

TDA8946AJ 2 x 15 W BTL audio amplifier with DC gain control Rev. 01 — 01 March 2002

Product data

General description 1.

The TDA8946AJ is a dual-channel audio power amplifier with DC gain control. It has an output power of 2×15 W at an 8 Ω load and an 18 V supply. The circuit contains two Bridge-Tied Load (BTL) amplifiers with an all-NPN output stage and standby/mute logic. The overall gain can be adjusted from +30 dB down to -50 dB using a DC control voltage. This feature can be used for volume control or for a preset gain. The TDA8946AJ comes in a 17-pin DIL-bent-SIL (DBS) power package and is pin compatible with the TDA8946J.

Features 2.

- Gain/volume adjustment via a DC control pin
- Soft clipping
- Operating at a low supply voltage
- Standby and mute mode
- No on/off switching plops
- Low standby current
- High supply voltage ripple rejection
- Outputs short-circuit protected to ground, supply and across the load
- Thermally protected
- Printed-circuit board compatible with TDA8944AJ and TDA8580J.

Applications 3.

- Mains fed applications (e.g. TV sound)
- PC audio
- Portable audio.

Quick reference data 4.

Table 1:	Quick reference data					
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V _{CC}	supply voltage		4.5	18	18	V
lq	quiescent supply current	V_{CC} = 18 V; R_L = ∞	-	45	55	mA
I _{stb}	standby supply current		-	-	10	μΑ
Po	output power	$\label{eq:thdef} \begin{split} THD &= 10\%; R_L = 8\ \Omega; \\ V_{CC} &= 18\ V \end{split}$	13	15	-	W
THD	total harmonic distortion	$P_o = 1 W$	-	0.07	0.5	%



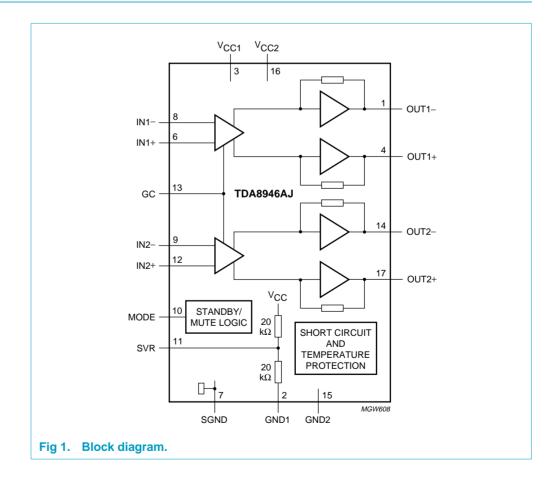
Table 1: Quick reference data...continued...continued

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
G _{v(max)}	maximum voltage gain		29	30	31	dB
G _{v(cr)}	voltage gain control range		-	80	-	dB
SVRR	supply voltage ripple rejection		-	55	-	dB

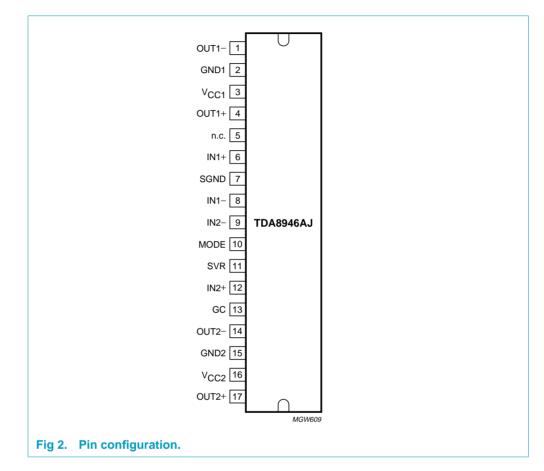
5. Ordering information

Table 2: Ordering information					
Type number	Package				
	Name	Description	Version		
TDA8946AJ	DBS17P	plastic DIL-bent-SIL power package; 17 leads (lead length 12 mm)	SOT243-1		

6. Block diagram



7. Pinning information



7.1 Pinning

7.2 Pin description

Table 3:	Pin description	
Symbol	Pin	Description
OUT1-	1	negative loudspeaker terminal 1
GND1	2	ground channel 1
V _{CC1}	3	supply voltage channel 1
OUT1+	4	positive loudspeaker terminal 1
n.c.	5	not connected
IN1+	6	positive input 1
SGND	7	signal ground
IN1–	8	negative input 1
IN2–	9	negative input 2
MODE	10	mode selection input (standby, mute, operating)
SVR	11	half supply voltage decoupling (ripple rejection)
IN2+	12	positive input 2

Table 3:	Pin descriptioncontinuedcontinued		
Symbol	Pin	Description	
GC	13	DC gain control	
OUT2-	14	negative loudspeaker terminal 2	
GND2	15	ground channel 2	
V _{CC2}	16	supply voltage channel 2	
OUT2+	17	positive loudspeaker terminal 2	

8. Functional description

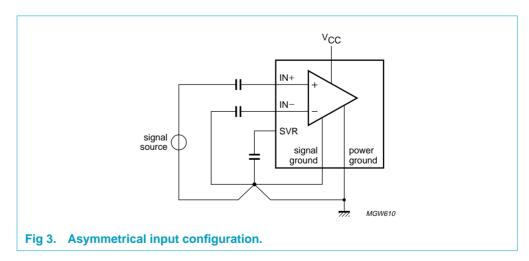
The TDA8946AJ is a stereo BTL audio power amplifier capable of delivering 2×15 W output power to an 8 Ω load at THD = 10%, using a 18 V power supply and an external heatsink. The gain of both amplifiers can be adjusted using a DC control voltage (pin GC). This feature can be used for volume control or a preset gain.

