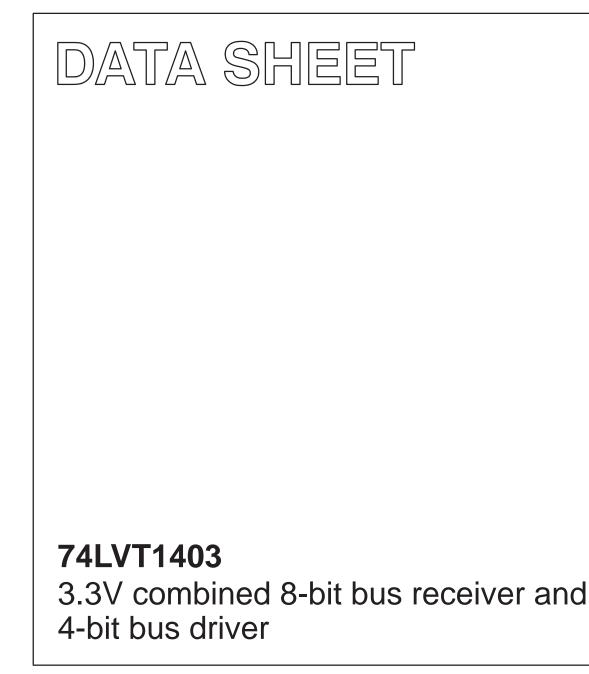
INTEGRATED CIRCUITS



Product specification

IC23 Data Handbook

1998 Nov 12

PHILIPS PHILIPS

74LVT1403

FEATURES

- 4-bit 74LVT125-like bus driver
- 8-bit 74LVT14-like Schmitt trigger
- Bus drive +64mA/–32mA
- 7 bus inputs with common inversion control pin
- 32-pin TSSOP footprint
- DE pin with resistive pull up and active LOW for easier live insertion
- DE pin includes Schmitt trigger with typical 0.6V hysteresis

DESCRIPTION

The 74LVT1403 is a high-performance BiCMOS product designed for V_{CC} operation at 3.3V.

This device combines the functionality of a 4-bit data path bus driver and 8-bit Schmitt trigger bus receiver, along with control logic in one 32-pin package.

The receiver inputs are Schmitt trigger type capable of transforming slowly changing input signals into sharply defined, jitter-free output signals. The receiver outputs are 74LVT14 style with +32mA/–20mA drive capability. The receiver inputs include the bus hold feature.

The driver outputs feature power-up in 3-State/live insertion capability and are all controlled by the A/B, EN1, and EN2 control pins. The driver inputs include the bus hold feature.

QUICK REFERENCE DATA

SYMBOL	PARAMETER	CONDITIONS T _{amb} = 25°C; GND = 0V	TYPICAL	UNIT
t _{PLH}	Propagation delay An to Yn	$C_{L} = 50 pF; V_{CC} = 3.3 V$	4.5	ns
t _{PHL}	Propagation delay An to Yn	$C_{L} = 50 pF; V_{CC} = 3.3 V$	4.0	ns
C _{IN}	Input capacitance	V _I = 0V or 3.0V	3	pF
Icc	Total supply current	Outputs low, $V_{CC} = 3.6V$	4	mA

ORDERING INFORMATION

PACKAGES	TEMPERATURE RANGE	OUTSIDE NORTH AMERICA	NORTH AMERICA	DWG NUMBER
32-pin plastic TSSOP	–40°C to +85°C	74LVT1403 DR	74LVT1403 DR	SOT487-1

PIN CONFIGURATION

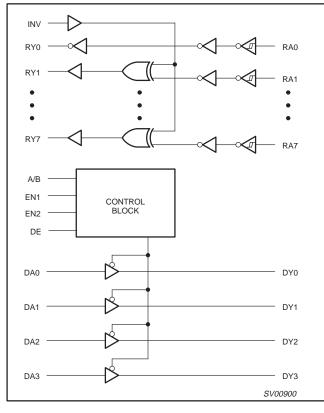
INV 1 RY0 2 RY1 3 RY2 4 RY3 5 RY4 6 RY5 7 RY6 8 RY7 9 EN1 10 EN2 11 DA0 12 DA1 13 DA2 14	THIN SHRINK SMALL OUTLINE PACKAGE (TSSOP)	32 V _{CC} 31 RA0 30 RA1 29 RA2 28 RA3 27 RA4 26 RA5 25 RA6 24 RA7 23 A/B 22 GND 21 DY0 20 DY1 19 DY2
DA1 13		20 DY1
GND 16	SI	17 DE /00907

