

# High-Speed (10Mbps), Fail-Safe, RS-485/RS-422 Transceivers with Slew-Rate-Limiting and ±15kV ESD Protection

# ADM3082/ADM3085/ADM3088

#### **FEATURES**

Enhanced Slew Rate Limiting for Error-Free Data Transmission

Fail-Safe Receiver Operation while Maintaining EIA/TIA-485 compatibility

Low-Current (1nA) Shutdown Mode

High Input Impedance — Up to 256 Transceivers on Bus ±15kV ESD Protection (Human Body Model) on RS-485 I/O pins

Pin-Compatible with Industry Standard 75176

#### **APPLICATIONS**

Enhanced Replacement for Industry-Standard Parts EMI-Sensitive Systems Level Translation LANs for Industrial Control Applications

### GENERAL DESCRIPTION

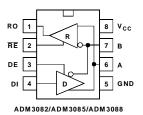
The ADM3082/ADM3085/ADM3088 are high-speed RS-485/RS-422 transceivers consisting of one driver and one receiver per package. The devices feature fail-safe operation, ensuring a logic-high receiver output when the receiver inputs are open-circuit or short-circuit. This guarantees that the receiver output will be high if all the transmitters on a terminated bus are disabled (high-impedance).

The ADM3082 has a slew-rate limited driver to minimize electromagnetic interference (EMI) and reduce reflections caused by incorrectly terminated cables. This allows error-free transmission at data rates up to 115kbps.

The ADM3085 offers a higher slew rate allowing data rates up to 500kbps, while the ADM3088 has a driver whose slew rate is not limited, allowing data rates up to 10Mbps.

All devices in the family feature  $\pm 15 \mathrm{kV}$  electrostatic discharge (ESD) protection and high receiver input impedance (1/8 unit load), allowing up to 256 transceivers on the bus. The devices have low current drain of  $375 \mu \mathrm{A}$  unloaded, or fully loaded with the drivers disabled, and feature an ultra-low power (1nA) shutdown mode.

#### FUNCTIONAL BLOCK DIAGRAM



## ADM3082/ADM3085/ADM3088

# ADM3082/ADM3085/ADM3088 SPECIFICATIONS

### DCELECTRICAL CHARACTERISTICS

 $(V_{CC} = +5V \pm 5\%, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{CC} = +5V \text{ and } T_A = +25^{\circ}C.) \text{ (Note 1)}$ 

### **DRIVER**

| Parameter   | Min        | Тур | Max | Units      | Test Conditions/Comments  |
|---|------------|-----|-----|------------|---|
| Differential Driver Output, V <sub>OD1</sub>                                    |            |     | 5   | V          | Figure 1 (No Load)  |
| Differential Driver Output,V <sub>OD2</sub>                                     | 2.0<br>1.5 |     |     | V<br>V     | Figure 1, R = $50\Omega$ (RS-422)<br>Figure 1, R = $27\Omega$ (RS-485)                    |
| Change-in-Magnitude of Differential Common-Mode Output Voltage, $\Delta V_{OD}$ |            |     | 0.2 | V          | Figure 1, $R = 50\Omega$ or $R = 27\Omega$ (Note 2)                                       |
| Driver Common-Mode<br>Output Voltage, V <sub>OC</sub>                           |            |     | 3   | V          | Figure 1, $R = 50\Omega$ or $R = 27\Omega$  |
| Change-in-Magnitude of Common-Mode Voltage, $\Delta V_{OC}$                     |            |     | 0.2 | V          | Figure 1, $R = 50\Omega$ or $R = 27\Omega$ (Note 2)                                       |
| Input High Voltage, $V_{IH1}$ (DE, DI, $\overline{RE}$ )                        | 2.0        |     |     | V          |   |
| Input Low Voltage, $V_{IL1}$ (DE, DI, $\overline{RE}$ )                         |            |     | 0.8 | V          |   |
| DI Input Hysteresis, V <sub>HYS</sub>   |            | 100 |     | mV         |   |
| Input Current, $I_{IN1}$ (DE, DI, $\overline{RE}$ )                             |            |     | ±2  | μA         |   |
| Input Current (A and B), $I_{\rm IN4}$  |            |     | 125 | μΑ         | DE = GND, $V_{CC}$ = GND or 5.25V,<br>$V_{IN}$ = 12V                                      |
|   |            |     | -75 | μΑ         | $V_{IN} = 12V$ $DE = GND$ , $V_{CC} = GND$ or 5.25V, $V_{IN} = -7V$                       |
| Output Leakage (Y and Z), Full Duplex, I <sub>O</sub>                           |            |     | 125 | μΑ         | DE = GND, $V_{CC}$ = GND or 5.25V,<br>$V_{IN}$ = 12V                                      |
| Tun Dupton, 10  | -100       |     |     | μΑ         | $DE = GND$ , $V_{CC} = GND$ or 5.25V, $V_{IN} = -7V$                                      |
| Driver Short-Circuit,V <sub>OD1</sub>   | -250       |     |     | m A        | $-7V \le V_{OUT} \le V_{CC} \text{ (Note 3)}$   |
| Output Current  | ±25        |     | 250 | m A<br>m A | $0V \le V_{OUT} \le 12V \text{ (Note 3)}$<br>$0V \le V_{OUT} \le V_{CC} \text{ (Note 3)}$ |

