (AC)	Selected Line for Line-Cursor	
"00"H to "0B"H	Entire 1st line (12 characters)	
"10"H to "1B"H	Entire 2nd line (12 characters)	
"20"H to "2B"H	Entire 3rd line (12 characters)	
"30"H to "3B"H	Entire 4th line (12 characters)	
"40"H to "4B"H	Entire 5th line (12 characters)	

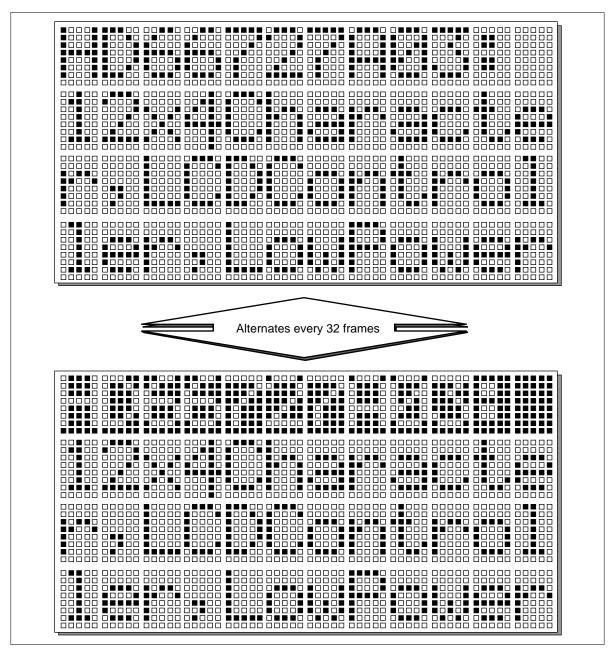


Figure 43 Example of Black-White Inverting Blink Cursor (LC = 1; B/W = 1)

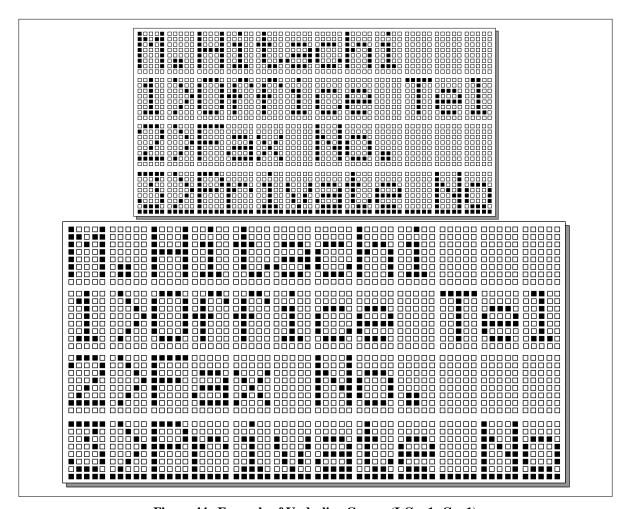


Figure 44 Example of Underline Cursor (LC = 1; C = 1)

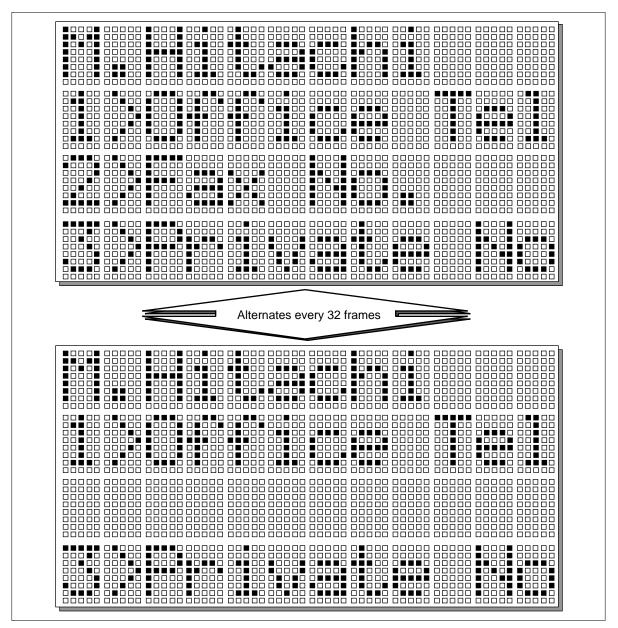


Figure 45 Example of Blink Cursor (LC = 1; B = 1)

#### **Double-Height Display**

The HD66727 can double the height of any desired line from the first to third lines. A line can be selected by the DL3 to DL1 bits as listed in Table 36. All the standard font characters stored in the CGROM and CGRAM can be doubled in height, providing an easy-to-see display. Note that there should be no space between lines for double-height display (Figure 46).