PIN DESCRIPTION

PIN NUMBER	SYMBOL	NAME AND FUNCTION
31, 30, 29, 28, 27, 26, 25, 24	RA0–RA7	Receive Data inputs
2, 3, 4, 5, 6, 7, 8, 9	RY0–RY7	Receive Data outputs
12, 13, 14, 15	DA0–DA3	Driver Data inputs
21, 20, 19, 18	DY0–DY3	Driver Data outputs
10, 11	EN1, EN2	Driver Output enables
23	A/B	Mode control for en- ables
1	INV	Inversion control
16, 22	GND	Ground (0V)
32	V _{CC}	Positive supply voltage
17	DE	Driver output enable ac- tive LOW with resistive pull up

74LVT1403

LOGIC SYMBOL



FUNCTION TABLE – RECEIVER

INP	UTS	OUTF	PUTS
RA0-RA7	INV	RY0	RY1–RY7
L	Х	Н	—
Н	Х	L	—
L	L	—	L
Н	L	—	Н
L	Н	—	Н
Н	Н	_	L

H = High voltage level L = Low voltage level

X = Don't care

--- = Reported on different line

FUNCTION TABLE – DRIVER

	CONT	ROL INPUT	rs	OUTPUT CONDITION
DE	A/B	EN1	EN2	DY Status
L	L	L	L	А
L	L	Х	Н	Z
L	L	Н	Х	Z
L	Н	Н	Н	А
L	Н	Х	L	Z
L	Н	L	Х	Z
Н	Х	Х	Х	Z

High voltage levelLow voltage level Н

L

X = Don't care Z = High impedance "off" state

A = Active

DATA PATH IN ACTIVE MODE

INPUT	OUTPUT
DAn	DYn
L	L
Н	Н

74LVT1403

ABSOLUTE MAXIMUM RATINGS^{1, 2}

SYMBOL	PARAMETER	CONDITIONS	RATING	UNIT
V _{CC}	DC supply voltage		-0.5 to +4.6	V
VI	DC input voltage ³		-0.5 to +7.0	V
V _{OUT}	DC output voltage ³	Output in Off or High state	-0.5 to +7.0	V
		Output in Low state	128	mA
	DYn DC output current	Output in High state	-64	mA
OUT	RYn DC output current	Output in Low state	-32	mA
		Output in High state	64	mA
I _{IK}	DC input diode current	V ₁ < 0	-50	mA
I _{OK}	DC output diode current	V _O < 0	-50	mA
T _{stg}	Storage temperature range		-65 to +150	°C

NOTES:

 Stresses beyond those listed may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

The performance capability of a high-performance integrated circuit in conjunction with its thermal environment can create junction temperatures which are detrimental to reliability. The maximum junction temperature of this integrated circuit should not exceed 150°C.

3. The input and output negative voltage ratings may be exceeded if the input and output clamp current ratings are observed.

RECOMMENDED OPERATING CONDITIONS

SYMBOL	PARAMETER		LIN	IITS	
STMBUL			MIN	MAX	
V _{CC}	DC supply voltage		2.7	3.6	V
VI	Input voltage		0	5.5	V
V _{IH}	High-level input voltage		2.0		V
V _{IL}	Low-level Input voltage			0.8	V
1		DYn		-32	mA
IOH	High-level output current RYn			-20	mA
		DYn		32	mA
I _{OL}	Low-level output current	RYn		32	mA
	Low-level output current; current duty cycle \leq 50%, f \geq 1kHz	DYn		64	mA
$\Delta t/\Delta V$	Input transition rise or fall rate; Outputs enabled			10	ns/V
T _{amb}	Operating free-air temperature range		-40	+85	°C

DC ELECTRICAL CHARACTERISTICS

Over recommended operating conditions. Voltages are referenced to GND (ground = 0V).

