AVR ONE!

Quick-start Guide

EVK1101 + Windows®



Continu	-	
Section		
	tion	
1.1	General	
1.2	Requirements	I-I
Section	2	
Quick-sta	art guide (short version)	2-1
2.1	Install Hardware and software	2-1
2.2	Create a demonstration project	2-1
2.3	Configure target MCU for a debug session using trace	2-1
2.4	Start the debug session and configure AVR32 Studio 2.5 for tra	.ce 2-2
2.5	Start the trace debug session	2-2
Section	3	
Software	e Installation	4-1
3.1	Download the software	4-1
3.2	Download the two installation files to your disk	4-2
3.3	Install AVR32 GNU Toolchain	4-2
3.4	Install AVR32 Studio 2.5	4-8
3.5	Connect the AVR ONE! to power and USB host	4-11
3.6	Install AVR ONE! Driver	4-12
Section	4	
4.1	Connect the AVR ONE! to the EVK1101	5-1
4.2	Connect the EVK1101 to power and RS232	5-2
Section	5	
Create d	demo application	6-1
	Start AVR32 Studio	
5.2	Configure adapter and target	6-2
	5.2.1 Add and configure the adapter (AVR ONE!)	6-3
	5.2.2 Configure target board and MCU	6-4
	5.2.3 Target MCU Chip erase	6-5
5.3	Create a demonstration project	6-6
5.4	Configure AVR32 Studio for a debug session using trace	6-9
	5.4.1 Create a new debug launch configuration	6-10
	5.4.2 Configure the target trace module for program trace	
	5.4.3 Configure the target trace module for data trace	
5.5	Start a debug session and configure the debugger for trace	
5.6	Add start and stop trace-points	
5.7	Start the trace debug session	
5.8	View trace data	6-24



Table of Contents (Continued)

	5.9	Modify the application	6-27
Se	ction	6	
Fir	mware	Upgrade	7-1
	6.1	Firmware upgrade overview	7-1
	6.2	Firmware version test and upgrade	7-1
	6.3	Adapter in use	7-2







Introduction

1.1 General

This document contains a quick-start guide describing how to get up and running using the AVR[®] ONE! debugger with AVR32 Studio. In addition to the AVR ONE! debugger, you need the following items:

- AVR32 Studio 2.5 software
- AVR32 GNU Toolchain 2.4
- EVK110x Evaluation board

Software and documents can be found at www.atmel.com/avrone

1.2 Requirements

This example was created on a PC running Microsoft® Windows® XP Professional. For other versions of Windows, the behaviour when installing software and drivers may be slightly different.

Please read the AVR32 Studio 2.5 release notes for information about support for other versions of Windows.

AVR ONE! Quick-start Guide 1-1



Quick-start guide (short version)

2.1 Install Hardware and software

- Download and install avr32-gnu-toolchain-2.4.x and AVR32Studio-2.5.x.
- Connect AVR ONE! to power and USB and turn it on.
- Install AVR ONE! USB driver.
- Connect AVR ONE! to the EVK1101 using the 10pin JTAG connector.
- Connect the EVK1101 to power and turn it on.
- Start AVR32 Studio.
- Select a suitable workspace folder to contain your projects.
- Exit from the welcome screen to workbench.
- Right-click in the AVR32 Targets view and select Scan Targets.
- Select the AVR ONE! and click on the *Properties*-tab.
- Select *Board*-tab. Set Board to **EVK1101**, MCU to **UC3B0256** or **UC3B256ES**, depending on what MCU is mounted on your EVK1101.
- Right-click on the AVR ONE! in the AVR32 Target view and select **Chip Erase**. This operation is only needed one time (when the EVK1101 is new).

2.2 Create a demonstration project

- Select File>New>Example.
- Select EVK1101>Components>Accelerometer example, then Next.
- Enter a name for the project, and click **Finish**.
- Right-click on the project in *Project Explorer* view and select **Build Project** (or use Ctrl+B).

2.3 Configure target MCU for a debug session using trace

- When the build process is finished, right-click on the project in the *Project Explorer*-view and select *Debug As>Debug Configurations*.
- In the *Debug*-view, select **AVR32 Application** and click **New**. A new launch configuration will be created and default values will be filled into all fields.
- Select the *Trace*-tab and click **Enable Trace**.
- Select the preferred trace method. In this case we want **Nano Trace**.
- Select the preferred action when buffer is full. In this case we choose Break, read out and halt.
- Deselect the option Break on application buffer access
- Set Buffer Size. Select **Specify size and location**, then click **Detect**.

AVR ONE! Quick-start Guide 2-1

2.4 Start the debug session and configure AVR32 Studio 2.5 for trace

- Click the **Debug**-button. Now the program will be loaded into the target, and run until main().
- When the program halts, add at least a trace start-point (Right-click to the left of the source code line in the source code view).

2.5 Start the trace debug session

- Click **Resume** (green *Play* button in Debug view) and wait until the program halts.
- You can now look at the trace data in the *Trace*-view.





Software Installation

3.1 Download the software

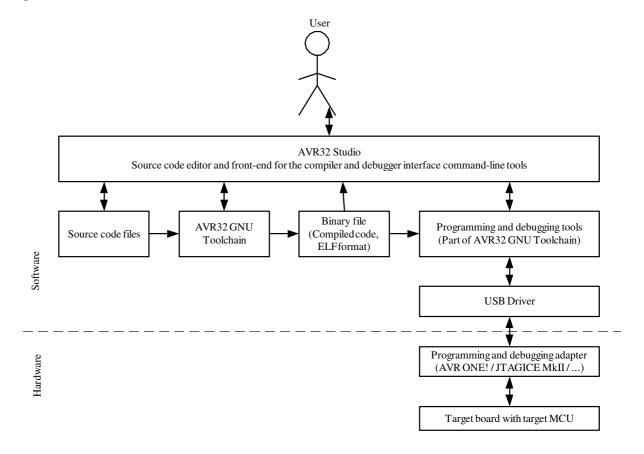
To use the AVR ONE!, you must download and install two software packages:

- avr32-gnu-toolchain-2.4.x.exe
- AVR32Studio-2.5.x.exe

The AVR32 Toolchain is a collection of tools that are required to be able to work with the AVR ONE! It contains command-line tools for controlling the AVR ONE!, and tools to compile code for the AVR32 MCUs.