With the three-level MODE input the device can be switched from 'standby' to 'mute' and to 'operating' mode.

The TDA8946AJ outputs are protected by an internal thermal shutdown protection mechanism and a short-circuit protection.

8.1 Input configuration

The TDA8946AJ inputs can be driven symmetrical (floating) as well as asymmetrical. In the asymmetrical mode (see Figure 3) one input pin is connected via a capacitor to the signal source and the other input is connected to the signal ground. The signal ground should be as close as possible to the SVR (electrolytic) capacitor ground. Note that the DC level of the input pins is half of the supply voltage V_{CC} , so coupling capacitors for both pins are necessary.



The input cut-off frequency is:

$$f_{i(cut-off)} = \frac{1}{2\pi(0.5 \times R_i \times C_i)}$$
(1)

For $R_i = 32 \text{ k}\Omega$ and $C_i = 220 \text{ nF}$:

$$f_{i(cut-off)} = \frac{1}{2\pi (0.5 \times 32 \times 10^3 \times 220 \times 10^{-9})} = 45.2 \text{ Hz}$$
 (2)

As shown in Equation 2, large capacitors values for the inputs are not necessary; so the switch-on delay during charging of the input capacitors can be minimized. This results in a good low frequency response and good switch-on behaviour.

Remark: To prevent high frequency oscillations do not leave the inputs open, connect a capacitor of 4.7 nF across the input pins close to the device (see Figure 15).

8.2 Power amplifier

The power amplifier is a Bridge-Tied Load (BTL) amplifier with an all-NPN output stage, capable of delivering a peak output current of 2 A.

The BTL principle offers the following advantages:

- Lower peak value of the supply current
- The ripple frequency on the supply voltage is twice the signal frequency
- No expensive DC-blocking capacitor
- Good low frequency performance.

8.2.1 Output power measurement

The output power as a function of the supply voltage is measured on the output pins at THD = 10%; see Figure 10. The maximum output power is limited by the supply voltage of 18 V and the maximum available output current: 2 A repetitive peak current.

8.2.2 Headroom

Typical CD music requires at least 12 dB (factor 15.85) dynamic headroom - compared to the average power output - for transferring the loudest parts without distortion. At V_{CC} = 18 V, R_L = 8 Ω and P_o = 10 W at THD = 0.5% (see Figure 8), the Average Listening Level (ALL) - music power - without any distortion yields:

$$P_{o(ALL)} = \frac{10 \text{ W}}{15.85} = 631 \text{ mW}$$
 (3)

The power dissipation can be derived from Figure 12 on page 11 for 0 dB respectively 12 dB headroom.

Table 4: Power	rating as function of neadroom	
Headroom	Power output (THD = 0.2%)	Power dissipation
0 dB	$P_o = 10 W$	P = 17 W
12 dB	$P_{o(ALL)} = 631 \text{ mW}$	P = 8.5 W

Table 4: Power rating as function of headroo	able 4: Power rating a	as function of headroo
----------------------------------------------	------------------------	------------------------

For the average listening level a power dissipation of 8.5 W can be used for a heatsink calculation.

8.3 Mode selection

The TDA8946AJ has three functional modes, which can be selected by applying the proper DC voltage to pin MODE.

Standby — In this mode the current consumption is very low and the outputs are floating. The device is in standby mode when $V_{MODE} > (V_{CC} - 0.5 V)$, or when the MODE pin is left floating.

Mute — In this mode the amplifier is DC-biased but not operational (no audio output). This allows the input coupling capacitors to be charged to avoid pop-noise. The device is in mute mode when 3.5 V < V_{MODE} < (V_{CC} – 1.5 V).

Operating — In this mode the amplifier is operating normally. The operating mode is activated at $V_{MODE} < 1.0$ V.

8.3.1 Switch-on and switch off

To avoid audible plops during supply voltage switch-on or switch-off, the device is set to standby mode before the supply voltage is applied (switch-on) or removed (switch-off).

The switch-on and switch-off time can be influenced by an RC-circuit on the MODE pin. Rapid on/off switching of the device or the rapid switching of the MODE pin may cause 'click-and pop-noise'. This can be prevented by proper timing of the RC-circuit on the MODE pin.

8.4 DC gain control

The gain of both amplifiers can be adjusted (logarithmic) by applying an external DC voltage source on pin GC (see Figure 6). The DC voltage source range is 0.5 to 4.0 V. This feature can be used for volume control or preset gain.

The maximum voltage gain is set at +30 dB and the control range is more than 80 dB, so the minimal gain is less than -50 dB. When pin GC is not connected, the gain is set at +24 dB.