						LIMITS		
SYMBOL	MBOL PARAMETER		OL PARAMETER TEST CONDITIONS		Temp	= -40°C to +	-85°C	
					MIN	TYP ¹	MAX	
V _{T+}	Positive-going threshold	RAn	V _{CC} = 3.3V		1.5	1.7	2.0	V
V_{T-}	Negative-going threshold	RAn	V _{CC} = 3.3V	V _{CC} = 3.3V		1.1	1.3	V
ΔV_T	Hysteresis	RAn	V _{CC} = 3.3V		0.4	0.6		V
VIK	Input clamp voltage		V _{CC} = 2.7V; I _{IK} = -18mA				-1.2	V
			$V_{CC} = 2.7$ to 3.6V; $I_{OH} = -10$	00μΑ	V _{CC} -0.2			V
		RYn	V _{CC} = 2.7V; I _{OH} = -6mA		2.4			V
V	High-level output		V _{CC} = 3.0V; I _{OH} = -20mA		2.0			V
V _{OH}	voltage		$V_{CC} = 2.7$ to 3.6V; $I_{OH} = -10$	0μΑ	V _{CC} -0.2	V _{CC} -0.1		V
		DYn	V _{CC} = 2.7V; I _{OH} = -8mA		2.4	2.5		V
			V _{CC} = 3.0V; I _{OH} = -32mA		2.0	2.2		V
			V _{CC} = 2.7V; I _{OL} = 100μA				0.2	V
		RYn	V _{CC} = 2.7V; I _{OL} = 24mA				0.5	V
			V _{CC} = 3.0V; I _{OL} = 32mA				0.5	V
V			V _{CC} = 2.7V; I _{OL} = 100μA			0.1	0.2	V
V _{OL}	Low-level output voltage		$V_{CC} = 2.7 V; I_{OL} = 24 m A$			0.3	0.5	V
		DYn	$V_{CC} = 3.0V; I_{OL} = 16mA$ $V_{CC} = 3.0V; I_{OL} = 32mA$			0.25	0.4	V
						0.3	0.5	V
			V _{CC} = 3.0V; I _{OL} = 64mA			0.4	0.55	V
			V _{CC} = 0 or 3.6V; V _I = 5.5V	All inputs		1	10	
		$V_{CC} = 3.6V; V_I = V_{CC}$ Control pins		Control pins		±0.1	±1	1
	INV, EN1,	INV, EN1, EN2, A/B		±0.1	±1	μA		
łı	Input leakage current		$V_{CC} = 3.6V; V_I = GND$	DE		-60	-100	1
			$V_{CC} = 3.6V; V_{I} = V_{CC}$	Data part4		0.1	1	
			V _{CC} = 3.6V; V _I = GND	Data port ⁴		-1	-5	μΑ
I _{OFF}	Output off current		$V_{CC} = 0V; V_{I} \text{ or } V_{O} = 0 \text{ to } 4.5$	5V		1	±100	μA
	Bus hold current RA and I	DA	V _{CC} = 3V; V _I = 0.8V		75	150		μA
HOLD	inputs		V _{CC} = 3V; V _I = 2.0V		-75	-150		μA
I _{EX}	Current into an output in the High state when $V_O > V_{CO}$		V _O = 5.5V; V _{CC} = 3.0V			60	125	μΑ
I _{PU/PD}	Power-up/down 3-State or current ³	utput	$V_{CC} \le 1.2V$; $V_O = 0.5V$ to V_C $V_I = GND$ or V_{CC} ; EN1, EN2, A/B, DE = Don't	$V_{CC} \le 1.2V$; $V_O = 0.5V$ to V_{CC} ; $V_I = GND$ or V_{CC} ; EN1. EN2. A/B. DE = Don't care		±1	±100	μΑ
I _{OZH}	3-State output high currer	ıt	V _{CC} = 3.6V; V _O = 3.0V			1	5	μA
I _{OZL}	3-State output low current		V _{CC} = 3.6V; V _O = 0.5V			-1	-5	μA
ICCH			$V_{CC} = 3.6V;$ Outputs High, V _I = GND or V	√ _{CC} , I _O = 0		0.13	0.19	mA
I _{CCL}	Quiescent supply current		V _{CC} = 3.6V; Outputs Low, V _I = GND or V	,		4	11	mA
I _{CCZ}	1		$V_{CC} = 3.6V;$ Outputs Disabled, $V_I = GND$	or V_{CC} , $I_0 = 0^5$		0.13	0.19	mA
ΔI_{CC}	Additional supply current pinput pin ²	ber	$V_{CC} = 3V$ to 3.6V; One input Other inputs at V_{CC} or GND	t at V _{CC} -0.6V,		0.1	0.2	mA

NOTES:

1. All typical values are at $V_{CC} = 3.3V$ and $T_{amb} = 25^{\circ}C$. 2. This is the increase in supply current for each input at the specified voltage level other than V_{CC} or GND. 3. This parameter is valid for any V_{CC} between 0V and 1.2V with a transition time of up to 10msec. From $V_{CC} = 1.2V$ to $V_{CC} = 3.3V \pm 0.3V$, a transition time of 100 μ sec is permitted. This parameter is valid for T_{amb} = 25°C only.

