

Digitally Controlled Potentiometer (DCP) Evaluation USB Kit

Introduction

The Digital Potentiometer Evaluation USB Kit provides application and design engineers with a tool for evaluating the operation of many kinds of different Digitally Controlled Potentiometers (DCPs). It includes a USB2DCP interface board also called a motherboard, DCP Evaluation Software and a DCP evaluation board also called a DCP Daughter Card. The DCP Evaluation Kit provides a platform for evaluating all functions and features of Digitally Controlled Potentiometers and supports I²C, SPI, UP/DOWN and Push Button interfaces. The two-piece construction, utilizing a motherboard and a daughter card, enables remote control operation of a DCP from PC through USB port.

Installation of the DCP Evaluation Software and USB Drivers

The DCP Evaluation Software and USB drivers have to be installed on a PC running Windows NT/2000/XP/Vista Operating System before connecting the USB2DCP interface board to USB port.

- Insert CD in the CD/DVD drive of the PC. Do not plug in the USB2DCP board yet.
- Run the Setup.exe. If Setup will not start automatically go to Explorer/DVD drive and run Setup.exe manually.
- Click to agree in the license window, then click to install. The installation program will place the DCP Evaluation software in C:\Program Files\Intersil\Intersil_DCP_Comm directory.
- After software has been installed, plug the USB2DCP board into the USB port and let Windows set up a driver for the new hardware. Note, the USB driver for the USB2DCP board is located in C:\ProgramFiles\Intersil\Intersil_DCP_Comm

Overview and Operation of the DCP Evaluation Platform

Hardware Overview

USB2DCP INTERFACE BOARD (MOTHERBOARD)

This board provides the interface between a PC and DCP Evaluation Board (Daughter Card), as shown in Figure 1. A USB cable, with type A and B connectors on each end, is required to plug the board into a PC (schematic of USB2DCP board in Appendix A). The USB2DCP board is powered from the USB port. It contains a microcontroller (U1) with USB interface (J1) for communicating with the PC, and I/O pin connector (J2) to supply power and communicate with the DCP daughter card. The mother board also provides power to the daughter card either from the USB port or from an external power supply through the adjustable voltage regulator (U4). An external power supply can be connected to JP2 (+6V) and JP3 (GND) hookup pins. A JP5 jumper allows the selection between USB or external power. An on-board inverter (U6) generates negative voltage from U4 output. Both positive (VCC) and negative (V-) outputs are controlled through the Graphical User Interface (GUI) of DCP Evaluation Software.

The U2 MUX minimizes the number of J2 pins by mapping selected interface to the daughter card connectors J2 and JP6. The J2 and JP6 mapping is fully compatible with previous generation of DCP evaluation boards, e.g. XLABVIEW01 board. The voltage at VINO, VIN1, VIN2 and VIN3 pins of JP8 can be measured through the onboard ADC. Usually these inputs are wiper outputs from the daughter card. Note, the ADC can measure only positive signals from 0V to 5.5V; negative inputs are blocked out by Schottky diodes D3~D6.

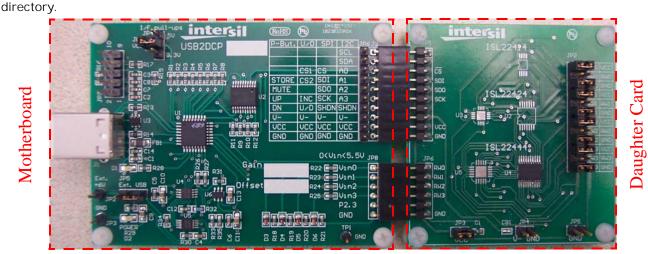
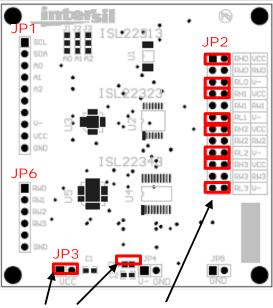


FIGURE 1. DCP EVALUATION PLATFORM

DCP Evaluation Board (Daughter Card)

Each DCP daughter card is different, but typically contains one DCP device, one or two connectors to attach to the mother board and a DCP terminal header allowing different terminal configurations, such as connection to VCC, GND, V- or to each other.

