

# Rail-to-Rail, Very Fast, 2.5 V to 5.5 V, Single-Supply TTL/CMOS Comparator

### **Preliminary Technical Data**

# ADCMP603

#### FEATURES

10 mV sensitivity rail to rail at V<sub>cc</sub> = 2.5 V Input common-mode voltage from -0.2 V to V<sub>cc</sub> + 0.2 V Low glitch CMOS-/TTL-compatible output stage Complementary outputs 3 ns propagation delay 15 mW at 3.3 V Shutdown pin Single-pin control for programmable hysteresis and latch Power supply rejection > 60 dB -40°C to +125°C operation

#### **APPLICATIONS**

High speed instrumentation Clock and data signal restoration Logic level shifting or translation Pulse spectroscopy High speed line receivers Threshold detection Peak and zero-crossing detectors High speed trigger circuitry Pulse-width modulators Current-/voltage-controlled oscillators Automatic test equipment (ATE)

#### **GENERAL DESCRIPTION**

The ADCMP603 is a very fast comparator fabricated on Analog Devices' proprietary XFCB2 process. This comparator is exceptionally versatile and easy to use. Features include an input range from V<sub>EE</sub> – 0.5 V to V<sub>CC</sub> + 0.5 V, low noise complementary TTL-/CMOS-compatible output drivers, and latch inputs with adjustable hysteresis and/or a shutdown input.

The device offers 3 ns propagation delay with 5 mV overdrive on 4 mA typical supply current.

A flexible power supply scheme allows the device to operate with a single +2.5 V positive supply and a -0.5 V to +3.0 V input signal range up to a +5.5 V positive supply with a -0.5 V to +6 V input signal range. Split input/output supplies with no sequencing restrictions support a wide input signal range while

#### FUNCTIONAL BLOCK DIAGRAM



still allowing independent output swing control and power savings.

The complementary TTL-/CMOS-compatible output stage is designed to drive up to 5 pF with full timing specs and to degrade in a graceful and linear fashion as additional capacitance is added. The comparator input stage offers robust protection against large input overdrive, and the outputs do not phase reverse when the valid input signal range is exceeded. High speed latch and programmable hysteresis features are also provided with a unique single-pin control option.

The ADCMP603 is available in a 12-lead LSCFP package.

Rev. PrA

Information furnished by Analog Devices is believed to be accurate and reliable. However, no responsibility is assumed by Analog Devices for its use, nor for any infringements of patents or other rights of third parties that may result from its use. Specifications subject to change without notice. No license is granted by implication or otherwise under any patent or patent rights of Analog Devices. Trademarks and registered trademarks are the property of their respective owners.

# TABLE OF CONTENTS

Features 1
Applications1
Functional Block Diagram1
General Description 1
Revision History
Electrical Characteristics
Absolute Maximum Ratings 5
Thermal Resistance
ESD Caution
Pin Configuration and Function Descriptions
Typical Performance Characteristics7

#### **REVISION HISTORY**

3/06—Revision PrA: Preliminary Version

Application Information9
Power/Ground Layout and Bypassing9
TTL-/CMOS-Compatible Output Stage9
Using/Disabling the Latch Feature9
Optimizing Performance10
Comparator Propagation Delay Dispersion
Comparator Hysteresis 10
Crossover Bias Point 11
Minimum Input Slew Rate Requirement11
Typical Application Circuits 12
Timing Information

# **ELECTRICAL CHARACTERISTICS**

 $V_{\rm CCI}$  =  $V_{\rm CCO}$  = 2.5 V,  $T_{\rm A}$  = 25°C, unless otherwise noted.

