Dual supply translating transceiver; auto direction sensing; 3-state

Rev. 3 — 10 November 2011

**Product data sheet** 

### 1. General description

The NTB0104 is a 4-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 4-bit input-output ports (An and Bn), one output enable input (OE) and two supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ).  $V_{CC(A)}$  can be supplied at any voltage between 1.2 V and 3.6 V and  $V_{CC(B)}$  can be supplied at any voltage between 1.2 V, and 3.6 V and  $V_{CC(B)}$  can be supplied at any voltage between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V).

Pins An and OE are referenced to  $V_{CC(A)}$  and pins Bn are referenced to  $V_{CC(B)}$ . A LOW level at pin OE causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using  $I_{OFF}$ . The  $I_{OFF}$  circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

### 2. Features and benefits

- Wide supply voltage range:
  - ◆ V<sub>CC(A)</sub>: 1.2 V to 3.6 V and V<sub>CC(B)</sub>: 1.65 V to 5.5 V
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
  - HBM JESD22-A114E Class 2 exceeds 2500 V for A port
  - ◆ HBM JESD22-A114E Class 3B exceeds 15000 V for B port
  - MM JESD22-A115-A exceeds 200 V
  - CDM JESD22-C101E exceeds 1500 V (For NTB0104UK 1000 V)
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Multiple package options
- Specified from –40 °C to +85 °C and –40 °C to +125 °C



# 3. Ordering information

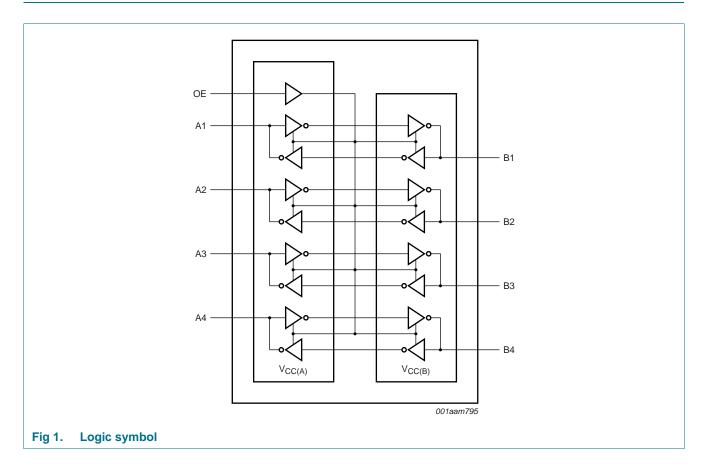
Type number	Package	Package								
	Temperature range	Name	Description	Version						
NTB0104BQ	–40 °C to +125 °C	DHVQFN14	plastic dual in-line compatible thermal enhanced very thin quad flat package; no leads; 14 terminals; body $2.5 \times 3 \times 0.85$ mm	SOT762-1						
NTB0104GU12	–40 °C to +125 °C	XQFN12	plastic, extremely thin quad flat package; no leads; 12 terminals; body $1.70 \times 2.0 \times 0.50$ mm	SOT1174-1						
NTB0104UK	–40 °C to +125 °C	WLCSP12	wafer level chip-size package, 12 bumps; body 1.20 $\times$ 1.60 $\times$ 0.56 mm. (Backside Coating included)	NTB0104UK						

# 4. Marking

Table 2. Marking	
Type number	Marking code
NTB0104BQ	B0104
NTB0104GU12	t4
NTB0104UK	t04

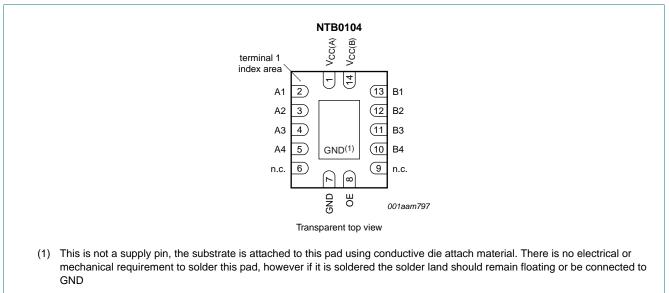
Dual supply translating transceiver; auto direction sensing; 3-state

# 5. Functional diagram

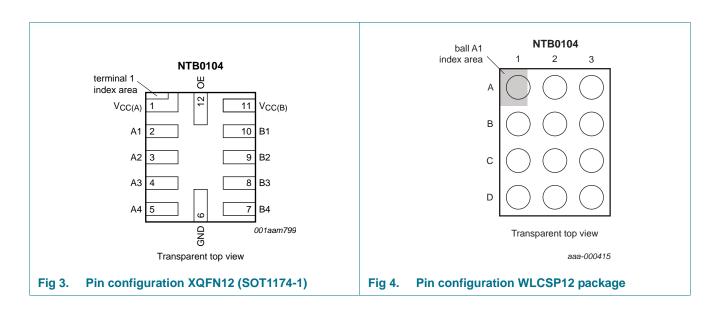


# 6. Pinning information

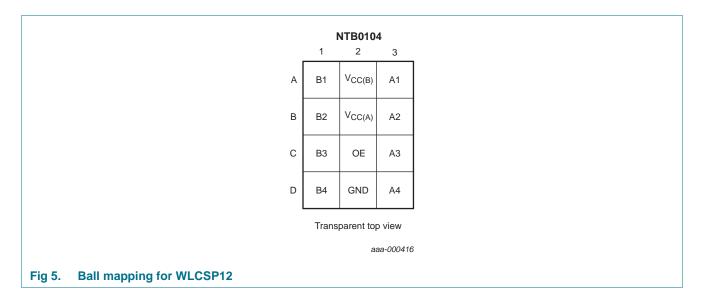
### 6.1 Pinning



#### Fig 2.Pin configuration DHVQFN14 (SOT762-1)



Dual supply translating transceiver; auto direction sensing; 3-state



### 6.2 Pin description

Table 3.	Pin description
----------	-----------------

Symbol	Pin		Ball	Description		
	SOT762-1	SOT1174-1	WLCSP12	-		
V <sub>CC(A)</sub>	1	1	B2	supply voltage A		
A1, A2, A3, A4	2, 3, 4, 5	2, 3, 4, 5	A3, B3, C3, D3	data input or output (referenced to $V_{CC(A)}$ )		
n.c.	6, 9	-	-	not connected		
GND	7	6	D2	ground (0 V)		
OE	8	12	C2	output enable input (active HIGH; referenced to $V_{\text{CC}(\text{A})})$		
B4, B3, B2, B1	10, 11, 12, 13	7, 8, 9, 10	D1, C1, B1, A1	data input or output (referenced to $V_{CC(B)}$ )		
V <sub>CC(B)</sub>	14	11	A2	supply voltage B		