For example, the ISL223x3 daughter card, which is shown in Figure 2, has a JP1 male connector to match with the J2 female connector of the mother board to provide VCC, V-, GND and I²C interface signals to the DCP. The JP6 male connector provides wiper outputs back to the mother board through the matching JP8 to be measured and displayed on the GUI, or measured from the terminal header JP2. The DCP terminals RHi, RWi and RLi can be left open, or connected to VCC, V-, each other or external circuitry by using jumpers. The VCC power is supplied through the JP3 jumper from the motherboard. The JP3 header also allows measuring power consumption of the DCP by connecting an ammeter between the JP3.1 and JP3.2 pins instead of jumper, or use an external power supply connected to JP3.2. An external negative power supply can be used by connecting to JP4 header. In this case, the CB1 shunt should be removed from the board.



Remove VCC and CB1 shunts if an external VCC and V- supplies are used Shunts installed for VCC and V- Terminal's Voltages

FIGURE 2. ISL223x3 DCP DAUGHTER CARD

DCP Evaluation Software

Software Overview

When the DCP Evaluation Software starts, the "Select DCP Type" window appears and the user can select the appropriate interface from a pull down menu as shown in

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Figure 3. Select either I²C, SPI, Up/Down or Push Button interface.

The Product Demonstration GUI automatically appears when the interface is selected as shown in Figure 4. It starts up with the Manual Setup window, where the user can choose a number of taps, number of DCPs in package (i.e. single, dual or quad), slave address, address pin settings A0~A4, enable or disable VCC and V- outputs etc. There are convenient initial setups available from the Device Select pull-down menu, located in menu bar, -> Parameter file.

All executable functions are separated by individual frames that provide more visibility and "easy to use" convenience. All "white text boxes" have either a pulldown menu, selectable or type in capability. Type in capability means that the user can type in a new value, hit the Enter button on the keyboard, or Write/Read software button, and this data will be executed by the software. "Gray boxes" are read only.

The interface clock frequency for the I²C and SPI interfaces is selectable from a pull-down menu as well.

VCC Control

In order to start communication with the DCP, the onboard voltage regulator has to be turned on. The regulator control, i.e. VCC Control, is located in the upper left corner of the GUI. There are several VCC options available in the pull-down menu from fixed to user-adjustable. By default VCC is set to 5V. The negative V- voltage tracks the VCC or can be turned off.

The VCC level is automatically sampled by an on-board analog-to-digital converter (ADC) every time the VCC is turned on or off, or can be manually sampled by pushing the Sample VCC button.

The ADC requires calibration in order to receive the correct VCC readings. The calibration procedure is shown in the following steps:

- 1. Set the VCC level to 5.0V. Use an external voltmeter to measure the actual VCC output and record its reading as Measure1. Write down the ADC reading as Read1.
- 2. Set the VCC level to 3.0V. Write down the voltmeter reading as Measure2 and the ADC reading as Read2.
- 3. Calculate the ADC Gain as

$$Gain = 2 \times \frac{Measure1 - Measure2}{Read1 - Read2}$$
(EQ. 1)

- 4. Type in the new Gain value and repeat the measurement starting at step 1.
- 5. The ADC Offset = Measure1 Read1.The calibrated Gain and Offset values can be written down directly on the USB2DCP mother board and should be used for correct readings.

🤳 Intersil DCP Evaluation Softw	are		- 🗆 ×
About			
USB Init 📄 Attach 📒			
	Select DCP Type		
	DCP Type Selections	•	
	DCP Type Selections	X	
	12C		
	SPI		
	Up /Down		
	Push Button		

NOTE: Green lights indicate that USB2DCP board is attached and communication is established. FIGURE 3. DCP TYPE SELECT WINDOW

