

# TA2145AFG

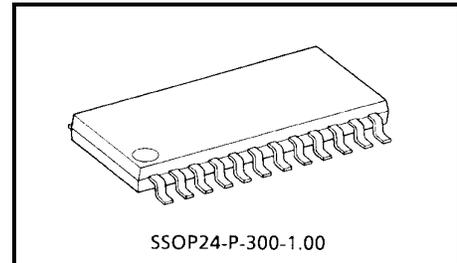
## 3 V Stereo Headphone Amplifier (3 V USE)

The TA2145AFG is developed for play-back stereo headphone equipments (3 V USE).

It is built in dual preamplifiers, dual OCL power amplifiers, motor governor, DC volume control and preamplifier on/off switch etc.

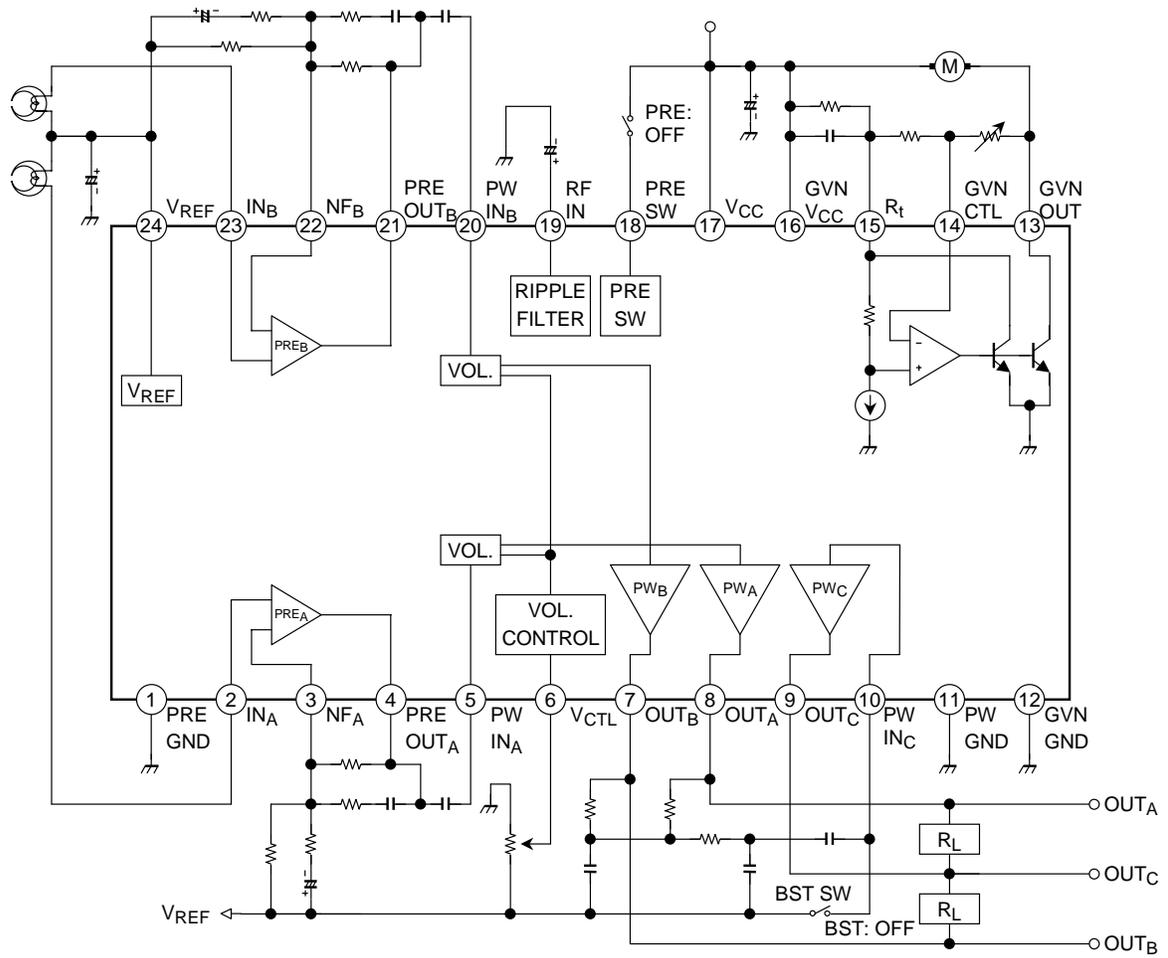
### Features

- Built-in preamplifier
  - Input coupling condenser-less
  - Built-in input capacitor for reducing buzz noise
  - Low noise:  $V_{ni} = 1.2 \mu\text{Vrms}$  (typ.)
  - Preamplifier on/off switch.
- Built-in power amplifier
  - OCL (Output condenser-less)
  - Voltage gain:  $G_V = 31 \text{ dB}$  (typ.)
- Built-in motor governor (Current proportion type)
- Built-in DC volume control function
  - $ATT = 82\text{dB}$  ( $T_a = 25^\circ\text{C}$ , typ.)
- Built-in bass boost function
- Low supply current ( $V_{CC} = 3 \text{ V}$ ,  $f = 1 \text{ kHz}$ ,  $\text{PRE OUT} = 100 \text{ mVrms}$ ,  $T_a = 25^\circ\text{C}$ , typ.)
  - Quiescent supply current
    - PRE + PW:  $I_{CCQ} = 8.5 \text{ mA}$
    - GVN:  $I_{CC} = 2.5 \text{ mA}$
  - $0.1 \text{ mW} \times 2 \text{ ch}$  output
    - $I_{CC1} = 9.8 \text{ mA}$  ( $R_L = 32 \Omega$ )
    - $I_{CC2} = 10.5 \text{ mA}$  ( $R_L = 16 \Omega$ )
  - $0.5 \text{ mW} \times 2 \text{ ch}$  output
    - $I_{CC3} = 14.0 \text{ mA}$  ( $R_L = 32 \Omega$ )
    - $I_{CC4} = 16.5 \text{ mA}$  ( $R_L = 16 \Omega$ )
- Operating supply voltage range ( $T_a = 25^\circ\text{C}$ )
  - $V_{CC(\text{opr})} = 1.8 \sim 3.6 \text{ V}$
  - GVN  $V_{CC(\text{opr})} = 2.1 \sim 3.6 \text{ V}$  (Motor voltage = 1.8 V)



Weight: 0.32 g (typ.)