Table 36 Double-Height Display Specifications

DL3	DL2	DL1	2-Line Display (NL1, NL0 = 01)	3-Line Display (NL1, NL0 = 10)	4-Line Display (NL1, NL0 = 11)
0	0	0	1st & 2nd lines: normal	1st to 3rd lines: normal	1st to 4th lines: normal
0	0	1	1st line: double-height	1st line: double-height 2nd line: normal	1st line: double-height 2nd & 3rd lines: normal
0	1	0	Disabled	2nd line: double-height 1st line: normal	2nd line: double-height 1st & 3rd lines: normal
0	1	1	1st line: double-height	Disabled	1st & 2nd lines: double-height
1	0	0	1st & 2nd lines: normal	Disabled	3rd line: double-height 1st & 2nd lines: normal
1	0	1	1st line: double-height	1st line: double-height 2nd line: normal	Disabled
1	1	0	Disabled	2nd line: double-height 1st line: normal	Disabled
1	1	1	1st line: double-height	Disabled	1st & 2nd lines: double-height

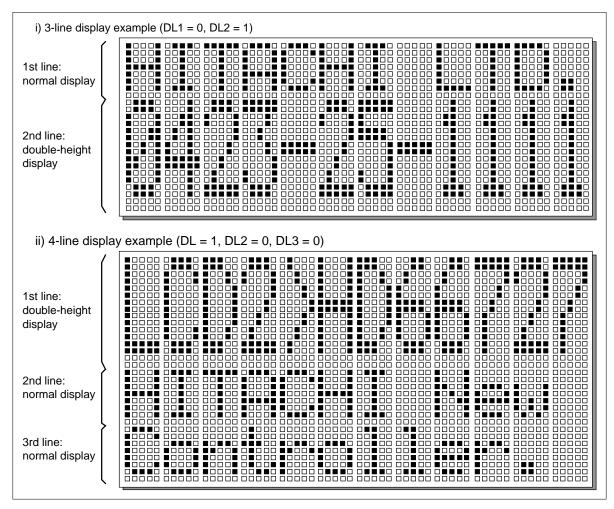
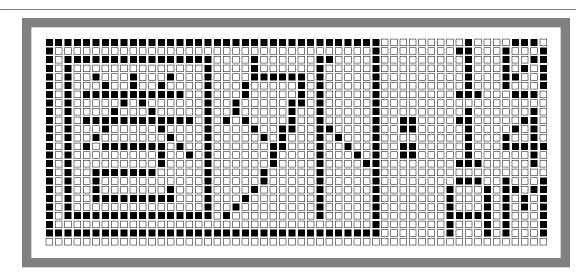


Figure 46 Double-Height Display Examples

### **Double-Width Display**

When the font width bit (FW) is set, the width is 5 dots or 6 dots. When FW = 0, the font width is 5 dots and can be displayed horizontally up to 12 digits. However, the spaces between characters should hold the ITO wiring on the LCD glass. When FW = 1, the font width is 6 dots and can be displayed horizontally up to 10 digits. However, when displaying double-width characters with the font in the CGROM, a special double-width font is needed. In that case, a custom ROM is used.

Double-height characters can be displayed by setting the register in combination with the above double-width display.



Note: This display can be performed with the custom CGROM.

Figure 47 Triple-Width Display Examples

### **LED/Back Light Control**

The HD66727 has three LED ports to control the LED and back light, which need current driving, and three general ports, which do not need current driving. However, the sink current in the LED port output is up to 3 mA. If the back light or LED needs more current, increase the current width with the transistor.

Table 37 LED Driving and General Output Port

AAN	l Addr	ess		LED Driving/General Output Port									
MSE	3		LSB Bit 7 Bit 6 Bit 5 Bit				Bit 4	Bit 3	Bit 2	Bit 1	Bit 0		
0	0	1	1	*	*	PORT2	PORT1	PORT0	LED2	LED1	LED0		

