

# UBA2080; UBA2080A; UBA2081

## Half-bridge driver IC

Rev. 3 — 18 June 2012

Product data sheet

## 1. General description

The UBA2080(A) and UBA2081 are high voltage monolithic integrated circuits made using the latch-up free Silicon-On-Insulator (SOI) process. The circuit is designed for driving MOSFETs in a half-bridge configuration.

## 2. Features and benefits

- Latch-up free and robust half bridge driver
- Output driver capability:  $I_{O(sink)} = 400\text{ mA}$  and  $I_{O(source)} = 200\text{ mA}$
- Maximum frequency 800 kHz
- UBA2080:
  - ◆ Outputs in phase with HIN and LIN inputs
  - ◆ Overlap protection
- UBA2081:
  - ◆ Outputs in phase with CLK input
  - ◆ Adjustable dead-time
  - ◆ Low active shutdown input

## 3. Applications

- Driver (via external MOSFETs) for any kind of load in a half-bridge configuration
- UBA2080A:
  - ◆ Selectable between UBA2080 and UBA2081 functionality
  - ◆ Thermally enhanced package for high frequency operation.

## 4. Ordering information

Table 1. Ordering information

Type number	Package		
	Name	Description	Version
UBA2080P	DIP8	plastic dual in-line package; 8 leads	SOT97-1
UBA2081P			
UBA2080T	SO8	plastic small outline package; 8 leads	SOT96-1
UBA2081T			
UBA2080AT	SO14	plastic small outline package; 14 leads	SOT108-1



## 5. Block diagram

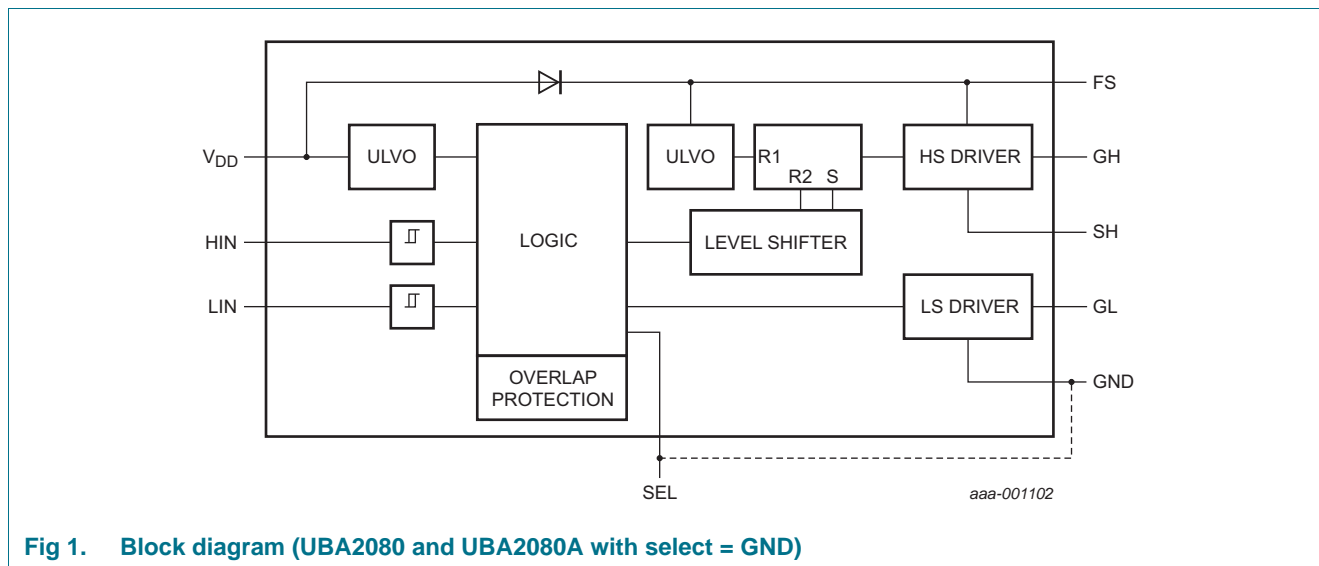


Fig 1. Block diagram (UBA2080 and UBA2080A with select = GND)