# 7. Functional description

#### Table 4. Function table<sup>[1]</sup>

Supply voltage		Input	Input/output		
V <sub>CC(A)</sub> V <sub>CC(B)</sub>		OE	An	Bn	
1.2 V to $V_{CC(B)}$	1.65 V to 5.5 V	L	Z	Z	
1.2 V to $V_{CC(B)}$	1.65 V to 5.5 V	Н	input or output	output or input	
GND[2]	GND[2]	Х	Z	Z	

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

[2] When either  $V_{CC(A)} \mbox{ or } V_{CC(B)}$  is at GND level, the device goes into power-down mode.

# 8. Limiting values

#### Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

			0	10	,
Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A		-0.5	+6.5	V
V <sub>CC(B)</sub>	supply voltage B		-0.5	+6.5	V
VI	input voltage		<u>[1]</u> –0.5	+6.5	V
Vo	output voltage	Active mode	<u>[1][2][3]</u> –0.5	V <sub>CCO</sub> + 0.5	V
		Power-down or 3-state mode	<u>[1]</u> –0.5	+6.5	V
I <sub>IK</sub>	input clamping current	V <sub>1</sub> < 0 V	-50	-	mA
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V	-50	-	mA
lo	output current	$V_{O} = 0 V$ to $V_{CCO}$	[2] _	±50	mA
I <sub>CC</sub>	supply current	I <sub>CC(A)</sub> or I <sub>CC(B)</sub>	-	100	mA
I <sub>GND</sub>	ground current		-100	-	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40 \ ^{\circ}C$ to +125 $^{\circ}C$	<u>[4]</u>	250	mW

[1] The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] V<sub>CCO</sub> is the supply voltage associated with the output.

[3]  $V_{CCO}$  + 0.5 V should not exceed 6.5 V.

[4] For DHVQFN14 packages: above 60 °C the value of P<sub>tot</sub> derates linearly with 4.5 mW/K.
 For XQFN12 packages: above 128 °C the value of P<sub>tot</sub> derates linearly with 11.5 mW/K.

# 9. Recommended operating conditions

#### Table 6. Recommended operating conditions<sup>[1][2]</sup>

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A		1.2	3.6	V
V <sub>CC(B)</sub>	supply voltage B		1.65	5.5	V
VI	input voltage		0	5.5	V
Vo	output voltage	Power-down or 3-state mode; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$			
		A port	0	3.6	V
		B port	0	5.5	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
Δt/ΔV	input transition rise and fall rate	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	40	ns/V

[1] The A and B sides of an unused I/O pair must be held in the same state, both at V<sub>CCI</sub> or both at GND.

[2]  $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$ .

# **10. Static characteristics**

#### Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

0	Demonster	Or a differen		<b>T</b>		11
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>OH</sub>	HIGH-level output voltage	A port; $V_{CC(A)} = 1.2$ V; $I_O = -20 \ \mu A$	-	1.1	-	V
V <sub>OL</sub>	LOW-level output voltage	A port; $V_{CC(A)}$ = 1.2 V; $I_O$ = 20 $\mu$ A	-	0.09	-	V
I <sub>I</sub>	input leakage current	OE input; V <sub>I</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	-	±1	μA
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0$ V to $V_{CCO}$ ; $V_{CC(A)} = 1.2$ V to 3.6 V; $V_{CC(B)} = 1.65$ V to 5.5 V	<u>[1]</u> -	-	±1	μA
I <sub>OFF</sub>	power-off leakage current	A port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 0 V to 5.5 V	-	-	±1	μA
		B port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 5.5 V; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 0 V to 3.6 V	-	-	±1	μA
I <sub>CC</sub>	supply current	$V_I = 0 V \text{ or } V_{CCI}; I_O = 0 A$	[2]			
		$I_{CC(A)}$ ; $V_{CC(A)} = 1.2$ V; $V_{CC(B)} = 1.65$ V to 5.5 V	-	0.05	-	μA
		$I_{CC(B)}$ ; $V_{CC(A)} = 1.2$ V; $V_{CC(B)} = 1.65$ V to 5.5 V	-	3.3	-	μA
		$I_{CC(A)} + I_{CC(B)}$ ; $V_{CC(A)} = 1.2$ V; $V_{CC(B)} = 1.65$ V to 5.5 V	-	3.5	-	μA
CI	input capacitance	OE input; $V_{CC(A)}$ = 1.2 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V	-	2.8	-	pF
C <sub>I/O</sub>	input/output	A port; $V_{CC(A)}$ = 1.2 V to 3.6 V; $V_{CC(B)}$ = 1.65 V to 5.5 V	-	4.0	-	pF
	capacitance	B port; V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	7.5	-	pF

[1]  $V_{CCO}$  is the supply voltage associated with the output.

[2]  $V_{CCI}$  is the supply voltage associated with the input.