AVR32 Studio is the front end that uses the AVR32 GNU Toolchain to generate binary code for the target, program the target, and control the debug sessions.

Figure 3-1. Tools structure



AVR ONE! Quick-start Guide 4-1

3.2 Download the two installation files to your disk.

The installation files can be found at this location: www.atmel.com/avrone

3.3 Install AVR32 GNU Toolchain

If you have any AVR tools connected to the USB hub, turn them off now. Otherwise the USB driver installation may fail.

Double-click on avr32-gnu-toolchain-2.4.x to start the installation process.

Figure 3-2. AVR32 GNU Toolchain installation welcome



Click Next.



Figure 3-3. AVR32 GNU Toolchain License Agreement form



Select I accept the terms of the licence agreement, then click Next.

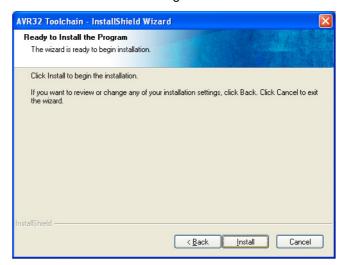
Figure 3-4. AVR32 GNU Toolchain installation folder select



Check that the installation folder is correct and click **Next**.



Figure 3-5. AVR32 GNU Toolchain installer configuration finished



Click Install.

Figure 3-6. AVR32 GNU Toolchain installation progress indicator



The AVR32 GNU Toolchain is now being installed. As a part of the installation process, USB drivers for all supported programming and debugging adapters are installed.



Figure 3-7. USB Drivers installation start



Figure 3-8. USB Driver installer welcome



Click Next.

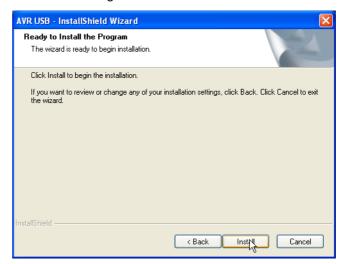


Figure 3-9. USB Drivers licence agreement form



Select I accept the terms of the licence agreement, then click Next.

Figure 3-10. USB drivers installer configuration finished



Click Install.



Figure 3-11. USB Drivers installation progress indicator

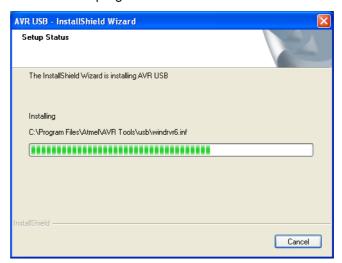
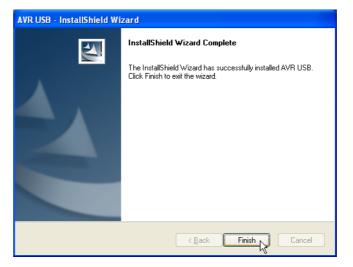


Figure 3-12. USB Drivers installation complete



Click Finish.



Figure 3-13. AVR32 GNU Toolchain installation complete



Click **Finish** to complete the AVR32 Toolchain installation process.

3.4 Install AVR32 Studio 2.5

Double-click on the AVR32Studio-2.5.x.exe file to start the installation process.

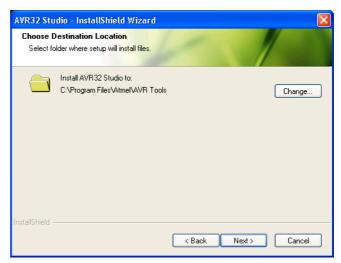
Figure 3-14. AVR32 Studio 2.5 installer welcome



Click Next.

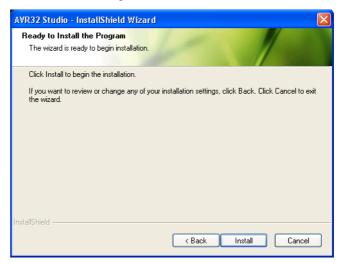


Figure 3-15. AVR32 Studio installation folder select



Check that the installation folder is correct and click Next.

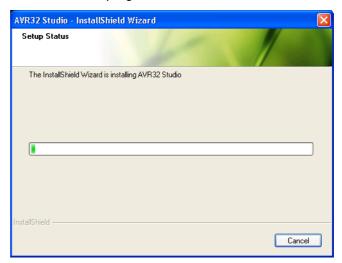
Figure 3-16. AVR32 Studio installer configuration finished



Click Install to start the installation.



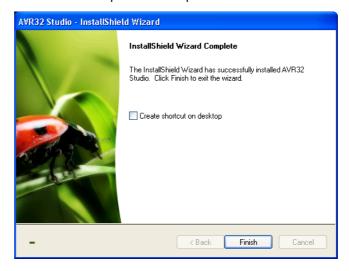
Figure 3-17. AVR32 Studio installation progress indicator



Wait for the installation process to complete.

If a suitable Java™ runtime is not installed, a Java installer wizard will guide you through the installation procedure.

Figure 3-18. AVR32 Studio installation process complete



Tick Create shortcut on desktop if you want a shortcut to be created. Then click Finish.