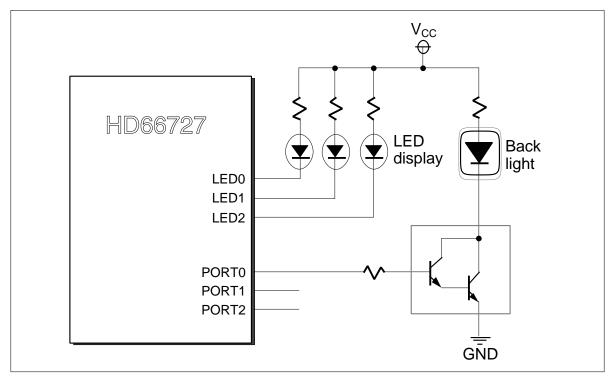


Figure 48 LED Driving Control Circuit Examples

### **Partial-Display-Off Function**

The HD66727 can program the number of display lines (NL bits), divide the internal operating frequency by four (OSC bit), and adjust the display contrast (CT bits). Combining these functions, the HD66727 can turn off the second and/or subsequent lines, displaying only the characters in the first line to reduce internal current consumption (partial-display-off function). This function is suitable for calendar or time display, which needs to be continuous during system standby with minimal current consumption. Here, the second to fourth non-displayed lines are constantly driven by the deselection level voltage, thus turning off the LCD for the lines.

Note that internal clock frequency is reduced to a quarter, quadrupling execution time of each instruction; MPU data transfer rate must be appropriately adjusted. Moreover, as being affected by the NL1 bit and the OSC1 bit, the key-scan cycle for partial-display-off is not the same as that for normal display. Adjust the key-scan cycle by the KF1 and KF0 bits.

Table 38 lists partial-display-off function specifications and Figure 49 shows a sample display using the partial-display-off function

Table 38 Partial-Display-Off Function

Function Item	Normal 4-Line Display	Partially-Off Display
Character display	1st to 4th lines displayed	Only 1st line displayed
Segment display	Possible	Possible
Annunciator display	Possible	Possible
R-C oscillation frequency	160 kHz	160 kHz
Internal operating frequency	160 kHz (OSC = 0)	40 kHz (OSC = 1)
LCD single-line drive frequency	2.7 kHz (1/34 duty ratio)	0.7 kHz (1/10 duty ratio)
Frame frequency	78 Hz	66 Hz
Key scan cycle	320 to 2,560 clock cycles (Clock cycle = 1 / internal operating frequency)	160 to 1,280 clock cycles (Clock cycle = 1 / internal operating frequency)

Note: Select an optimum LCD drive voltage (between  $V_{CC}$  and V5) for the multiplexing duty ratio used, using a reference voltage input pin (Vci) for the booster or the contrast adjust bits (CT).

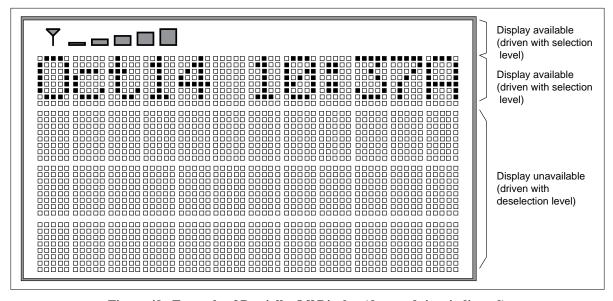


Figure 49 Example of Partially-Off Display (date and time indicated)

#### **Sleep Mode**

Setting the sleep mode bit (SLP) to 1 puts the HD66727 in the sleep mode, where the device halts all the internal display operations except for annunciator display and key scan operations, thus reducing current consumption. Specifically, character and segment displays, which are controlled by the multiplexing drive method, are completely halted. Here, all the SEG (SEG1 to SEG60) and COM (COM1 to COM34) pins output the  $V_{\rm CC}$  level, resulting in no display. If the AMP bit is set to 0 in the sleep mode, the LCD drive power supply can be turned off, reducing the total current consumption of the LCD module.

Annunciators can be normally displayed in the sleep mode. Since they are driven at logic operating power supply voltage ( $V_{CC}$  – AGND), they are available even if the LCD power supply is turned off (AMP = 0). This function allows time and alarm marker indication during system standby with reduced current consumption.

During the sleep mode, no instructions can be accepted for character/segment display and neither DDRAM, CGRAM, nor SEGRAM can be accessed.

The key scan circuit operates normally in the sleep mode, thus allowing normal key scan and key scan interrupt generation. All keys can be scanned while only displaying annunciators. For details, refer to the Key Scan Control section.

Table 38 compares the functions of the sleep mode and standby mode.