#### Table 8. Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

V <sub>CC(A)</sub>	V <sub>CC(B)</sub>							Unit	
	1.8	3 V	2.5 V		3.3 V		5.0 V		
	I <sub>CC(A)</sub>	I <sub>CC(B)</sub>							
1.2 V	10	10	10	10	10	20	10	1050	nA
1.5 V	10	10	10	10	10	10	10	650	nA
1.8 V	10	10	10	10	10	10	10	350	nA
2.5 V	-	-	10	10	10	10	10	40	nA
3.3 V	-	-	-	-	10	10	10	10	nA

# **NTB0104**

#### Dual supply translating transceiver; auto direction sensing; 3-state

#### Table 9. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		–40 °C to	o +85 ℃	–40 °C to	+125 °C	Unit
				Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level	A or B port and OE input	[1]	'				•
	input voltage	$V_{CC(A)} = 1.2 V \text{ to } 3.6 V;$ $V_{CC(B)} = 1.65 V \text{ to } 5.5 V$		0.65V <sub>CCI</sub>	-	0.65V <sub>CCI</sub>	-	V
V <sub>IL</sub>	LOW-level	A or B port and OE input	[1]					
	input voltage	$V_{CC(A)} = 1.2 V \text{ to } 3.6 V;$ $V_{CC(B)} = 1.65 V \text{ to } 5.5 V$		-	0.35V <sub>CCI</sub>	-	0.35V <sub>CCI</sub>	V
V <sub>OH</sub> HIGH-level		A or B port; $I_0 = -20 \ \mu A$	[2]					
	output voltage	A port; $V_{CC(A)} = 1.4$ V to 3.6 V		$V_{CCO}-0.4$	-	$V_{CCO}-0.4$	-	V
		B port; $V_{CC(B)}$ = 1.65 V to 5.5 V		$V_{CCO}-0.4$	-	$V_{CCO}-0.4$	-	V
V <sub>OL</sub>	LOW-level	A or B port; $I_0 = 20 \ \mu A$	[2]					
	output voltage	A port; $V_{CC(A)} = 1.4$ V to 3.6 V		-	0.4	-	0.4	V
		B port; $V_{CC(B)}$ = 1.65 V to 5.5 V		-	0.4	-	0.4	V
lı	input leakage current	$\begin{array}{l} \text{OE input; V}_{I} = 0 \ \text{V to } 3.6 \ \text{V;} \\ \text{V}_{\text{CC}(A)} = 1.2 \ \text{V to } 3.6 \ \text{V;} \\ \text{V}_{\text{CC}(B)} = 1.65 \ \text{V to } 5.5 \ \text{V} \end{array}$		-	±2	-	±5	μΑ
l <sub>oz</sub>	OFF-state output current	A or B port; $V_O = 0$ V or $V_{CCO}$ ; $V_{CC(A)} = 1.2$ V to 3.6 V; $V_{CC(B)} = 1.65$ V to 5.5 V	[2]	-	±2	-	±10	μΑ
I <sub>OFF</sub>	power-off leakage	A port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 0 V to 5.5 V		-	±2	-	±10	μA
	current	B port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 5.5 V; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 0 V to 3.6 V		-	±2	-	±10	μA

# NTB0104

#### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol	Parameter	Conditions	-40 °C t	to +85 °C	–40 °C to	o +125 °C	Unit
			Min	Max	Min	Max	_
I <sub>CC</sub>	supply current	$V_{I} = 0 V \text{ or } V_{CCI}; I_{O} = 0 A$ [1]					
		I <sub>CC(A)</sub>					
		OE = LOW; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	15	μA
		OE = HIGH; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	20	μA
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$	-	2	-	15	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$	-	-2	-	-15	μΑ
		I <sub>CC(B)</sub>					
		OE = LOW; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	15	μA
		OE = HIGH; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	5	-	20	μA
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$	-	-2	-	-15	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$	-	2	-	15	μΑ
		$I_{CC(A)} + I_{CC(B)}$					
		$V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	10	-	40	μA

#### Table 9. Static characteristics ... continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

[1]  $V_{CCI}$  is the supply voltage associated with the input.

[2]  $V_{CCO}$  is the supply voltage associated with the output.

# **11. Dynamic characteristics**

 Table 10.
 Typical dynamic characteristics for temperature 25 °C<sup>[1]</sup>

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for waveforms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions			Vco	С(В)		Unit
				1.8 V	2.5 V	3.3 V	5.0 V	
$V_{CC(A)} = 2$	1.2 V; T <sub>amb</sub> = 25 °C							
t <sub>pd</sub>	propagation delay	A to B		5.9	4.8	4.4	4.2	ns
		B to A		5.6	4.8	4.5	4.4	ns
t <sub>en</sub>	enable time	OE to A, B		0.5	0.5	0.5	0.5	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	8.3	8.3	8.3	8.3	ns
		OE to B; no external load	[2]	10.4	9.4	9.3	8.8	ns
		OE to A		81	69	83	68	ns
		OE to B		81	69	83	68	ns
t <sub>t</sub>	transition time	A port		4.0	4.0	4.1	4.1	ns
		B port		2.6	2.0	1.7	1.4	ns

Voltages a	are referenced to GN	ID (ground = 0 V); for tes	t circuit see	e <u>Figure 8</u> ; fo	or waveforms	s see <u>Figure (</u>	and <u>Figure</u>	<u>9 7</u> .
Symbol	Parameter	Conditions V <sub>CC(B)</sub>						Unit
				1.8 V	2.5 V	3.3 V	5.0 V	
t <sub>sk(o)</sub>	output skew time	between channels	[3]	0.2	0.2	0.2	0.2	ns
t <sub>W</sub>	pulse width	data inputs		15	13	13	13	ns
f <sub>data</sub>	data rate			70	80	80	80	Mbps

#### Typical dynamic characteristics for temperature 25 °C<sup>[1]</sup> ...continued Table 10.

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

ten is the same as tPZL and tPZH.

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}.$ 

 $t_{t}$  is the same as  $t_{\text{THL}}$  and  $t_{\text{TLH}}$ 

[2] Delay between OE going LOW and when the outputs are actually disabled.

Skew between any two outputs of the same package switching in the same direction. [3]

#### Table 11. Dynamic characteristics for temperature range –40 °C to +85 °C<sup>[1]</sup>

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7.