# ADM3082/ADM3085/ADM3088 SPECIFICATIONS (continued)

### DC ELECTRICAL CHARACTERISTICS

 $(V_{CC} = +5V \pm 5\%, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $V_{CC} = +5V$  and  $T_A = +25^{\circ}C$ .) (Note 1)

### **RECEIVER**

| Parameter  | Min                   | Тур  | Max | Units | Test Conditions/Comments                             |
|--|-----------------------|------|-----|-------|--|
| Receiver Differential Threshold Voltage, $V_{TH}$          | -200                  | -125 | -50 | mV    | $-7V \le V_{CM} \le 12V$                             |
| Receiver Input Hysteresis, $\Delta V_{TH}$                 |                       | 25   |     | mV    |  |
| Receiver Output High Voltage, V <sub>OH</sub>              | V <sub>CC</sub> -1 .5 |      |     | V     | $I_{\rm O}$ = -4mA, $V_{\rm ID}$ = -50mV             |
| Receiver Output Low Voltage, V <sub>OL</sub>               |                       |      | 0.4 | V     | $I_{\rm O} = 4 {\rm mA}, V_{\rm ID} = -200 {\rm mV}$ |
| Three-State Output Current at Receiver, $I_{\rm OZR}$      |                       |      | ±1  | μA    | $0.4V \le V_{\rm O} \le 2.4V$                        |
| Receiver Input Resistance, R <sub>IN</sub>                 | 96                    |      |     | kΩ    | $-7V \le V_{CM} \le 12V$                             |
| Receiver Output Short-Circuit<br>Current, I <sub>OSR</sub> | ±7                    |      | ±95 | m A   | $0V \le V_{RO} \le V_{CC}$                           |

#### **SUPPLY CURRENT**

| Parameter  | Min | Тур   | Max | Units | Test Conditions/Comments   |
|--|-----|-------|-----|-------|--|
| Supply Current, I <sub>CC</sub>                    |     | 430   | 900 | μΑ    | No load, $\overline{RE} = DI = GND$ or $V_{CC}$ ,                              |
|  |     | 375   | 600 | μΑ    | $DE = V_{CC}$<br>No load, $\overline{RE} = DI = GND$ or $V_{CC}$ ,<br>DE = GND |
| Supply Current in Shutdown Mode, I <sub>SHDN</sub> |     | 0.001 | 10  | μА    | DE = GND, $V_{\overline{RE}} = V_{CC}$   |
| ESD Protection for Y, Z, A, B                      |     | ±15   |     | kV    | Human Body Model   |

### NOTES

<sup>&</sup>lt;sup>1</sup>All currents into the device are positive; all currents out of the device are negative. All voltages are referred to device ground unless otherwise noted.

 $<sup>^2\</sup>Delta_{DO}$  and  $\Delta V_{CC}$  are the changes in  $V_{OD}$  and  $V_{OC}$ , respectively, when the DI input changes state.

<sup>&</sup>lt;sup>3</sup>Maximum current level applies to peak current just prior to foldback-current limiting; minimum current level applies during current limiting.

### ADM3082/ADM3085/ADM3088

# ADM3082/ADM3085/ADM3088 SPECIFICATIONS (continued)

### SWITCHING CHARACTERISTICS—ADM3082

 $(V_{CC} = +5V \pm 5\%, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{CC} = +5V \text{ and } T_A = +25^{\circ}C.) \text{ (Note 1)}$ 