**Block Diagram**



## Terminal Explanation (Terminal Voltage: Typical terminal voltage at no signal with test circuit, $V_{CC} = 3\text{ V}$ , $T_a = 25^\circ\text{C}$ )

Terminal		Function	Internal Circuit	Terminal Voltage (v)
No.	Name			
1	PRE GND	The GND, except for power drive stage and motor governer stage.	—	0
2	IN <sub>A</sub>	Input of preamplifier		1.2
23	IN <sub>B</sub>			1.2
3	NF <sub>A</sub>			NF of preamplifier
22	NF <sub>B</sub>			
4	PRE OUT <sub>A</sub>	Output of preamplifier		1.2
21	PRE OUT <sub>B</sub>			
7	OUT <sub>B</sub>	Output of power amplifier		1.2
8	OUT <sub>A</sub>			
9	OUT <sub>C</sub>			
5	PW IN <sub>A</sub>	Input of power amplifier		1.2
20	PW IN <sub>B</sub>			
6	V <sub>CTL</sub>	The terminal of DC volume control		—

Terminal		Function	Internal Circuit	Terminal Voltage (v)
No.	Name			
10	PW IN <sub>C</sub>	Input of center amplifier		1.2
11	PW GND	GND for power drive stage	—	0
12	GVN GND	GND for motor governor stage	—	0
13	GVN OUT	Motor terminal		—
14	GVN CTL	The terminal of motor speed control		—
15	R <sub>t</sub>	The terminal of amateur compensation resistor		—
16	GVN V <sub>CC</sub>	V <sub>CC</sub> for motor governor stage		3
17	V <sub>CC</sub>	V <sub>CC</sub> for preamplifier stage and power amplifier stage.	—	3
18	PRE SW	Muting switch of preamplifier [ Preamp. on: "L" level/open Preamp. off: "H" level Refer to application note		—

Terminal		Function	Internal Circuit	Terminal Voltage (v)
No.	Name			
19	RF IN	Ripple filter of power supply		2.5
24	VREF	Reference voltage Preamplifier and power amplifier operate on this reference.		1.2

## Application Note

- VCC and GND
 

This IC has two VCC terminals and three GND terminals. Pattern layout should be designed carefully to reduce the common impedance.

  - VCC
    - VCC (pin 17) ----- Preamplifier stage and power amplifier stage.
    - GVN VCC (pin 16) ----- Motor governor stage.
  - GND
    - PRE GND (pin 1) ----- Preamplifier stage, and power amplifier stage except for the power drive stage.
    - PW GND (pin 11) ----- Power drive stage of power amplifier.
    - GVN GND (pin 12) ----- Motor governor stage.
- VREF
 

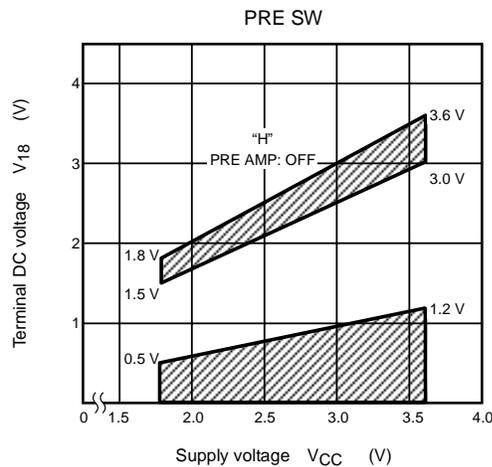
It is necessary to stabilize the VREF circuit, because the internal circuit operate on this reference.
- RF IN
 

As this terminal is an input terminal of the ripple filter, it cannot supply a power supply to other ICs etc.
- Preamplifier
 

Input signal should be applied to VREF standard, otherwise pop noise become bigger when VCC is turned on and off.
- Power amplifier
 

It is necessary to insert the coupling capacitor through the PW IN terminal. In case that DC current or DC voltage is applied to the PW IN terminal, the internal circuit has unbalance and the power amplifier doesn't operate normally.
- Operating supply voltage range of motor governor stage
 

As for the minimum of operating supply voltage range, the motor voltage is 1.8 V.  
In case that it is more than 1.8 V, the low voltage performance becomes bad.
- PRE SW sensitivity (Ta = 25°C)



**Maximum Ratings (Ta = 25°C)**

Characteristic	Symbol	Rating	Unit
Supply voltage	V <sub>CC</sub>	4	V
Power dissipation	P <sub>D</sub>	(Note 1)	400
		(Note 2)	925
Output current (PW AMP.)	I <sub>O</sub> (PW)	200	mA
Output current (GVN)	I <sub>O</sub> (GVN)	700	mA
Operating temperature	T <sub>opr</sub>	-25~75	°C
Storage temperature	T <sub>stg</sub>	-55~150	°C

Note 1: IC only: Derated above Ta = 25°C in the proportion 3.2 mW/°C

Note 2: IC + PCB (TOSHIBA typical PCB): Derated above Ta = 25°C in the proportion 7.4 mW/°C

**Electrical Characteristics**

(Unless otherwise specified,  $V_{CC} = 3\text{ V}$ ,  $T_a = 25^\circ\text{C}$ ,  $f = 1\text{ kHz}$ , SW2: a, SW5: OPEN