Symbol	Parameter	Conditions					Vcc	C(B)				Unit
				1.8 V ±	: 0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V :	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
$V_{CC(A)} =$	$1.5~V\pm0.1~V$											
t <sub>pd</sub>	propagation	A to B		1.4	12.9	1.2	10.1	1.1	10.0	0.8	9.9	ns
	delay	B to A		0.9	14.2	0.7	12.0	0.4	11.7	0.3	13.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	12.9	1.0	12.9	1.0	12.9	1.0	12.9	ns
		OE to B; no external load	[2]	1.0	18.7	1.0	15.8	1.0	15.1	1.0	14.4	ns
		OE to A		-	320	-	260	-	260	-	280	ns
		OE to B		-	200	-	200	-	200	-	200	ns
tt	transition time	A port		0.9	5.1	0.9	5.1	0.9	5.1	0.9	5.1	ns
		B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f <sub>data</sub>	data rate			-	40	-	40	-	40	-	40	Mbps
$V_{CC(A)} =$	$1.8 \text{ V} \pm 0.15 \text{ V}$											
t <sub>pd</sub>	propagation	A to B		1.6	11.0	1.4	7.7	1.3	6.8	1.2	6.5	ns
	delay	B to A		1.5	12.0	1.3	8.4	1.0	7.6	0.9	7.1	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	11.7	1.0	11.7	1.0	11.7	1.0	11.7	ns
		OE to B; no external load	[2]	1.0	16.9	1.0	14.5	1.0	13.7	1.0	12.7	ns
		OE to A		-	260	-	230	-	230	-	230	ns
		OE to B		-	200	-	200	-	200	-	200	ns
t <sub>t</sub>	transition	A port		0.8	4.1	0.8	4.1	0.8	4.1	0.8	4.1	ns
-	time	B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns

Symbol	Parameter	Conditions					Vcc	С(В)				Unit
				1.8 V ±	: 0.15 V	2.5 V :		1	± 0.3 V	5.0 V :	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		20	-	17	-	17	-	17	-	ns
f <sub>data</sub>	data rate			-	49	-	60	-	60	-	60	Mbps
$V_{CC(A)} =$	2.5 V ± 0.2 V											
t <sub>pd</sub>	propagation	A to B		-	-	1.1	6.3	1.0	5.2	0.9	4.7	ns
	delay	B to A		-	-	1.2	6.6	1.1	5.1	0.9	4.4	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μs
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	1.0	9.7	1.0	9.7	1.0	9.7	ns
	OE to B; no external load	[2]	-	-	1.0	12.9	1.0	12.0	1.0	11.0	ns	
		OE to A		-	-	-	200	-	200	-	200	ns
		OE to B		-	-	-	200	-	200	-	200	ns
t <sub>t</sub> transition time	transition	A port		-	-	0.7	3.0	0.7	3.0	0.7	3.0	ns
	time	B port		-	-	0.7	3.2	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	-	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	12	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	85	-	100	-	100	Mbps
V <sub>CC(A)</sub> =	3.3 V ± 0.3 V											
t <sub>pd</sub>	propagation	A to B		-	-	-	-	0.9	4.7	0.8	4.0	ns
	delay	B to A		-	-	-	-	1.0	4.9	0.9	3.8	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.4	1.0	9.4	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	11.3	1.0	10.4	ns
		OE to A		-	-	-	-	-	260	-	260	ns
		OE to B		-	-	-	-	-	200	-	200	ns
t <sub>t</sub>	transition	A port		-	-	-	-	0.7	2.5	0.7	2.5	ns
	time	B port		-	-	-	-	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	putput skew time	between channels	<u>[3]</u>	-	-	-	-	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	-	-	100	-	100	Mbps

Dynamic characteristics for temperature range -40 °C to +85 °C[1] ... continued Table 11.

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

 $t_{en} \mbox{ is the same as } t_{PZL} \mbox{ and } t_{PZH}.$ 

 $t_{\text{dis}}$  is the same as  $t_{\text{PLZ}}$  and  $t_{\text{PHZ}}.$ 

 $t_{t}$  is the same as  $t_{THL}$  and  $t_{TLH}$ 

[2] Delay between OE going LOW and when the outputs are actually disabled.

[3] Skew between any two outputs of the same package switching in the same direction.

# NTB0104

### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol	Parameter	Conditions					Vcc					Unit
				1.8 V ±	0.15 V	2.5 V :	± 0.2 V	3.3 V :	± 0.3 V	5.0 V <u>-</u>	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.5 V ± 0.1 V											
t <sub>pd</sub>	propagation	A to B		1.4	15.9	1.2	13.1	1.1	13.0	0.8	12.9	ns
	delay	B to A		0.9	17.2	0.7	15.0	0.4	14.7	0.3	16.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	13.5	1.0	13.5	1.0	13.5	1.0	13.5	ns
		OE to B; no external load	[2]	1.0	19.9	1.0	16.8	1.0	16.1	1.0	15.2	ns
		OE to A		-	340	-	280	-	280	-	300	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		0.9	7.1	0.9	7.1	0.9	7.1	0.9	7.1	ns
time		B port		0.9	6.5	0.6	5.2	0.5	4.8	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	0.5	-	0.5	-	0.5	-	0.5	ns
tw	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f <sub>data</sub>	data rate			-	40	-	40	-	40	-	40	Mbp
V <sub>CC(A)</sub> =	1.8 V ± 0.15 V											
	propagation	A to B		1.6	14.0	1.4	10.7	1.3	9.8	1.2	9.5	ns
	delay	B to A		1.5	15.0	1.3	11.4	1.0	10.6	0.9	10.1	ns
en	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
dis	disable time	OE to A; no external load	[2]	1.0	12.3	1.0	12.3	1.0	12.3	1.0	12.3	ns
		OE to B; no external load	[2]	1.0	18.1	1.0	15.3	1.0	14.5	1.0	13.5	ns
		OE to A		-	280	-	250	-	250	-	250	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t	transition	A port		0.8	6.2	0.8	6.1	0.8	6.1	0.8	6.1	ns
	time	B port		0.9	5.8	0.6	5.2	0.5	4.8	0.4	4.7	ns
sk(o)	output skew time	between channels	<u>[3]</u>	-	0.5	-	0.5	-	0.5	-	0.5	ns
tw	pulse width	data inputs		22	-	19	-	19	-	19	-	ns
data	data rate			-	45	-	55	-	55	-	55	Mbp
V <sub>CC(A)</sub> =	2.5 V ± 0.2 V											
pd	propagation	A to B		-	-	1.1	9.3	1.0	8.2	0.9	7.7	ns
	delay	B to A		-	-	1.2	9.6	1.1	8.1	0.9	7.4	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
dis	disable time	OE to A; no external load	[2]	-	-	1.0	10.1	1.0	10.1	1.0	10.1	ns
		OE to B; no external load	[2]	-	-	1.0	13.5	1.0	12.7	1.0	11.7	ns
		OE to A		-	-	-	220	-	220	-	220	ns
		OE to B		-	-	-	220	-	220	-	220	ns
t	transition	A port		-	-	0.7	5.0	0.7	5.0	0.7	5.0	ns
time	time	B port		-	-	0.7	4.6	0.5	4.8	0.4	4.7	ns

