

MODEL: NDM2Z-25H | DESCRIPTION: AUTO COMPENSATED, DIGITAL DC-DC POL CONVERTER
GENERAL CHARACTERISTICS

- 4.5~14 V input range
- 0.6~3.3 V programmable output
- voltage tracking
- voltage margining
- active current sharing
- Snapshot™ parametric capture
- voltage/current/temperature monitoring
- synchronization and phase spreading
- remote differential voltage sense
- programmable soft start and soft stop
- fault management

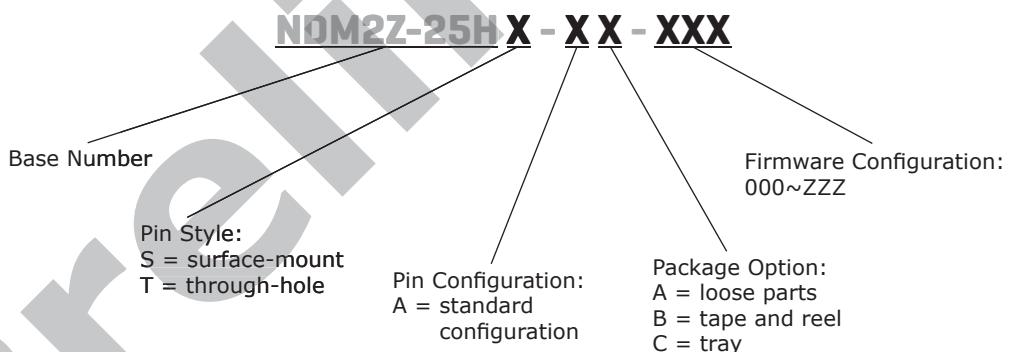

FEATURES

- compact package
- horizontal:
25.65 x 13.80 x 7.22 mm
(1.01 x 0.54 x 0.28 in)
- vertical (SIP):
26.3 x 7.6 x 15.6 mm
(1.04 x 0.30 x 0.61 in)
- 25 A output
- high efficiency
- auto compensation
- SMBus interface
- PMBus™ Compatible
- Ericsson footprint compatible


novum
advanced power

MODEL

	input voltage	output voltage	output current	output wattage
	(Vdc)	(Vdc)	max (A)	max (W)
NDM2Z-25H	4.5~14	0.6~3.3	25	82.5

PART NUMBER KEY

Example part number: **NDM2Z-25HT-AA-002**

horizontal module
through-hole pins
standard pin configuration
loose parts package option
firmware configuration 002

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RECOMMENDED OPERATING CONDITIONS

$-30^{\circ}\text{C} < T_{\text{P1}} < +95^{\circ}\text{C}$, $4.5 \text{ V} < V_{\text{in}} < 14 \text{ V}$, typical measurements made at $V_{\text{in}} = 12 \text{ V}$, $V_{\text{out}} = 1.0 \text{ V}$, $I_{\text{out}} = I_{\text{max}}$, $T_{\text{P1}} = 25^{\circ}\text{C}$, $= C_{\text{in}} = 470 \mu\text{F}/10 \text{ m}\Omega$, $C_{\text{out}} = 470 \mu\text{F}/8 \text{ m}\Omega$