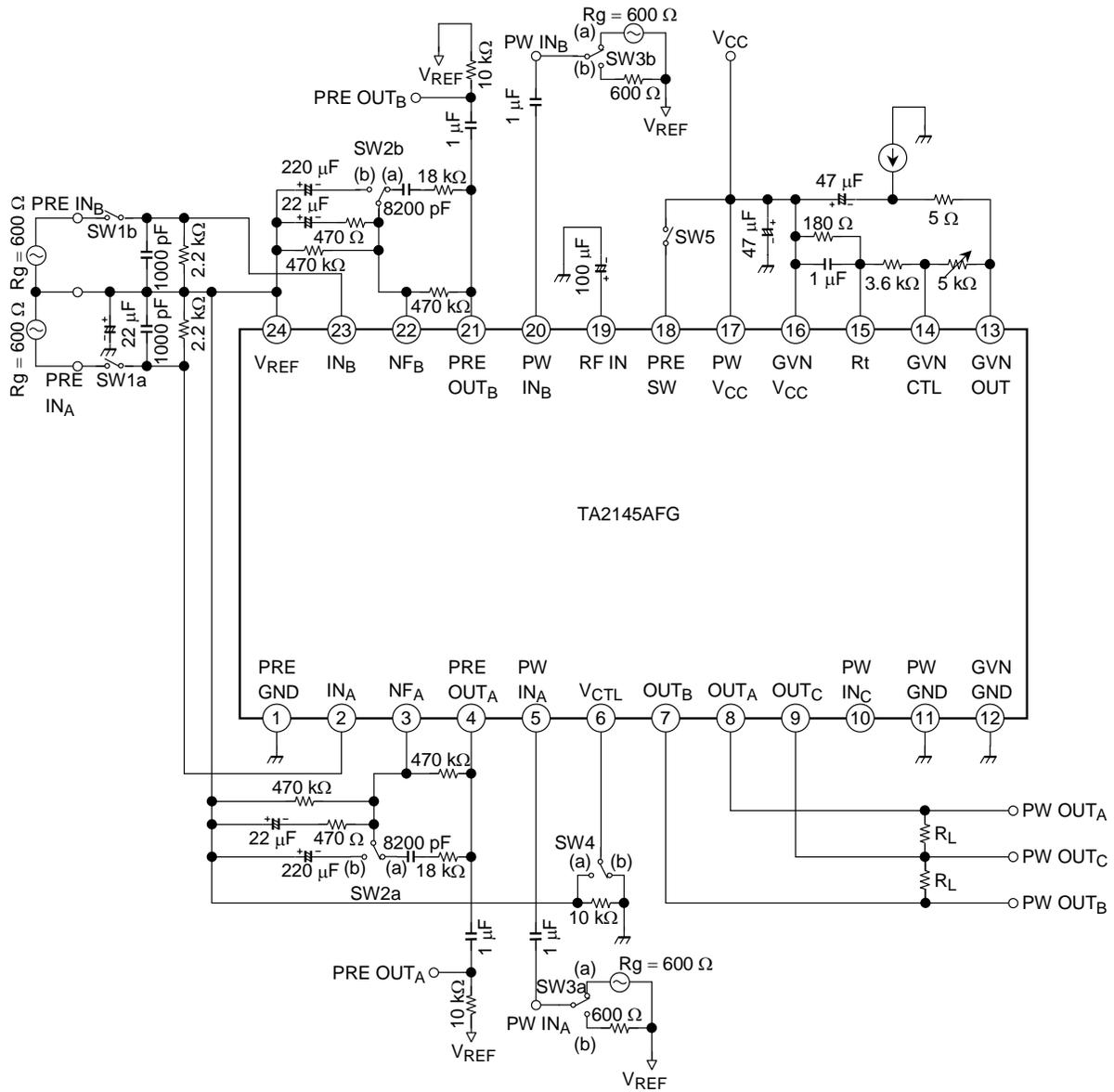
Preamplifier:  $R_g = 2.2\text{ k}\Omega$ ,  $R_L = 10\text{ k}\Omega$ , SW1: ON, SW3: b, SW4: b

Power amplifier:  $R_g = 600\ \Omega$ ,  $R_L = 16\ \Omega$ , Vol.: max, SW1: OPEN, SW3: a, SW4: a