 Table 12.
 Dynamic characteristics for temperature range -40 °C to +125 °C<sup>[1]</sup>

NTB0104 Product data sheet

Symbol	Parameter	Conditions					Vcc	C(B)				Unit
				1.8 V ±	0.15 V	2.5 V :	$2.5 V \pm 0.2 V$		± 0.3 V	5.0 V :	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	-	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs;		-	-	14	-	13	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	75	-	80	-	100	Mbps
V <sub>CC(A)</sub> =	3.3 V ± 0.3 V											
t <sub>pd</sub> propagation delay	propagation	A to B		-	-	-	-	0.9	7.7	0.8	7.0	ns
	B to A		-	-	-	-	1.0	7.9	0.9	6.8	ns	
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t <sub>dis</sub>		OE to A; no external load	[2]	-	-	-	-	1.0	9.9	1.0	9.9	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	12.1	1.0	10.9	ns
		OE to A		-	-	-	-	-	280	-	280	ns
		OE to B		-	-	-	-	-	220	-	220	ns
t <sub>t</sub>	transition	A port		-	-	-	-	0.7	4.5	0.7	4.5	ns
	time	B port		-	-	-	-	0.5	4.1	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	-	-	-	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	-	-	100	-	100	Mbps

Table 12. Dynamic characteristics for temperature range –40 °C to +125 °C<sup>[1]</sup>

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 8; for wave forms see Figure 6 and Figure 7.

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

 $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .

 $t_{dis}$  is the same as  $t_{\mathsf{PLZ}}$  and  $t_{\mathsf{PHZ}}.$   $t_t$  is the same as  $t_{\mathsf{THL}}$  and  $t_{\mathsf{TLH}}$ 

[2] Delay between OE going LOW and when the outputs are actually disabled.

[3] Skew between any two outputs of the same package switching in the same direction.

#### Dual supply translating transceiver; auto direction sensing; 3-state

Symbol	Parameter	Conditions	ditions V <sub>CC(A)</sub>								
			1.2 V	1.2 V	1.5 V	1.8 V	2.5 V	2.5 V	3.3 V		
			V <sub>CC(B)</sub>								
		1.8 V	5.0 V	1.8 V	1.8 V	2.5 V	5.0 V	3.3 V to 5.0 V			
T <sub>amb</sub> = 2	25 °C										
10 1	power	outputs enabled; $OE = V_{CC(A)}$									
	dissipation capacitance	A port: (direction A to B)	5	5	5	5	5	5	5	pF	
	capacitance	A port: (direction B to A)	8	8	8	8	8	8	8	pF	
		B port: (direction A to B)	18	18	18	18	18	18	18	pF	
		B port: (direction B to A)	13	16	12	12	12	12	13	pF	
		outputs disabled; OE = GND									
	A port: (direction A to B)	0.12	0.12	0.04	0.05	0.08	0.08	0.07	pF		
		A port: (direction B to A)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF	
		B port: (direction A to B)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF	
		B port: (direction B to A)	0.07	0.09	0.07	0.07	0.05	0.09	0.09	pF	

# **Table 13.** Typical power dissipation capacitance

[1]  $C_{PD}$  is used to determine the dynamic power dissipation (P<sub>D</sub> in  $\mu$ W).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$  where:

 $f_i$  = input frequency in MHz;

 $f_o = output frequency in MHz;$ 

 $C_L$  = load capacitance in pF;

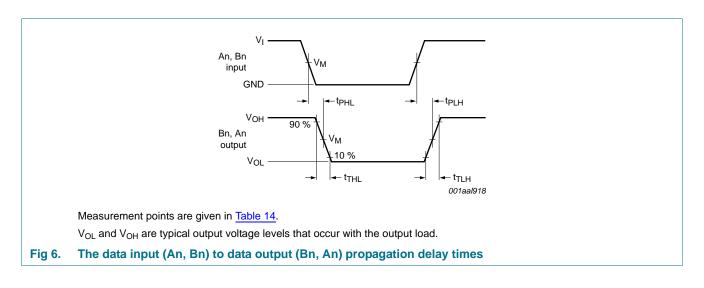
V<sub>CC</sub> = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_o)$  = sum of the outputs.

[2]  $f_i = 10 \text{ MHz}$ ;  $V_I = \text{GND}$  to  $V_{CC}$ ;  $t_f = t_f = 1 \text{ ns}$ ;  $C_L = 0 \text{ pF}$ ;  $R_L = \infty \Omega$ .