3.5 Connect the AVR ONE! to power and USB host

- Connect the AVR ONE! to power using the supplied power supply.
- Connect the AVR ONE! to the USB host (PC) using the supplied USB cable
- Turn on the AVR ONE! using the power switch next to the power connector

Figure 3-19. AVR ONE! connected to power and USB



3.6 Install AVR ONE! Driver

When the AVR ONE! is powered up and connected to the PC for the first time, the proper USB driver must be installed. Since the PC is keeping track of the serial number of each USB device, this will happen every time a new AVR ONE! is connected to the PC, even if the driver is the same as for all other AVR ONE!s that have been connected previously. This is a property of the operating system, and is not controlled by any Atmel software installed.

Figure 3-20. "New hardware" notification pop-up

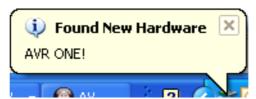


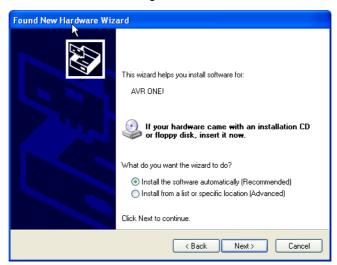
Figure 3-21. AVR ONE! Hardware installation wizard



When the hardware installation wizard pops up, select No, not this time and click Next.

32104B-AVR ONE!-02/10

Figure 3-22. Hardware installation wizard configuration



Select Install the software automatically and click Next.

Figure 3-23. Hardware installation in progress



Wait for the installation process to complete.

Figure 3-24. Hardware installation wizard complete



Click Finish.





4.1 Connect the AVR ONE! to the EVK1101

Connect the AVR ONE! debugger to the EVK1101 evaluation board using the 10 pin JTAG connector. To make it possible to use the joystick while the AVR ONE! is connected to the JTAG connector, the 100mil - 100mil JTAG stand-off adapted can be used.

Figure 4-1. AVR ONE! connected to the EVK1101



AVR ONE! Quick-start Guide 5-1

4.2 Connect the EVK1101 to power and RS232

Connect the EVK1101 to power and turn it on. The easiest way to provide power is to use the supplied USB cable. Also connect the RS232 port to your PC using the supplied RS232 cable.

Switch it on by setting the power switch to **VBUS**.

Figure 4-2. Powering the EVK1101 using the USB cable



Note: If the EVK1101 contains the Control Panel Demo Application, you may be requested to install drivers for it. Just cancel this request (you do not need to install this driver).



Create demo application

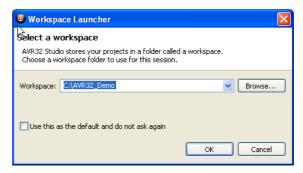
5.1 Start AVR32 Studio

Start AVR32 Studio. Start-up may take a while (because of all the Java libraries being loaded).

Figure 5-1. AVR32 Studio splash screen



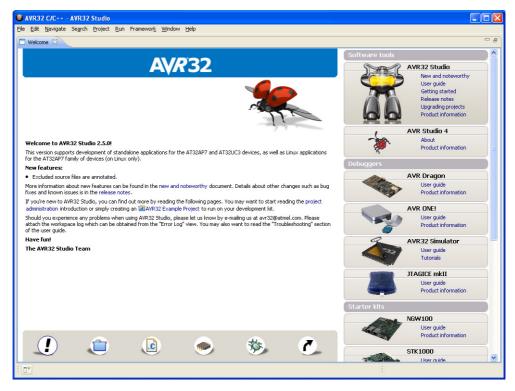
Figure 5-2. AVR32 Studio workspace selection



Select a suitable workspace folder for your project files. If you want to use the same folder for your workspace every time you start AVR32 Studio, you should tick the box before clicking **OK**.

AVR ONE! Quick-start Guide 6-1

Figure 5-3. AVR32 Studio Welcome view



Exit from the welcome screen to the workbench by clicking on the **Close Page** icon (Arrow).

5.2 Configure adapter and target

Before you can use the AVR ONE! and the EVK1101, you have to tell AVR32 Studio what type of equipment is connected to your PC.

"Target" refers to the MCU on the EVK1101 evaluation board, and "Adapter" refers to the tool connecting the target to the PC (in this case, the AVR ONE!).



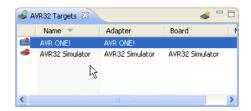
5.2.1 Add and configure the adapter (AVR ONE!)

Figure 5-4. Scan Targets



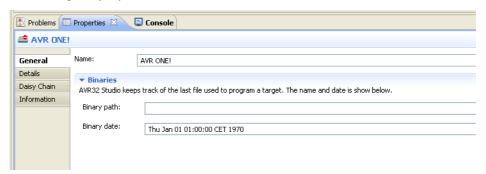
Right-click in the AVR32 Target-view and select Scan Targets.

Figure 5-5. Available targets



Select the AVR ONE!

Figure 5-6. Selecting the properties view



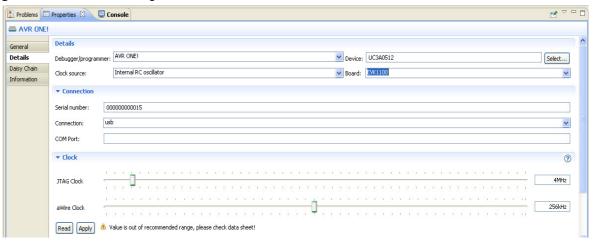
Click on the Properties tab.

You are now looking at the *Target* properties. If you have several adapters connected at the same time, this is the place where you can give them unique names. Just type the name you want to use in the **Name** field.



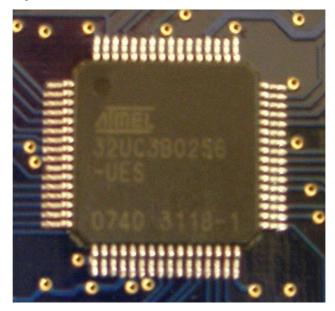
5.2.2 Configure target board and MCU

Figure 5-7. Details configuration tab



Set Device to UC3B0256 or UC3B0256ES, depending on what MCU is installed on your EVK1101.

