# STK611-721-E

## Thick-Film Hybrid IC 3-Phase Motor Drive Inverter Hybrid IC

#### Overview

This "Inverter Power H-IC" includes the output stage of a 3-phase inverter, pre-drive circuits, as well as protection circuits in one package.

#### **Applications**

• For 3-phase motor drive for fan etc.

#### Features

- Pre-drive low voltage protection circuits are built in.
- Direct input of CMOS level control signals without insulating circuits is possible.(Active HIGH)
- Built-in simultaneous upper/ lower ON prevention circuit to prevent arm shorting caused by simultaneous ON input for the upper and lower side transistors.
- (Dead time is required for preventing shorting due to switching delay.)
- Overcurrent protection is possible by connecting a shunt resistor externally.
- Monitoring substrate temperature is possible through the use of an internal thermistor.





#### **Specifications**

#### Absolute Maximum Ratings at Tc = 25°C

Parameter	Symbol	Conditions		Ratings	unit
Supply voltage	V <sub>CC</sub>	+ to -, surge < 450V	*1	450	V
Collector-emitter voltage	V <sub>DS</sub>	+ to U (V, W) or U (V, W) to -		600	V
Output current	I <sub>O</sub>	+, -, U, V, W terminal current		±2	А
Output peak current	Іор	+, -, U, V, W terminal current P.W. = 100µs		<u>±</u> 4	А
Pre-driver voltage	VD1, 2, 3, 4	VB1 to U, VB2 to V, VB3 to W, V_{DD} to V_{SS}	*2	20	V
Input signal voltage	VIN	HIN1, 2, 3, LIN1, 2, 3 terminal		0 to 15	V
FAULT/EN terminal voltage	VFAULT	FAULT/EN terminal		20	V
ITRIP terminal voltage	VITRIP	ITRIP terminal		5	V
Maximum power dissipation	Pd	MOSFET/1 channel		16.6	W
Junction temperature	Tj	MOSFET		150	°C
Storage temperature	Tstg			-40 to +125	°C
Operating substrate temperature	Тс	H-IC case temperature		-20 to +100	°C
Tightening torque		A screw part	*3	0.6	N•m

Reference voltage is "-" terminal = "VSS" terminal voltage unless otherwise specified.

\*1 Surge voltage developed by the switching operation due to the wiring inductance between "+" and "-" terminals.

\*2 Terminal voltage : VD1=VB1 to U, VD2=VB2 to V, VD3=VB3 to W, VD4=VDD to VSS.

\*3 Flatness of the heat-sink should be 0.15mm and below.

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

#### Parameter Symbol Conditions Test circuit min max unit typ Power output section Drain-Source Leakage current $V_{DS} = 600V$ 0.1 Fig.1 mΑ IDSS Drain-Source On Resistance R<sub>DS</sub>(ON) I<sub>D</sub> = 2A Fig.2 4 Ω Diode forward voltage I<sub>D</sub> = -2A Fig.3 1.5 V VSD MOSFET 7.5 °C/W Junction to case thermal resistance θj-c(T) Control (Pre-driver) section Pre-driver power dissipation $I_D$ VD1, 2, 3 = 15V 0.05 0.2 Fig.4 mΑ VD4 = 15V 4.0 1.4 Input ON threshold voltage HIN1, HIN2, HIN3, LIN1, LIN2, 1.5 2.1 2.5 V Vinth(on) LIN3 to VSS Input OFF threshold voltage Vinth(off) 0.8 1.3 1.5 V FAULT/EN clearness delay time FLTCLR After each protection operation 8 ms ending Protection section UVLO Pre-drive power supply 8 98 V low voltage protection voltage Resistance for substrate temperature Rt Resistance between TH and 90 100 110 kO monitors V<sub>SS</sub> terminals Fault/EN terminal input current IOSD VFault = 0.15V 2 mΑ ITRIP threshold voltage VITRIP 0.41 0.465 0.52 V Switching time tON $I_{O} = 2A$ 0.8 Fig.5 μs Inductive load tOFF 1.5

#### Electrical Characteristics at Tc=25°C, VD=15V

Reference voltage is "-" terminal = "Vss" terminal voltage unless otherwise specified.

#### Notes

1. <<Input ON threshold voltage>> indicates the threshold of input signal to turn on output stage MOSFET. <<Input OFF threshold voltage>> indicates the threshold of input signal to turn off output stage MOSFET. At the time of output ON, set the input signal voltage to Vinth (on)MAX to 15V. At the time of output OFF, set the input signal voltage to 0V to Vinth (off)MIN.

2. When the internal protection circuit operates, a "FAULT/EN" signal is turned ON (When the "FAULT/EN" terminal is low level, "FAULT/EN" signal is ON state: output form is open DRAIN) but the "FAULT/EN" signal does not latch. After protection operation ends, it returns automatically within typ. 8ms and resumes operation beginning condition. So,after "FAULT/EN" signal detection, set all signals to OFF (LOW) at once. However, the operation of pre-drive power supply low voltage protection (UVLO with hysteresis about 0.2V) is as

follows: Upper side : There is no "FAULT/EN" signal output, but a corresponding gate signal is turned OFF. Incidentally, it returns to the regular operation when recovering to the normal voltage, but the latch continues while the input signal is ON (HIGH).