Table 38 Comparison of Sleep Mode and Standby Mode

Function	Sleep Mode (SLP = 1)	Standby Mode (STB = 1)
Character display	Turned off	Turned off
Segment display	Turned off	Turned off
Annunciator display	Can be turned on	Can be turned on when an alternating signal is supplied to the EXM pin
R-C oscillation	Operates normally	Halted
Key scan	Can operate normally	Halted but IRQ* can be generated

#### **Standby Mode**

Setting the standby mode bit (STB) to 1 puts the HD66727 in the standby mode, where the device stops completely, halting all internal operations including the R-C oscillator, thus further reducing current consumption compared to that in the sleep mode. Specifically, character and segment displays, which are controlled by the multiplexing drive method, are completely halted. Here, all the SEG (SEG1 to SEG60) and COM (COM1 to COM34) pins output the  $V_{\rm CC}$  level, resulting in no display. If the AMP bit is set to 0 in the standby mode, the LCD drive power supply can be turned off.

Annunciators can be displayed simply by supplying an approximately 40-Hz alternating signal for the LCD drive signals to the EXM pin externally. If annunciator display is unnecessary during the standby mode, the EXM pin must be fixed to the  $V_{CC}$  or GND level and the annunciator display on bit (DA) set to 0.

During the standby mode, no instructions can be accepted other than those for annunciator display, the start-oscillator instruction, and the key scan interrupt generation enable instruction. To cancel the standby mode, issue the start oscillator instruction to stabilize R-C oscillation before setting the STB bit to 0.

Although key scan is halted in the standby mode, the HD66727 can detect four key inputs connected with strobe signal KST0, thus generating the key scan interrupt (IRQ\*). This means, the system can be activated from the completely inactive state. For details, refer to the Key Scan Control section.

Figure 50 shows the procedure for setting and canceling the standby mode.

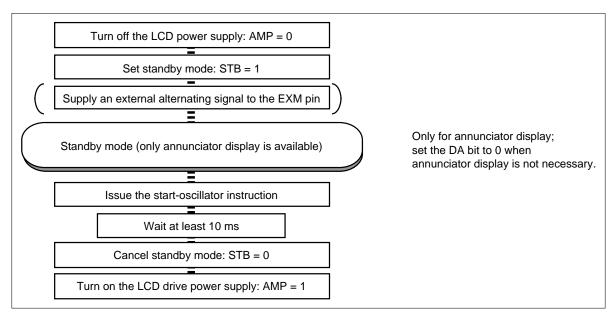


Figure 50 Procedure for Setting and Canceling Standby Mode

# **Absolute Maximum Ratings \***

Item	Symbol	Unit	Value	Notes**	
Power supply voltage (1)	V <sub>cc</sub>	V	-0.3 to +7.0	1	
Power supply voltage (2)	$V_{\rm CC} - V_{\rm EE}$	V	-0.3 to +15.0	1, 2	
Input voltage	Vt	V	$-0.3$ to $V_{cc}$ + 0.3	1	
Operating temperature	Topr	°C	-20 to +75		
Storage temperature	Tstg	°C	-40 to +125	4	

Note: \* If the LSI is used above these absolute maximum ratings, it may become permanently damaged.

Using the LSI within the following electrical characteristic limits is strongly recommended for normal operation. If these electrical characteristic conditions are also exceeded, the LSI will malfunction and cause poor reliability.

DC Characteristics (V  $_{\rm CC}$  = 2.4 to 5.5V, Ta = –20 to +75°C\*  $^3$ )