Figure 5-8. MCU Markings



To check which type of MCU is mounted on your EVK1101 evaluation board, you can read the part number printed on the MCU. The picture shows the part number printed on an -ES part (-UES suffix).

Set Board to EVK1101.

Set **MCU Clock source** to **Crystal** and adjust the JTAG Clock to a suitable value (Usually 33MHz or less. Max speed depends on target board signal quality). Click **Apply**.

The target and adapter configuration process is now complete.



5.2.3 Target MCU Chip erase

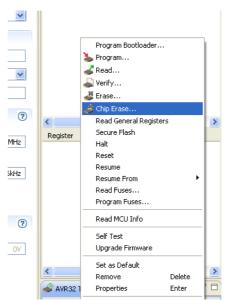
If the EVK1101 evaluation board is brand new, or if it still contains the original demo application (Control Panel Demo), the FLASH lock-bits need to be cleared. Right-click on the AVR ONE! In the AVR32 Target view and select **Chip Erase**.

WARNING! This process will erase the original demo application programmed at the factory. After this operation the EVK1101 evaluation board will be completely empty. If you need to keep the original application, you should not perform this operation.

If you would like to use your EVK1101 for this example, it is not difficult to restore the original "Control Panel Demo application". All you have to do is to build the "Control Panel Demo example" enclosed with AVR32 Studio.

You should now perform the **Chip Erase** operation.

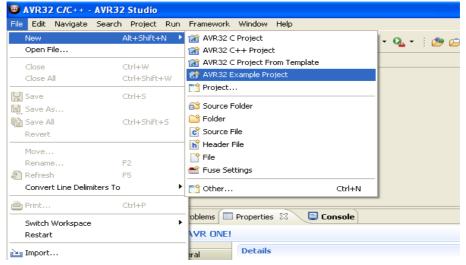
Figure 5-9. Chip erase operation



Right click on the target (AVR ONE!), and select **Chip Erase**.

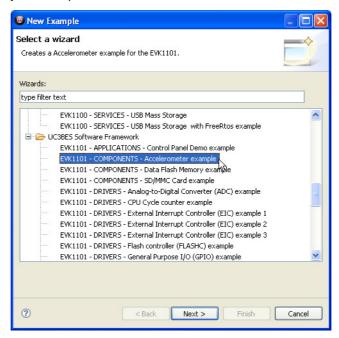
5.3 Create a demonstration project

Figure 5-10. Create new project



Create a new project by clicking File>New>AVR32 Example Project.

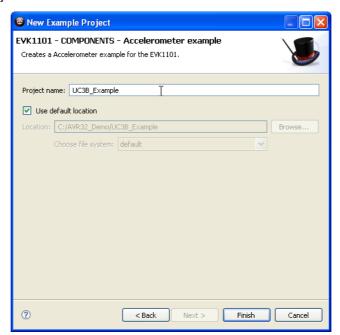
Figure 5-11. Select project example



Select EVK1101 - Components - Accelerometer example, then click Next



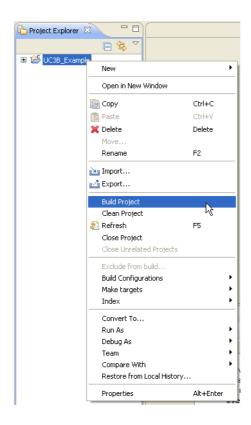
Figure 5-12. New project name



Enter a name for the project, and click **Finish**.

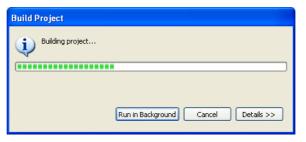


Figure 5-13. Build project



Right-click on the project in **Project Explorer**-view and select **Build Project** (or press CTRL+B).

Figure 5-14. Project build progress



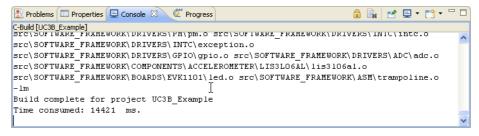
Wait for the project build process to finish.



6-8

32104B-AVR ONE!-02/10

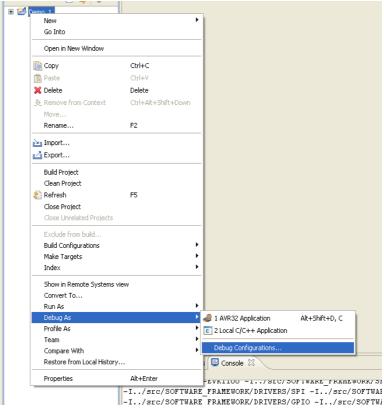
Figure 5-15. Console view



The console shows output from the compiler. Make sure that this ends with a "Build complete ..." message (Except for the "Time consumed" message). If something is not working, you will see error messages in this view.

5.4 Configure AVR32 Studio for a debug session using trace





When the build process is finished, right-click on the project in the *Project Explorer* view and select *Debug As>Debug Configurations*.

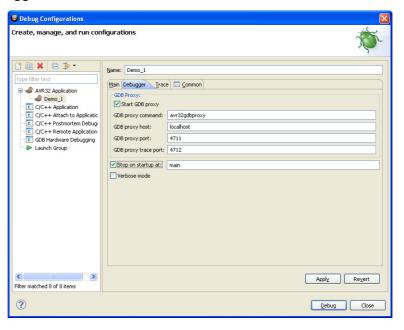


5.4.1 Create a new debug launch configuration

In the *Debug Configurations* view, select **AVR32 Application** and right click and select **New**. A new launch configuration will be created and default values will be filled into all applicable fields.