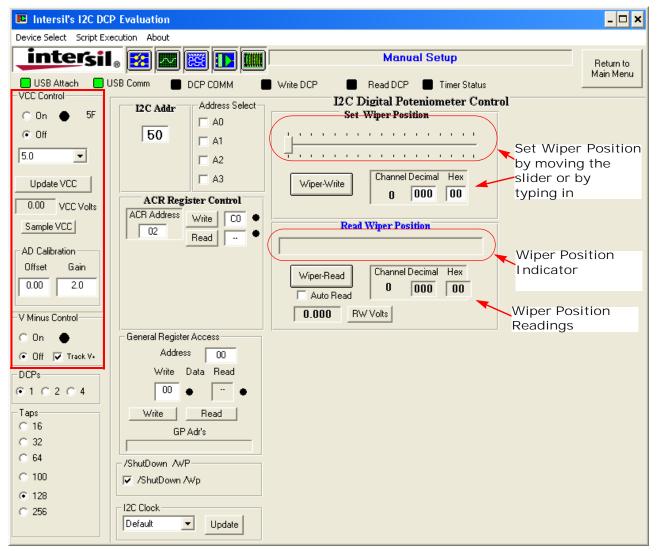


FIGURE 4. I²C INTERFACE PRODUCT EVALUATION WINDOW, MANUAL SETUP

Set Wiper Position in I²C and SPI interfaces

The wiper position can be set by moving the slider or by typing in a hex or decimal value in the corresponding text box, see Figure 4. Software will automatically read back the wiper register if Auto Read box is checked out. Each DCP channel has its own wiper control and read capability.

Set Wiper Position in Up/Down and Push-Button Interfaces

In order to move the wiper in Up or Down direction, type in the number of counts in corresponding text box as shown in Figure 5 and push the Up or Down button.

Script Execution

The DCP Evaluation software allows multiple commands to be executed, that had been written in sequence in a script file. A script file is a text file written in Notepad or other simple text editing programs. There are some examples of script files provided for your convenience, that can be opened by following Script Execution > File > Open Script File from the menu bar. Script files can be executed only in I^2C and SPI interface product windows. Script execution is not supported for Up/Down and Pushbutton DCPs.

I²C Script File

The structure of the command line for the I²C interface is a Slave Address followed by a Register Address, Write Data, Read Data and Comments. The data in the command line is separated by a comma without spacing. All spaces will be ignored.

The Slave Address should be written once at the beginning of the command sequence, starting with an acute symbol and letter "A", e.g. 'AAO for address AO or 'A50 for address 50. This slave address will be used for all

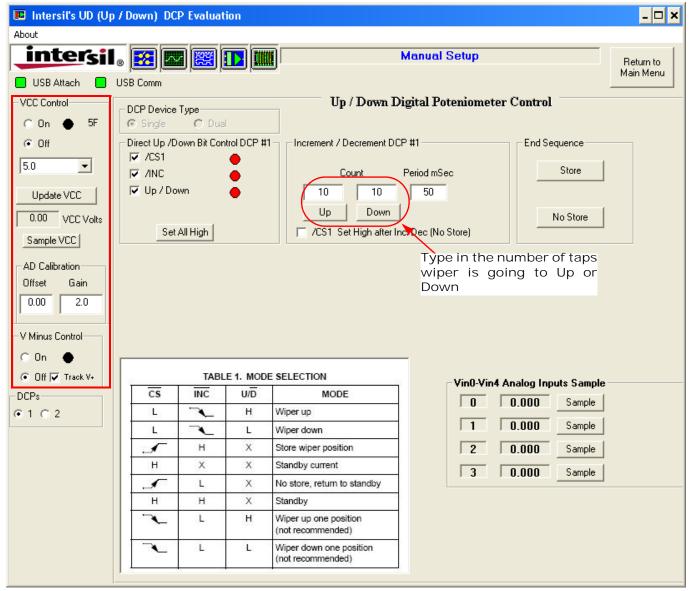


FIGURE 5. UP/DOWN INTERFACE PRODUCT EVALUATION WINDOW

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lines below in the sequence until the next address line, if a script file is written to communicate with several DCPs on the bus. Comments must start with the number sign "#" followed by any ASCII symbols.

The Write Data or Read Data can be omitted for Read only or Write only operation. For example:

- 00,55, #write 55 to address 0 without reading back
- 00,55,55 #write 55 to address 0, then read back from address 0. The read data will be compared with 55
- 00, ,55 #read from address 0 and compare result with 55

The wait command starts with the acute symbol followed by a letter "w" and a number that represents waiting time before execution of the next command in milliseconds. For example, 'w1000 #delay for 1000ms. The script execution window is shown in Figure 6.