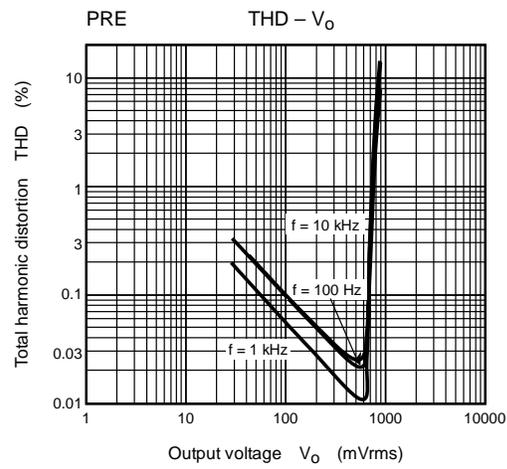
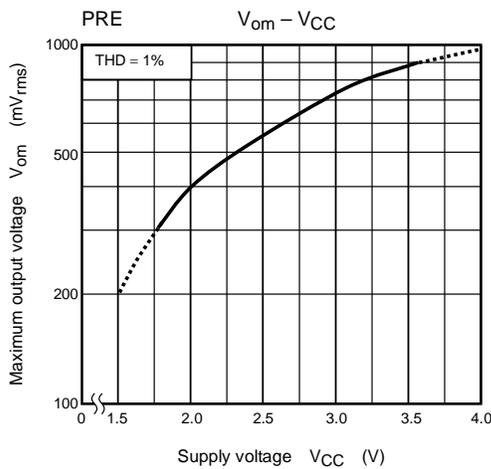
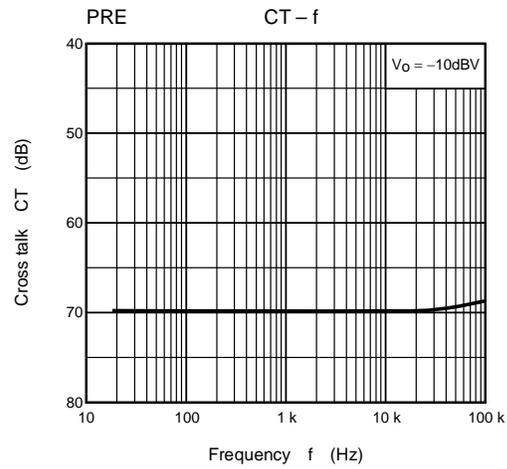
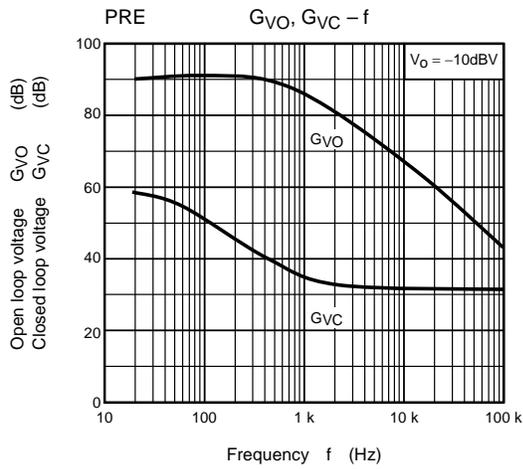
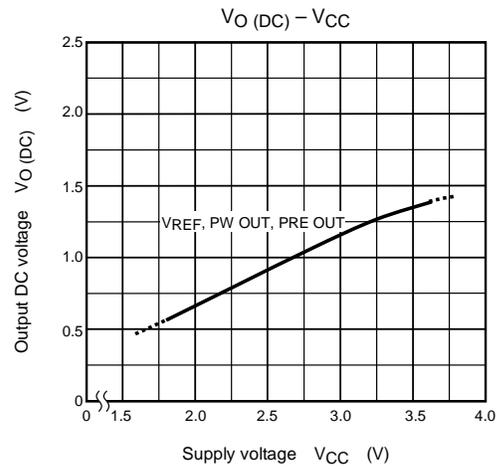
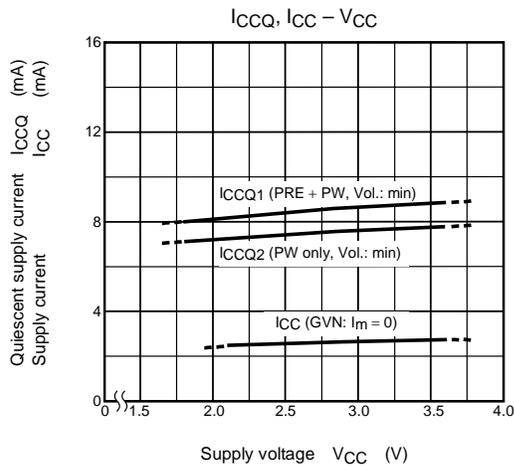
Motor governor:  $I_m = 100\text{ mA}$ , SW1: OPEN, SW3: b, SW4: b)