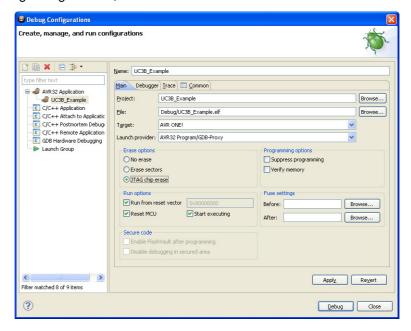
Select the *Debugger* tab and tick the **Stop on startup at: main** option.

Figure 5-17. Debugger tab



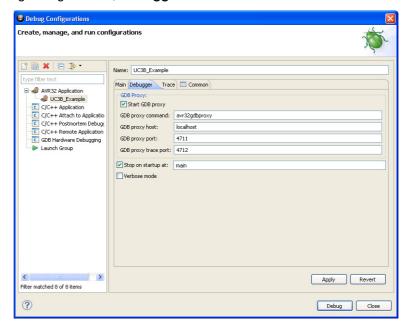
5.4.2 Configure the target trace module for program trace

Figure 5-18. Debug configurations, Main tab



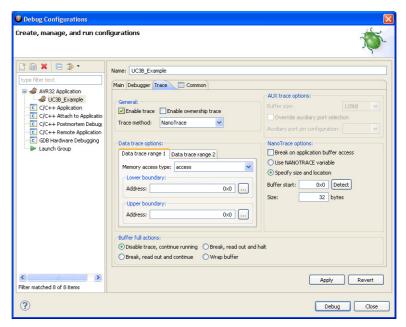
In the Main tab, make sure that Target is set to AVR ONE!

Figure 5-19. Debug configurations, Debugger tab



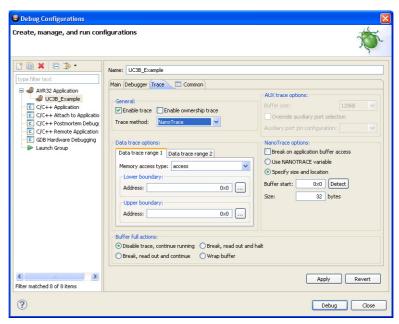
Select the **Debugger** tab and check the checkbox at the option **Stop on startup at: main**.

Figure 5-20. Enable Trace



Select the **Trace** tab and check **Enable Trace**.

Figure 5-21. Preferred Trace method

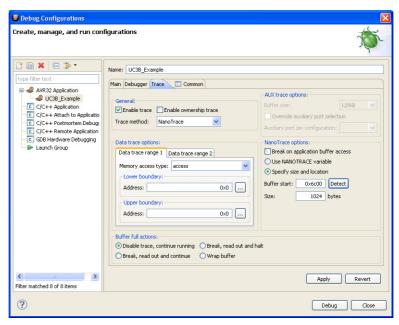


Select the preferred trace method. In this case we want Nano Trace.

Deselect Break on application buffer access.

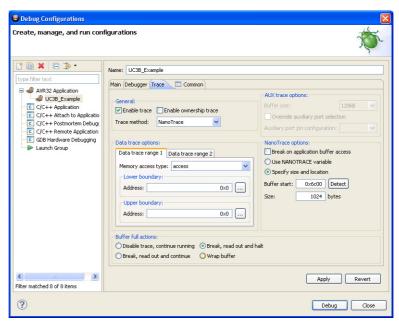


Figure 5-22. Trace buffer size



Select **Specify size and location** option. Then click **Detect** to configure trace buffer size and location.

Figure 5-23. Buffer full action



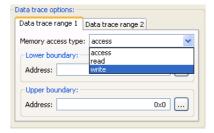
Selected the preferred action when buffer is full. In this case we choose **Break**, read out and halt.

32104B-AVR ONE!-02/10

5.4.3 Configure the target trace module for data trace

We would like to trace all data written to the debug UART. We do a quick lookup in the datasheet and find that the UART registers are located between 0xffff1400 and 0xffff1d00. Although we only use one UART in this application, we configure the data trace range to cover all UARTs.

Figure 5-24. Memory access type



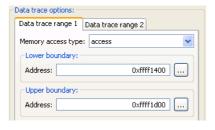
Set Memory access type to write.

Figure 5-25. Data trace lower boundary



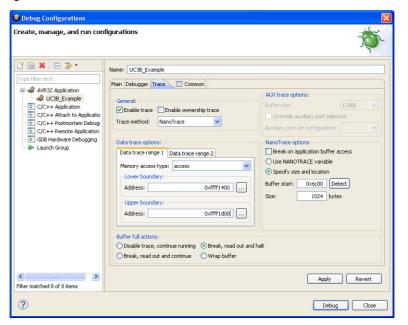
Set lower boundary to 0xffff1400.

Figure 5-26. Data trace upper boundary



Set upper boundary to 0xffff1d00.

Figure 5-27. Configured trace





32104B-AVR ONE!-02/10

5.5 Start a debug session and configure the debugger for trace

Click the **Debug** button in the *Debug Confugurations* view. Now the program will be loaded into the target, and run until main().

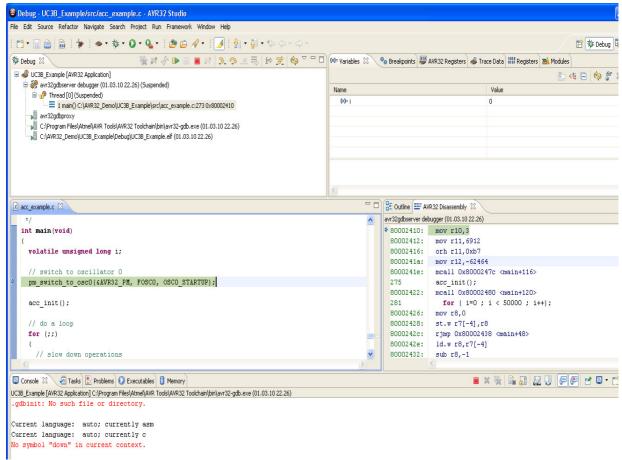
Figure 5-28. Switching perspective



When the debug session starts, AVR32 Studio 2.5 will change to the *Debug* perspective (desktop layout designed for use during debug sessions). You should click **Yes**. To avoid being asked every time you start a debug session, you should also click the **Remember my decision** box before answering **Yes**.