Item	Symbol	Min	Тур	Max	Unit	Test Condition	Notes
Input high voltage	VIH	0.7V <sub>cc</sub>	_	$V_{cc}$	V		6
Input low voltage	VIL	-0.3	_	0.15V <sub>cc</sub>	, V	$V_{CC} = 2.4 \text{ to } 3.0 \text{V}$	6
Input low voltage	VIL	-0.3	_	0.6	V	$V_{CC} = 3.0 \text{ to } 5.5 \text{V}$	6
Output high voltage (1) (SDA pin)	VOH1	0.75V <sub>cc</sub>	_	_	V	$I_{OH} = -0.1 \text{ mA}$	7
Output low voltage (1) (SDA pin)	VOL1	_	_	0.2V <sub>cc</sub>	V	$V_{CC} = 2.4 \text{ to } 4.5 \text{V},$ $I_{OL} = 0.4 \text{ mA}$	
Output low voltage (1) (SDA pin)	V OL1	_	_	0.4	V	$V_{CC} = 4.5 \text{ to } 5.5 \text{V},$ $I_{OL} = 1.0 \text{ mA}$	
Output high voltage (2) (KST0-7, IRQ* pins)	VOH2	0.7V <sub>cc</sub>	_	_	V	$-I_{OH} = 0.5 \mu A,$ $V_{CC} = 3V$	
Output low voltage (2) (KST0-7, IRQ* pins)	VOL2	_	_	0.2V <sub>cc</sub>	V	I <sub>OL</sub> = 0.1 mA	
Driver ON resistance (COM pins)	R <sub>COM</sub>	_	2	20	kΩ	$\pm Id = 0.05 \text{ mA},$ VLCD = 4V	8
Driver ON resistance (SEG pins)	$R_{\text{SEG}}$	_	2	30	kΩ	$\pm Id = 0.05 \text{ mA},$ VLCD = 4V	8
I/O leakage current	I <sub>Li</sub>	-1	_	1	μΑ	Vin = 0 to V <sub>CC</sub>	9
Pull-up MOS current 1 (KIN0-3 pins)	-lp1	1	10	40	μΑ	$V_{CC} = 3V$ , $Vin = 0V$	
Pull-up MOS current 2 (RESET* pins)	-lp2	5	50	120	μΑ	V <sub>CC</sub> = 3V, Vin = 0V	
Current consumption during normal operation (V <sub>cc</sub> –GND)	I <sub>OP</sub>	_	30	60	μΑ	R-C oscillation, $V_{cc} = 3V$ , $f_{osc} = 160$ kHz (1/34  duty)	10, 11
Current consumption during sleep mode (V <sub>cc</sub> –GND)	I <sub>SL</sub>	_	25	_	μΑ	R-C oscillation, $V_{cc} = 3V$ , $f_{osc} = 160$ kHz (1/34  duty)	10, 11
Current consumption during standby mode (V <sub>cc</sub> –GND)	I <sub>ST</sub>	_	0.1	5	μΑ	No R <sub>f</sub> oscillation, $V_{CC} = 3V$ , $Ta = 25$ °C	10, 11
LCD drive power supply current (V <sub>CC</sub> -V <sub>EE</sub> )	I <sub>EE</sub>	_	25	60	μΑ	$V_{CC} - V_{EE} = 7V,$ $f_{OSC} = 160 \text{ kHz}$	11
LCD drive voltage with 1/4 bias (V <sub>CC</sub> -V <sub>EE</sub> )	VLCD1	3.0	_	13.0	V	V2–V3 short-circuited	12
LCD voltage with 1/6 bias (V <sub>cc</sub> –V <sub>EE</sub> )	VLCD2	3.0		13.0	V	V2-V3 open	12

Note: For the numbered notes, refer to the Electrical Characteristics Notes section following these tables.

### **Booster Characteristics**

Item	Symbol	Min	Тур	Max	Unit	Test Condition	Notes
Output voltage (V5OUT2 pin)	VUP2	8.0	8.8	_	V	$V_{CC} = Vci = 4.5V,$ $I_{O} = 0.1 \text{ mA, C} = 1 \mu\text{F,}$ $f_{OSC} = 160 \text{ kHz, Ta} = 25^{\circ}\text{C}$	15
Output voltage (V5OUT3 pin)	VUP3	7.0	7.9	_	V	$V_{CC} = Vci = 2.7V,$ $I_{O} = 0.1 \text{ mA, C} = 1 \mu\text{F,}$ $f_{OSC} = 160 \text{ kHz, Ta} = 25^{\circ}\text{C}$	15
Input voltage	VCi	1.0	_	5.0	V	Vci ≤ V <sub>cc</sub>	15

Note: For the numbered notes, refer to the Electrical Characteristics Notes section following these tables.

# AC Characteristics (V $_{\rm CC}$ = 2.4 to 5.5V, Ta = –20 to +75°C\* $^3$ )

### **Clock Characteristics**

Item	Symbol	Min	Тур	Max	Unit	<b>Test Condition</b>	Notes
External clock frequency	f <sub>cp</sub>	20	160	350	kHz		13
External clock duty ratio	Duty	45	50	55	%		13
External clock rise time	t <sub>rcp</sub>	_	_	0.2	μs		13
External clock fall time	t <sub>fcp</sub>	_	_	0.2	μs		13
Internal Rf oscillation frequency	t <sub>osc</sub>	120	160	200	kHz	$R_f = 150 \text{ k}\Omega,$ $V_{CC} = 3V$	14

Note: For the numbered notes, refer to the Electrical Characteristics Notes section following these tables.