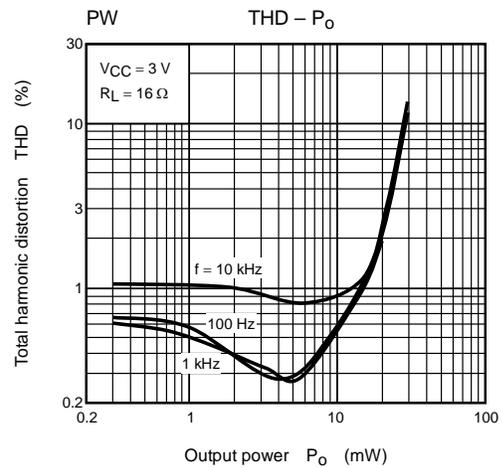
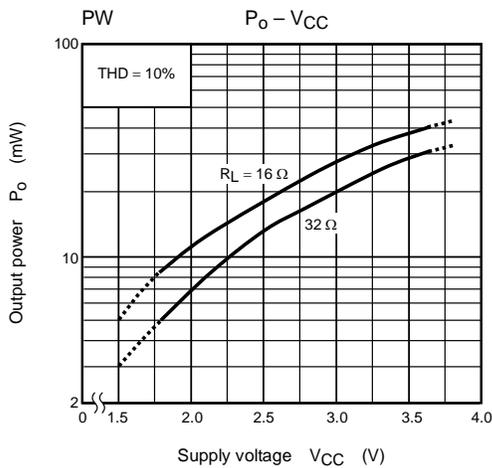
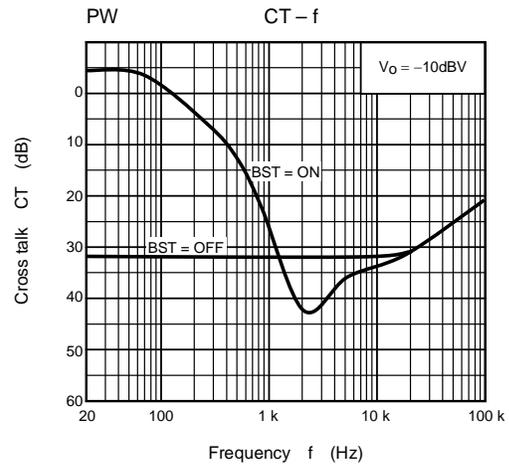
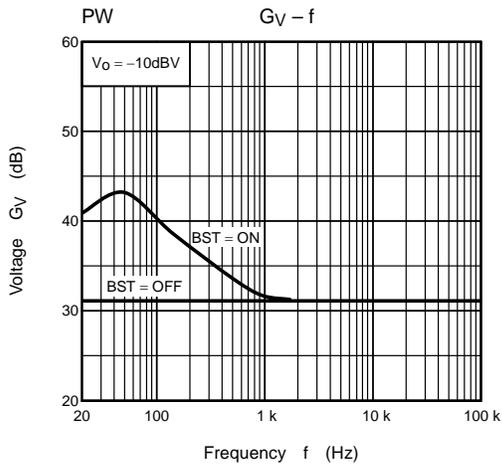
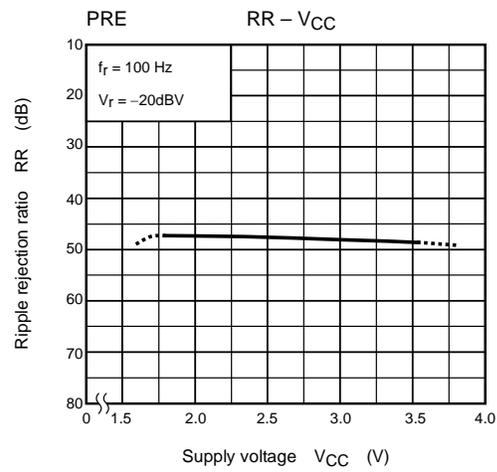
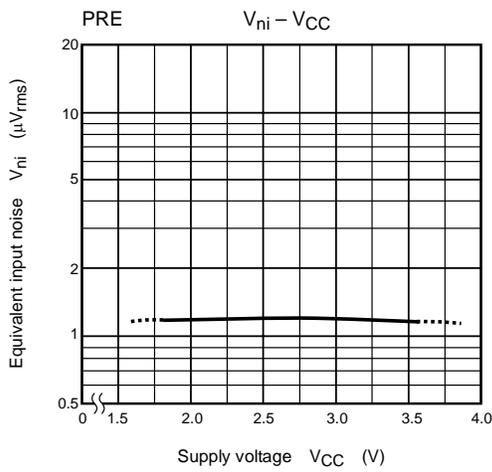
	Characteristic	Symbol	Test circuit	Test condition	Min	Typ.	Max	Unit
	Quiescent supply current	$I_{CCQ1}$	—	Pre off, $V_{in} = 0$ , Vol.: min, SW4: b, SW5: ON	—	7.5	13	mA
		$I_{CCQ2}$	—	$V_{in} = 0$ , Vol.: min, SW4: b	—	8.5	14.5	
Pre amp.	Open loop voltage gain	$G_{VO}$	—	$V_o = -10\text{dBV}$ , SW2: b	—	86	—	dB
	Closed loop voltage gain	$G_{VC}$	—	$V_o = -10\text{dBV}$	—	35	—	dB
	Maximum output voltage	$V_{om}$	—	THD = 1%	550	720	—	mVrms
	Total harmonic distortion	THD1	—	$V_o = -10\text{dBV}$	—	0.02	0.3	%
	Equivalent input noise voltage	$V_{ni}$	—	$R_g = 2.2\text{ k}\Omega$ , SW1: OPEN BPF = 20 Hz~20 kHz, NAB ( $G_V = 35\text{dB}$ , $f = 1\text{ kHz}$ )	—	1.2	2.4	$\mu\text{Vrms}$
	Cross talk	CT1	—	$V_o = -10\text{dBV}$	—	70	—	dB
	Ripple rejection ratio	RR1	—	$f_r = 100\text{ Hz}$ , $V_r = -20\text{dBV}$	—	48	—	dB
	Preamplifier muting attenuation	ATT1	—	$V_o = -10\text{dBV}$ , SW5: OPEN → ON	—	80	—	dB
	Preamplifier on voltage	$V_{18}(\text{ON})$	—	$V_{CC} = 1.8\text{ V}$	0	—	0.5	V
	Preamplifier off voltage	$V_{18}(\text{OFF})$	—		1.5	—	1.8	V
Power amp.	Voltage gain	$G_V$	—	$V_o = -10\text{dBV}$	29	31	33	dB
	Channel balance	CB	—	$V_o = -10\text{dBV}$	-1.5	0	+1.5	dB
	Output power 1	$P_{o1}$	—	$R_L = 16\ \Omega$ , THD = 10%	17	28	—	mW
	Output power 2	$P_{o2}$	—	$R_L = 32\ \Omega$ , THD = 10%	—	20	—	mW
	Total harmonic distortion	THD2	—	$P_o = 1\text{ mW}$	—	0.5	—	%
	Output noise voltage	$V_{no}$	—	$R_g = 600\ \Omega$ , SW3: b BPF = 20 Hz~20 kHz	—	270	400	$\mu\text{Vrms}$
	Ripple rejection ratio	RR2	—	$f_r = 100\text{ Hz}$ , $V_r = -20\text{dBV}$	—	52	—	dB
	Cross talk	CT2	—	$V_o = -10\text{dBV}$	—	32	—	dB
Motor governor	Supply current	$I_{CC}$	—	$I_m = 0$	—	2.5	3.5	mA
	Saturation voltage	$V_{CE}(\text{sat})$	—	$I_m = 200\text{ mA}$	—	—	0.5	V
	Reference voltage	$\Delta V_{REF}$	—	$I_m = 100\text{ mA}$	0.76	0.81	0.86	V
	Reference voltage fluctuation 1	$\Delta V_{REF1}$	—	$V_{CC} = 2.1\text{--}3.6\text{ V}$	—	0.25	—	%/V
	Reference voltage fluctuation 2	$\Delta V_{REF2}$	—	$I_m = 25\text{--}250\text{ mA}$	—	0.003	—	%/mA
	Reference voltage fluctuation 3	$\Delta V_{REF3}$	—	$T_a = -25\text{--}75^\circ\text{C}$	—	0.005	—	%/°C
	Current ratio	K	—	—	34.5	37.5	40.5	
	Current ratio fluctuation 1	$\Delta K1$	—	$V_{CC} = 2.1\text{--}3.6\text{ V}$	—	0.25	—	%/V
	Current ratio fluctuation 2	$\Delta K2$	—	$I_m = 25\text{--}250\text{ mA}$	—	0.08	—	%/mA
	Current ratio fluctuation 3	$\Delta K3$	—	$T_a = -25\text{--}75^\circ\text{C}$	—	0.005	—	%/°C