INPUT / OUTPUT

parameter	conditions/description	min	typ	max	units
V_{in}	input supply voltage	4.5		14	V
I_{out}	output current	0		25	A
V_{out}	adjustable via resistor or PMBus™ commands	0.6		3.3	V
V_{out} margin	adjustable via PMBus commands	0		110	%
voltage accuracy	over line, load and temperature measured at +S and -S	-1		1	%
line regulation	$4.5 \text{ V} \leq V_{\text{in}} \leq 14 \text{ V}$				
	$V_{\text{out}} = 0.6 \text{ V}$		0.4		
	$V_{\text{out}} = 1.0 \text{ V}$		0.3		
	$V_{\text{out}} = 1.8 \text{ V}$		1.8		
	$V_{\text{out}} = 3.3 \text{ V}$		2.3		mV
load regulation	$0 \text{ A} \leq I_{\text{out}} \leq I_{\text{max}}$				
	$V_{\text{out}} = 0.6 \text{ V}$		0.7		
	$V_{\text{out}} = 1.0 \text{ V}$		0.8		
	$V_{\text{out}} = 1.8 \text{ V}$		1.8		
	$V_{\text{out}} = 3.3 \text{ V}$		4.2		mV
voltage set-point resolution	when V_{out} set via PMBus commands	-0.025		0.025	% FS
voltage ripple and noise	$V_{\text{out}} = 0.6 \text{ V}$		14		
	$V_{\text{out}} = 1.0 \text{ V}$		19		
	$V_{\text{out}} = 1.8 \text{ V}$		24		mVp-p
	$V_{\text{out}} = 3.3 \text{ V}$		31		
ramp-up time	adjustable via PMBus	0		200	ms
on time delay	adjustable via PMBus	5		500,000	ms
load transient voltage deviation	I_{out} : 25% \rightarrow 75% \rightarrow 25% of I_{max} , $dI/dt=2 \text{ A}/\mu\text{s}$				
	$V_{\text{out}} = 0.6 \text{ V}$		49		
	$V_{\text{out}} = 1.0 \text{ V}$		55		
	$V_{\text{out}} = 1.8 \text{ V}$		68		mV
	$V_{\text{out}} = 3.3 \text{ V}$		95		
load transient recovery time ¹	I_{out} : 25% \rightarrow 75% \rightarrow 25% of I_{max} , $dI/dt=2 \text{ A}/\mu\text{s}$				
	$V_{\text{out}} = 0.6 \text{ V}$		60		
	$V_{\text{out}} = 1.0 \text{ V}$		35		
	$V_{\text{out}} = 1.8 \text{ V}$		20		μs
	$V_{\text{out}} = 3.3 \text{ V}$		0		

Notes: 1. settling to within 3% of V_{out}

POWER / EFFICIENCY

parameter	conditions/description	min	typ	max	units
output power	$V_{out} = 3.3 \text{ V} + 10\% \text{ margin}$	0		90.75	W
	$I_{out} = 50\% \text{ of max}$	$V_{out} = 0.6 \text{ V}$ $V_{out} = 1.0 \text{ V}$ $V_{out} = 1.8 \text{ V}$ $V_{out} = 3.3 \text{ V}$	85.8 89.9 92.3 93.2		%
efficiency	$I_{out} = \text{max}$	$V_{out} = 0.6 \text{ V}$ $V_{out} = 1.0 \text{ V}$ $V_{out} = 1.8 \text{ V}$ $V_{out} = 3.3 \text{ V}$	82.5 87.3 90.3 91.5		%
idle power	$V_{out} = 0.6 \text{ V}$ $V_{out} = 1.0 \text{ V}$ $V_{out} = 1.8 \text{ V}$ $V_{out} = 3.3 \text{ V}$ CTRL deasserted	0.55 0.69 0.24 1.9			W
switching frequency		350			kHz

POWER CONNECTIONS

symbol	pin	IO type	description
VIN	1A	Power	Input voltage
GND	2A	Ground	Power ground
VOUT	3A	Power	Output voltage

COMMUNICATION CONNECTIONS

symbol	pin	IO type	description
VTRK	4A	Analog	Voltage tracking input
PREF	4B	Ground	Pin-strap ground
+S	5A	Analog	Output voltage positive sense input
-S	5B	Analog	Output voltage negative sense input
SA0	6A	Digital	SMBus address pinstrap
DDC	6B	Digital	Digital-DC Communications bus (equivalent to Ericsson Power GCB)
SCL	7A	Digital	SBMBus clock
SDA	7B	Digital	SBMBus data
VSET	8A	Digital	Output voltage pin-strap
SYNC	8B	Digital	Synchronization I/O
SALRT	9A	Digital	SMBus alert
CTRL	9B	Digital	Remote control or enable pin

MECHANICAL DRAWING [THROUGH HOLE]