### **Clock-Synchronized Serial Interface Timing**

Item	Symbol	Min	Тур	Max	Unit	<b>Test Condition</b>
Serial clock cycle time	t <sub>scyc</sub>	1	_	20	μs	Figures 57 and 58
Serial clock high-level width	t <sub>sch</sub>	400	_	_	ns	Figures 57 and 58
Serial clock low-level width	t <sub>SCL</sub>	400	_	_	ns	Figures 57 and 58
Serial clock rise/fall time	$t_{scr}, t_{scf}$	_	_	50	ns	Figures 57 and 58
Chip select set-up time	t <sub>CSU</sub>	60	_	_	ns	Figures 57 and 58
Chip select hold time	t <sub>CH</sub>	200	_	_	ns	Figures 57 and 58
Serial input data set-up time	t <sub>SISU</sub>	200	_	_	ns	Figure 57
Serial input data hold time	t <sub>SIH</sub>	200	_	_	ns	Figure 57
Serial output data delay time	t <sub>SOD</sub>	_	_	400	ns	Figure 58
Serial output data hold time	t <sub>soh</sub>	0	_	_	ns	Figure 59

# I<sup>2</sup>C bus Interface Timing

Item	Symbol	Min	Тур	Max	Unit	Test Condition
SCL clock cycle time	t <sub>scl</sub>	2	_	20	μs	Figure 59
SCL clock high-level width	t <sub>sclh</sub>	500	_	_	ns	Figure 59
SCL clock low-level width	t <sub>SCLL</sub>	1000	_	_	ns	Figure 59
SCL/SDA rise/fall time	$t_{sr}$ , $t_{sf}$	_	_	300	ns	Figure 59
Bus free time	t <sub>BUF</sub>	100	_	_	ns	Figure 59
Start hold time	t <sub>STAH</sub>	500	_	_	ns	Figure 59
Retransmit start set-up time	t <sub>STAS</sub>	500	_	_	ns	Figure 59
Stop set-up time	t <sub>stos</sub>	500	_	_	ns	Figure 59
SDA data set-up time	t <sub>SDAS</sub>	140	_	_	ns	V <sub>cc</sub> =2.4V-4.5V
SDA data set-up time	t <sub>SDAS</sub>	100	_	_	ns	V <sub>cc</sub> =4.5V–5.5V
SDA data hold time	t <sub>SDAH</sub>	0	_	_	ns	Figure 59

# **Reset Timing**

Item	Symbol	Min	Тур	Max	Unit	Test Condition
Reset low-level width	t <sub>RES</sub>	10	_	_	ms	Figure 60

#### **Electrical Characteristics Notes**

- All voltage values are referred to GND = 0V. If the LSI is used above the absolute maximum ratings, it
  may become permanently damaged. Using the LSI within the given electrical characteristic is strongly
  recommended to ensure normal operation. If these electrical characteristic are exceeded, the LSI may
  malfunction or exhibit poor reliability.
- 2.  $V_{CC} > V1 \ge V2 \ge V3 \ge V4 \ge V5 > V_{EE}$  must be maintained.
- 3. For bare die products, specified up to 75°C.
- 4. For bare die products, specified by the common die shipment specification.
- 5. The following four circuits are I/O pin configurations except for liquid crystal display output (Figure 51).

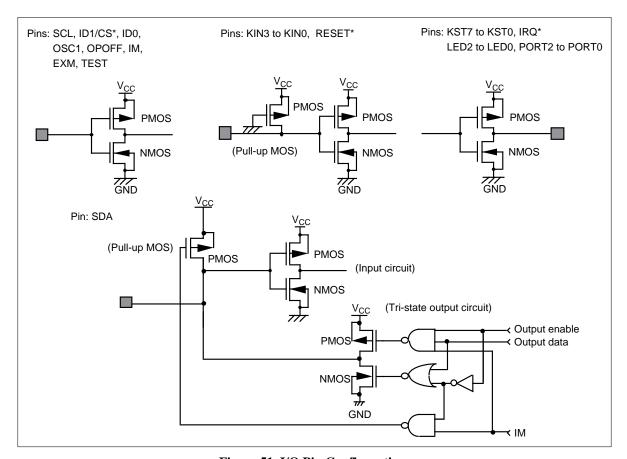


Figure 51 I/O Pin Configurations

- 6. The TEST pin must be grounded and the ID1 and ID0, IM, EXM, and OPOFF pins must be grounded or connected to  $V_{\rm CC}$ .
- 7. Corresponds to the high output for clock-synchronized serial interface.
- 8. Applies to resistor values (R<sub>COM</sub>) between power supply pins V<sub>CC</sub>, V1OUT, V4OUT, V5OUT and common signal pins (COM1 to COM32, COMS1, and COMS2), and resistor values (R<sub>SEG</sub>) between power supply pins V<sub>CC</sub>, V2OUT, V3OUT, V5OUT and segment signal pins (SEG1 to SEG60).
- 9. This excludes the current flowing through pull-up MOSs and output drive MOSs.