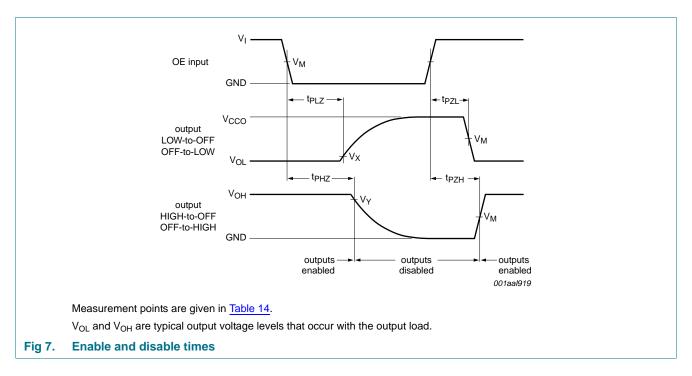
# 12. Waveforms



All information provided in this document is subject to legal disclaimers.

# NTB0104

#### Dual supply translating transceiver; auto direction sensing; 3-state



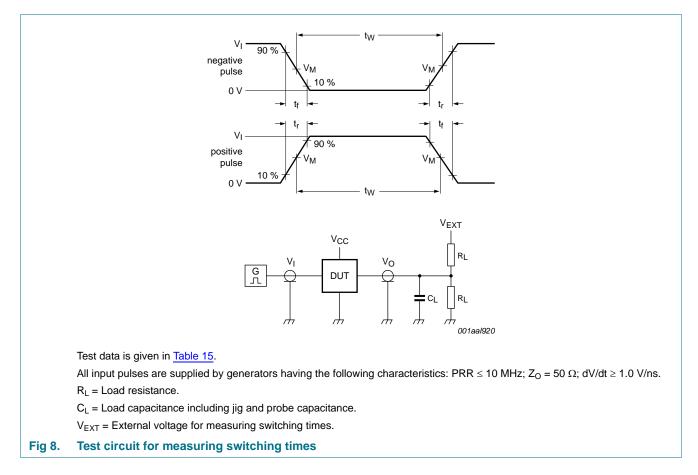
#### Table 14. Measurement points<sup>[1]</sup>

Tuble 14. Measuren									
Supply voltage	Input	Output	Output						
V <sub>cco</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>					
1.2 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> – 0.1 V					
$1.5~\text{V}\pm0.1~\text{V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> – 0.1 V					
$1.8 \text{ V} \pm 0.15 \text{ V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V					
$2.5~\textrm{V}\pm0.2~\textrm{V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V					
$3.3 \text{ V} \pm 0.3 \text{ V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> – 0.3 V					
$5.0~\text{V}\pm0.5~\text{V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> – 0.3 V					

[1]  $V_{CCI}$  is the supply voltage associated with the input and  $V_{CCO}$  is the supply voltage associated with the output.

# NTB0104

#### Dual supply translating transceiver; auto direction sensing; 3-state



#### Table 15. Test data

Supply voltage		Input		Load		V <sub>EXT</sub>			
V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	VI <mark>[1]</mark>	∆t/∆V	CL	RL <sup>[2]</sup>	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub> [3]	
1.2 V to 3.6 V	1.65 V to 5.5 V	V <sub>CCI</sub>	$\leq$ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V <sub>CCO</sub>	

[1] V<sub>CCI</sub> is the supply voltage associated with the input.

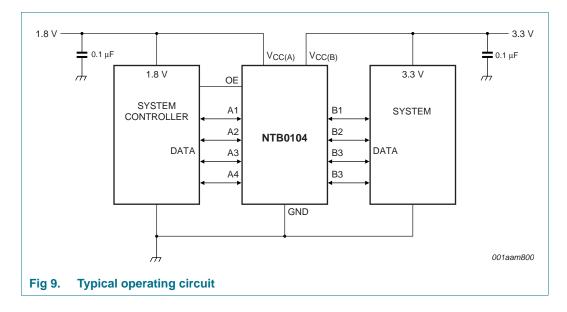
[2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements,  $R_L = 1 M\Omega$ ; for measuring enable and disable times,  $R_L = 50 k\Omega$ .

[3]  $V_{CCO}$  is the supply voltage associated with the output.

# **13. Application information**

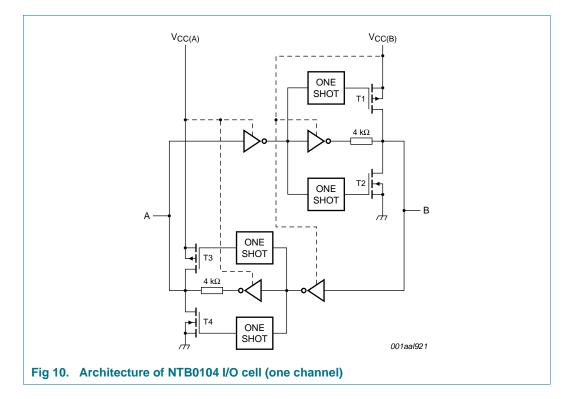
### **13.1 Applications**

Voltage level-translation applications. The NTB0104 can be used to interface between devices or systems operating at different supply voltages. See Figure 9 for a typical operating circuit using the NTB0104.



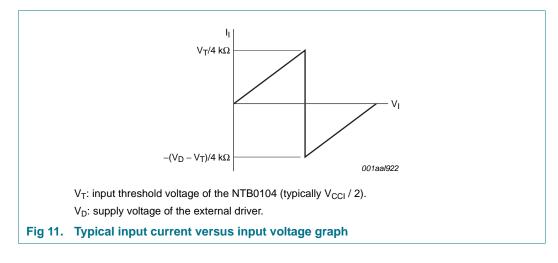
#### 13.2 Architecture

The architecture of the NTB0104 is shown in Figure 10. The device does not require an extra input signal to control the direction of data flow from A to B or from B to A. In a static state, the output drivers of the NTB0104 can maintain a defined output level, but the output architecture is designed to be weak, so that they can be overdriven by an external driver when data on the bus starts flowing in the opposite direction. The output one shots detect rising or falling edges on the A or B ports. During a rising edge, the one shots turn on the PMOS transistors (T1, T3) for a short duration, accelerating the low-to-high transition. Similarly, during a falling edge, the one shots turn on the NMOS transistors (T2, T4) for a short duration, accelerating the high-to-low transition. During output transitions the typical output impedance is 70  $\Omega$  at V<sub>CCO</sub> = 1.2 V to 1.8 V, 50  $\Omega$  at V<sub>CCO</sub> = 1.8 V to 3.3 V and 40  $\Omega$  at V<sub>CCO</sub> = 3.3 V to 5.0 V.



