

PIP213-12M

DC-to-DC converter power train

Rev. 01 — 25 September 2007

Product data sheet

1. General description

The PIP213-12M is a fully optimized power train for high-current high-frequency synchronous buck DC-to-DC converter applications. The PIP213-12M replaces two power MOSFETs, a Schottky diode and a driver IC, resulting in a significant increase in power density. The integrated solution allows for optimization of individual components and greatly reduces the parasitics associated with conventional discrete solutions, resulting in higher system efficiencies at higher operating frequencies.

2. Features

- Input voltage range from 3.3 V to 16 V
- Output voltages from 0.8 V to 6 V
- Capable of up to 25 A maximum output current at 1 MHz
- Operating frequency up to 1 MHz
- Peak system efficiency > 85 % at 1 MHz
- Automatic Dead-time Reduction (ADR) for maximum efficiency
- Internal thermal shutdown
- Auxiliary 5 V output
- Power ready output flag
- Power sequencing functions
- Internal 6.5 V regulator for efficient gate drive
- Compatible with single and multi-phase Pulse Width Modulation (PWM) controllers
- Low-profile, surface-mounted package (8 mm × 8 mm × 0.85 mm)

3. Applications

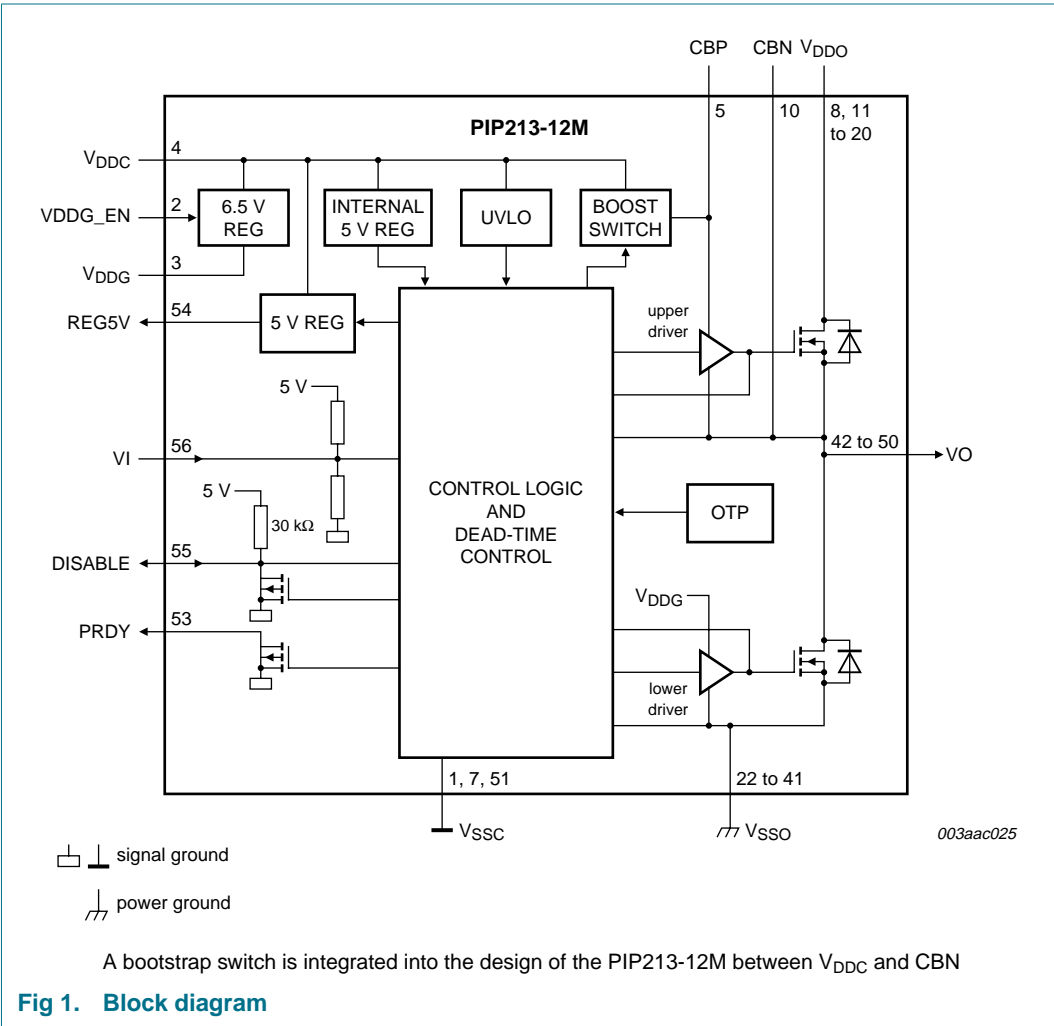
- High-current DC-to-DC point-of-load converters
- Small form-factor voltage regulator modules
- Microprocessor and memory voltage regulators
- Intel DriverMOS (DrMOS) compatible