#### Table 1.

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
DC INPUT CHARACTERISTICS			1			
Voltage Range	VP, VN	$V_{CC} = 2.5 V$ to 5.5 V	-0.5		$V_{CC} + 0.5 V$	V
Common-Mode Range		$V_{CC} = 2.5 V$ to 5.5 V	-0.2		$V_{CC} + 0.2 V$	V
Differential Voltage		$V_{CC} = 2.5 V \text{ to } 5.5 V$			Vcc	V
Offset Voltage	Vos		-5.0		+5.0	mV
Bias Current	I <sub>P</sub> , I <sub>N</sub>		-5.0	±2	+5.0	μA
Offset Current			2.0		2.0	μΑ
Capacitance	C <sub>P</sub> , C <sub>N</sub>			TBD		рF
Resistance, Differential Mode		0.1 V to V <sub>cc</sub>		100		kΩ
Resistance, Common Mode		-0.5 V to V <sub>CC</sub> + 0.5 V		100		kΩ
Active Gain	Av			85		dB
Common-Mode Rejection	CMRR	$V_{CCI} = 2.5 \text{ V}, V_{CCO} = 2.5 \text{ V}, \\ V_{CM} = -0.2 \text{ V} \text{ to } 2.7 \text{ V}$		50		dB
		$\label{eq:Vccl} \begin{split} V_{\text{CCl}} &= 5.5 \text{ V}, V_{\text{CCO}} = 5.5 \text{ V}, \\ V_{\text{CM}} &= -0.2 \text{ V} \text{ to } 5.7 \text{ V} \end{split}$		60		dB
Hysteresis		$R_{HYS} = \infty$		0.1		mV
LATCH ENABLE PIN CHARACTERISTICS						
VIH		Hysteresis is shut off	2.0		Vcc	v
VIL		Latch mode guaranteed	-0.2	+0.4	+0.8	v
Ін		V <sub>IH</sub> = V <sub>CCV</sub>			0.2	mA
Iol		$V_{IL} = 0.4 V$			-0.2	mA
HYSTERESIS MODE AND TIMING						
Hysteresis Mode Bias Voltage		Current sink 0 µA	1.145	1.25	1.35	v
Minimum Resistor Value		Hysteresis = 16 mV	150			kΩ
Latch Setup Time	ts	$V_{OD} = 100 \text{ mV}$		2		ns
Latch Hold Time	tн	$V_{OD} = 100 \text{ mV}$		5		ns
Latch-to-Output Delay	t <sub>PLOH</sub> , t <sub>PLOL</sub>	$V_{OD} = 100 \text{ mV}$		3		ns
Latch Minimum Pulse Width	t <sub>PL</sub>	$V_{OD} = 100 \text{ mV}$		3		ns
SHUTDOWN PIN CHARACTERISTICS						
ViH		Comparator is operating	2.0		Vcco	v
VIL		Shutdown guaranteed	-0.2	+0.4	+0.6	v
l <sub>in</sub>		V <sub>IH</sub> = V <sub>CC</sub>			0.3	mA
I <sub>OL</sub>		$V_{IL} = 0 V$	1		-0.3	mA
Sleep Time t <sub>SD</sub>		Icc < 300 μA		60		ns
Wake-Up Time	t <sub>H</sub>	$V_{OD} = 10 \text{ mV}$	1	40		ns
DC OUTPUT CHARACTERISTICS		$V_{CCO} = 2.5 \text{ V} \text{ to } 6 \text{ V}$	1			
Output Voltage High Level	V <sub>OH</sub>	I <sub>он</sub> = 12 mA V <sub>ссо</sub> = 2.5 V	Vcc - 0.4			v
Output Voltage Low Level	Vol	$I_{OL} = 12 \text{ mA}, V_{CCO} = 2.5 \text{ V}$			0.4	v