#### 13.3 Input driver requirements

For correct operation, the device driving the data I/Os of the NTB0104 must have a minimum drive capability of  $\pm 2$  mA See <u>Figure 11</u> for a plot of typical input current versus input voltage.



#### 13.4 Power up

During operation  $V_{CC(A)}$  must never be higher than  $V_{CC(B)}$ , however during power-up  $V_{CC(A)} \ge V_{CC(B)}$  does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NTB0104 includes circuitry that disables all output ports when either  $V_{CC(A)}$  or  $V_{CC(B)}$  is switched off.

#### 13.5 Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = LOW causes all I/Os to assume the high-impedance OFF-state. The disable time ( $t_{dis}$  with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time ( $t_{en}$ ) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

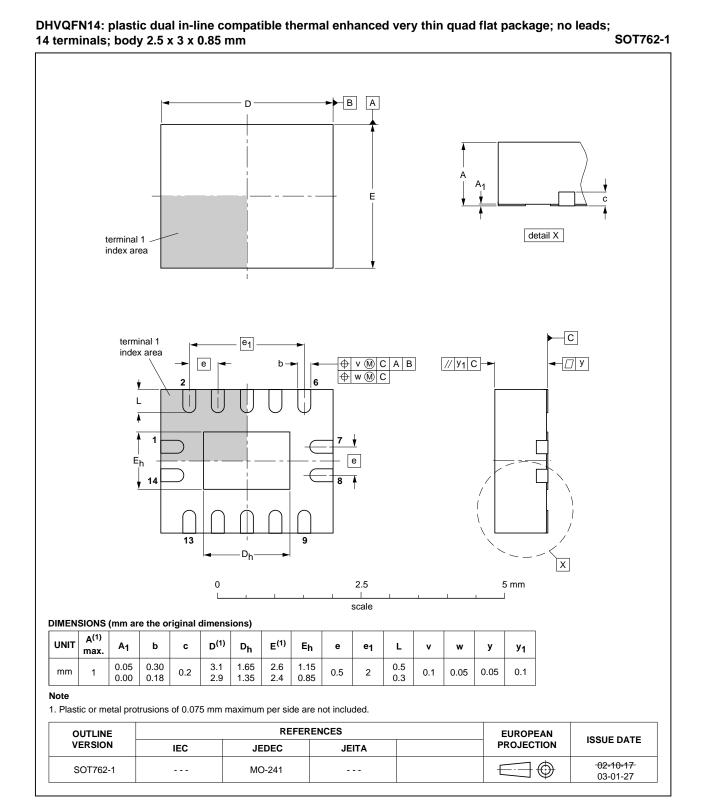
#### 13.6 Pull-up or pull-down resistors on I/O lines

As mentioned previously the NTB0104 is designed with low static drive strength to drive capacitive loads of up to 70 pF. To avoid output contention issues, any pull-up or pull-down resistors used must be kept higher than 50 k $\Omega$ . For this reason the NTB0104 is not recommended for use in open drain driver applications such as 1-Wire or I<sup>2</sup>C. For these applications, the NTS0104 level translator is recommended.

NTB0104

Dual supply translating transceiver; auto direction sensing; 3-state

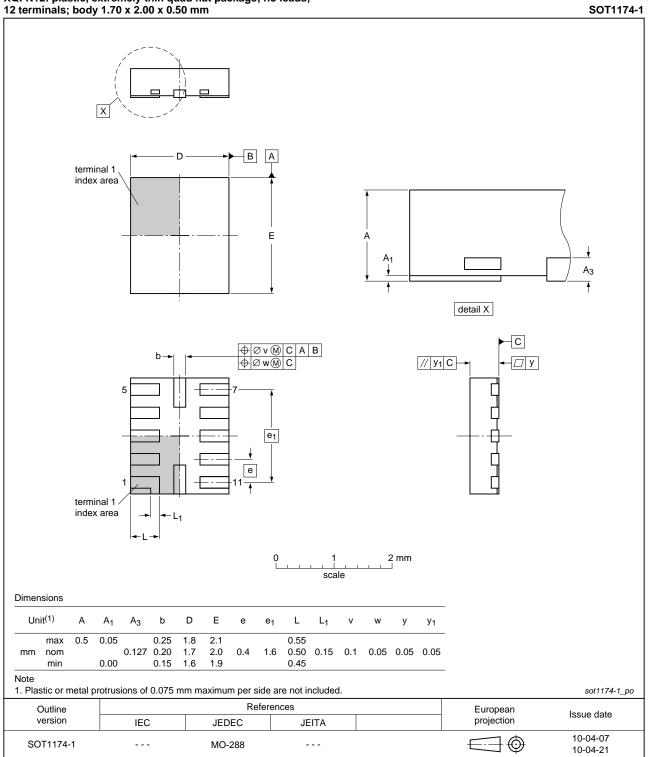
### 14. Package outline



#### Fig 12. Package outline SOT762-1 (DHVQFN14)

All information provided in this document is subject to legal disclaimers.