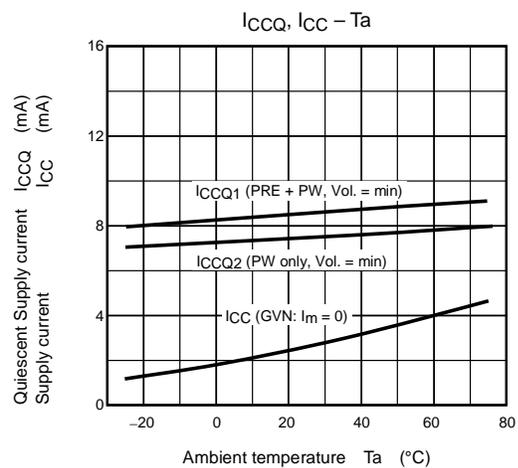
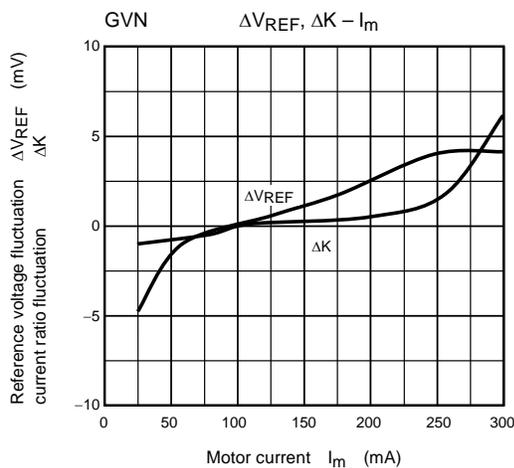
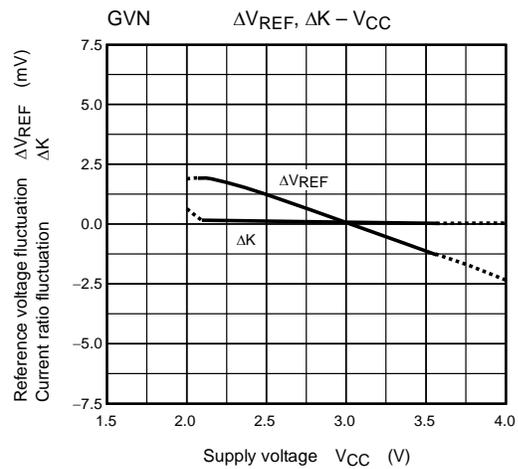
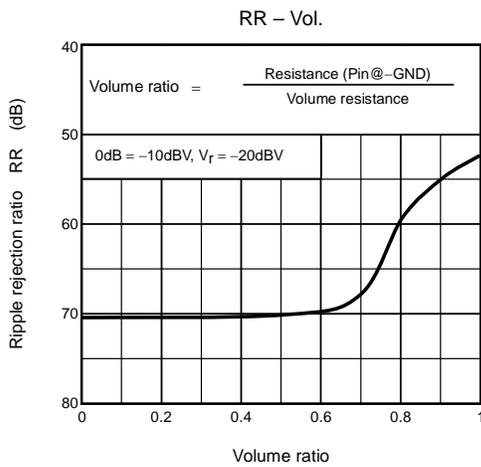
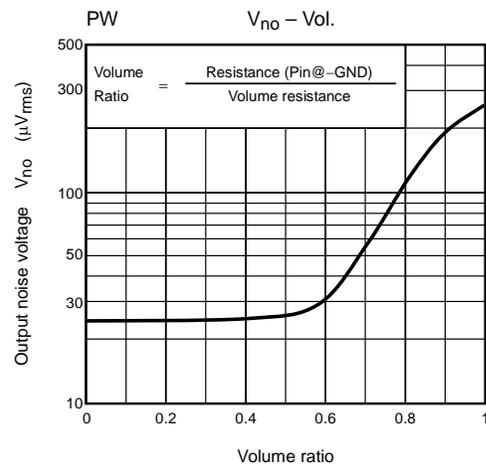
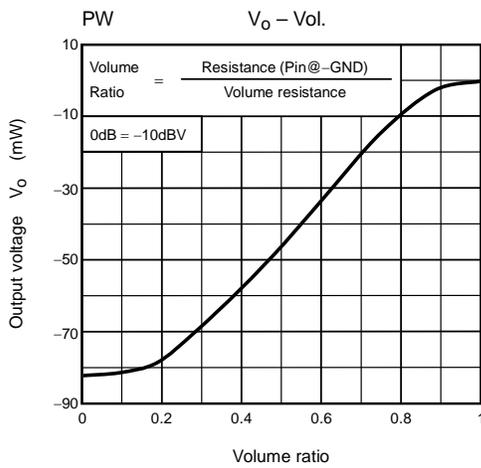
## Test Circuit