| Parameter   | Min        | Тур          | Max          | Units    | Test Conditions/Comments   |
|---|------------|--------------|--------------|----------|--|
| Driver Input-to-Output, t <sub>DPLH</sub> Driver Input-to-Output, t <sub>DPHL</sub> | 500<br>500 | 2030<br>2030 | 2600<br>2600 | ns<br>ns | Figures 2 and 3, $R_{DIFF}$ = 54 $\Omega$ , $C_{L1}$ = $C_{L2}$ = 100pF  |
| Driver Output Skew,  t <sub>DPLH</sub> -t <sub>DPHL</sub>  , t <sub>DSKEW</sub>     |            | -3           | ±200         | ns       | Figures 2 and 3, $R_{DIFF}$ = 54 $\Omega$ , $C_{L1}$ = $C_{L2}$ = 100pF  |
| Driver Rise or Fall Time, $t_{DR}$ , $t_{DF}$                                       | 667        | 1320         | 2500         | ns       | Figures 2 and 3, $R_{DIFF}$ = 54 $\Omega$ , $C_{L1}$ = $C_{L2}$ = 100pF  |
| Maximum Data Rate, f <sub>MAX</sub>   | 115        |              |              | kbps     |  |
| Driver Enable to Output High, t <sub>DZH</sub>                                      |            |              | 3500         | ns       | Figures 5 and 6, C <sub>L</sub> = 100pF, S2 closed                       |
| Driver Enable to Output Low, $t_{\rm DZL}$  |            |              | 3500         | ns       | Figures 5 and 6, C <sub>L</sub> = 100pF, S1 closed                       |
| Driver Disable Time from Low, t <sub>DLZ</sub>                                      |            |              | 100          | ns       | Figures 5 and 6, C <sub>L</sub> = 15pF, S1 closed                        |
| Driver Disable Time from High, t <sub>DHZ</sub>                                     |            |              | 100          | ns       | Figures 4 and 5, C <sub>L</sub> = 15pF, S2 closed                        |
| Receiver Input to Output, t <sub>RPLH</sub> , t <sub>RPHL</sub>                     |            | 127          | 200          | ns       | Figure 7; $ V_{ID}  \ge 2.0V$ ; rise and fall time of $V_{ID} \le 15$ ns |
| Differential Receiver Skew, t <sub>RSKD</sub>                                       |            | 3            | ±30          | ns       | Figure 7; $ V_{ID}  \ge 2.0V$ ; rise and fall time of $V_{ID} \le 15 ns$ |
| Receiver Enable to Output Low, t <sub>RZL</sub>                                     |            | 20           | 50           | ns       | Figures 7 and 8; C <sub>L</sub> = 100pF, S1 closed                       |
| Receiver Enable to Output High, t <sub>RZH</sub>                                    |            | 20           | 50           | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S2 closed                       |
| Receiver Disable Time from Low, t <sub>RLZ</sub>                                    |            | 20           | 50           | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S1 closed                       |
| Receiver Disable Time from High, t <sub>RHZ</sub>                                   |            | 20           | 50           | ns       | Figures 7 and 8 C <sub>L</sub> = 100pF,<br>S2 closed                     |
| Time to Shutdown, t <sub>SHDN</sub>   | 50         | 200          | 600          | ns       | (Note 5)   |
| Driver Enable from Shutdown to Output High, t <sub>DZH(SHDN)</sub>                  |            |              | 6000         | ns       | Figures 5 and 6, C <sub>L</sub> = 15pF, S2 closed                        |
| Driver Enable from Shutdown to Output Low, t <sub>DZL(SHDN)</sub>                   |            |              | 6000         | ns       | Figures 5 and 6, C <sub>L</sub> = 15pF, S1 closed                        |
| Receiver Enable from Shutdown to Output High, t <sub>RZH(SHDN)</sub>                |            |              | 3500         | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S2 closed                       |
| Receiver Enable from Shutdown to Output Low, t <sub>RZL(SHDN)</sub>                 |            |              | 3500         | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF,<br>S1 closed                    |

# ADM3082/ADM3085/ADM3088 SPECIFICATIONS (continued)

### SWITCHING CHARACTERISTICS—ADM3085

 $(V_{CC} = +5V \pm 5\%, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{CC} = +5V \text{ and } T_A = +25^{\circ}\text{C.}) \text{ (Note 1)}$ 