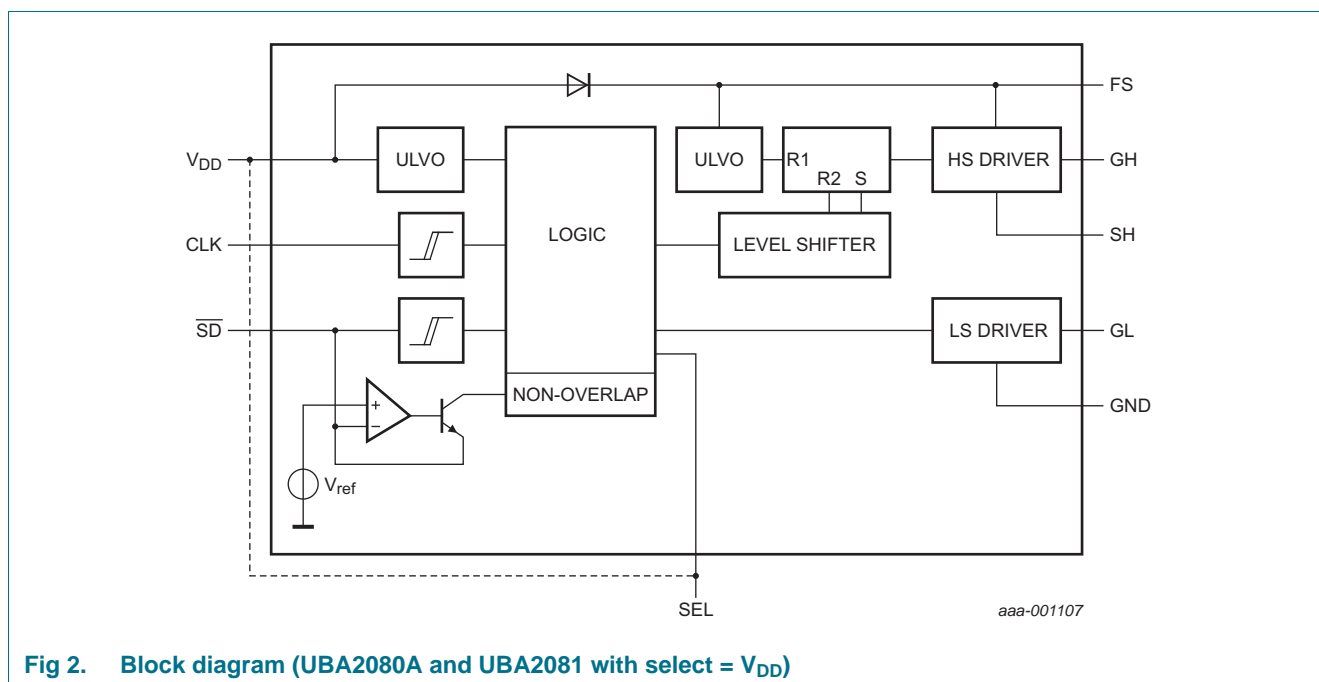
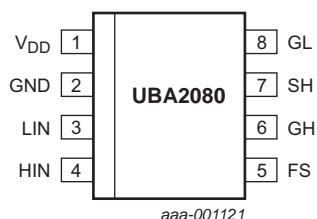


Fig 2. Block diagram (UBA2080A and UBA2081 with select =  $V_{DD}$ )

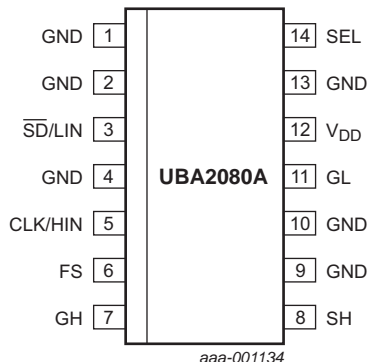
Refer to [Figure 7](#) and [Figure 8](#) for detailed information on the required application components.

## 6. Pinning information

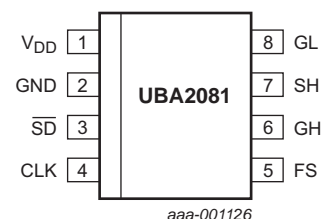
### 6.1 Pinning



**Fig 3. UBA2080: Pin configuration DIP8 and SO8 package**



**Fig 4. UBA2080A: Pin configuration SO14 package**



**Fig 5. UBA2081: Pin configuration DIP8 and SO8 package**

### 6.2 Pin description

**Table 2. Pin description UBA2080/UBA2081 DIP8 and SO8**

Symbol	Pin		Description
	UBA2080 (DIP8/SO8)	UBA2081 (DIP8/SO8)	
V <sub>DD</sub>	1		IC supply
GND	2		IC ground and low-side driver return
LIN	3	-	low-side driver logic input
$\overline{\text{SD}}$	-	3	low active analog shutdown input and non-overlap time setting
HIN	4	-	high-side driver logic input
CLK	-	4	clock logic input
FS	5		floating supply voltage
GH	6		high-side MOSFET gate
SH	7		high-side MOSFET source
GL	8		low-side MOSFET gate

**Table 3. Pin description UBA2080AT (SO14)**

Symbol	Pin	Description
GND	1, 2, 4, 9, 10, 13	IC ground and low side driver return
$\overline{\text{SD}}$ /LIN	3	low-side driver logic input or low active shutdown and non-overlap time setting
CLK/HIN	5	high-side driver logic input or clock logic input
FS	6	floating supply voltage
SH	8	high-side MOSFET source

Table 3. Pin description UBA2080AT (SO14) ...continued

Symbol	Pin	Description
GH	7	high-side MOSFET gate
GL	11	low-side MOSFET gate
V <sub>DD</sub>	12	IC supply
SEL	14	select UBA2080 or UBA2081 functionality; only connect to GND or V <sub>DD</sub>

## 7. Functional description

### 7.1 Start-up state

The IC enters the start-up state when the supply voltage on pin V<sub>DD</sub> increases. In the start-up state, the high-side power transistor is non-conducting and the low-side power transistor is switched on. The internal circuit is reset and the capacitor on the bootstrap pin FS is charged. The start-up state is defined until the value of V<sub>DD</sub> = the V<sub>DD(start)</sub> value. After which the IC switches to the oscillation state.