Successfully executed commands are highlighted by a green color, while non successful command or unexpected returned values are highlighted by a red color. A script file can be executed at once, or put in a loop by pressing the "Run All Steps" or "Loop Count" buttons in the upper right corner of the Script Execution Window. The actual read data can be stored in an updated script file by specifying a path and press the "Write to Disk" button.

IC - Script Load / Execute						Script Control	Reload	
50 USB						Done of	14 Reload	
Update Expected Read Data & Save Script to File						Run All Steps	Loop Cont 🔲 Abort On fail	
						Read Ope	erations Loop Count Last Load	
						Total Pass	Fail East 2000	
Browse Write to Disk Append						5 4	1 7 16:25:55	
	ipt Status-					- Interrupt Servic	ce Steps	
_	ample 🔽 ct LastRe		Sample le Disal	hla Diata	ct Step	Start		
000								
1000				_		,		
Line	12C Adr	Reg Adr	Data_Wr	Data_Rd	Act_Rd	Operation	Comment	
001 002	50 50					NOP NOP	#ISL22316 DCP Step and Wait #050708 rgrist	
002	50					NOP	Script File has a blank line	
003	50					Cmd:Set I2C Adr	# Default Address 50	
004	50	02	CO	CO	C0	Reg:1 W:1 R:1	# Write to ACR. Set WR active. Shutdown is off	
005	50	02	7F	7F	ZE ZE	Reg:1 W:1 R:1	# Write to Wiper set to max and read back	
007	50	00	ri		Delay 1000	Cmd:Delay:1000: mSec		
008	50	00	00	00	00	Reg:1 W:1 R:1	# Wait one second # Write to Wiper Set to Min and read back	
009	50	00	00	00	Delay 1000	Cmd:Delay:1000: mSec		
003	50	00	54		Delay 1000	Reg:1 W:1	# write to reg.0 data 5A	
010	50	00		5A	5A	Reg:1 R:1	# write to regio data and # read only command reads from address 0 and compared with 5A	
012	50	00	00			Reg:1 W:1	# read only command reads nonn address 0 and compared with 3A # write only command writes 0 to address 0	
012	50	00	00	5A	00	Reg:1 R:1	# read address 0 and compare with 5A	
014	50	00				NOP	Script File has a blank line	
014	50					NOI	Sonper lie has a blank line	

FIGURE 6. THE ISL22316 SCRIPT EXECUTION EXAMPLE

SPI Script File

The structure of the command line for SPI interface is slightly different than for I²C. The first executable command should be an acute symbol followed by letters "SPIO", e.g. 'SPIO. All the following commands start with the comma followed by data bytes. The total number of data bytes is limited to 32 for this application. Comments must start with the number sign "#" followed by any ASCII symbols. The acute symbol followed by the ENDM, e.g. 'ENDM, indicates the end of the script.

Command examples for ISL224x4 family (2 byte Write, 4 byte Read operation), see Figure 7.

- ,60C0 #Write C0h into the ACR register to set volatile #operation
- ,C05A #Write 5Ah into reg. 0
- ,80000000, XXXXX5A #Read from reg. 0 and compare #with the anticipated data of 5Ah.

where the "X" symbol represents ignored by test.

Command examples for ISL224x6 family (3 byte Write, 3 byte Read operation) are as follows:

- ,50C8C0 #Write C0h into the ACR register, reg. 8, to set #volatile operation
- ,50C07F # Write 7Fh into reg. 0
- ,50B000,XXXX7F #Read back from reg. 0 and compare with #the anticipated data of 7Fh

The script file can be used for programming DCPs in daisy chain configuration. The DCP Evaluation software supports up to 8 daisy chained devices. The example of daisy chain programming is shown in Figure 8. Note, not all SPI DCPs have daisy chain capability.