4. Ordering information

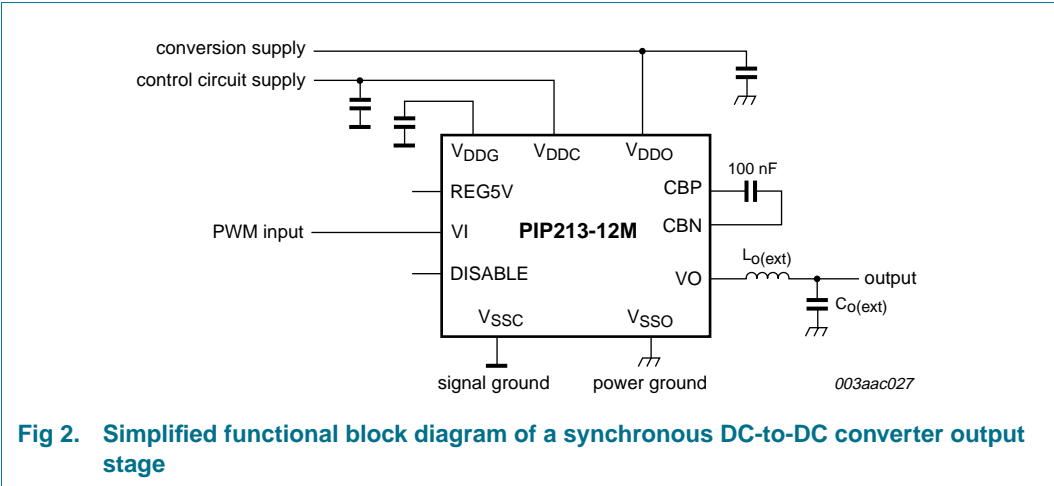
Table 1. Ordering information

Type number	Package		Version
	Name	Description	
PIP213-12M	HVQFN56	plastic thermal enhanced very thin quad flat package; no leads; 56 terminals; body 8 × 8 × 0.85 mm	SOT684-4