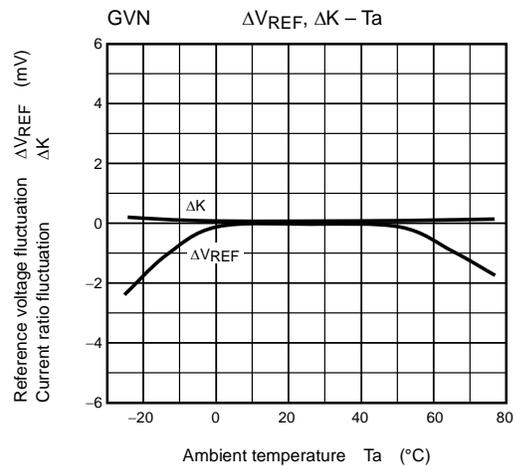
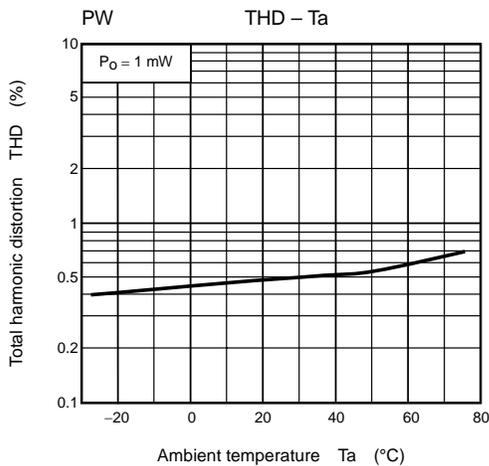
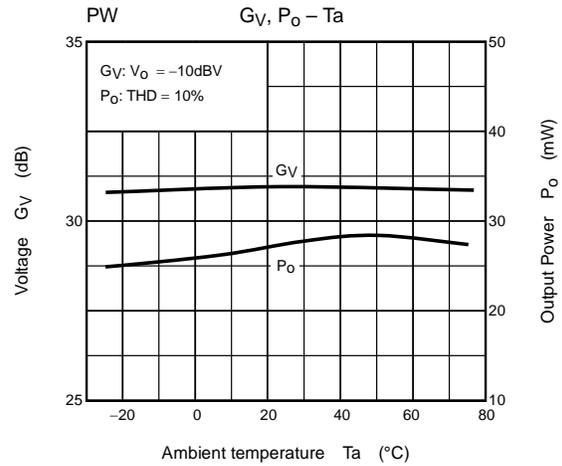
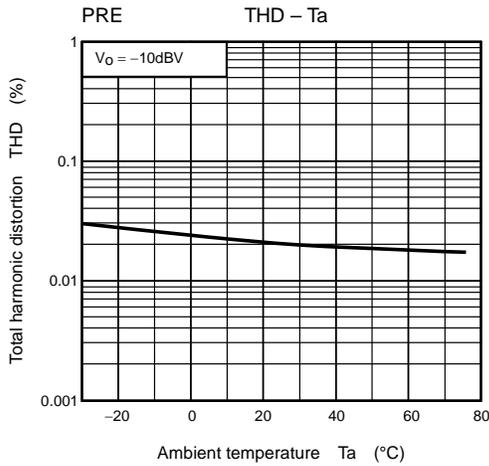
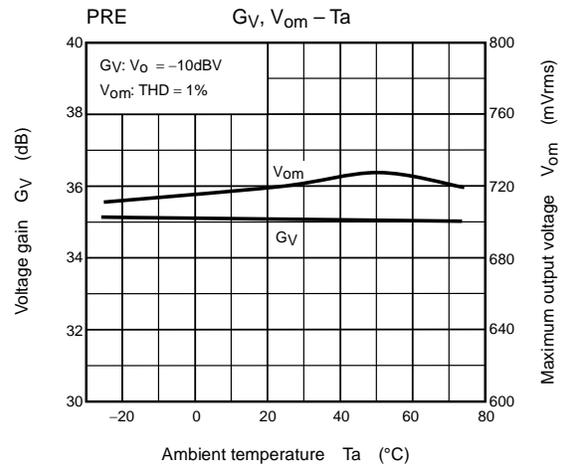
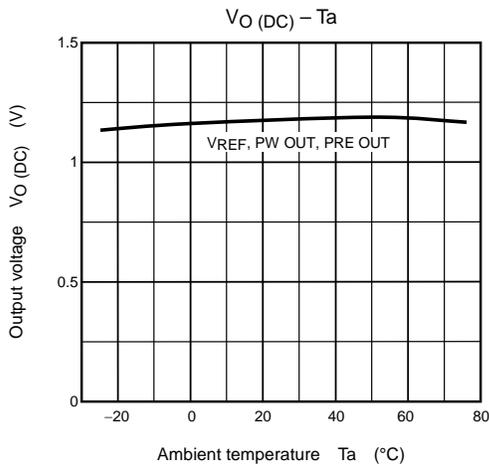


**Characteristic Curves** (Unless otherwise specified,  $V_{CC} = 3\text{ V}$ ,  $T_a = 25^\circ\text{C}$ ,  $f = 1\text{ kHz}$ ,  
**Preamplifier:**  $R_g = 2.2\text{ k}\Omega$ ,  $R_L = 10\text{ k}\Omega$   
**Power amplifier:**  $R_g = 600\ \Omega$ ,  $R_L = 16\ \Omega$ ,  $\text{Vol.} = \text{max}$   
**Motor governor:**  $I_m = 100\text{ mA}$ )