| Parameter   | Min        | Typ        | Max          | Units    | Test Conditions/Comments   |
|---|------------|------------|--------------|----------|--|
| Driver Input-to-Output, t <sub>DPLH</sub> Driver Input-to-Output, t <sub>DPHL</sub> | 250<br>250 | 720<br>720 | 1000<br>1000 | ns<br>ns | Figures 2 and 3 $R_{\rm DIFF}$ = 54 $\Omega$ , $C_{\rm L1}$ = $C_{\rm L2}$ = 100pF     |
| Driver Output Skew, $ t_{DPLH} - t_{DPHL} $ , $t_{DSKEW}$                           |            | -3         | ±100         | ns       | Figures 2 and 3, $R_{DIFF}$ = 54 $\Omega$ , $C_{L1}$ = $C_{L2}$ = 100pF                |
| Driver Rise or Fall Time, $t_{DR}$ , $t_{DF}$                                       | 200        | 530        | 750          | ns       | Figures 2 and 3, $R_{DIFF}$ = 54 $\Omega$ , $C_{L1}$ = $C_{L2}$ = 100pF                |
| Maximum Data Rate, f <sub>MAX</sub>   | 500        |            |              | kbps     |  |
| Driver Enable to Output High, t <sub>DZH</sub>                                      |            |            | 2500         | ns       | Figures 5 and 6, C <sub>L</sub> = 100pF, S2 closed                                     |
| Driver Enable to Output Low, t <sub>DZL</sub>                                       |            |            | 2500         | ns       | Figures 5 and 6, C <sub>L</sub> = 100pF, S1 closed                                     |
| Driver Disable Time from Low, t <sub>DLZ</sub>                                      |            |            | 100          | ns       | Figures 5 and 6, C <sub>L</sub> = 15pF, S1 closed                                      |
| Driver Disable Time from High, t <sub>DHZ</sub>                                     |            |            | 100          | ns       | Figures 5 and 6, C <sub>L</sub> = 15pF, S2 closed                                      |
| Receiver Input to Output, t <sub>RPLH</sub> , t <sub>RPHL</sub>                     |            | 127        | 200          | ns       | Figure 7; $ V_{\rm ID}  \ge 2.0V$ ; rise and fall time of $V_{\rm ID} \le 15 {\rm ns}$ |
| Differential Receiver Skew, $t_{RSKD}$<br>$ t_{RPLH} - t_{RPHL} $                   |            | 3          | ±30          | ns       | Figure 7; $ V_{ID}  \ge 2.0V$ ; rise and fall time of $V_{ID} \le 15 ns$               |
| Receiver Enable to Output Low, t <sub>RZL</sub>                                     |            | 20         | 50           | ns       | Figures 7 and 8 C <sub>L</sub> = 100pF, S1 closed                                      |
| Receiver Enable to Output High, t <sub>RZH</sub>                                    |            | 20         | 50           | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S2 closed                                     |
| Receiver Disable Time from Low, t <sub>RLZ</sub>                                    |            | 20         | 50           | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S1 closed                                     |
| Receiver Disable Time from High, t <sub>RHZ</sub>                                   |            | 20         | 50           | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S2 closed                                     |
| Time to Shutdown, t <sub>SHDN</sub>   | 50         | 200        | 600          | ns       | (Note 5)   |
| Driver Enable from Shutdown to Output High, t <sub>DZH(SHDN)</sub>                  |            |            | 4500         | ns       | Figures 5 and 6, C <sub>L</sub> = 15pF, S2 closed                                      |
| Driver Enable from Shutdown to Output Low, t <sub>OZL(SHDN)</sub>                   |            |            | 4500         | ns       | Figures 5 and 6, C <sub>L</sub> = 15pF, S1 closed                                      |
| Receiver Enable from Shutdown to Output High, t <sub>RZH(SHDN)</sub>                |            |            | 3500         | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S2 closed                                     |
| Receiver Enable from Shutdown to Output Low, t <sub>RZL(SHDN)</sub>                 |            |            | 3500         | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S1 closed                                     |

# ADM3082/ADM3085/ADM3088 SPECIFICATIONS (continued)

### SWITCHING CHARACTERISTICS—ADM3088

 $(V_{CC} = +5V \pm 5\%, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $V_{CC} = +5V$  and  $T_A = +25^{\circ}C$ .) (Note 1)