8.5 Supply Voltage Ripple Rejection (SVRR)

The SVRR is measured with an electrolytic capacitor of 10 μ F on pin SVR at a bandwidth of 10 Hz to 80 kHz. Figure 14 illustrates the SVRR as function of the frequency. A larger capacitor value on the SVR pin improves the ripple rejection behaviour at the lower frequencies.

8.6 Built-in protection circuits

The TDA8946AJ contains two types of protection circuits, i.e. short-circuit and thermal shutdown.

8.6.1 Short-circuit protection

Short-circuit to ground or supply line — This is detected by a so-called 'missing current' detection circuit which measures the current in the positive supply line and the current in the ground line. A difference between both currents larger than 0.8 A, switches the power stage to the standby mode; high impedance of the outputs and very low supply current.

Short-circuit across the load — This is detected by an absolute-current measurement. An absolute-current larger than 2 A, switches the power stage to standby mode; high impedance of the outputs and a very low supply current.

8.6.2 Thermal shutdown protection

The junction temperature is measured by a temperature sensor; at a junction temperature of approximately 150 °C this detection circuit switches the power stage to the standby mode; high impedance of the outputs and very low supply current.

9. Limiting values

Table 5: Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Мах	Unit
V _{CC}	supply voltage	no signal	-0.3	+25	V
		operating	-0.3	+18	V
VI	input voltage		-0.3	V _{CC} + 0.3	V
I _{ORM}	repetitive peak output current		-	2	А
T _{stg}	storage temperature	non-operating	-55	+150	°C
T _{amb}	operating ambient temperature		-40	+85	°C
P _{tot}	total power dissipation		-	28	W
V _{CC(sc)}	supply voltage to guarantee short-circuit protection		-	15	V

10. Thermal characteristics

Table 6:Thermal characteristics

Symbol	Parameter	Conditions	Value	Unit
R _{th(j-a)}	thermal resistance from junction to ambient	in free air	40	K/W
R _{th(j-mb)}	thermal resistance from junction to mounting base	both channels driven	2.5 <mark>[1]</mark>	K/W

[1] This is a typical value.

11. Static characteristics

Table 7: Static characteristics

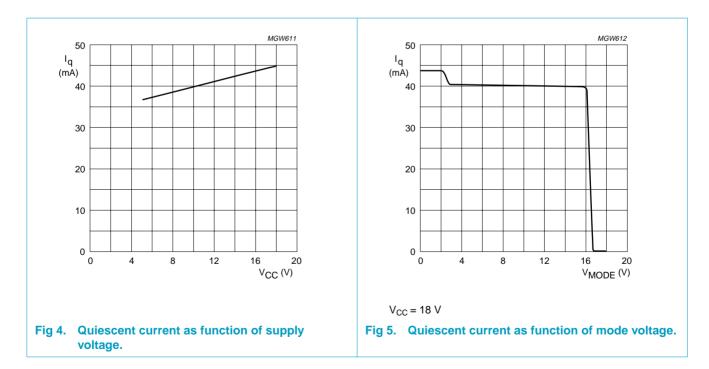
 $V_{CC} = 18 V$; $T_{amb} = 25 \circ C$; $R_L = 8 \Omega$; $V_{MODE} = 0 V$; $V_i = 0 V$; measured in test circuit Figure 15; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
V _{CC}	supply voltage	operating		4.5	18	18	V
lq	quiescent supply current	R _L = ∞	[1]	-	45	55	mA
I _{stb}	standby supply current	$V_{MODE} = V_{CC}$		-	-	10	μA
Vo	DC output voltage		[2]	-	9	-	V
ΔV _{OUT} ^[3]	differential output voltage offset			-	-	170	mV
V _{MODE}	mode selection input voltage	operating mode		0	-	1.0	V
		mute mode		3.5	-	V _{CC} – 1.5	V
		standby mode		$V_{CC}-0.5$	-	V _{CC}	V
I _{MODE}	mode selection input current	$0 < V_{MODE} < V_{CC}$		-	-	20	μA
V _{GC}	gain control voltage (pin GC)	pin GC not connected		-	2.75	-	V
I _{GC}	current into pin GC	$V_{GC} = 0 V$		-	600	-	μA

[1] With a load connected at the outputs the quiescent current will increase, the maximum of this increase being equal to the differential output voltage offset (ΔV_{OUT}) divided by the load resistance (R_L).

[2] The DC output voltage with respect to ground is approximately $0.5 V_{\text{CC}}.$