**Preliminary Technical Data** 

Parameter	Symbol	Conditions	Min	Тур	Max	Unit
AC PERFORMANCE						
Propagation Delay	t <sub>PD</sub>	$V_{CCO} = 2.5 \text{ V}$ to 5.5 V, $V_{OD} = 5 \text{ mV}$		3		ns
		$V_{CCO} = 2.5 V \text{ to } 5.5 V,$ $V_{OD} = 200 \text{ mV}$		2.5		ns
Propagation Delay Skew—Rising to Falling Transition		$V_{OD} = 5 \text{ mV}$		200		ps
Overdrive Dispersion		$10 \text{ mV} < V_{\text{OD}} < 2.5 \text{ V}$		TBD		ps
Slew Rate Dispersion		0.05 V/ns to 2.5 V/ns		TBD		ps
Pulse-Width Dispersion		3 ns to 20 ns		TBD		ps
10% to 90% Duty Cycle Dispersion		$1 \text{ V/ns}, \text{V}_{CM} = 2.5 \text{ V}$		TBD		ps
Common-Mode Dispersion		$0 < V_{CM} < V_{CC}$		TBD		ps
Toggle Rate		>50% output swing		TBD		Mbp
Deterministic Jitter TTL/CMOS Outputs	LD	$V_{OD} = 200 \text{ mV}, 5 \text{ V/ns},$ $P_{RBS}^{31} - 1 \text{ NRZ}, 0.25 \text{ Gbps}$		TBD		ns
RMS Random Jitter	RJ	V <sub>OD</sub> = 200 mV, 5 V/ns		TBD		ps
Minimum Pulse Width	PW <sub>MIN</sub>	$\Delta t_{PD}/\Delta PW < 50 \text{ ps}$		3		ns
Rise Time	t <sub>R</sub>	10% to 90%, $C_{LOAD} = 5 \text{ pF}$ , V <sub>CCO</sub> = 5 V		2.0		ns
Fall Time	t⊧	10% to 90%, $C_{LOAD} = 5 \text{ pF}$ , $V_{CCO} = 5 \text{ V}$		2.0		ns
Output skew	tskew	$50\% C_{LOAD} = 5 pF$		300		ps
POWER SUPPLY						
Input Supply Voltage Range	Vcci		2.5		5.5	V
Output Supply Voltage Range	V <sub>cco</sub>		2.5		5.5	V
Positive Supply Differential	V <sub>CCI</sub> — V <sub>CCO</sub>	Operating	-3.0		+3.0	V
Positive Supply Differential	V <sub>CCI</sub> — V <sub>CCO</sub>	Nonoperating	-5.5		+5.5	V
Input Section Supply Current	Ілссі	$V_{CCI} = 2.5 V \text{ to } 5 V$		0.8		mA
Output Section Supply Current	lvcco	V <sub>CCI</sub> = 5.5 V		2.8		mA
Power Dissipation	PD	$V_{CC} = 2.5 V$		9		mW
	PD	$V_{cc} = 5.5 V$		20		mW
Power Supply Rejection	PSRR	$V_{CCI} = 2.5 V \text{ to } 5 V$		-50		dB

### **ABSOLUTE MAXIMUM RATINGS**

#### Table 2.

Parameter	Rating
Supply Voltages	
Input Supply Voltage (Vcci to GND)	–0.5 V to +6.0 V
Output Supply Voltage (Vcco to GND)	–0.5 V to +6.0 V
Positive Supply Differential (V <sub>CCI</sub> – V <sub>CCO</sub> )	-6.0 V to +6.0 V
Input Voltages	
Input Voltage	$-0.5$ V to $V_{\text{CCI}}$ + 0.5 V
Differential Input Voltage	$\pm(V_{CCI} + 0.5 V)$
Maximum Input/Output Current	±50 mA
Shutdown Control Pin	
Applied Voltage (HYS to GND)	-0.5 V to V <sub>CCO</sub> + 0.5 V
Maximum Input/Output Current	±50 mA
Latch/Hysteresis Control Pin	
Applied Voltage (HYS to GND)	$-0.5$ V to $V_{\text{CCO}}$ + 0.5 V
Maximum Input/Output Current	±50 mA
Output Current	±50 mA
Temperature	
Operating Temperature, Ambient	–40°C to +125°C
Operating Temperature, Junction	150°C
Storage Temperature Range	–65°C to +150°C

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### THERMAL RESISTANCE

JA is specified for the worst-case conditions, that is, a device soldered in a circuit board for surface-mount packages.

#### **Table 3. Thermal Resistance**

Package Type	θ <sub>JA</sub> 1	Unit
ADCMP603 LSCFP 12-lead	62	°C/W

<sup>1</sup> Measurement in still air.

#### **ESD CAUTION**

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



# **PIN CONFIGURATION AND FUNCTION DESCRIPTIONS**



Figure 3. ADCMP603 Pin Configuration

#### **Table 4. Pin Function Descriptions**

Pin No.	Mnemonic	Description
1	V <sub>cco</sub>	Output Section Supply.
2	Vcci	Input Section Supply.
3	V <sub>EE</sub>	Negative Supply Voltage.
4	VP	Noninverting Analog Input.
5	V <sub>EE</sub>	Negative Supply Voltage.
6	V <sub>N</sub>	Inverting Analog Input.
7	S <sub>DN</sub>	Shutdown. Drive this pin low to shut down the device.
8	LE/HYS	Latch/Hysteresis Control. Bias with resistor or current for hysteresis adjustment; drive low to latch.
9	V <sub>EE</sub>	Negative Supply Voltage.
10	$\overline{Q}$	Inverting Output. $\overline{Q}$ is at logic low if the analog voltage at the noninverting input, V <sub>P</sub> , is greater than
		the analog voltage at the inverting input, V <sub>N</sub> , provided that the comparator is in compare mode. See the LE pin description (Pin 8) for more information.
11	V <sub>EE</sub>	Negative Supply Voltage.
12	Q	Noninverting Output. Q is at logic high if the analog voltage at the noninverting input, $V_P$ , is greater than the analog voltage at the inverting input, $V_N$ , provided that the comparator is in compare mode. See the LE pin description (Pin 8) for more information.
Heat Sink Paddle	V <sub>EE</sub>	The metallic back surface of the package is electrically connected to $V_{\text{EE}}$ . It can be left floating because Pin 3, Pin 5, Pin 9, and Pin 11 provide adequate electrical connection. It can also be soldered to the application board if improved thermal and/or mechanical stability is desired.