| Parameter   | Min | Тур      | Max      | Units    | Test Conditions/Comments   |
|---|-----|----------|----------|----------|--|
| Driver Input-to-Output, t <sub>DPLH</sub> Driver Input-to-Output, t <sub>DPHL</sub> |     | 34<br>34 | 60<br>60 | ns<br>ns | Figures 2 and 5, $R_{DIFF}$ = $54\Omega$ , $C_{L1}$ = $C_{L2}$ = $100 pF$              |
| Driver Output Skew,   t <sub>DPLH</sub> -t <sub>DPHL</sub>  , t <sub>DSKEW</sub>    |     | -2.5     | ±10      | ns       | Figures 2 and 5, $R_{DIFF}$ = $54\Omega$ , $C_{L1}$ = $C_{L2}$ = $100pF$               |
| Driver Rise or Fall Time, tDR, tDF  |     | 14       | 25       | ns       | Figures 7 and 9, $R_{DIFF}$ = 54 $\Omega$ , $C_{L1}$ = $C_{L2}$ = 100pF                |
| Maximum Data Rate, f <sub>MAX</sub>   | 10  |          |          | Mbps     |  |
| Driver Enable to Output High, t <sub>DZH</sub>                                      |     |          | 150      | ns       | Figures 5 and 6, C <sub>L</sub> = 100pF, S2 closed                                     |
| Driver Enable to Output Low, t <sub>DZL</sub>                                       |     |          | 150      | ns       | Figures 5 and 6, C <sub>L</sub> = 100pF, S1 closed                                     |
| Driver Disable Time from Low, t <sub>DLZ</sub>                                      |     |          | 100      | ns       | Figures 5 and 6, C <sub>L</sub> = 15pF, S1 closed                                      |
| Driver Disable Time from High, t <sub>DHZ</sub>                                     |     |          | 100      | ns       | Figures 5 and 6, C <sub>L</sub> = 15pF, S2 closed                                      |
| Receiver Input-to-Output, t <sub>RPLH</sub> , t <sub>RPHL</sub>                     |     | 106      | 150      | ns       | Figure 7; $ V_{ID}  \ge 2.0V$ ; rise and fall time of $V_{ID} \le 15 \text{ns}$        |
| Differential<br>Receiver Skew, $t_{RSKD}$ $ t_{RPLH} - t_{RPHL} $                   |     | 0        | ±10      | ns       | Figures 7; $ V_{\rm ID}  \ge 2.0 V$ ; rise and fall time of $V_{\rm ID} \le 15 \rm ns$ |
| Receiver Enable to Output Low, t <sub>RZL</sub>                                     |     | 20       | 50       | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S1 closed                                     |
| Receiver Enable to Output High, t <sub>RZH</sub>                                    |     | 20       | 50       | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S2 closed                                     |
| Receiver Disable Time from Low, t <sub>RLZ</sub>                                    |     | 20       | 50       | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S1 closed                                     |
| Receiver Disable Time from High, t <sub>RHZ</sub>                                   |     | 20       | 50       | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S2 closed                                     |
| Time to Shutdown, t <sub>SHDN</sub>   | 50  | 200      | 600      | ns       | (Note 5)   |
| Driver Enable from Shutdown toOutput High, t <sub>DZH(SHDN)</sub>                   |     |          | 250      | ns       | Figures 5 and 6, C <sub>L</sub> = 15pF, S2 closed                                      |
| Driver Enable from Shutdown to Output Low, t <sub>DZL(SHDN)</sub>                   |     |          | 250      | ns       | Figures 5 and 6, $C_L = 15pF$ , S1 closed  |
| Receiver Enable from Shutdown to Output High, t <sub>RZH(SHDN)</sub>                |     |          | 3500     | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF, S2 closed                                     |
| Receiver Enable from Shutdown to Output Low, t <sub>RZL(SHDN)</sub>                 |     |          | 3500     | ns       | Figures 7 and 8, C <sub>L</sub> = 100pF,<br>S1 closed                                  |

#### NOTES

<sup>&</sup>lt;sup>5</sup>The device is put into shutdown by bringing  $\overline{RE}$  high and DE low. If the enable inputs are in this state for less than 50ns, the device is guaranteed not to enter shutdown. If the enable inputs are in this state for at least 600ns, the device is guaranteed to have entered shutdown.