 $[3] \quad \Delta V_{OUT} = \left| V_{OUT+} - V_{OUT-} \right|.$



12. Dynamic characteristics

Table 8: Dynamic characteristics

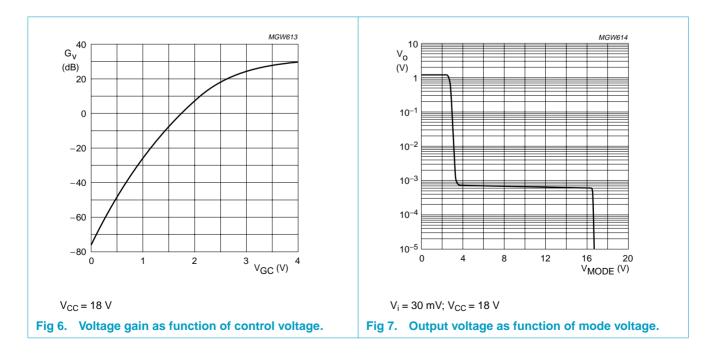
 $V_{CC} = 18 \text{ V}; T_{amb} = 25 \degree C; R_L = 8 \Omega; f = 1 \text{ kHz}; V_{MODE} = 0 \text{ V}; G_v = 30 \text{ dB}; V_{GC} = 4.0 \text{ V}; \text{ measured in test circuit Figure 15}; unless otherwise specified.}$

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Po	output power	THD = 10%	13	15	-	W
		THD = 0.5%	-	11.5	-	W
THD	total harmonic distortion	$P_o = 1 W$	-	0.07	0.5	%
G _{v(max)}	maximum voltage gain		29	30	31	dB
G _{v(cr)}	gain control range	$0.5 < V_{GC} < 4.0 V$	-	80	-	dB
V _{i(rms)}	input voltage (RMS value)	$G_v = 0 \text{ dB}; \text{ THD } < 1\%$	1.0	-	-	V
Z _{i(dif)}	differential input impedance		50	65	-	kΩ
V _{n(o)}	noise output voltage	$V_{GC} = 4.0 V$	[1] _	120	170	μV
		V _{GC} = 1.0 V	[1] _	30	-	μV
SVRR	supply voltage ripple rejection	f _{ripple} = 1 kHz	[2] _	55	-	dB
		f _{ripple} = 100 Hz to 20 kHz	[2] _	55	-	dB
V _{o(mute)}	output voltage	mute mode	[3] _	30	50	μV
α_{cs}	channel separation	$R_{source} = 0 \Omega$	50	75	-	dB
$ \Delta G_v $	channel unbalance	$G_v = 0 \text{ dB}; V_{GC} = 1.8 \text{ V}$	-	-	1	dB

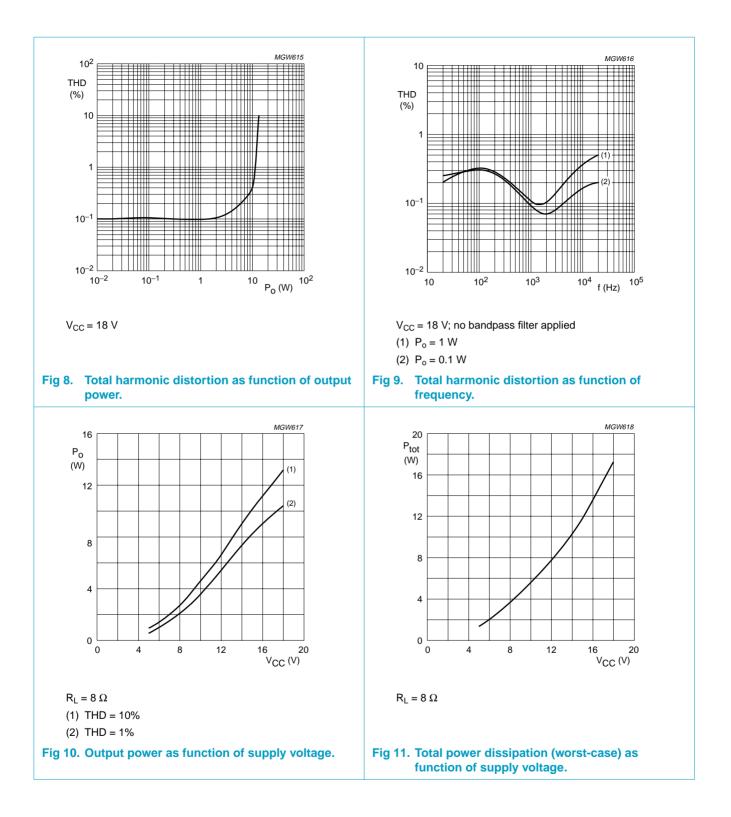
[1] The noise output voltage is measured at the output in a frequency range from 20 Hz to 20 kHz (unweighted), with a source impedance $R_{source} = 0 \Omega$ at the input.

[2] Supply voltage ripple rejection is measured at the output, with a source impedance $R_{source} = 0 \Omega$ at the input. The ripple voltage is a sine wave with a frequency f_{ripple} and an amplitude of 700 mV (RMS), which is applied to the positive supply rail.