The circuit enters the start-up state again when the voltage on pin V<sub>DD</sub> < V<sub>DD(stop)</sub>.

### 7.2 UBA2080 oscillation state

In the oscillation state, the output voltage of the GL and GH drivers depend on the logical signals HIN and LIN (see [Table 4](#)).

To prevent cross conduction in the half-bridge MOSFETs, the combination HIN = LIN = 1 is not allowed. Both GL and GH are LOW under this condition.

Table 4. UBA2080 Logic table

State	HIN	LIN	GH	GL
Start-up	-	-	LOW	HIGH
Oscillation	0	0	LOW	LOW
Oscillation	0	1	LOW	HIGH
Oscillation	1	0	HIGH	LOW
Oscillation	1	1	LOW	LOW

### 7.3 UBA2081 oscillation state

In the oscillation state, the output voltage of the GL and GH drivers depend on the logical signals CLK and SD (see [Table 5](#)).

Table 5. UBA2081 Logic table

State	CLK	SD	GH	GL
Start-up	-	-	LOW	HIGH
Oscillation	0	0	LOW	HIGH
Oscillation	1	0	HIGH	LOW
Oscillation	0	1	LOW	LOW
Oscillation	1	1	LOW	LOW

## 7.4 UBA2081 non-overlap time

The external resistor ( $R_{SD}$ ) on pin SD sets the non-overlap time of the UBA2081. The relationship between this resistor value and actual dead-time is listed in [Figure 6](#).

It is essential to add a 10 nF to 100 nF decoupling capacitor across  $R_{SD}$  to ensure a noise immune dead-time system.

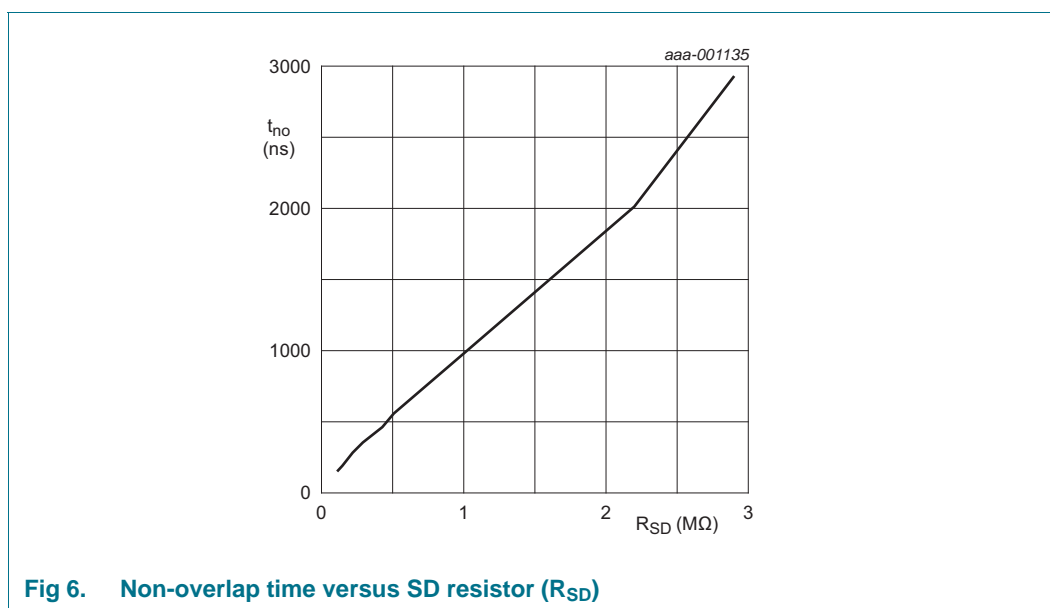


Fig 6. Non-overlap time versus SD resistor ( $R_{SD}$ )

## 7.5 UBA2081 shutdown protection

When the voltage at pin  $\overline{SD}$  is pulled below  $V_{IH}$ , the internal sink drivers of the pins GL and GH are immediately enabled to switch off the external power MOSFETs.

The shutdown comparator has a hysteresis of  $V_{hys}(\overline{SD})$  to avoid multiple switching.

Preferably, pin  $\overline{SD}$  is pulled low via a collector of a transistor (see application schematic) to avoid loading of this pin (Influences the non-overlap time settings) at normal operation.

## 7.6 UBA2080 overlap protection

The internal logic takes care that the GL driver and GH driver are both set to LOW in this situation to avoid that  $HIN = LIN = 1$  causes a cross current in the external half-bridge.