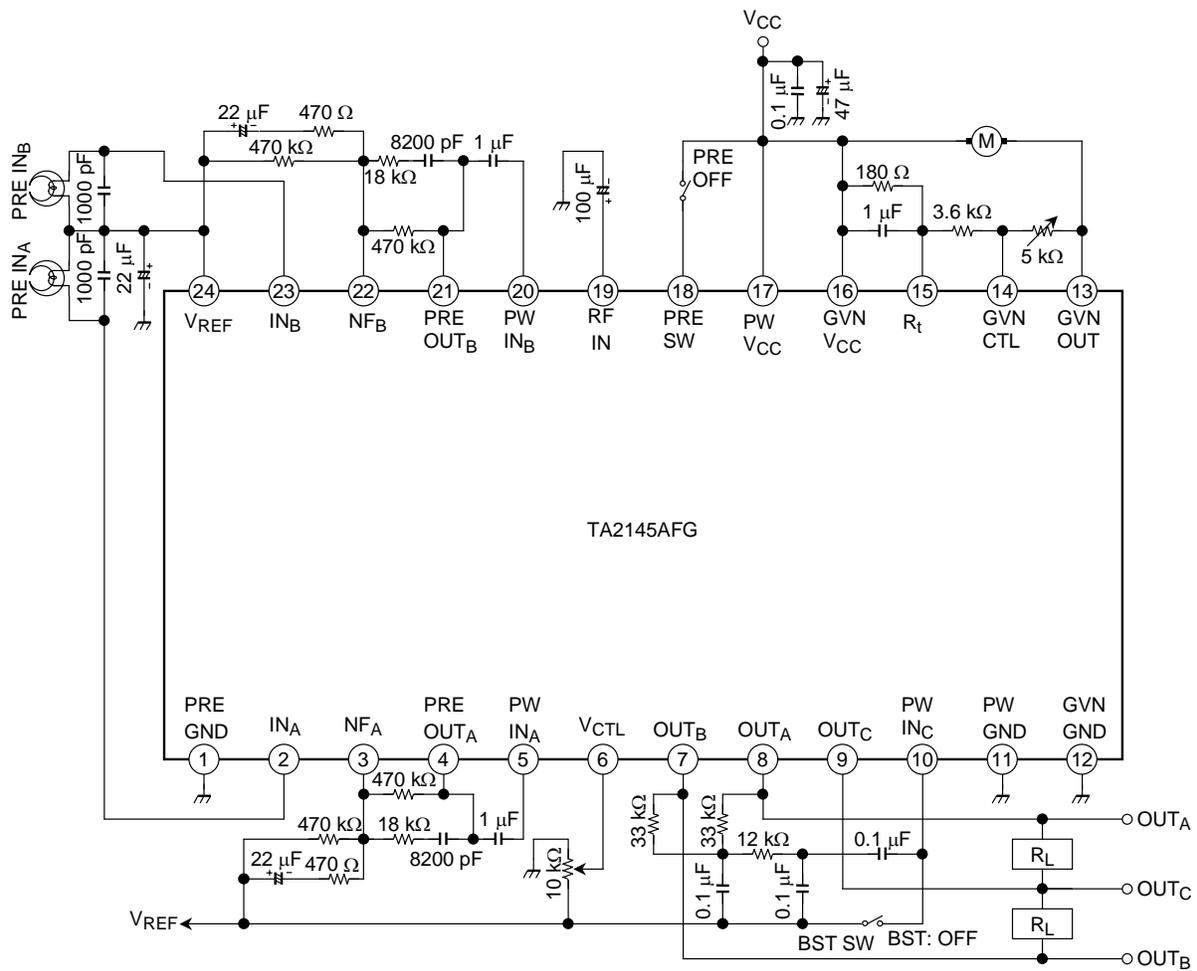








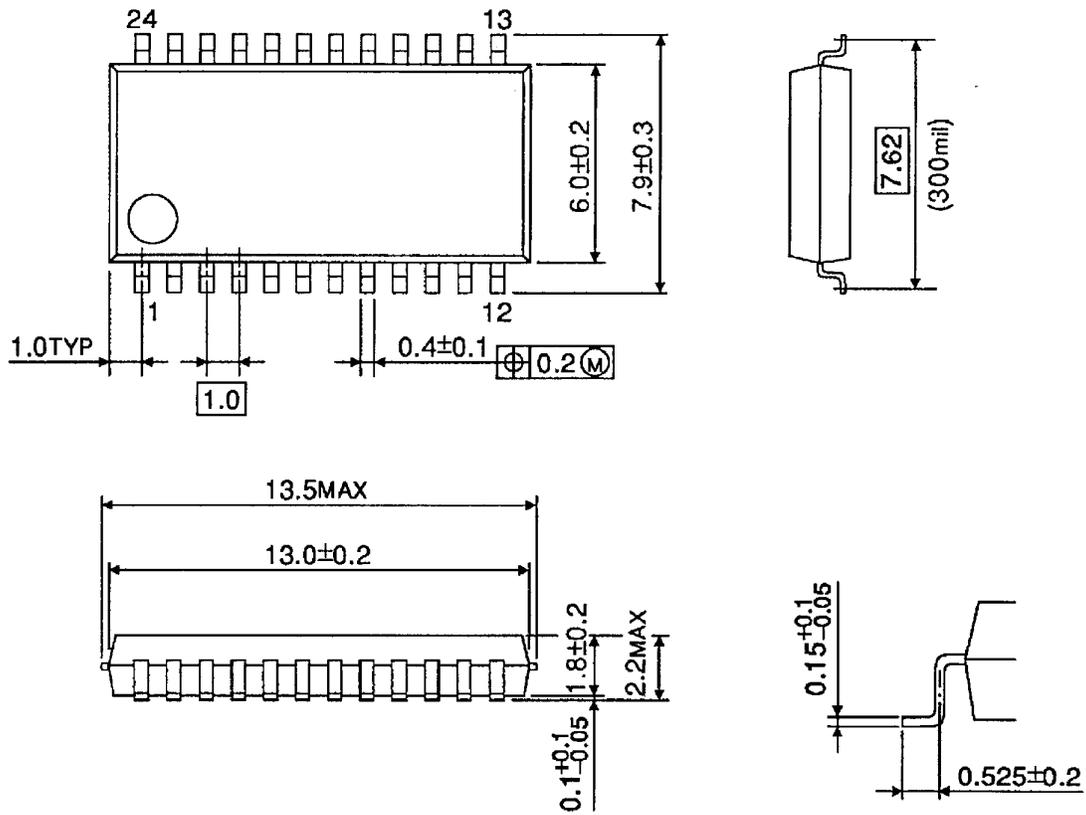
## Application Circuit



## Package Dimensions

SSOP24-P-300-1.00

Unit : mm



Weight: 0.32 g (typ.)

About solderability, following conditions were confirmed

- Solderability
  - (1) Use of Sn-63Pb solder Bath
    - solder bath temperature = 230°C
    - dipping time = 5 seconds
    - the number of times = once
    - use of R-type flux
  - (2) Use of Sn-3.0Ag-0.5Cu solder Bath
    - solder bath temperature = 245°C
    - dipping time = 5 seconds
    - the number of times = once
    - use of R-type flux

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