Wait until the target has stopped at the first instruction in the ${\tt main}$ () routine.

Figure 5-29. Program halted at main()



5.6 Add start and stop trace-points

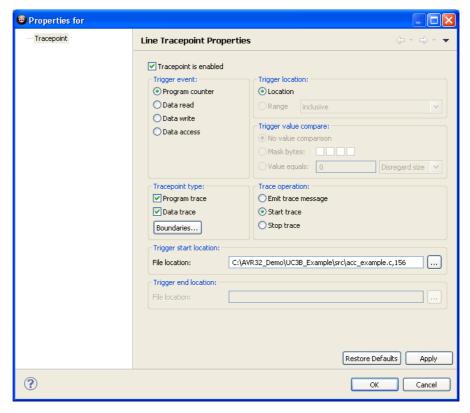
Figure 5-30. Source code editor

```
□ □ □ Outline ■ AVR32 Disass
avr32gdbserver debugger (01.
    static xyz t angle ;
                                                                                                         ♦ 80002410: mov r
                                                                                                          80002412:
80002416:
  // if ( ! is_acc_slow() ) { return }
                                                                                                                      mov r
                                                                                                                      orh r
              0!=(res=is\_acc\_abs\_angle\_x(60)) ) angle.x = 60;
                                                                                                          8000241a: mov r
    else if( 0!=(res=is_acc_abs_angle_x(30)) ) angle.x = 30;
                                                                                                          8000241e:
                                                                                                                      mcall
                                                 angle.x = 0;
    else
                                                                                                          275
                                                                                                                      acc_i
                                                                                                          80002422: mcall
    if (angle.x > 0)
                                                                                                          80002426:
                                                                                                                      mov r
       if(     res>0 ) print dbg("LEFT ") ;
                                                                                                          80002428:
                                                                                                                      st.w
       else if( res<0 ) print_dbg("RIGHT ") ;</pre>
                                                                                                          8000242c:
                                                                                                                      rjmp
                                                                                                          8000242e: ld.w
                                                                                                                     sub r
                                                                                                          80002432:
       print_dbg_ulong(angle.x) ;
🖳 Console 🛭 🙋 Tasks 🦹 Problems 🕡 Executables 📋 Memory
UC3B_Example [AVR32 Application] C:\Program Files\Atmel\AVR Tools\AVR32 Toolchain\bin\avr32-gdb.exe (01.03.10 22.26)
Current language: auto; currently c
No symbol "down" in current context.
```

Scroll up to line 156 in the file acc_example.c and right-click at the left edge of the editor. Select **Add Tracepoint...** from the pop-up menu.



Figure 5-31. Tracepoint (Start)



Set Tracepoint Configuration values:

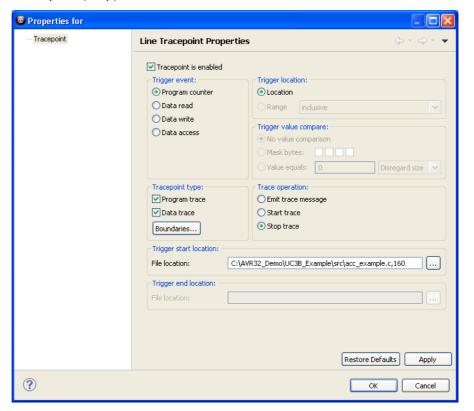
- Set Trigger Event to Program Counter
- Set Trace Operation to Start Trace
- Set Tracepoint type to both Program trace and Data trace
- Click OK

This will create a tracepoint that starts both program and data trace when the program counter hits this code line.

Scroll down to line 160 in the file acc_example.c and right-click at the left edge of the editor. Select **Add Tracepoint...** from the pop-up menu.

32104B-AVR ONE!-02/10

Figure 5-32. Tracepoint (Stop)



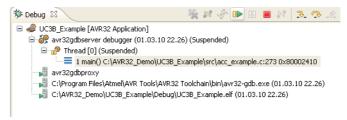
Set Tracepoint Configuration values:

- Set Trigger Event to Program Counter
- Set Trace Operation to Stop Trace
- Set Tracepoint type to both Program trace and Data trace
- Click OK

This will create a tracepoint that stops both program and data trace when the program counter hits this code line.

5.7 Start the trace debug session

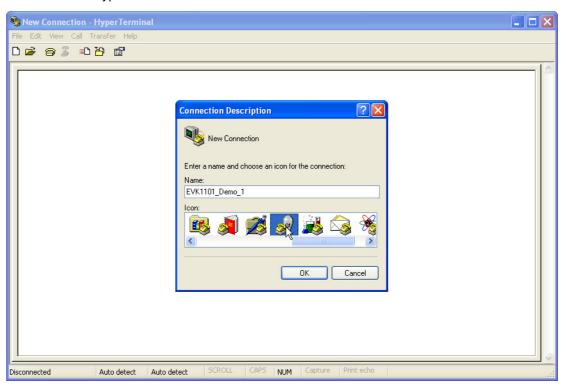
Figure 5-33. Resume debug session



Make sure that the main() process is still selected in the *Debug* view before pressing the **Resume** button.

Start a serial port terminal to view the output from the debug UART. To make it simple, we just start Hyperterminal. Click on *Start>All Programs>Accessories>Communications>Hyperterminal*.

Figure 5-34. New Hyperterminal



Enter a name for the session and click **OK**.