## 7.7 UBA2080A select function

Pin SEL enables the selection of either the UBA2080 or the UBA2081 functionality.  $SEL = 0$  gives the UBA2080 functionality.  $SEL = V_{DD}$  gives the UBA2081 functionality.

## 8. Limiting values

**Table 6. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD</sub>	supply voltage	nominal	0	15.5	V
V <sub>FS</sub>	voltage on pin FS		V <sub>SH</sub>	V <sub>SH</sub> + 15.5	V
V <sub>SH</sub>	voltage on pin SH	source high-side MOSFET	−3	+600	V
		t < 1 μs	−14	+600	V
V <sub>i(HIN)</sub>	input voltage on pin HIN	logic input for high-side driver	0	15.5	V
V <sub>i(LIN)</sub>	input voltage on pin LIN	logic input for low-side driver	0	15.5	V
V <sub>i(SEL)</sub>	input voltage on pin SEL		0	15.5	V
V <sub>CLK</sub>	voltage on pin CLK	logic input for output drivers	0	15.5	V
V <sub>i(SD)</sub>	input voltage on pin SD	logic input for output drivers and analog input for non-overlap setting	0	15.5	V
SR	slew rate	on pin SH; repetitive	−6	+6	V/ns
T <sub>j</sub>	junction temperature		−40	+150	°C
T <sub>amb</sub>	ambient temperature		−40	+150	°C
T <sub>stg</sub>	storage temperature		−55	+150	°C
V <sub>ESD</sub>	electrostatic discharge voltage	human body model:	[1]		
		pins FS, GH and SH	-	1	kV
		pins V <sub>DD</sub> , HIN, LIN, SD, CLK, SEL	-	2	kV
		machine model:	[2]		
		all pins	-	250	V

[1] In accordance with the Human Body Model (HBM): equivalent to discharging a 100 pF capacitor through a 1.5 kΩ series resistor.

[2] In accordance with the Machine Model (MM): equivalent to discharging a 200 pF capacitor through a 1.5 kΩ series resistor and a 0.75 μH inductor.

## 9. Thermal characteristics

**Table 7. Thermal characteristics**

Symbol	Parameter	Conditions	Typ	Unit
<b>SO8</b>				
R <sub>th(j-a)</sub>	thermal resistance from junction to ambient	in free air	[1] 160	K/W
<b>SO14 and DIP8</b>				
R <sub>th(j-a)</sub>	thermal resistance from junction to ambient	in free air	[1] 100	K/W

[1] In accordance with IEC 60747-1.

## 10. Characteristics

**Table 8. Characteristics**

$T_j = 25\text{ }^{\circ}\text{C}$ ; all voltages are measured with respect to SGND;  $V_{DD} = 12.8\text{ V}$ ; positive currents flow into the IC.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
<b>High-voltage supply</b>						
$I_{leak}$	leakage current	FS = GH = SH = 600 V	-	-	10	$\mu\text{A}$
<b>Start-up state</b>						
$I_{VDD}$	current on pin $V_{DD}$		420	520	620	$\mu\text{A}$
$V_{DD(start)}$	start supply voltage		11	12	13	V
$V_{DD(stop)}$	stop supply voltage		8	8.5	9	V
$V_{DD(hys)}$	hysteresis of supply voltage	start-to-stop	3	3.5	4	V
<b>Pin LIN input</b>						
$V_{IH}$	HIGH-level input voltage		1.6	2.2	2.8	V
$V_{hys(LIN)}$	hysteresis voltage on pin LIN		-	400	-	mV
$I_{I(LIN)}$	input current on pin LIN		-	0	1	$\mu\text{A}$
<b>Pin HIN input</b>						
$V_{IH}$	HIGH-level input voltage		1.6	2.2	2.8	V
$V_{hys(HIN)}$	hysteresis voltage on pin HIN		-	400	-	mV
$I_{I(HIN)}$	input current on pin HIN		-	0	1	$\mu\text{A}$
<b>Pin CLK input</b>						
$V_{IH}$	HIGH-level input voltage		2.7	-	-	V
$V_{IL}$	LOW-level input voltage		-	-	0.8	V
$I_{I(CLK)}$	input current on pin CLK		-	0	1	$\mu\text{A}$
<b>Pin SD input</b>						
$V_{IH}$	HIGH-level input voltage	to activate shutdown	1.6	2.2	2.8	V
$V_{hys(SD)}$	hysteresis voltage on pin SD		-	400	-	mV
$t_{no}$	non-overlap time	$R_{SD} = 100\text{ k}\Omega$ ; typical minimum	-	140	-	ns
		$R_{SD} = 3\text{ M}\Omega$ ; typical maximum	-	2.4	-	$\mu\text{s}$
<b>Pin SEL input</b>						
$I_{I(SEL)}$	input current on pin SEL		-	0	1	$\mu\text{A}$
<b>gate drivers</b>						
$I_{O(source)}$	output source current	$V_{FS} = V_{VDD} = 12\text{ V}$ ; $V_{SH} = 0\text{ V}$ ; $V_{GH} = V_{GL} = 8\text{ V}$	-	200	-	mA
$I_{O(sink)}$	output sink current	$V_{FS} = V_{VDD} = 12\text{ V}$ ; $V_{SH} = 0\text{ V}$ ; $V_{GH} = V_{GL} = 4\text{ V}$	-	400	-	mA
$V_{d(bs)}$	bootstrap diode voltage	$I_{d(bs)} = 20\text{ mA}$	-	2.3	-	V
$V_{UVLO}$	undervoltage lockout voltage	reset	3.6	4.2	4.8	V
$I_{FS}$	current on pin FS	$V_{FS} = V_{VDD} = 12\text{ V}$ ; $V_{SH} = 0\text{ V}$	27	32	37	$\mu\text{A}$
<b>Timing</b>						
$t_{PD}$	propagation delay	UBA2080; matching; $C_{(GL)} = C_{(GH)} = 0$ , propagation time difference between GL and GH.	-	50	-	ns