4. Unused pins at V_{CC} or GND.

^{5.} All RYn outputs High. All DYn outputs pulled up to V_{CC} or pulled down to ground.

74LVT1403

Product specification

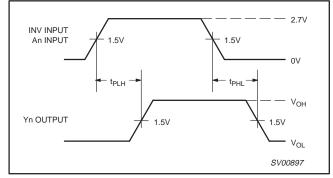
AC CHARACTERISTICS

RAn = Receive inputs; Ryn = Receive outputs DAn = Driver inputs; Dyn = Driver outputs

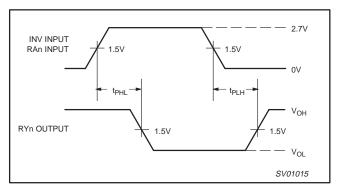
				L	MITS		
SYMBOL	PARAMETER	WAVEFORM	V _{CO}	$_{ m C}$ = 3.3V \pm 0	.3V	V _{CC} = 2.7V	UNIT
			MIN	TYP	MAX	MAX	
t _{PLH} t _{PHL}	Propagation delay RA0 to RY0	2	1.0 1.0	3.8 3.2	5.7 4.4	6.9 4.3	ns
t _{PLH} t _{PHL}	Propagation delay RAn to RYn (n = 1 to 7)	1, 2	2.0 2.0	4.5 4.0	6.7 5.7	7.8 6.4	ns
t _{PLH} t _{PHL}	Propagation delay Invert to RYn	1, 2	2.0 2.0	4.0 3.6	6.3 5.5	7.1 7.4	ns
t _{PLH} t _{PHL}	Propagation delay DAn to DYn	1	1.0 1.0	3.1 2.0	4.2 3.0	4.7 3.5	ns
t _{PZH} t _{PZL}	Output enable time ENn to DYn with $A/B = 0$	3	2.0 2.0	4.8 4.3	7.1 6.7	9.6 7.4	ns
t _{PZH} t _{PZL}	Output enable time ENn to DYn with $A/B = 1$	4	2.0 2.0	4.3 4.0	6.5 6.1	7.8 6.6	ns
t _{PHZ} t _{PLZ}	Output disable time ENn to DYn with A/B =0	3	2.0 2.0	4.7 4.0	7.1 6.3	8.2 6.9	ns
t _{PHZ} t _{PLZ}	Output disable time ENn to DYn with A/B =1	4	2.0 2.0	4.2 4.0	6.8 6.2	8.3 6.5	ns
t _{PZH} t _{PZL}	Output enable time A/B to DYn	3, 4	2.0 2.0	5.0 4.2	8.6 6.5	9.5 7.2	ns
t _{PHZ} t _{PLZ}	Output disable time A/B to DYn	3, 4	2.0 2.0	5.1 4.3	7.5 6.2	7.7 6.6	ns
t _{PZH} t _{PZL}	Output enable time DE to DYn	3	2.0 2.0	5.1 4.7	7.6 6.8	9.1 7.5	ns
t _{PHZ} t _{PLZ}	Output disable time DE to DYn	3	2.0 2.0	5.9 4.9	9.3 7.2	9.7 7.7	ns

AC WAVEFORMS

 V_{M} = 1.5V, V_{IN} = GND to 2.7V



Waveform 1. Input (An) to Output (Yn) Propagation Delays

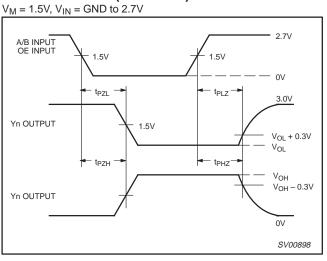


Waveform 2. Input (An) to Output (Yn) Propagation Delays

Product specification

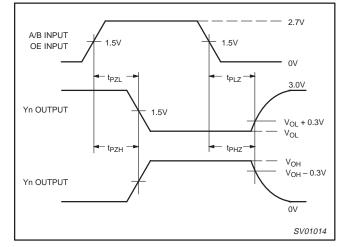
74LVT1403

AC WAVEFORMS (Continued)