6-21

32104B-AVR ONE!-02/10

Figure 5-35. Hyperterminal port selection



Seletc the com-port that you connected the EVK1101 to (in this case we use **Com1**).

Figure 5-36. Hyperterminal port configuration



Set port parameters:

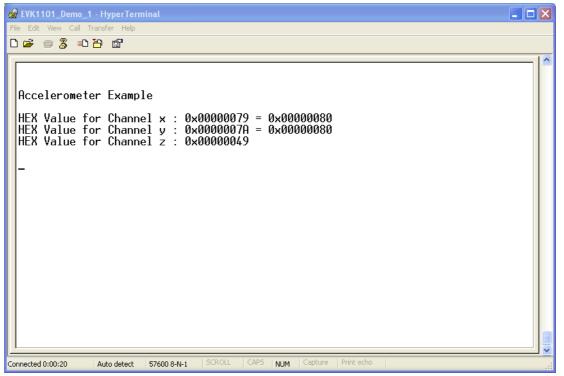
Bits per second: 57600

Data bits: 8Parity: NoneStop bits: 1

- Flow control: None

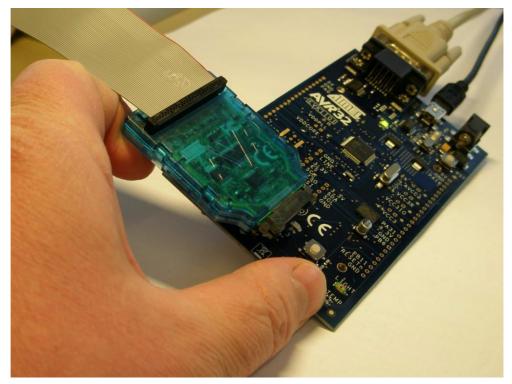
Click OK.

Figure 5-37. Demo application output



Tilt the EVK1101 board carefully as shown in the photograph. Start with the board laying flat on the table, and increase the tilt slowly.

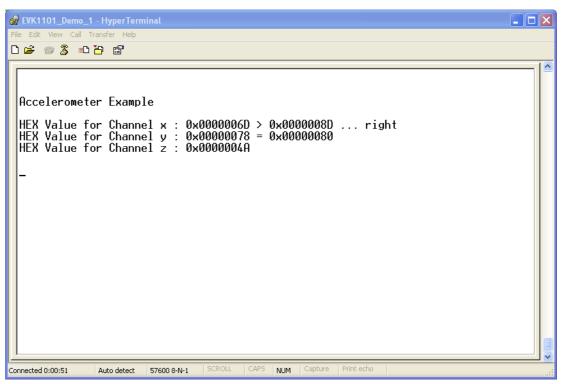
Figure 5-38. Tilting the EVK1101 board





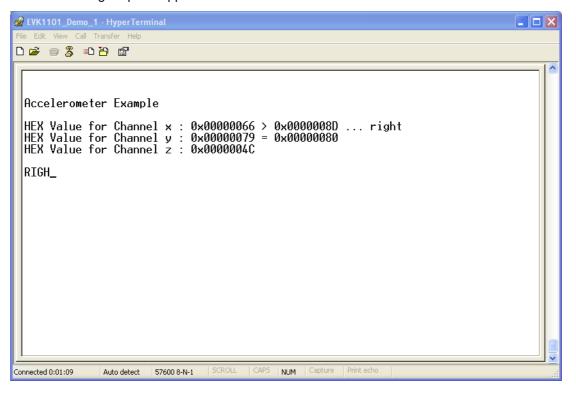
When the tilting angle reaches a certain value, the debug output notifies you about which direction the board is being tilted.

Figure 5-39. Tilt direction indicator



When the tilt angle reaches 30 degrees, the program wants to print an additional message saying RIGHT30. When this happens, the program counter hits the start tracepoint, and trace data will start being collected.

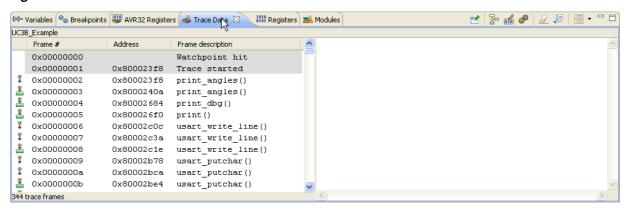
Figure 5-40. Debug output stopped when trace buffer full



When the trace buffer in the target MCU is full, the program will break, and trace data will be uploaded to AVR32 Studio for inspection.

5.8 View trace data

Figure 5-41. Trace data view

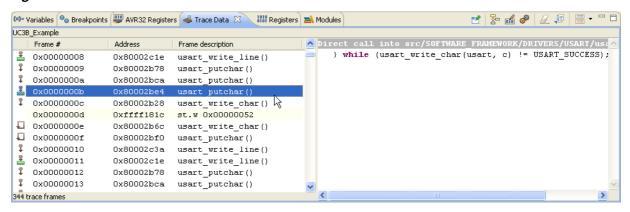


Click on the Trace Data tab to view the trace frames.



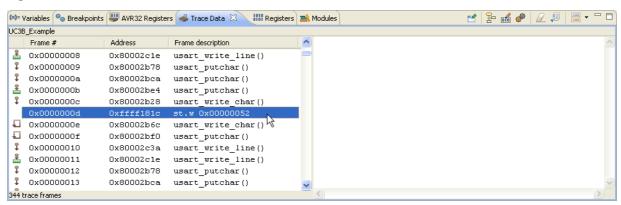
6-24

Figure 5-42. Reconstructed source code



Click on a trace frame to view the reconstructed code that was executed by the MCU.