Dual supply translating transceiver; auto direction sensing; 3-state



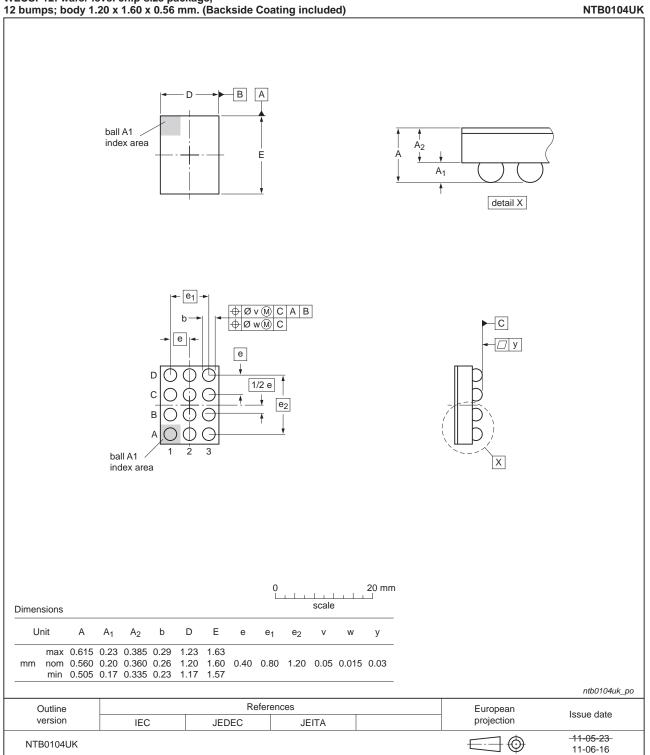
XQFN12: plastic, extremely thin quad flat package; no leads; 12 terminals; body 1.70 x 2.00 x 0.50 mm

#### Fig 13. Package outline SOT1174-1 (XQFN12)

All information provided in this document is subject to legal disclaimers.

Dual supply translating transceiver; auto direction sensing; 3-state

WLCSP12: wafer level chip-size package,



#### Fig 14. Package outline WLCSP12 package

All information provided in this document is subject to legal disclaimers.

# **15. Abbreviations**

Table 16. Abbreviations						
Acronym	Description					
CDM	Charged Device Model					
CMOS	Complementary Metal Oxide Semiconductor					
DUT	Device Under Test					
ESD	ElectroStatic Discharge					
НВМ	Human Body Model					
MM	Machine Model					

# 16. Revision history

Table 17. Revision his	tory			
Document ID	Release date	Data sheet status	Change notice	Supersedes
NTB0104 v.3	20111110	Product data sheet	-	NTB0104 v.2
Modifications:	<ul> <li>Legal pages</li> </ul>	updated.		
NTB0104 v.2	20111109	Product data sheet	-	NTB0104 v.1
NTB0104 v.1	20101026	Product data sheet	-	-

# 17. Legal information

#### 17.1 Data sheet status

Document status[1][2]	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <a href="http://www.nxp.com">http://www.nxp.com</a>.

#### 17.2 Definitions

**Draft** — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

Short data sheet — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local NXP Semiconductors sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

**Product specification** — The information and data provided in a Product data sheet shall define the specification of the product as agreed between NXP Semiconductors and its customer, unless NXP Semiconductors and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the NXP Semiconductors product is deemed to offer functions and qualities beyond those described in the Product data sheet.

### 17.3 Disclaimers

Limited warranty and liability — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information.

In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the *Terms and conditions of commercial sale* of NXP Semiconductors.

Right to make changes — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

Suitability for use — NXP Semiconductors products are not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors accepts no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

**Applications** — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

Limiting values — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) will cause permanent damage to the device. Limiting values are stress ratings only and (proper) operation of the device at these or any other conditions above those given in the Recommended operating conditions section (if present) or the Characteristics sections of this document is not warranted. Constant or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the device.

Terms and conditions of commercial sale — NXP Semiconductors products are sold subject to the general terms and conditions of commercial sale, as published at <a href="http://www.nxp.com/profile/terms">http://www.nxp.com/profile/terms</a>, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. NXP Semiconductors hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of NXP Semiconductors products by customer.

**No offer to sell or license** — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

**Export control** — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

# **NTB0104**

#### Dual supply translating transceiver; auto direction sensing; 3-state

**Non-automotive qualified products** — Unless this data sheet expressly states that this specific NXP Semiconductors product is automotive qualified, the product is not suitable for automotive use. It is neither qualified nor tested in accordance with automotive testing or application requirements. NXP Semiconductors accepts no liability for inclusion and/or use of non-automotive qualified products in automotive equipment or applications.

In the event that customer uses the product for design-in and use in automotive applications to automotive specifications and standards, customer (a) shall use the product without NXP Semiconductors' warranty of the product for such automotive applications, use and specifications, and (b) whenever customer uses the product for automotive applications beyond

# **18. Contact information**

NXP Semiconductors' specifications such use shall be solely at customer's own risk, and (c) customer fully indemnifies NXP Semiconductors for any liability, damages or failed product claims resulting from customer design and use of the product for automotive applications beyond NXP Semiconductors' standard warranty and NXP Semiconductors' product specifications.

### 17.4 Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

For more information, please visit: http://www.nxp.com

For sales office addresses, please send an email to: <a href="mailto:salesaddresses@nxp.com">salesaddresses@nxp.com</a>

# **NTB0104**

Dual supply translating transceiver; auto direction sensing; 3-state

### **19. Contents**

1	General description 1	1
2	Features and benefits 1	1
3	Ordering information	2
4	Marking	2
5		3
6	Pinning information	4
6.1	Pinning	4
6.2	Pin description	5
7	Functional description	5
8	Limiting values	ô
9	Recommended operating conditions	ô
10	Static characteristics	7
11	Dynamic characteristics	9
12	Waveforms 14	4
13	Application information 17	7
13.1	Applications 17	7
13.2	Architecture 18	3
13.3	Input driver requirements 19	9
13.4	Power up 19	9
13.5	Enable and disable	9
13.6	Pull-up or pull-down resistors on I/O lines 19	9
14	Package outline 20	)
15	Abbreviations 23	3
16	Revision history 23	3
17	Legal information 24	4
17.1	Data sheet status 24	
17.2	Definitions 24	4
17.3	Disclaimers	4
17.4	Trademarks 25	5
18	Contact information 25	5
19	Contents 26	6

Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

© NXP B.V. 2011.

All rights reserved.

For more information, please visit: http://www.nxp.com For sales office addresses, please send an email to: salesaddresses@nxp.com

Date of release: 10 November 2011 Document identifier: NTB0104