# **TYPICAL PERFORMANCE CHARACTERISTICS**

 $V_{CCI} = V_{CCO} = 2.5 \text{ V}, T_A = 25^{\circ}\text{C}$ , unless otherwise noted.



Figure 4. Propagation Delay vs. Input Overdrive



Figure 5. Propagation Delay vs. Input Common Mode



Figure 7. Hysteresis vs. V<sub>CC</sub>



Figure 8. Hysteresis vs. R<sub>HYS</sub> Control Resistor



Figure 9. Input Bias Current vs. Input Common Mode



Figure 6. Propagation Delay vs. Temperature



Figure 10. Input Bias Current vs. Temperature



Figure 12. Latch/Hysteresis Control Pin I/V Characteristics



Figure 11. Input Offset Voltage vs. Temperature

### APPLICATION INFORMATION POWER/GROUND LAYOUT AND BYPASSING

The ADCMP603 comparator is a very high speed device. Despite the low noise output stage, it is essential to use proper high speed design techniques to achieve the specified performance. Because comparators are uncompensated amplifiers, feedback in any phase relationship is likely to cause oscillations or undesired hysteresis. Of critical importance is the use of low impedance supply planes, particularly the output supply plane ( $V_{CCO}$ ) and the ground plane (GND). Individual supply planes are recommended as part of a multilayer board. Providing the lowest inductance return path for switching currents ensures the best possible performance in the target application.

It is also important to adequately bypass the input and output supplies. Multiple high quality 0.01  $\mu$ F bypass capacitors should be placed as close as possible to each of the V<sub>CCI</sub> and V<sub>CCO</sub> supply pins and should be connected to the GND plane with redundant vias. At least one of these should be placed to provide a physically short return path for output currents flowing back from ground to the V<sub>CCO</sub> pin. High frequency bypass capacitors should be carefully selected for minimum inductance and ESR. Parasitic layout inductance should also be strictly controlled to maximize the effectiveness of the bypass at high frequencies.

If the input and output supplies have been connected separately such that  $V_{CCI} \neq V_{CCO}$ , care should be taken to bypass each of these supplies separately to the GND plane. A bypass capacitor should never be connected between them. It is recommended that the GND plane separate the  $V_{CCI}$  and  $V_{CCO}$  planes when the circuit board layout is designed to minimize coupling between the two supplies and to take advantage of the additional bypass capacitance from each respective supply to the ground plane. This enhances the performance when split input/output supplies are used. If the input and output supplies are connected together for single-supply operation such that  $V_{CCI} = V_{CCO}$ , coupling between the two supplies is unavoidable; however, careful board placement can help keep output return currents away from the inputs.

#### TTL-/CMOS-COMPATIBLE OUTPUT STAGE

Specified propagation delay performance can be achieved only by keeping the capacitive load at or below the specified minimums. The low skew complementary outputs of the ADCMP603 are designed to directly drive one Schottky TTL or three low power Schottky TTL loads or equivalent. For large fan outputs, buses, or transmission lines, an appropriate buffer should be used to maintain the comparator's excellent speed and stability.

With the rated 5 pF load capacitance applied, more than half of the total device propagation delay is output stage slew time, even at 2.5 V  $V_{\rm CC}$ . Because of this, the total prop delay decreases as  $V_{\rm CCO}$  decreases, and instability in the power supply may appear as excess delay dispersion.

This delay is measured to the 50% point for the supply in use; therefore, the fastest times are observed with the  $V_{\rm CC}$  supply at 2.5 V, and larger values are observed when driving loads that switch at other levels.