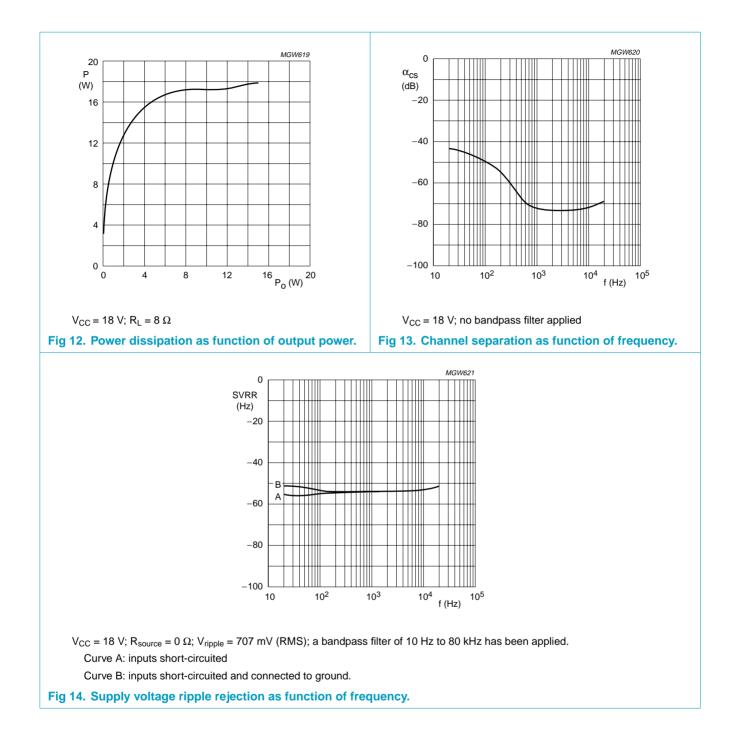
[3] Output voltage in mute mode is measured with V_{GC} = 0 V and an input voltage of 1 V (RMS) in a bandwidth of 20 kHz, thus including noise.