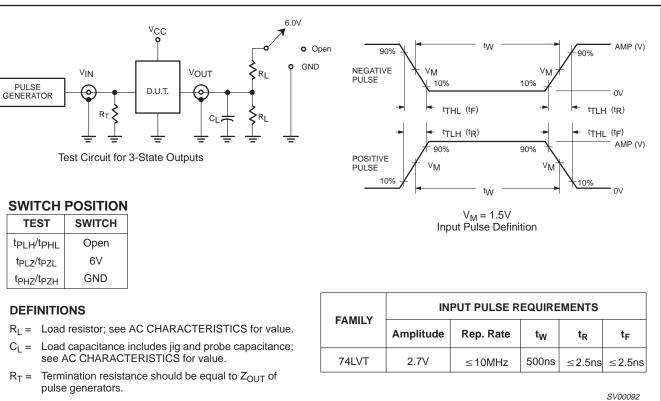


Waveform 3. 3-State Output Enable and Disable Times

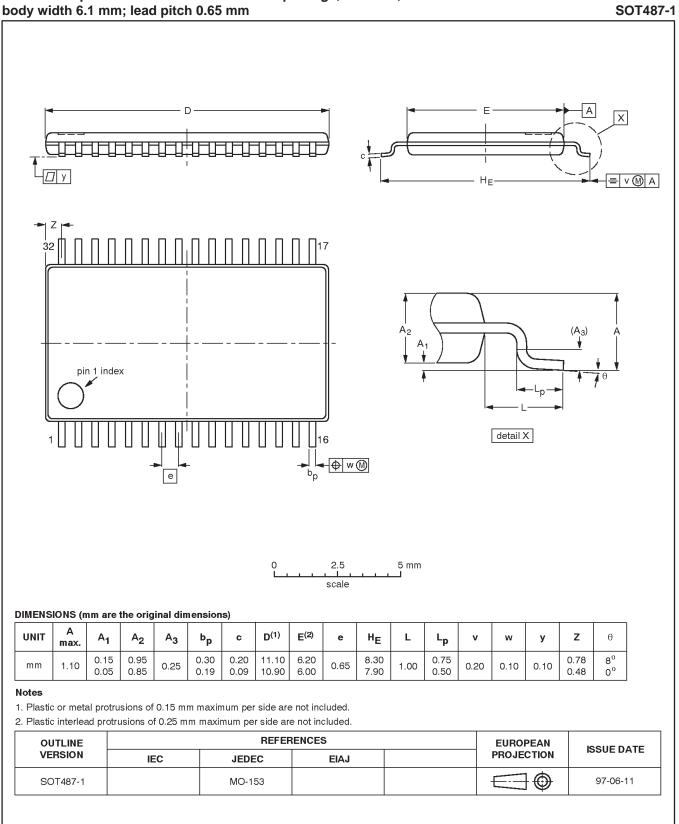
TEST CIRCUIT AND WAVEFORM







74LVT1403



TSSOP32: plastic thin shrink small outline package; 32 leads;

74LVT1403

NOTES

Data sheet status

Data sheet status	Product status	Definition ^[1]
Objective specification	Development	This data sheet contains the design target or goal specifications for product development. Specification may change in any manner without notice.
Preliminary specification	Qualification	This data sheet contains preliminary data, and supplementary data will be published at a later date. Philips Semiconductors reserves the right to make chages at any time without notice in order to improve design and supply the best possible product.
Product specification	Production	This data sheet contains final specifications. Philips Semiconductors reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.

[1] Please consult the most recently issued datasheet before initiating or completing a design.

Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition - Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

Application information - Applications that are described herein for any of these products are for illustrative purposes only. Philips Semiconductors make no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Disclaimers

Life support — These products are not designed for use in life support appliances, devices or systems where malfunction of these products can reasonably be expected to result in personal injury. Philips Semiconductors customers using or selling these products for use in such applications do so at their own risk and agree to fully indemnify Philips Semiconductors for any damages resulting from such application.

Right to make changes — Philips Semiconductors reserves the right to make changes, without notice, in the products, including circuits, standard cells, and/or software, described or contained herein in order to improve design and/or performance. Philips Semiconductors assumes no responsibility or liability for the use of any of these products, conveys no license or title under any patent, copyright, or mask work right to these products, and makes no representations or warranties that these products are free from patent, copyright, or mask work right infringement, unless otherwise specified.

Philips Semiconductors 811 East Arques Avenue P.O. Box 3409 Sunnyvale, California 94088-3409 Telephone 800-234-7381

© Copyright Philips Electronics North America Corporation 1998 All rights reserved. Printed in U.S.A.

Date of release: 05-98

Document order number:

9397-750-04815

Let's make things better.