🀜 [ISL224x4_Test1.txt] Script IC Send / Receive 🗕 🗆 🗙								
File								
IC - Script Load / Execute 50 USB 1 Update Expected Read Data & Save Script to File					Script Control Done of Run All Steps	Done of 15 Reload		
Browse Write to Disk Append					Total Pass			
Interrupt Status ■ Sample Enable Sample Inter Expect LastRead Enable Disable Detect Step 0000						End Executing		
Line		Data_Wr	Data_Rd	Act_Rd	Operation	Comment		
001 002	SPI				NOP Cmd:Set SPIComm	#ISL224x4 DCP Step. NV write & Wait		
003		60C0			W:2	# Write to ACR - Set Volatile, Shutdown is off		
004		COFF			W:2	# Set Wiper to Max (FFh)		
005		80000000	XXXXXFF	XXXXXXFF	W:4 R:4	# Read back data XXXXXFF from reg.0		
006		C000			W:2	# Set Wiper to Min (00h)		
007		80000000	XXXXX00	XXXXXX00	W:4 R:4	# Read back data XXXXX00 from reg.0		
008		C05A			W:2	# write 5Ah to reg.0		
009		80000000	XXXXX5A	XXXXX5A	W:4 R:4	# Read back data XXXXXX5A from reg.0		
010		6040			W:2	# Write to ACR - Set Non-volatile, shutdown is off		
011		C455			W:2	# Write 55h to NV reg.4		
012				Delay 100	Cmd:Delay :100: mSec	# Wait 100 msec		
013		84000000	∞∞∞8455	XXXX8455	W:4 R:4	# Read back data >>>>>>>5 from NV reg.4		
014		60C0			W:2	# Write to ACR - Set Volatile, Shutdown is off		
015					Cmd: End Main			
,								

FIGURE 7. THE ISL224X4 SCRIPT EXECUTION EXAMPLE

A [ISL22414_3DCP_daisy_chain_Test1.txt] Script IC Send / Receive									
50 Update E Brow Interrupt	vse	ad Data & Save Scri Write to Disk	Append	Tota	Read Operations	Reload Abort On fail cop Count 15:52:33 Executing			
0000									
Line		Data_Wr	Data_Rd	Act_Rd	Operation	Comment			
001					NOP	#3 ISL22414 daisv chain programming			
002	SPI				Cmd:Set SPI Comm				
003		60C060C060C0			W:6	# Write to ACR, Set volatile operation, Shutdown is off			
004		COFFC0AAC055			W:6	# Set wiper of DCP2 to FF, DCP1 to AA and DCP0 to 55			
005		800080008000			W:6	# Send Read command to the DCPs			
006		000000000000	XXFFXXAAXX55	# Get data back from reg.0					
007					Cmd: End Main				
4						Þ			

FIGURE 8. THE THREE DAISY CHAINED ISL22414 PROGRAMMING EXAMPLE

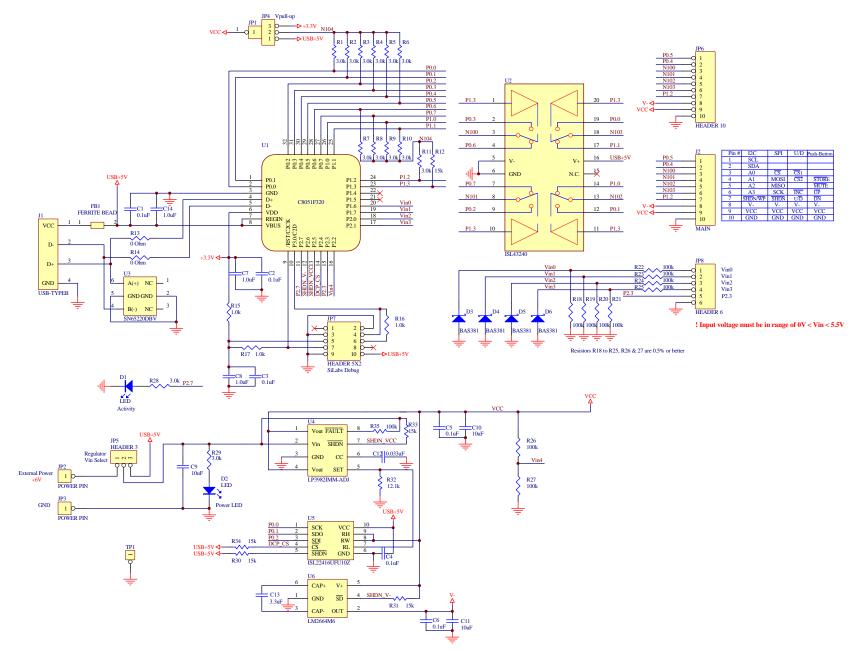
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Appendix A

USB2DCP Board Schematic



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