**Table 8. Characteristics ...continued**  
*T<sub>j</sub> = 25 °C; all voltages are measured with respect to SGND; V<sub>DD</sub> = 12.8 V; positive currents flow into the IC.*

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t <sub>PD(LIN-GL)</sub>	propagation delay from LIN to GL	UBA2080; C <sub>(GL)</sub> = 0 pF	-	240	-	ns
t <sub>PD(HIN-GH)</sub>	propagation delay from HIN to GH	UBA2080; C <sub>(GH)</sub> = 0 pF	-	180	-	ns
f <sub>max</sub>	maximum frequency		800	-	-	kHz

11. Application information

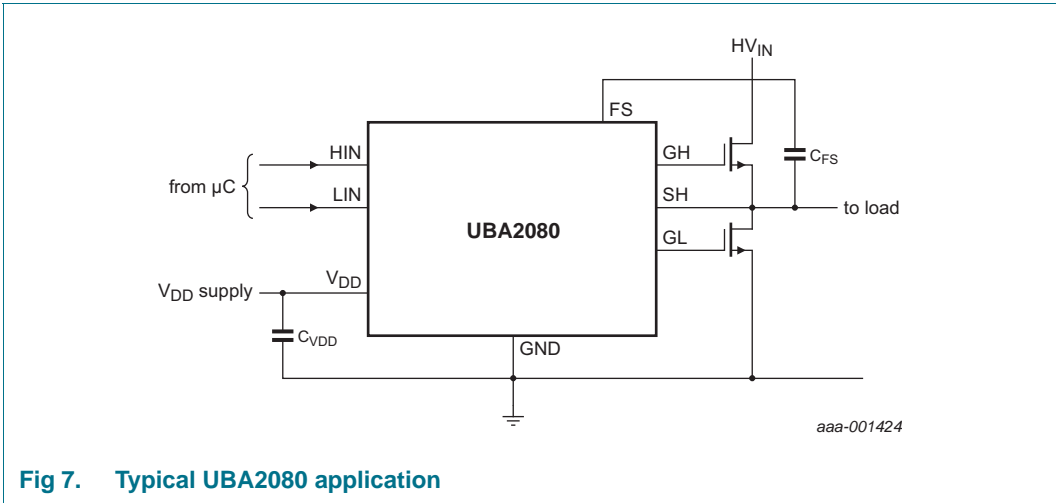


Fig 7. Typical UBA2080 application

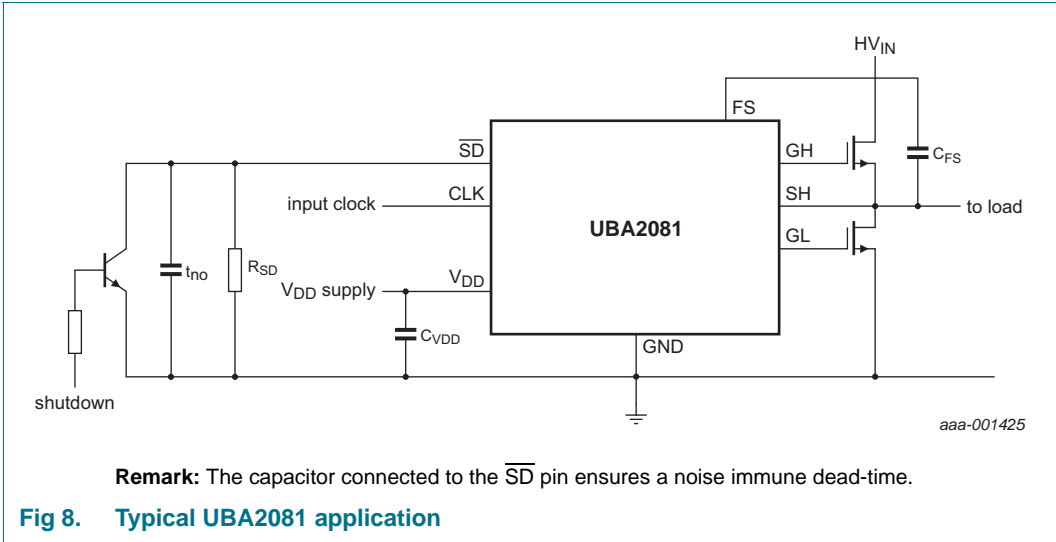


Fig 8. Typical UBA2081 application



12. Package outline

SO8: plastic small outline package; 8 leads; body width 3.9 mm SOT96-1

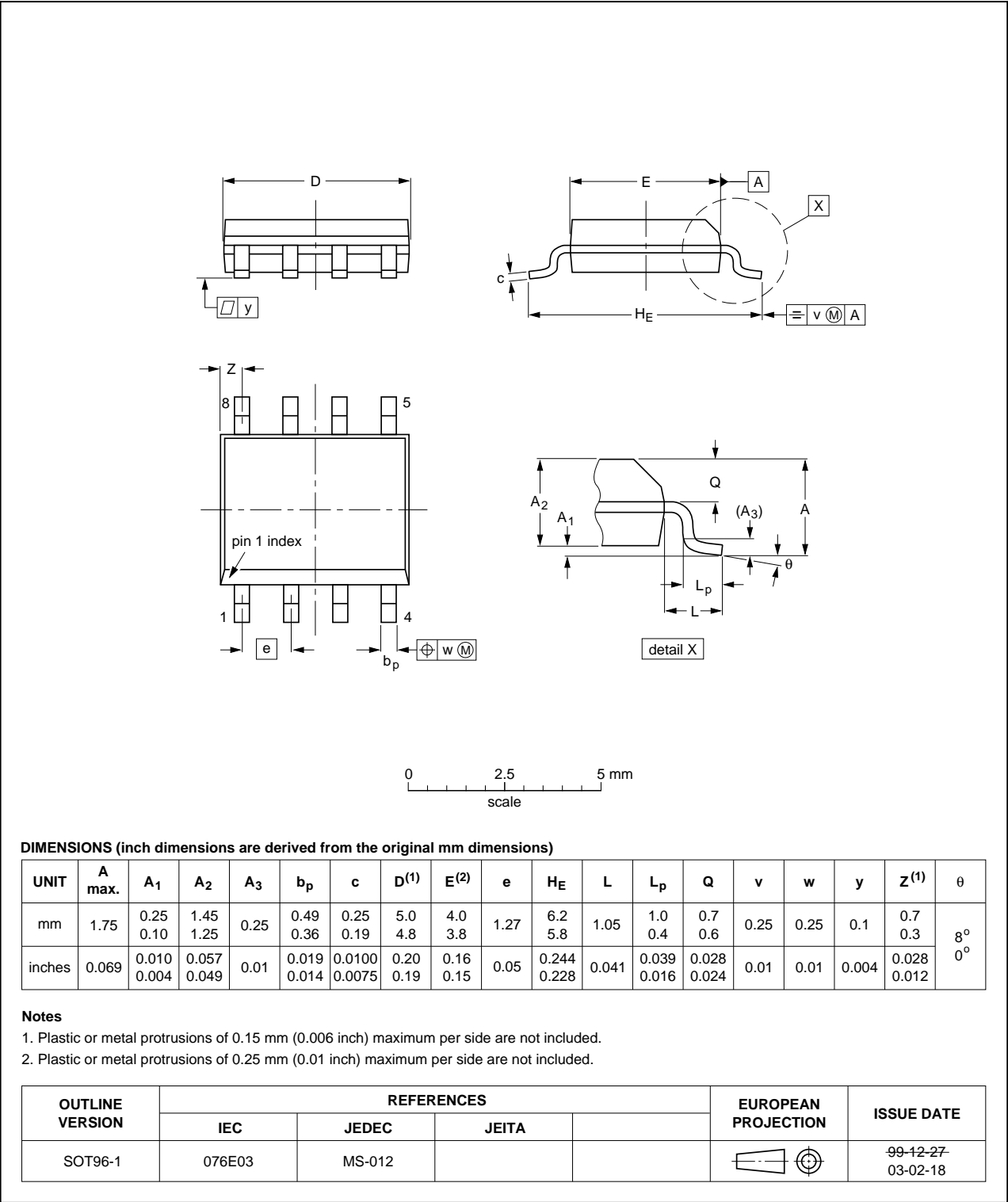


Fig 9. Package outline SOT96-1 (SO8)

DIP8: plastic dual in-line package; 8 leads (300 mil)