When duty cycle accuracy is critical, the logic being driven should switch at 50% of  $V_{\rm CC}$  and load capacitance should be minimized. When in doubt, it is best to power  $V_{\rm CCO}$  or the entire device from the logic supply and rely on the input PSRR and CMRR to reject noise.

Overdrive and input slew rate dispersions are not significantly affected by output loading and  $V_{\rm CC}$  variations.

The TTL-/CMOS-compatible output stage is shown in the simplified schematic diagram (Figure 13). Because of its inherent symmetry and generally good behavior, this output stage is readily adaptable for driving various filters and other unusual loads.



#### **USING/DISABLING THE LATCH FEATURE**

The latch input is designed for maximum versatility. It can safely be left floating for fixed hysteresis or be tied to  $V_{CC}$  to remove the hysteresis, or it can be driven low by any standard TTL/CMOS device as a high speed latch.

In addition, the pin can be operated as a hysteresis control pin with a bias voltage of 1.25 V nominal and an input resistance of approximately 7000  $\Omega$ , allowing the comparator hysteresis to be easily controlled by either a resistor or an inexpensive CMOS DAC.

Hysteresis control and latch mode can be used together if an open drain, an open collector, or a three-state driver is connected parallel to the hysteresis control resistor or current source.

Due to the programmable hysteresis feature, the logic threshold of the latch pin is approximately 1.1 V regardless of  $V_{\rm CC}$ .

#### **OPTIMIZING PERFORMANCE**

As with any high speed comparator, proper design and layout techniques are essential for obtaining the specified performance. Stray capacitance, inductance, inductive power and ground impedances, or other layout issues can severely limit performance and often cause oscillation. Large discontinuities along input and output transmission lines can also limit the specified pulsewidth dispersion performance. The source impedance should be minimized as much as is practicable. High source impedance, in combination with the parasitic input capacitance of the comparator, causes an undesirable degradation in bandwidth at the input, thus degrading the overall response. Thermal noise from large resistances can easily cause extra jitter with slowly slewing input signals; higher impedances encourage undesired coupling.

# COMPARATOR PROPAGATION DELAY DISPERSION

The ADCMP603 comparator is designed to reduce propagation delay dispersion over a wide input overdrive range of 5 mV to  $V_{CCI}$  – 1 V. Propagation delay dispersion is the variation in propagation delay that results from a change in the degree of overdrive or slew rate (that is, how far or how fast the input signal exceeds the switching threshold).

Propagation delay dispersion is a specification that becomes important in high speed, time-critical applications, such as data communication, automatic test and measurement, and instrumentation. It is also important in event-driven applications, such as pulse spectroscopy, nuclear instrumentation, and medical imaging. Dispersion is defined as the variation in propagation delay as the input overdrive conditions are changed (Figure 14 and Figure 15).

ADCMP603 dispersion is typically <TBD ps as the overdrive varies from 5 mV to 500 mV and the input slew rate varies from 2 V/ns to 10 V/ns. This specification applies to both positive and negative signals because the device has very closely matched delays for both positive-going and negative-going inputs.







#### **COMPARATOR HYSTERESIS**

The addition of hysteresis to a comparator is often desirable in a noisy environment, or when the differential input amplitudes are relatively small or slow moving. Figure 16 shows the transfer function for a comparator with hysteresis. As the input voltage approaches the threshold (0.0 V, in this example) from below the threshold region in a positive direction, the comparator switches from low to high when the input crosses  $+V_H/2$ , and the new switching threshold becomes  $-V_H/2$ . The comparator remains in the high state until the new threshold,  $-V_H/2$ , is crossed from below the threshold region in a negative direction. In this manner, noise or feedback output signals centered on 0.0 V input cannot cause the comparator to switch states unless it exceeds the region bounded by  $\pm V_H/2$ .



Figure 16. Comparator Hysteresis Transfer Function

The customary technique for introducing hysteresis into a comparator uses positive feedback from the output back to the input. One limitation of this approach is that the amount of hysteresis varies with the output logic levels, resulting in hysteresis that is not symmetric about the threshold. The external feedback network can also introduce significant parasitics that reduce high speed performance and induce oscillation in some cases.

The ADCMP603 comparator offers a programmable hysteresis feature that can significantly improve accuracy and stability. Connecting an external pull-down resistor or a current source from the LE/HYS pin to GND, varies the amount of hysteresis in a predictable, stable manner. Leaving the LE/HYS pin disconnected or driving it high removes the hysteresis. The

## **Preliminary Technical Data**

maximum hysteresis that can be applied using this pin is approximately 160 mV. Figure 17 illustrates the amount of hysteresis applied as a function of the external resistor value, and Figure TBD illustrates hysteresis as a function of the current.