- Lower side : It outputs "FAULT/EN" signal with gate signal OFF. However, it is different from the protection operation of upper side, it is automatically reset and resumes operation beginning condition when recovering to normal voltage. (The protection operation is not latched by the input signal.)
- 3. When assembling the H-IC on the heat sink, tightening torque range is 0.4N•m to 0.6•Nm.
- 4. The pre-drive low voltage protection is the function to protect devices when the pre-drive supply voltage declines with an operating malfunction. As for the pre-driver supply voltage decline in case of operation beginning, and so on, check it in your set.
- 5. Please seal the entire leads of H-IC with the resin for securing the insulation between leads after mounting H-IC on the set.

#### **Package Dimensions**

unit:mm (typ)



### **Equivalent Block Diagram**



#### **Test Circuit**

(The tested phase: U+ shows the upper side of the U phase and U- shows the lower side of the U phase.)

IDSS

	U+	V+	W+	U-	V-	W-
м	3	3	3	8	6	4
N	8	6	4	2	2	2



VDS (RDS) (Test by pulse)

	U+	V+	W+	U-	V-	W-
М	3	3	3	8	6	4
N	8	6	4	2	2	2
m	11	12	13	14	15	16



V<sub>F</sub> (Test by pulse)

	U+	V+	W+	U-	V-	W-
М	3	3	3	8	6	4
N	8	6	4	2	2	2



Fig.3



Fig.4

ID

	VD1	VD2	VD3	VD4
М	9	7	5	18
Ν	8	6	4	19

Switching time (The circuit is a representative example of the lower side U phase.)





### **Sample Application Circuit**



#### **Recommendation Operating Conditions**

Parameter	Symbol	Conditions		min	typ	max	unit
Supply voltage	VCC	+ to - terminal	0		400	V	
Pre-driver supply voltage	VD1, 2, 3	VB1 to U, VB2 to V, VB3 to W		12.5	15	17.5	N
	VD4	V <sub>DD</sub> to V <sub>SS</sub>	*1	13.5	15	16.5	V
ON-state input voltage	V <sub>IN</sub> (ON)	HIN1, HIN2, HIN3,		3.0		5.0	N
OFF-state input voltage	V <sub>IN</sub> (OFF)	LIN1, LIN2, LIN3		0		0.3	v
PWM frequency	fPWM			1		20	kHz
Dead time	DT	Turn-off to turn-on		2			μs
Allowable input pulse width	PWIN	ON and OFF		1			μs
Tightening torque		'M3' type screw		0.4		0.6	N•m

\*1 Pre-driver power supply (VD4 =  $15\pm1.5$ V) must have the capacity of I<sub>O</sub> = 20mA (DC), 0.5A (Peak).

#### Usage Precaution

- 1. By the addition of the diode for the bootstrap (DB : high speed type with withstand voltage of 600V or more) and of the capacitor (CB : about 1 to  $47\mu$ F), a single power supply drive is enabled. In this case, an electric charge is charged to CB by turning on the lower side IGBT (By inputting LOW signal to lower side). The problem of causing the adverse effect by the noise etc. might occur because big charging current flows when the voltage of CB is low as started, and put limitation resistor RB (About tens of  $\Omega$  from the number of  $\Omega$ ), please. (When not using bootstrap circuit, each upper side pre-driver needs an external independent power supply.) Also, the upper side power supply voltage sometimes declines depending on controlling condition. Please confirm the voltage with an actual set.
- 2. The voltage jump associated with vibration caused by the switching operation occurs through the influence of floating inductance on the wiring of the external power supply, which is connected to "+" and "-" terminals; therefore, it is recommended that the wiring inductance be low by shortening the wiring length (between CI and each terminal) and the snubber circuit (capacitor/CS/about 0.1 to  $10\mu$ F) for voltage absorption be connected as close as possible between "+" and "-" terminals to reduce the surge voltage.
- 3. Output form of "FAULT/EN" terminal (pin 17) is open DRAIN (it operates as "FAULT" when becoming "LOW"). Moreover, please connect the pull-up resistor (RP) so that the voltage of this terminal may usually become 2.5V or more because this terminal holds the shutdown input of internal pre-driver (It usually operates by 2.5V or more, and stop operation by 0.8V or less) concurrently. When the pull-up voltage is 5V, use RP with resistance  $6.8k\Omega$  or more, and in case of 15V, use RP with resistance  $20k\Omega$  or more.
- 4. Inside the H-IC, a thermistor is connected between "TH" terminal (pin 1) and "VSS" terminal (pin 19). The thermistor can be used as the temperature monitor by connecting the pull-up resistor (RP) externally. When the pull-up voltage is 5V, use "RP" with resistance  $10k\Omega$  or more, and in case of 15V, use "RP" with resistance  $39k\Omega$  or more.
- 5. Although the pull-down resistor is connected with the inside of the signal input terminal, connect the pull-down resistor (about 2.2 to  $3.3k\Omega$ ) outside to decrease the influence of the noise by wiring etc.
- 6. The H-IC may be destroyed when the motor connection terminals (pins 4, 6 and 8) are opened while the motor is running; therefore please be especially careful about the connection (soldering condition) of these terminals.
- 7. The "ITRIP" terminal (pin 16) is the input terminal of the built-in comparator. It can stop operation by inputting the voltage more than VITRIP (0.41V to 0.52V). (Apply voltage less than VITRIP to this pin when normal operation). Please use it as various protections such as the overcurrent protection (feedback from external shunt resistor). In addition, the protection operation will not be latched.
  After the protection operation ends, the H-IC operation resumes typ.8ms later. Therefore, turn all the input signals OFF (low) as soon as the protection operation is detected.
- 8. When input pulse width is less than 1µs, an output may not react to the pulse. (Both ON signal and OFF signal)

This data shows the example of the application circuit and does not guarantee a design as the mass production set.

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