# ADM3082/ADM3085/ADM3088 TEST CIRCUITS AND TIMING

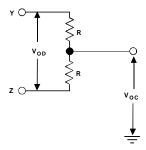


Figure 1. Driver DC Load Test Circuit

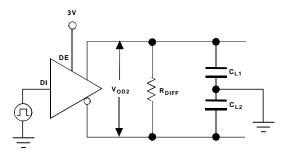


Figure 2. Test Load for Driver Timing Tests

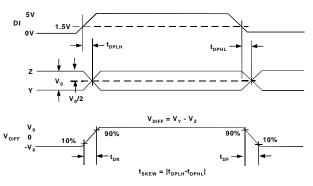


Figure 3. Driver Propagation Delays

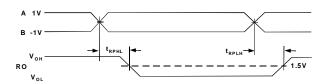


Figure 4. Receiver Propagation Delays

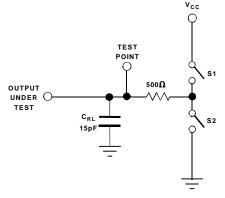


Figure 5. Test Load for Driver Enable/Disable Time Test

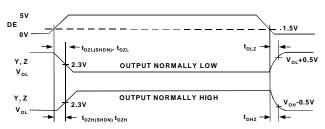


Figure 6. Driver Enable and Disable Times

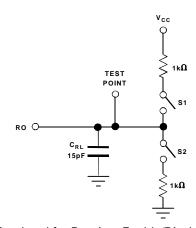


Figure 7. Test Load for Receiver Enable/Disable Time Test

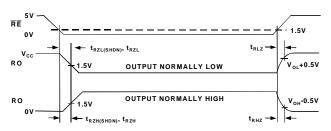


Figure 8. Receiver Enable and Disable Delay Times

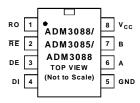
| ABSOLUTE MAXIMUM RATINGS                                    |
|---|
| Supply Voltage (V <sub>CC</sub> )+7V                        |
| Logic Input Voltage0.3V to (V <sub>CC</sub> +0.3V)          |
| Driver Output Voltage (A, B)±13V                            |
| Receiver Input Voltage (A, B)±13V                           |
| Receiver Input Voltage, Full Duplex (A, B) ±13V             |
| Receiver Output Voltage (RO)0.3V to (V <sub>CC</sub> +0.3V) |
| Continuous Power Dissipation                                |
| 8-Pin Plastic DIP   |
| (derate 9.09mW/°C above +70°C)                              |
| 8-Pin Plastic SO  |
| (derate 5.88mW/°C above +70°C) 471mW                        |
| Maximum Junction Temperature (T <sub>J</sub> max) 150 °C    |
| Storage Temperature Range65°C to +150°C                     |
| Lead Temperature, Soldering                                 |
| Vapor Phase 60 sec+215°C                                    |
| Infra-Red 15 sec+200°C                                      |

<sup>\*</sup>Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### THERMAL CHARACTERISTICS

8-Pin Plastic DIP Package  $\theta_{JA} = tbd$  K/Watt,  $\theta_{JC} = tbd$  K/Watt 8-Pin Plastic SO Package  $\theta_{JA} = tbd$  K/Watt,  $\theta_{JC} = tbd$  K/Watt

### PIN CONFIGURATION



### ORDERING INFORMATION

| Model     | Temperature Range | Package Option    |
|-----------|-------------------|-------------------|
| ADM3082JN | 0°C to +70°C      | 8 Pin Plastic DIP |
| ADM3082JR | 0°C to +70°C      | 8 Pin SO          |
| ADM3082AN | -40°C to +85°C    | 8 Pin Plastic DIP |
| ADM3082AR | -40°C to +85°C    | 8 Pin SO          |
| ADM3085JN | 0°C to +70°C      | 8 Pin Plastic DIP |
| ADM3085JR | 0°C to +70°C      | 8 Pin SO          |
| ADM3085AN | -40°C to +85°C    | 8 Pin Plastic DIP |
| ADM3085AR | -40°C to +85°C    | 8 Pin SO          |
| ADM3088JN | 0°C to +70°C      | 8 Pin Plastic DIP |
| ADM3088JR | 0°C to +70°C      | 8 Pin SO          |
| ADM3088AN | -40°C to +85°C    | 8 Pin Plastic DIP |
| ADM3088AR | -40°C to +85°C    | 8 Pin SO          |

# ADM3082/ADM3085/ADM3088TYPICALPERFORMANCE CHARACTERISTICS



TPC1. No-load Supply Current vs.
Temperature



TPC2. Output Current vs. Receiver Output High Voltage



TPC3. Output Current vs. Receiver Output Low Voltage

## ADM3082/ADM3085/ADM3088 TYPICAL PERFORMANCE CHARACTERISTICS (continued)



TPC4. Receiver Output High Voltage vs. Temperature



TPC5. Receiver Output Low Voltage vs. Temperature



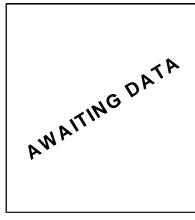
TPC6. Shutdown Current vs.
Temperature



TPC7. ADM3082 Driver Propagation Delay vs. Temperature



TPC8. ADM3085 Driver Propagation Delay vs. Temperature



TPC9. ADM3088 Driver Propagation Delay vs. Temperature



TPC10. ADM3082/5 Receiver Propagation Delay vs. Temperature



TPC11. ADM3088 Receiver Propagation Delay vs. Temperature



TPC12. Driver Differential Output Voltage vs. Temperature

### ADM3082/ADM3085/ADM3088 TYPICAL PERFORMANCE CHARACTERISTICS (continued)



TPC13. Driver Output Current vs. Differential Output Voltage



TPC14. Output Current vs. Driver Output High Voltage



TPC15. Output Current vs. Driver Output Low Voltage



TPC16. ADM3082 Driver Propagation
Delay



TPC17. ADM3085 Driver Propagation Delay



TPC18. ADM3088 Driver Propagation Delay



TPC19. ADM3082/5 Receiver Propagation Delay



TPC20. ADM3088 Receiver Propagation Delay

# ADM3082/ADM3085/ADM3088

### PIN FUNCTION DESCRIPTION

| Pin | Mnemonic        | Description  |
|-----|-----------------|--|
| 1   | RO              | Receiver Output. When $\overline{RE}$ is low and A - B $\geq$ (more positive than) -50mV, RO will be high. When $\overline{RE}$ is low and A - B $\leq$ (more negative than) -200mV, RO will be low. |
| 2   | RE              | Receiver Output Enable. Take $\overline{RE}$ low to enable RO; RO is high impedance when $\overline{RE}$ is high. Take $\overline{RE}$ high and DE low to enter low-power shutdown mode.             |
| 3   | DE              | Driver Output Enable. Take DE high to enable driver outputs. These outputs are high impedance when DE is low. Take RE high and DE low to enter low-power shutdown mode.                              |
| 4   | DI              | Driver Input. With DE high, a low on DI forces non-inverting output low and inverting output high. Similarly, a high on DI forces non-inverting output high and inverting output low.                |
| 5   | GND             | Ground   |
| 6   | A               | Non-Inverting Receiver Input and Non-Inverting Driver Output   |
| 7   | В               | Inverting Receiver Input and Inverting Driver Output   |
| 8   | V <sub>CC</sub> | Positive Supply 4.75V =V <sub>CC</sub> =5.25V  |