2 x 15 W BTL audio amplifier with DC gain control

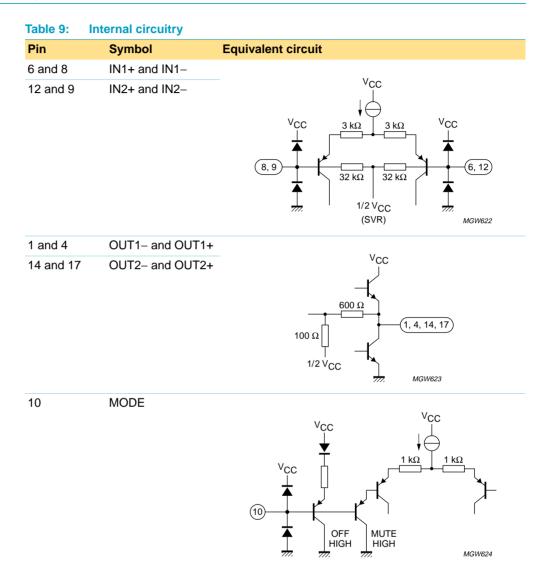


TDA8946AJ

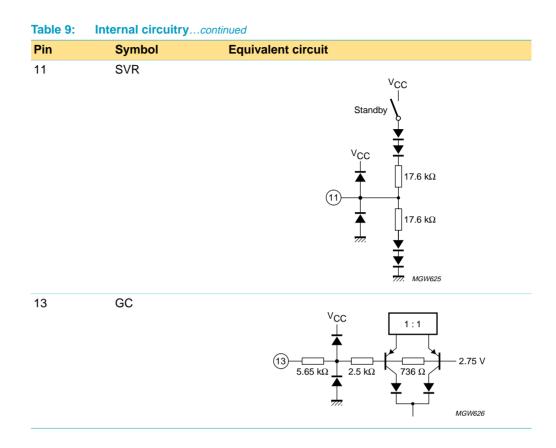


2 x 15 W BTL audio amplifier with DC gain control

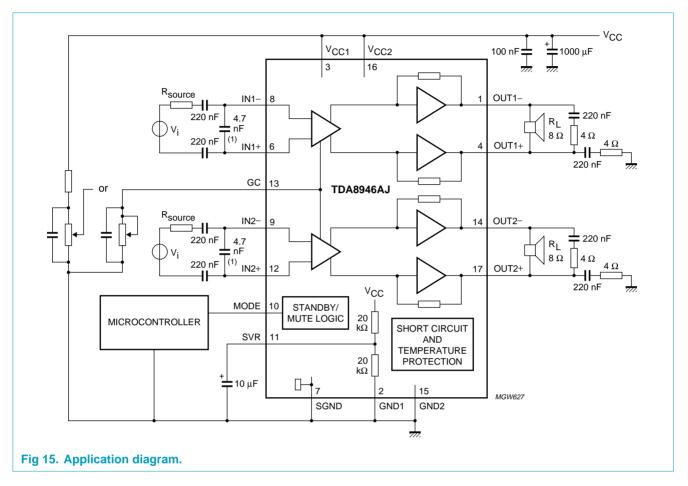
13. Internal circuitry



2 x 15 W BTL audio amplifier with DC gain control



14. Application information

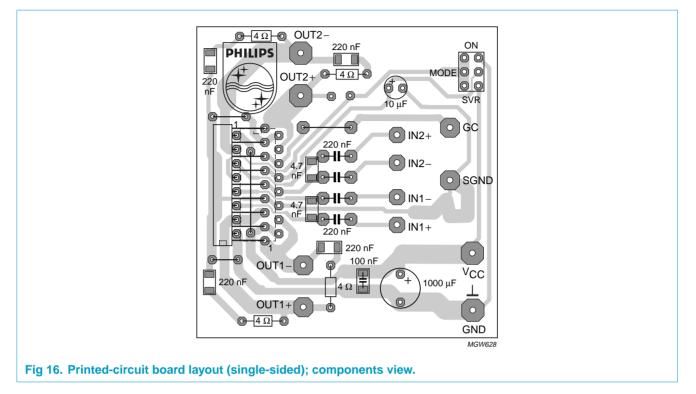


14.1 Printed-circuit board

14.1.1 Layout and grounding

For a high system performance level certain grounding techniques are essential. The input reference grounds have to be tied with their respective source grounds and must have separate tracks from the power ground tracks; this will prevent the large (output) signal currents from interfering with the small AC input signals. The small-signal ground tracks should be physically located as far as possible from the power ground tracks. Supply and output tracks should be as wide as possible for delivering maximum output power.

2 x 15 W BTL audio amplifier with DC gain control



14.1.2 Power supply decoupling

Proper supply bypassing is critical for low-noise performance and high supply voltage ripple rejection. The respective capacitor location should be as close as possible to the device and grounded to the power ground. Proper power supply decoupling also prevents oscillations.

For suppressing higher frequency transients (spikes) on the supply line a capacitor with low ESR - typical 100 nF - has to be placed as close as possible to the device. For suppressing lower frequency noise and ripple signals, a large electrolytic capacitor - e.g. 1000 μ F or greater - must be placed close to the device.

The bypass capacitor on the SVR pin reduces the noise and ripple on the midrail voltage. For good THD and noise performance a low ESR capacitor is recommended.

14.2 Thermal behaviour and heatsink calculation

The measured maximum thermal resistance of the IC package, $R_{th(j-mb)}$ is 2.5 K/W. A calculation for the heatsink can be made, with the following parameters:

 $T_{amb} = 50 \ ^{\circ}C$ $V_{CC} = 18 \ V \text{ and } R_L = 8 \ \Omega$ $T_{j(max)} = 150 \ ^{\circ}C$

 $R_{th(tot)}$ is the total thermal resistance between the junction and the ambient including the heatsink. In the heatsink calculations the value of $R_{th(mb-h)}$ is ignored.

At V_{CC} = 18 V and R_L = 8 Ω the measured worst-case sine-wave dissipation is 17 W; see Figure 12. For T_{j(max)} = 150 °C the temperature rise - caused by the power dissipation - is: 150 - 50 = 100 °C.

$$\begin{split} P \times R_{th(tot)} &= 100 \ ^{\circ}\text{C} \\ R_{th(tot)} &= 100/17 = 5.88 \ \text{K/W} \\ R_{th(h-a)} &= R_{th(tot)} - R_{th(j-mb)} = 5.88 - 2.5 = 3.38 \ \text{K/W}. \end{split}$$

The calculation above is for an application at worst-case (stereo) sine-wave output signals. In practice music signals will be applied, which decreases the maximum power dissipation to approximately half of the sine-wave power dissipation (see Section 8.2.2). This allows for the use of a smaller heatsink:

$$\begin{split} P \times R_{th(tot)} &= 100 \ ^{\circ}\text{C} \\ R_{th(tot)} &= 100/(0.5 \times 17) = 11.76 \ \text{K/W} \\ R_{th(h-a)} &= R_{th(tot)} - R_{th(j\text{-mb})} = 11.76 - 2.5 = 9.26 \ \text{K/W}. \end{split}$$

To increase the lifetime of the IC, $T_{j(max)}$ should be reduced to 125 °C. This requires a heatsink of approximately 6.3 K/W for music signals.

15. Test information

15.1 Quality information

The *"General Quality Specification for Integrated Circuits, SNW-FQ-611D"* is applicable (ordering code 9397 750 05459).

15.1.1 Test conditions

 T_{amb} = 25 °C; V_{CC} = 18 V; f = 1 kHz; R_L = 8 Ω ; audio pass band 22 Hz to 22 kHz; unless otherwise specified.

Remark: In the graphs as function of frequency no bandpass filter was applied; see Figure 9 and 13.