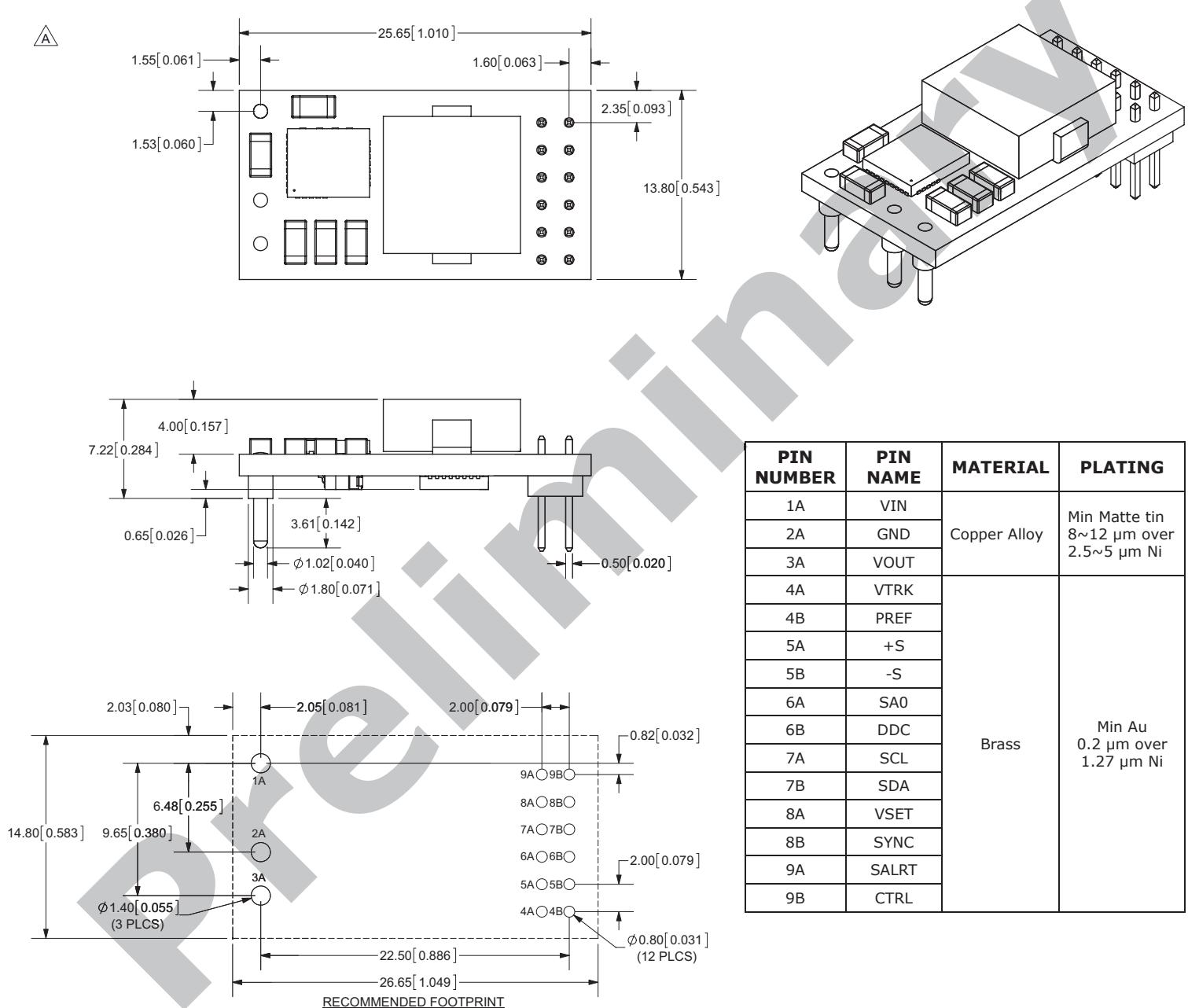
units: mm [inches]

tolerance unless specified:

X.X ±0.50 [0.02]

X.XX ±0.25 [0.01]

(not applied on footprint or typical values)



For more information and complete data sheets please contact a CUI representative.

REVISION HISTORY

rev.	description	date
0.9	preliminary release	09/11/2012
0.91	misc. updates	09/25/2012
0.92	misc. updates	12/07/2012
0.93	pin label update	12/20/2012

The revision history provided is for informational purposes only and is believed to be accurate.



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