- 10. This excludes the current flowing through the input/output units. The input level must be fixed high or low because through current increases if the CMOS input is left floating.
- 11. The following shows the relationship between the operation frequency ( $f_{OSC}$ ) and current consumption ( $I_{CC}$ ) (Figure 52).

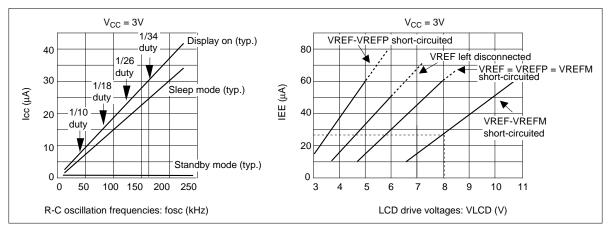


Figure 52 Relationship between the Operation Frequency and Current Consumption

- 12. Each COM and SEG output voltage is within ±0.15V of the LCD voltage (V<sub>CC</sub>, V1, V2, V3, V4, V5) when there is no load.
- 13. Applies to the external clock input (Figure 53).

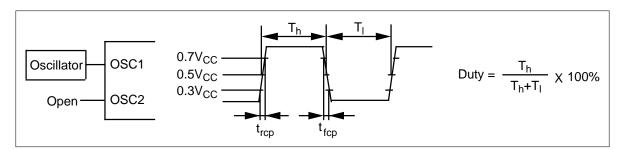


Figure 53 External Clock Supply

14. Applies to the internal oscillator operations using oscillation resistor Rf (Figure 54).

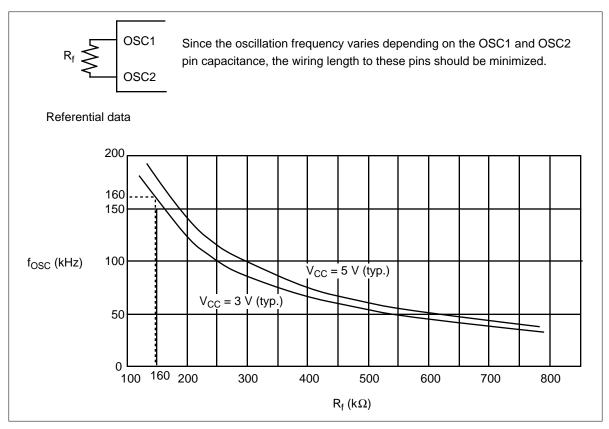


Figure 54 Internal Oscillation

15. Booster characteristics test circuits are shown in Figure 55.

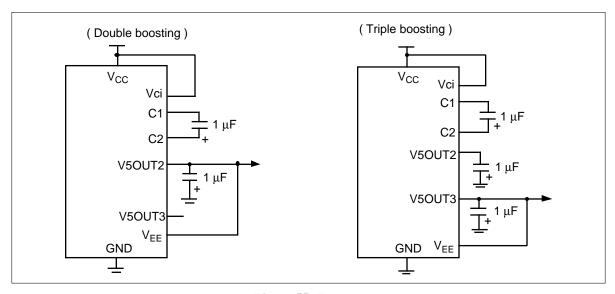
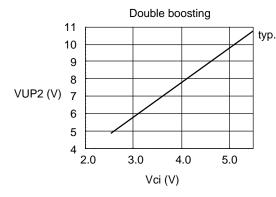


Figure 55 Booster

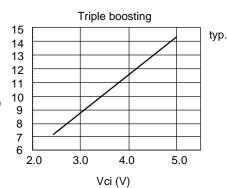
#### Referential data

$$VUP2 = V_{CC} - V5OUT2$$
;  $VUP3 = V_{CC} - V5OUT3$ 

(i) Relation between the obtained voltage and input voltage



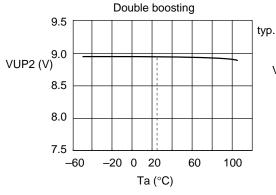
VUP3 (V)

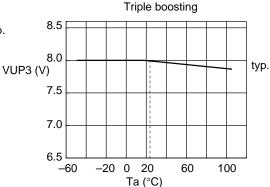


 $Vci = V_{CC}$ , fcp =160 kHz, Ta = 25°C

$$Vci = V_{CC}$$
, fcp =160 kHz,  $Ta = 25$ °C

(ii) Relation between the obtained voltage and temperature

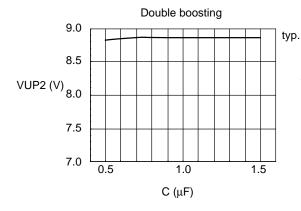




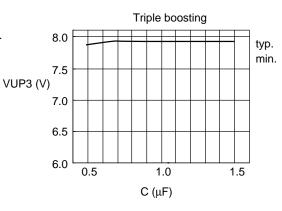
 $Vci = V_{CC} = 4.5 \text{ V}, \text{ Rf} = 180 \text{ k}\Omega, \text{ lo} = 0.1 \text{ mA}$ 