The hysteresis control pin appears as a 1.25 V bias voltage seen through a series resistance of  $7k \pm 20\%$  throughout the hysteresis control range. The advantages of applying hysteresis in this manner are improved accuracy, improved stability, reduced component count, and maximum versatility. An external bypass capacitor is not recommended on the HYS pin because it impairs the latch function and often degrades the jitter performance of the device. As described in the Using/Disabling the Latch Feature section, hysteresis control need not compromise the latch function.

#### **CROSSOVER BIAS POINT**

In both op amps and comparators, rail-to-rail inputs of this type have a dual front-end design. Certain devices are active near the  $V_{\rm CC}$  rail and others are active near the  $V_{\rm EE}$  rail. At some predetermined point in the common-mode range, a crossover occurs. At this point, normally  $V_{\rm CC}/2$ , the direction of the bias current reverses and the measured offset voltages and currents change.

The ADCMP603 slightly elaborates on this scheme. With  $V_{\rm CC}$  less than 4 V, this crossover is at the expected  $V_{\rm CC}/2$ , but with  $V_{\rm CC}$  greater than 4 V, the crossover point instead follows  $V_{\rm CC}$  1:1, bringing it to approximately 3 V with  $V_{\rm CC}$  at 5 V. This means that when  $V_{\rm CC}$  is greater than 4, the comparator input characteristics more closely resemble those of common types of inputs that are not rail to rail.



Figure 17. Hysteresis vs. R<sub>HYS</sub> Control Resistor

#### MINIMUM INPUT SLEW RATE REQUIREMENT

(Remove if device is stable.)

As with most high speed comparators without hysteresis, a minimum slew rate must be met to ensure that the device does not oscillate as the input signal crosses the threshold. This oscillation is due to the high gain bandwidth of the comparator in combination with feedback parasitics inherent in the package and PC board. A minimum slew rate of TBD V/ $\mu$ s ensures clean output transitions from the ADCMP603 comparator without hysteresis. In many applications, chattering is not harmful.

### **TYPICAL APPLICATION CIRCUITS**





Figure 21. Duty Cycle to Differential Voltage Converter





Figure 19. LVDS-to-CMOS Receiver



Figure 22. Oscillator and Pulse-Width Modulator



### TIMING INFORMATION

Figure 24 illustrates the ADCMP603 latch timing relationships. Table 5 provides definitions of the terms shown in the figure.



Table 5	Timing	Descriptions
---------	--------	--------------

Symbol	Timing Description				
<b>t</b> PDH	Input to output high delay	Propagation delay measured from the time the input signal crosses the reference ( $\pm$ the input offset voltage) to the 50% point of an output low-to-high transition.			
<b>t</b> PDL	Input to output low delay	Propagation delay measured from the time the input signal crosses the reference (± the input offset voltage) to the 50% point of an output high-to-low transition.			
t <sub>PLOH</sub>	Latch enable to output high delay	Propagation delay measured from the 50% point of the latch enable signal low-to-high transition to the 50% point of an output low-to-high transition.			
<b>t</b> plol	Latch enable to output low delay	o output low delay Propagation delay measured from the 50% point of the latch enable signal low-to-high transition to the 50% point of an output high-to-low transition.			
t <sub>H</sub>	Minimum hold time	Minimum time after the negative transition of the latch enable signal that the input signal must remain unchanged to be acquired and held at the outputs.			
t <sub>PL</sub>	Minimum latch enable pulse width	Minimum time that the latch enable signal must be high to acquire an input signal change.			
ts	Minimum setup time	Minimum time before the negative transition of the latch enable signal occurs that an input signal change must be present to be acquired and held at the outputs.			
t <sub>R</sub>	Output rise time	Amount of time required to transition from a low to a high output as measured at the 20% and 80% points.			
t⊧	Output fall time	Amount of time required to transition from a high to a low output as measured at the 20% and 80% points.			
Vod	Voltage overdrive	Difference between the input voltages $V_A$ and $V_B$ .			

# NOTES

# NOTES

## NOTES

Rev. PrA | Page 16 of 16

www.analog.com

©2006 Analog Devices, Inc. All rights reserved. Trademarks and registered trademarks are the property of their respective owners. PR05915-0-3/06(PrA)