### **DEVICE TRUTH TABLES**

### **TRANSMITTING**

| INPUTS |    |    | OUTPUTS  |        |  |
|--------|----|----|----------|--------|--|
| RE     | DE | DI | B/Z      | A/Y    |  |
| X      | 1  | 1  | 0        | 1      |  |
| X      | 1  | 0  | 1        | 0      |  |
| 0      | 0  | X  | High-Z   | High-Z |  |
| 1      | 0  | X  | Shutdown |        |  |

### **RECEIVING**

|                            | OUTPUT |              |          |
|----------------------------|--------|--------------|----------|
| $\overline{R}\overline{E}$ | DE     | RO           |          |
| 0                          | X      | ≥ -0.05V     | 1        |
| 0                          | X      | ≤ -0.2V      | 0        |
| 0                          | X      | Open/shorted | 1        |
| 1                          | 1      | X            | High-Z   |
| 1                          | 0      | X            | Shutdown |

X = Don't care

Shutdown mode, driver and receiver outputs high impedance

### ADM3082/ADM3085/ADM3088

#### DETAILED DESCRIPTION

The ADM3082, ADM3085 and ADM3088 are high-speed RS-485/RS-422 transceivers offering enhanced performance over industry-standard devices All devices in the family contain one driver and one receiver, but there is a choice of performance options. The devices feature fail-safe operation, which means that a logic-high receiver output is *guaranteed* when the receiver inputs are open-circuit or short-circuit, or when they are connected to a terminated transmission line with all drivers disabled (see the section on Fail-Safe Operation).

#### SLEW RATE CONTROL

The ADM3082 features a controlled slew-rate driver that minimize electromagnetic interference (EMI) and reduce reflections caused by incorrectly terminated cables, allowing error-free data transmission rates up to 115kbps (see the section on Reduced EMI and Reflections).

The ADM3085 offers a higher limit on driver output slew-rate, allowing data transmission rates up to 500kbps.

The driver slew rate of the ADM3088 is not limited, offering data transmission rates up to 10Mbps.

### RECEIVER INPUT FILTERING

The receivers of all devices incorporate input hysteresis. In addition, when operating in 115kbps or 500kbps mode, the receivers of the ADM3082 and ADM3085 incorporate input filtering. This enhances noise immunity with differential signals that have very slow rise and fall times, but it does increase propagation delay by 20%.

### HALF-/FULL-DUPLEX OPERATION

The ADM3082, ADM3085, and ADM3088 are dedicated half-duplex devices (driver outputs internally linked to receiver inputs). Figure 29 shows a typical half-duplex connection between two devices.

### THREE-STATE BUS CONNECTION

All the devices have a Driver Enable pin (DE) that enables the driver outputs when taken high or puts the driver outputs into a high-impedance state when taken low. This allows several driver outputs to be connected to an RS-422/RS-485 bus.

Similarly, all the devices have a (active-low) Receiver Enable pin  $(\overline{RE})$ . Taking this low enables the receiver, while taking it high puts the receiver outputs into a high-impedance state. This allows several receiver outputs to be connected to a serial data bus.

#### HIGH INPUT IMPEDANCE

The input impedance of the devices is  $96k\Omega$ , which is 8 times higher than the standard RS-485 load of  $12k\Omega$ . A standard driver can driver 32 standard loads, so up to 256 ADM308X receivers, or a combination of ADM308X and other devices up to 32 unit loads, may be connected to an RS-422/RS485 bus driven by a single driver.

#### SHUTDOWN MODE

All the devices have a low power shutdown mode that is enabled by taking  $\overline{RE}$  high and DE low.

If shutdown mode is not used, the fact that DE is active-high and  $\overline{RE}$  is active-low offers a convenient way of switching the device between transmit and receive, by tying DE and  $\overline{RE}$  together. This is useful, for example, in applications using half duplex operation and where several receiver outputs are connected to a serial bus.

The device is guaranteed not to enter shutdown mode if DE and  $\overline{RE}$  are driven in this way. If DE is low and  $\overline{RE}$  is high for less than 50ns the device will not enter shutdown. If DE is low and  $\overline{RE}$  is high for greater than 600ns, the device is guaranteed to enter shutdown.