SOT97-1

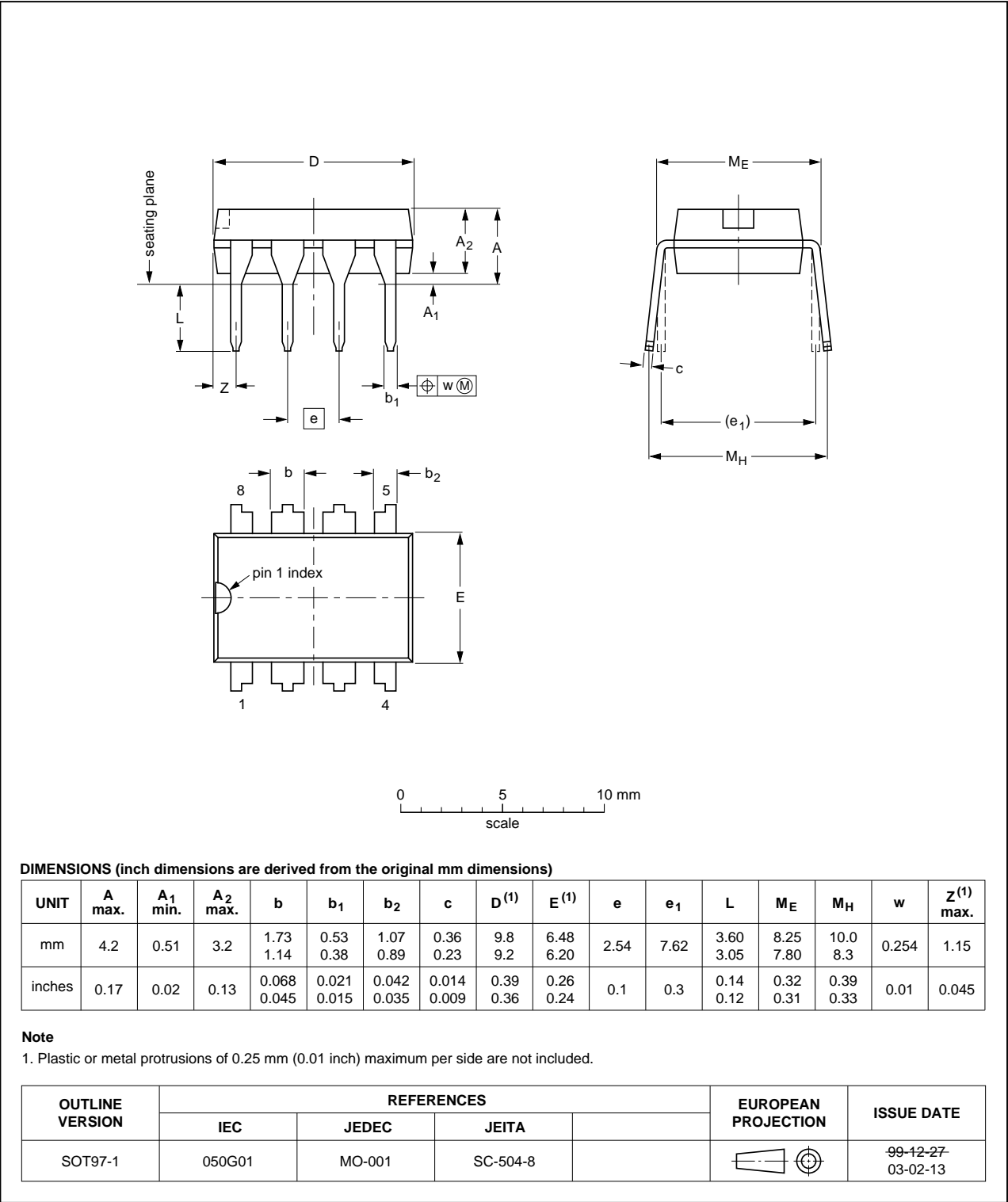


Fig 10. Package outline SOT97-1 (DIP8)