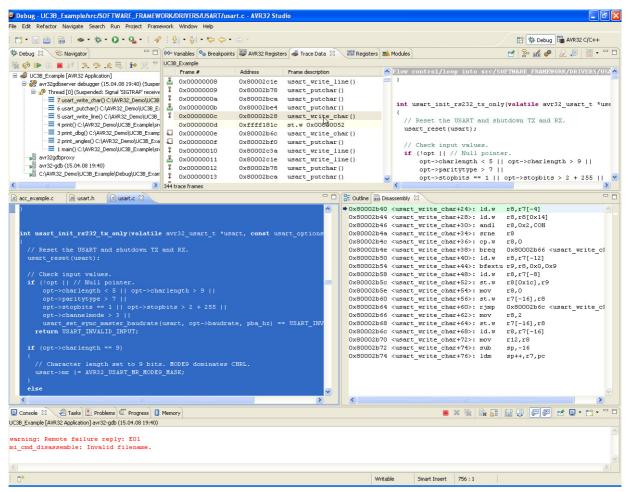
Figure 5-43. Data trace frame



A data trace frame showing a byte being written to the debug UART transmit register. By enabling data trace only, we can see all characters being sent to the terminal.



Figure 5-44. Source code in editor

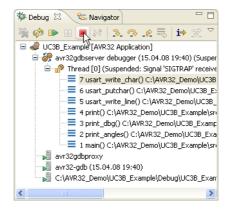


Double-click on a trace frame to show the source code in the editor.



5.9 Modify the application

Figure 5-45. Terminate the debug session



Click the **Stop** icon to terminate the debug session.

Figure 5-46. Go to source code

```
- -
© acc_example.c ☒ In usart.h © usart.c
    // switch to oscillator O
    pm_switch_to_oscO(&AVR32_PM, FOSCO, OSCO_STARTUP);
    acc_init();
    // do a loop
    for (;;)
      // slow down operations
      for ( i=0 ; i < 50000 ; i++);</pre>
      // display a header to user
     print_dbg("\x1B[2J\x1B[H\r\n\r\nAccelerometer Example r\n\r\n");
      // Get accelerometer acquisition and process datas
      acc update();
      // test for fast or slow changes
      // depending on that, play with angles or moves
      if ( is_acc_slow() )
        print_mouse() ;
        print angles();
```

Edit the string.

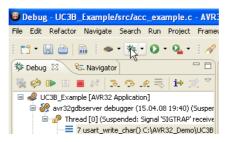


Figure 5-47. Modified source code

```
© *acc_example.c ☒ 🖟 usart.h
                            🕝 usart.c
    // switch to oscillator O
                                                                                    ^ =
    pm switch to osc0(&AVR32 PM, FOSCO, OSCO STARTUP);
    acc init();
    // do a loop
    for (;;)
      // slow down operations
      for ( i=0 ; i < 50000 ; i++);
      // display a header to user
      print_dbg("\x1B[2J\x1B[H\r\n\r\nMy First UC3 Application\r\n\r\n");
      // Get accelerometer acquisition and process datas
                                                                           Ι
      acc update();
      // test for fast or slow changes
      // depending on that, play with angles or moves
      if ( is_acc_slow() )
        print mouse();
        print_angles() ;
```

When the source code has been edited, simply restart the previous debug session.

Figure 5-48. Restart debug session



Click on the **Debug** icon to start a new debug session using the same launch configuration as the previous session.

Figure 5-49. Save modifide source code

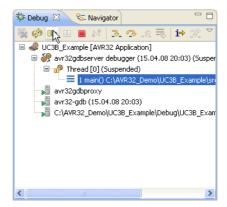


If you did not save the modifide source code, you will be notified now (click **Yes**). After the source code has been saved, AVR32 Studio will re-compile the application and program the target MCU before starting the debug session. The code will run break at main() again.

AVR ONE! Quick-start Guide 6-28

32104B-AVR ONE!-02/10

Figure 5-50. Resume debug session



Click on the **Resume** icon to resume the debug session.

Figure 5-51. Modified debug output

Observe the modified output containing your own text.

Congratulations! You have now created your first AVR32 application and collected real time trace data from the target MCU running your program using the AVR ONE!





Firmware Upgrade

6.1 Firmware upgrade overview

The tools (adapters) used to provide the physical connection between PC and target MCU contains firmware. This firmware needs to be compatible with the gnu toolchain and AVR32 Studio installed on the PC.

When AVR32 Studio is started, or when a new adapter is detected, AVR32 Studio will perform a firmware version check to determine if the adapter firmware needs to be upgraded.

If AVR32 Studio contains a newer firmware than present in the adapter, the adapter will be upgraded.

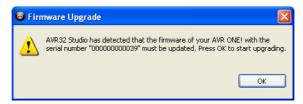
6.2 Firmware version test and upgrade

When AVR32 Studio is testing the firmware version of connected adapters, you can see a progress indicator in the status line.

Figure 6-1. Firmware version test



Figure 6-2. Firmware upgrade message



If the adapter firmware must be upgraded, you will be notified by a pop-up. Click **OK** to continue.

AVR ONE! Quick-start Guide 7-1

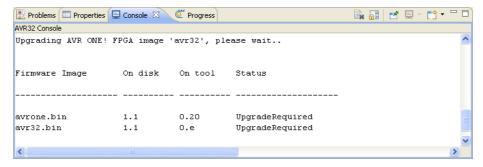
Firmware upgrade progress can be monitored by activating the *Progress* view.

Figure 6-3. Firmware upgrade progress



A firmware upgrade report can be found in the *Console* view.

Figure 6-4. Firmware upgrade report

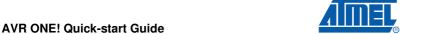


6.3 Adapter in use

The firmware version test is a process that is running in the background. This may cause a situation where the adapter is busy (debug session active) when AVR32 Studio determines that the firmware should be upgraded. In this case, the firmware upgrade process will wait until the adapter is not busy anymore (debug session terminated).

Figure 6-5. Firmware upgrade process waiting for adapter







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