#### **FAIL-SAFE OPERATION**

The ADM3082/ADM3085/ADM3088 offer true fail-safe operation while remaining fully compliant with the ±200mV EIA/TIA-485 standard. A logic-high receiver output is guaranteed when the receiver inputs are shorted together or open-circuit, or when they are connected to a terminated transmission line with all drivers disabled. This is done by setting the receiver threshold between -50mV and -200mV. If the differential receiver input voltage (A-B) is greater than or equal to -50mV, RO is logic high. If A-B is less than or equal to -200mV, RO is logic low. In the case of a terminated bus with all transmitters disabled, the receiver's differential input voltage is pulled to 0V by ADM308X family, which results in a logic high with a 50mV minimum noise margin.

#### ENHANCED ESD PROTECTION

All Analog Devices parts incorporate protection against electrostatic discharge (ESD) to protect the devices during handling, assembly and normal operation. In addition, the ADM308X family has enhanced ESD protection up to ±15kV on the receiver inputs and driver outputs (A, B) to protect against severe operational conditions such as line transients, connection and disconnection.

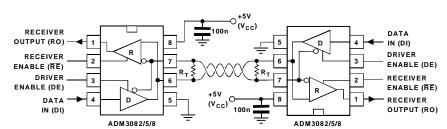


Figure 29. Half-Duplex Configuration for ADM3082, ADM3085 or ADM3088

### **CURRENT LIMIT AND THERMAL SHUTDOWN**

The ADM3082/ADM3085/ADM3088 incorporate two protection mechanisms to guard the drivers against short-circuits, bus contention or other fault conditions. The first is a foldback current-limited output stage that protects the driver against short-circuits over the entire common-mode voltage range. The second is a thermal shutdown circuit that puts the driver outputs into a high-impedance state if the die temperature exceeds a safe limit.

#### REDUCED EMI AND REFLECTIONS

The ADM3082 and ADM3085 incorporate slew-rating limiting in the drivers. This reduces reflections due to incorrect cable termination and minimizes electromagnetic interference (EMI).

Figures 9 to 11 show driver output waveforms and Fourier analyses of 20kHz signals for the three different slew-rate settings. It can be seen that the harmonic content is greatly reduced for the ADM3085 and still further for the ADM3082 (Figures 10 and 9 respectively).



Figure 9 ADM3082 Driver Output Waveform and FFT Plot



Figure 10. ADM3085 Driver Output Waveform and FFT Plot



Figure 11. ADM3088 Driver Output Waveform and FFT Plot

The length of an unterminated stub that can be driven with only minor reflections depends on the rise time of the transmitter. A conservative estimate for this is given by the following equation:

L (metres) =  $t_R$  / 49.2

where  $t_R$  is the transmitter's rise time in ns (multiply result by 3.28 for answer in feet).

For example, the rise time of the ADM3082 is typically 1320ns, which results in acceptable waveforms with stub lengths up to 27 metres. This is not the ultimate limit on unterminated stub length, as a system can still work if the waveformis allowed to settle before sampling the data.

The RS-485/RS-422 standard covers line lengths up to 4000 feet (1219 metres). Driver output and receiver output waveforms for the three slew rate settings, driving a 4000 foot cable, are shown in figures 12 to 14.



Figure 12. Driver Input, Driver Output and Receiver Output Waveforms of ADM3082, Driving 4000ft (1219m) of Cable at 50kHz

### ADM3082/ADM3085/ADM3088



Figure 13. Driver Input, Driver Output and Receiver Output Waveforms of ADM3085, Driving 4000ft (1219m) of Cable at 50kHz



Figure 14. Driver Input, Driver Output and Receiver Output Waveforms of ADM3088, Driving 4000ft (1219m) of Cable at 200kHz

For line lengths in excess of 1220 metres the line should be split into smaller sections with intermediate repeaters.

#### APPLICATIONS

Figures 15 shows a typical application of the device on a half--duplex network. The line should be terminated at both ends to minimize reflections and any stubs off the main line should be kept as short as possible.

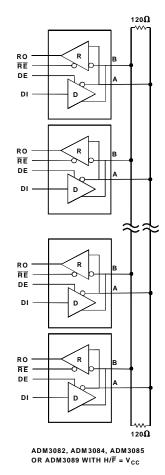
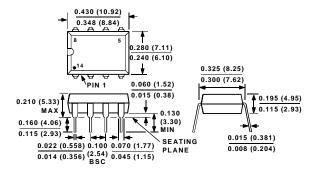


Figure 15. Typical Half-Duplex Network Application

#### **OUTLINE DIMENSIONS**

Dimensions shown in inches and (mm).

### 8-Pin Plastic Dual-In-Line Package (N-8)



### 8-Pin SO Package (R-8)