2 x 15 W BTL audio amplifier with DC gain control

16. Package outline

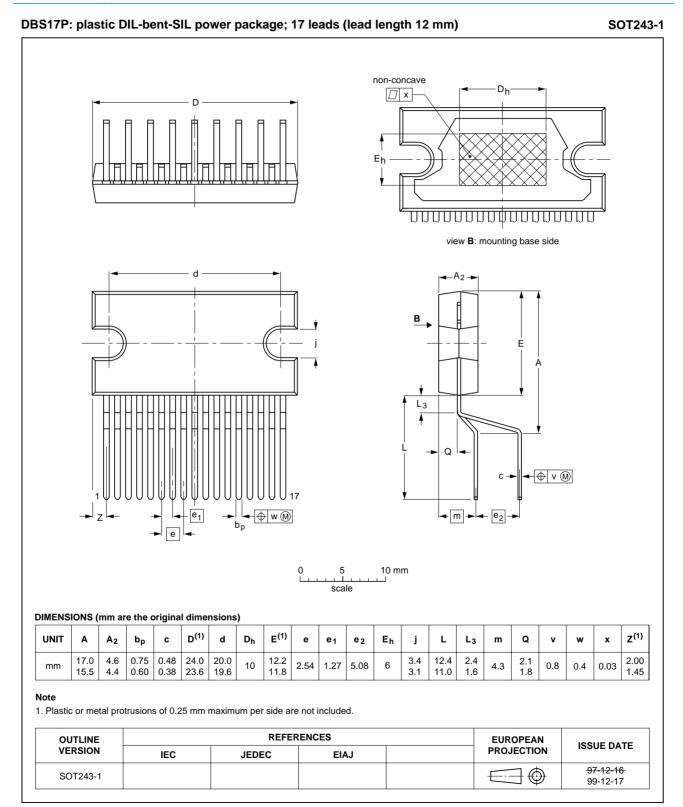


Fig 17. DBS17P package outline.

9397 750 09434

17. Soldering

17.1 Introduction to soldering through-hole mount packages

This text gives a brief insight to wave, dip and manual soldering. A more in-depth account of soldering ICs can be found in our *Data Handbook IC26; Integrated Circuit Packages* (document order number 9398 652 90011).

Wave soldering is the preferred method for mounting of through-hole mount IC packages on a printed-circuit board.

17.2 Soldering by dipping or by solder wave

The maximum permissible temperature of the solder is 260 °C; solder at this temperature must not be in contact with the joints for more than 5 seconds. The total contact time of successive solder waves must not exceed 5 seconds.

The device may be mounted up to the seating plane, but the temperature of the plastic body must not exceed the specified maximum storage temperature $(T_{stg(max)})$. If the printed-circuit board has been pre-heated, forced cooling may be necessary immediately after soldering to keep the temperature within the permissible limit.

17.3 Manual soldering

Apply the soldering iron (24 V or less) to the lead(s) of the package, either below the seating plane or not more than 2 mm above it. If the temperature of the soldering iron bit is less than 300 °C it may remain in contact for up to 10 seconds. If the bit temperature is between 300 and 400 °C, contact may be up to 5 seconds.

17.4 Package related soldering information

 Table 10:
 Suitability of through-hole mount IC packages for dipping and wave soldering methods

Package	Soldering method			
	Dipping	Wave		
DBS, DIP, HDIP, SDIP, SIL	suitable	suitable ^[1]		

[1] For SDIP packages, the longitudinal axis must be parallel to the transport direction of the printed-circuit board.

18. Revision history

Table 11:Revision history

Rev	Date	CPCN	Description
01	20020301	-	Product data (9397 750 09434)

19. Data sheet status

Data sheet status ^[1]	Product status ^[2]	Definition
Objective data	Development	This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice.
Preliminary data	Qualification	This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product.
Product data	Production	This data sheet contains data from the product specification. Philips Semiconductors reserves the right to make changes at any time in order to improve the design, manufacturing and supply. Changes will be communicated according to the Customer Product/Process Change Notification (CPCN) procedure SNW-SQ-650A.

[1] Please consult the most recently issued data sheet before initiating or completing a design.

[2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.

20. Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

Application information — Applications that are described herein for any of these products are for illustrative purposes only. Philips Semiconductors make no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

21. Disclaimers

Life support — These products are not designed for use in life support appliances, devices, or systems where malfunction of these products can reasonably be expected to result in personal injury. Philips Semiconductors customers using or selling these products for use in such applications do so at their own risk and agree to fully indemnify Philips Semiconductors for any damages resulting from such application.

Right to make changes — Philips Semiconductors reserves the right to make changes, without notice, in the products, including circuits, standard cells, and/or software, described or contained herein in order to improve design and/or performance. Philips Semiconductors assumes no responsibility or liability for the use of any of these products, conveys no licence or title under any patent, copyright, or mask work right to these products, and makes no representations or warranties that these products are free from patent, copyright, or mask work right infringement, unless otherwise specified.

Contact information

For additional information, please visit http://www.semiconductors.philips.com. For sales office addresses, send e-mail to: sales.addresses@www.semiconductors.philips.com.

Fax: +31 40 27 24825

© Koninklijke Philips Electronics N.V. 2002. All rights reserved.