SO14: plastic small outline package; 14 leads; body width 3.9 mm

SOT108-1

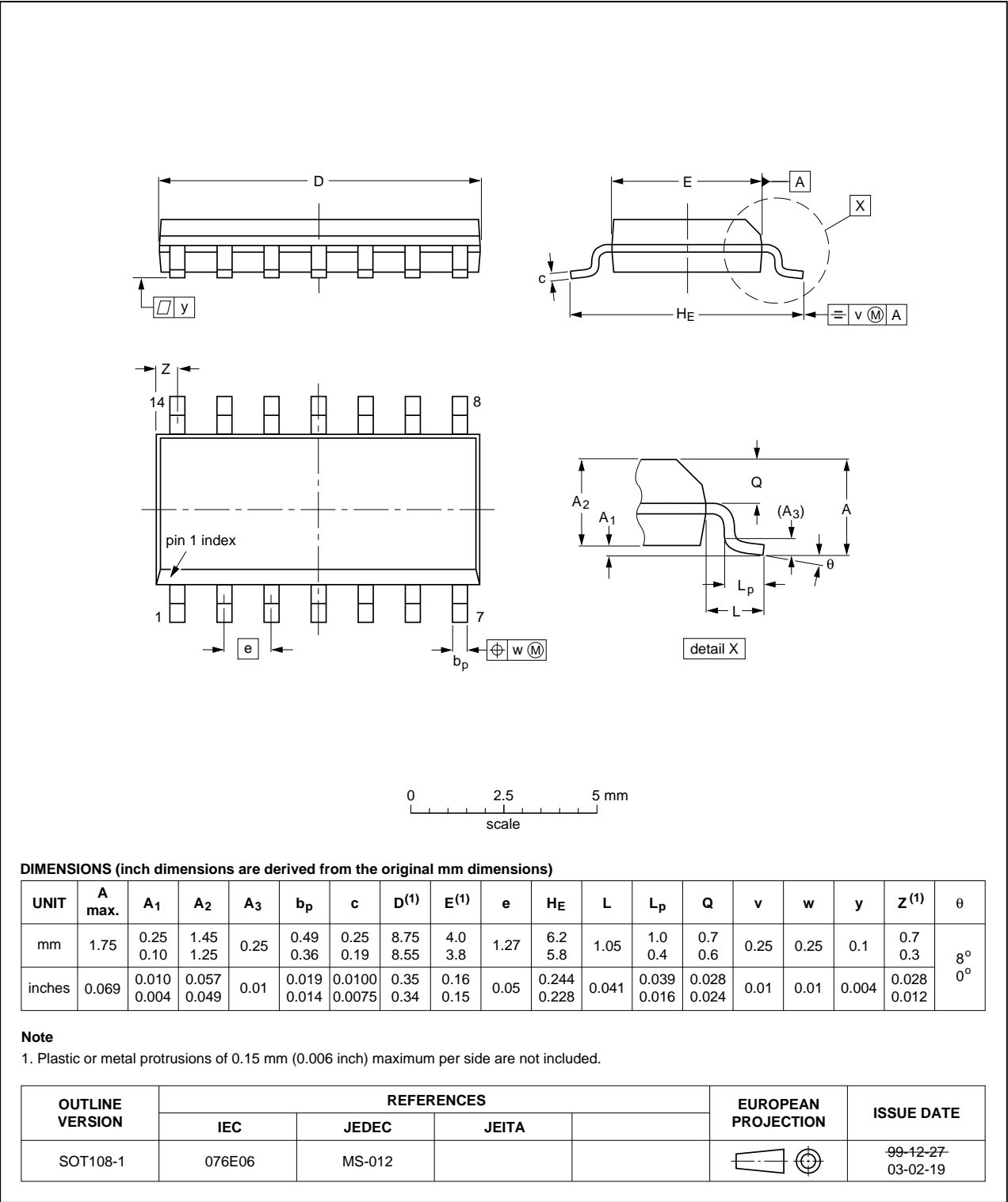


Fig 11. Package outline SOT108-1 (SO14)

## 13. Revision history

**Table 9.** Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
UBA2080_UBA2081 v.3	20120618	Product data sheet	-	UBA2080_UBA2081 v.2
Modifications:	<ul style="list-style-type: none"><li>• Data sheet status changed from Preliminary to Product.</li><li>• <a href="#">Table 6 "Limiting values"</a> has been updated.</li></ul>			
UBA2080_UBA2081 v.2	20120426	Preliminary data sheet	-	UBA2080_UBA2081 v 1.1
UBA2080_UBA2081 v.1.1	20111206	Objective data sheet	-	UBA2080_UBA2081 v.1
UBA2080_UBA2081 v.1	20111116	Objective data sheet	-	

## 14. Legal information

### 14.1 Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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## 16. Contents

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<b>1</b>	<b>General description</b> .....	<b>1</b>
<b>2</b>	<b>Features and benefits</b> .....	<b>1</b>
<b>3</b>	<b>Applications</b> .....	<b>1</b>
<b>4</b>	<b>Ordering information</b> .....	<b>1</b>
<b>5</b>	<b>Block diagram</b> .....	<b>2</b>
<b>6</b>	<b>Pinning information</b> .....	<b>3</b>
6.1	Pinning .....	3
6.2	Pin description .....	3
<b>7</b>	<b>Functional description</b> .....	<b>4</b>
7.1	Start-up state .....	4
7.2	UBA2080 oscillation state .....	4
7.3	UBA2081 oscillation state .....	4
7.4	UBA2081 non-overlap time .....	5
7.5	UBA2081 shutdown protection .....	5
7.6	UBA2080 overlap protection .....	5
7.7	UBA2080A select function .....	5
<b>8</b>	<b>Limiting values</b> .....	<b>6</b>
<b>9</b>	<b>Thermal characteristics</b> .....	<b>6</b>
<b>10</b>	<b>Characteristics</b> .....	<b>7</b>
<b>11</b>	<b>Application information</b> .....	<b>8</b>
<b>12</b>	<b>Package outline</b> .....	<b>9</b>
<b>13</b>	<b>Revision history</b> .....	<b>12</b>
<b>14</b>	<b>Legal information</b> .....	<b>13</b>
14.1	Data sheet status .....	13
14.2	Definitions .....	13
14.3	Disclaimers .....	13
14.4	Trademarks .....	14
<b>15</b>	<b>Contact information</b> .....	<b>14</b>
<b>16</b>	<b>Contents</b> .....	<b>15</b>

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