Vci =  $V_{CC}$  = 2.7 V, Rf = 150  $k\Omega,\ lo$  = 0.1 mA

(iii) Relation between the obtained voltage and capacitance

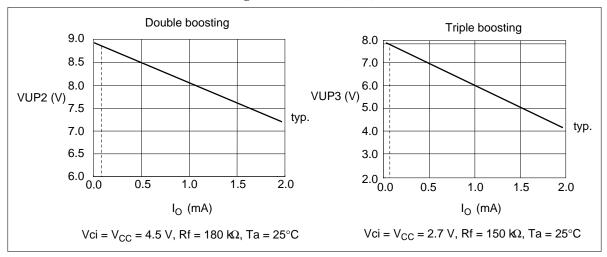


 $Vci=V_{CC}=4.5~V,~Rf=180~k\Omega,~lo=0.1~mA$ 



 $Vci=V_{CC}$  = 2.7 V, Rf = 150 k $\Omega,$  lo = 0.1 mA

Figure 55 Booster (cont)



# **Load Circuits**

#### **AC Characteristics Test Load Circuits**

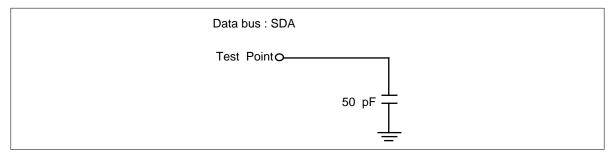


Figure 56 Load Circuit

# **Timing Characteristics**

### **Clock-Synchronized Serial Interface Timing**

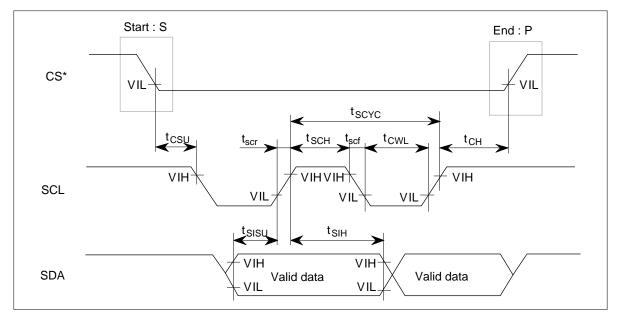


Figure 57 Clock-Synchronized Serial Interface Input Timing

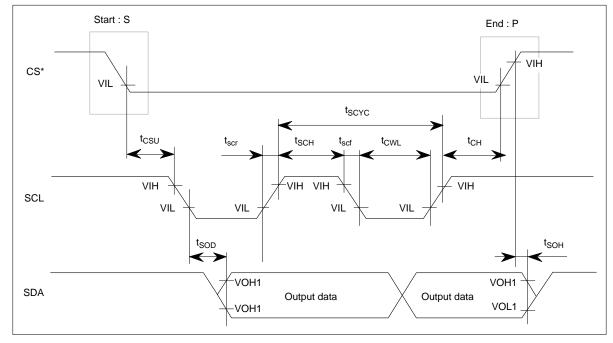


Figure 58 Clock-Synchronized Serial Interface Output Timing

### I<sup>2</sup>C Bus Interface Timing

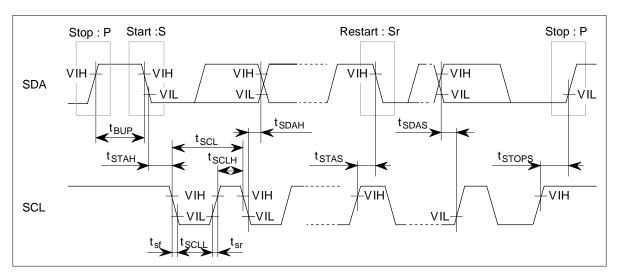


Figure 59 I<sup>2</sup>C Bus Interface Timing

### **Reset Timing**

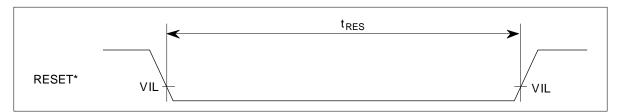


Figure 60 Reset Timing