9397 750 09434

2 x 15 W BTL audio amplifier with DC gain control

Contents

1	General description	. 1
2	Features	. 1
3	Applications	. 1
4	Quick reference data	. 1
5	Ordering information	. 2
6	Block diagram	. 2
7	Pinning information	
7.1	Pinning	
7.2	Pin description	
8	Functional description	. 4
8.1	Input configuration	
8.2	Power amplifier	. 5
8.2.1	Output power measurement	
8.2.2	Headroom	
8.3	Mode selection	
8.3.1 8.4	Switch-on and switch off	
8.4 8.5	DC gain control Supply Voltage Ripple Rejection (SVRR)	
8.6	Built-in protection circuits	
8.6.1	Short-circuit protection	
8.6.2	Thermal shutdown protection	
9	Limiting values	
10	Thermal characteristics	
11	Static characteristics.	
	Static characteristics	. 8
11	Static characteristics Dynamic characteristics	.8 .9
11 12	Static characteristics Dynamic characteristics Internal circuitry	.8 .9 12
11 12 13	Static characteristics Dynamic characteristics Internal circuitry Application information	.8 .9 12 14
11 12 13 14	Static characteristics Dynamic characteristics Internal circuitry	. 8 . 9 12 14 14
11 12 13 14 14.1	Static characteristics. Dynamic characteristics Internal circuitry. Application information. Printed-circuit board Layout and grounding. Power supply decoupling	. 8 . 9 12 14 14 14 15
11 12 13 14 14.1 14.1.1	Static characteristics Dynamic characteristics Internal circuitry Application information Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation	. 8 . 9 12 14 14 14 15 15
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15	Static characteristics.	. 8 . 9 12 14 14 14 15 15 15
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15 15.1	Static characteristics Dynamic characteristics Internal circuitry Application information Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation Test information Quality information	. 8 . 9 12 14 14 14 15 15 15 16
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15	Static characteristics. Dynamic characteristics Internal circuitry. Application information. Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation Test information Quality information Test conditions	. 8 . 9 12 14 14 14 15 15 15 16 16
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15 15.1	Static characteristics Dynamic characteristics Internal circuitry Application information. Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation Test information Quality information Test conditions Package outline	 8 9 12 14 14 15 15 16 16 16 17
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15 15.1 15.1.1	Static characteristics. Dynamic characteristics . Internal circuitry. Application information. Printed-circuit board . Layout and grounding . Power supply decoupling . Thermal behaviour and heatsink calculation . Test information . Quality information . Test conditions . Package outline . Soldering .	 8 9 12 14 14 15 15 16 16 16 17
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15 15.1 15.1.1 16	Static characteristics Dynamic characteristics Internal circuitry Application information Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation Quality information Test conditions Package outline Soldering Introduction to soldering through-hole	. 8 . 9 12 14 14 15 15 16 16 16 16 17 18
11 12 13 14 14.1 14.1.2 14.2 15.1 15.1.1 16 17 17.1	Static characteristics. Dynamic characteristics Internal circuitry. Application information. Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation Quality information Test conditions Package outline Soldering Introduction to soldering through-hole mount packages	. 8 . 9 12 14 14 15 15 16 16 16 16 17 18
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15 15.1 15.1.1 16 17 17.1 17.2	Static characteristics Dynamic characteristics Internal circuitry Application information Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation Test information Quality information Test conditions Package outline Soldering Introduction to soldering through-hole mount packages Soldering by dipping or by solder wave	. 8 . 9 12 14 14 15 15 16 16 16 16 17 18 18
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15 15.1 15.1.1 16 17 17.1 17.2 17.3	Static characteristics Dynamic characteristics Internal circuitry Application information Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation Test information Quality information Test conditions Package outline Soldering Introduction to soldering through-hole mount packages Soldering by dipping or by solder wave Manual soldering	. 8 . 9 12 14 14 15 15 16 16 16 16 16 17 18 18 18
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15.1 15.1.1 16 17.1 17.2 17.3 17.4	Static characteristics. Dynamic characteristics Internal circuitry. Application information. Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation Test information Quality information Test conditions Package outline Soldering Introduction to soldering through-hole mount packages Soldering by dipping or by solder wave Manual soldering Package related soldering information	. 8 . 9 12 14 14 15 15 16 16 16 16 16 17 18 18 18 18 18
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15.1 15.1 15.1.1 16 17.1 17.2 17.3 17.4 18	Static characteristics Dynamic characteristics Internal circuitry Application information Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation Test information Quality information Test conditions Package outline Soldering Introduction to soldering through-hole mount packages Soldering by dipping or by solder wave Manual soldering Package related soldering information	. 8 . 9 12 14 14 15 15 16 16 16 16 16 16 16 18 18 18 18 18
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15.1 15.1 15.1.1 16 17.1 17.2 17.3 17.4 18 19	Static characteristics Dynamic characteristics Internal circuitry Application information Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation Test information Quality information Test conditions Package outline Soldering Introduction to soldering through-hole mount packages Soldering by dipping or by solder wave Manual soldering Package related soldering information Data sheet status	. 8 . 9 12 14 14 14 15 15 16 16 16 16 16 16 18 18 18 18 18 18 19
11 12 13 14 14.1 14.1.1 14.1.2 14.2 15.1 15.1 15.1.1 16 17.1 17.2 17.3 17.4 18	Static characteristics Dynamic characteristics Internal circuitry Application information Printed-circuit board Layout and grounding Power supply decoupling Thermal behaviour and heatsink calculation Test information Quality information Test conditions Package outline Soldering Introduction to soldering through-hole mount packages Soldering by dipping or by solder wave Manual soldering Package related soldering information	. 8 . 9 12 14 14 15 15 16 16 16 16 16 16 16 18 18 18 18 18

© Koninklijke Philips Electronics N.V. 2002. Printed in The Netherlands

All rights are reserved. Reproduction in whole or in part is prohibited without the prior written consent of the copyright owner.

The information presented in this document does not form part of any quotation or contract, is believed to be accurate and reliable and may be changed without notice. No liability will be accepted by the publisher for any consequence of its use. Publication thereof does not convey nor imply any license under patent- or other industrial or intellectual property rights.



Let's make things better.