5. Block diagram

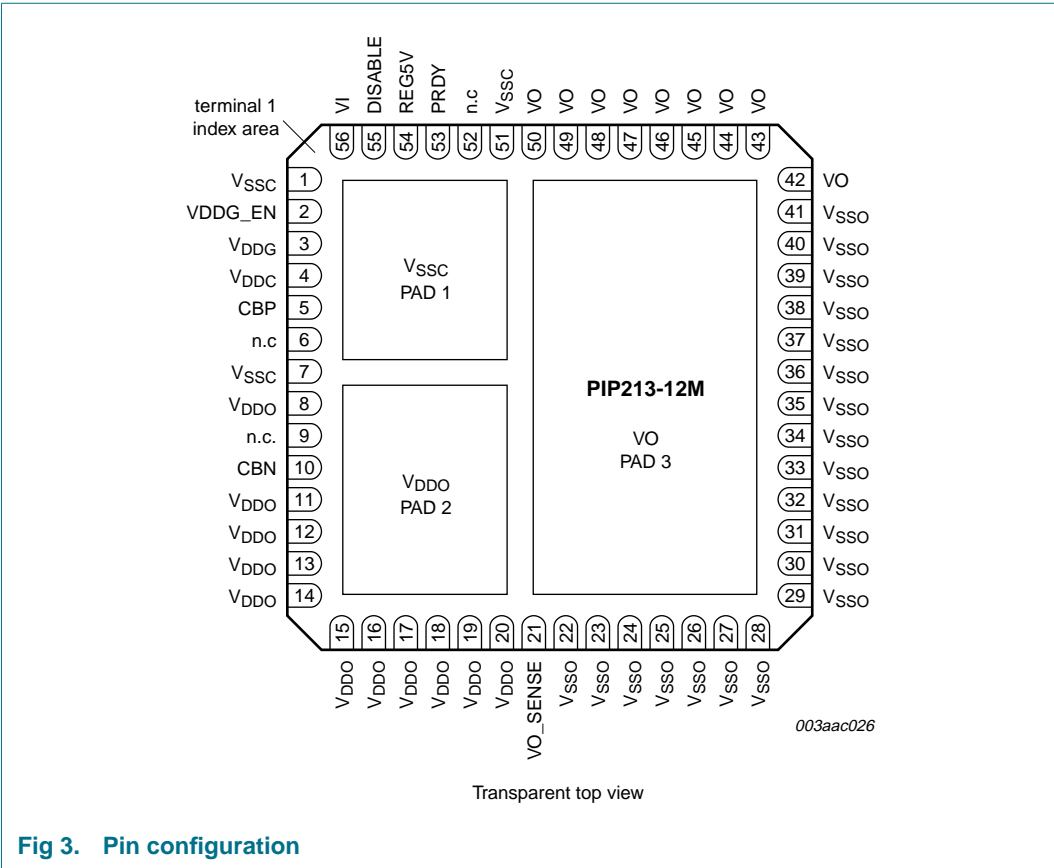


6. Functional diagram



7. Pinning information

7.1 Pinning



7.2 Pin description

Table 2. Pin description

Symbol	Pin	Type	Description
V _{DDC}	4	-	control circuit supply voltage
V _{DDO}	8, 11 to 20, pad 2	I	output stage supply voltage
V _{SSC}	1, 7, 51, pad 1	-	control circuit ground
V _{SSO}	22 to 41	-	output stage ground supply voltage
VI	56	I	pulse width modulation input
VO	42 to 50, pad 3	O	output voltage
VO_SENSE	21	O	sense connection to VO often required for remote current sensing
CBP	5	-	connection to bootstrap capacitor
CBN	10	-	connection to bootstrap capacitor
VDDG_EN	2	I	enables internal 6.5 V regulator for V _{DDG}
V _{DDG}	3	-	gate driver supply voltage
PRDY	53	O	indicates that V _{DDC} is above the UVLO (UnderVoltage Lockout) level (open drain)
REG5V	54	O	5 V regulated supply output
DISABLE	55	I/O	disable driver function (active LOW)
n.c.	6, 9, 52	-	not connected - leave open or connected to GND on PCB (Printed-Circuit Board) layout

8. Functional description

8.1 Basic operation

The PIP213-12M combines two MOSFET's and a MOSFET driver in a thermally enhanced low inductance package for use in high frequency and high efficiency synchronous buck DC-to-DC converters; see [Figure 2](#). The two MOSFETs are connected in a half bridge configuration between V_{DDO} and V_{SSO}. The mid point of the two transistors is V_O which is connected to the output of DC-to-DC converter via an inductor. A logic HIGH signal on the VI pin causes the lower MOSFET to be switched off and the upper MOSFET to be switched on. Current will then flow from the supply (V_{DDO}), through the upper MOSFET and the inductor (L_{O(ext)}) to the output.

A logic LOW signal on the VI pin causes the upper MOSFET to be turned off and the lower MOSFET to be switched on. Current then flows from the power ground (V_{SSO}), through the lower MOSFET and the inductor (L_{O(ext)}), to the output. The output voltage is determined by the ratio of the times that the upper and lower MOSFETs conduct.

8.2 UnderVoltage Lockout (UVLO)

The UVLO function ensures the correct operation of the control circuit during a power-up and power-down sequence. Power to the control circuit is provided by the V_{DDC} pin. This voltage is internally monitored to ensure that if V_{DDC} is below the UVLO threshold, the DISABLE pin is internally pulled LOW and both MOSFETs are off. This is indicated by the power ready (PRDY) flag, an open drain output that is pulled LOW whenever V_{DDC} is below the UVLO threshold.

8.3 Upper driver operation

The gate drive to the upper MOSFET is provided by a bootstrap capacitor (typically 100 nF) that is placed between the CBP and CBN pins. This capacitor is charged via an internal boost switch to a voltage within a few millivolts of V_{DDC} up to a maximum of 12 V (this is to prevent excessive gate charge losses when $V_{DDC} > 12$ V). The upper MOSFET will be switched according to PWM input once the boost capacitor voltage is above $V_{th(CBP-CBN)}$ on. When ever the voltage is below $V_{th(CBP-CBN)}$ off the upper MOSFET will remain off.

8.4 V_{DDG} regulator

The gate drive voltage level to the lower MOSFET is set by the voltage on the V_{DDG} pin. A 1 μ F capacitor must be connected between this pin and V_{SSC} . For minimum power loss within the PIP213-12M, an external power supply of between 5 V and 12 V must be connected to this pin. The optimum value for this voltage is dependent on the application but in the majority of cases a 5 V supply is recommended; see [Figure 11](#). In cases where the V_{DDG} maximum voltage will not be exceeded, the V_{DDG} pin can be connected to the V_{DDC} pin and the V_{DDG} capacitor can be omitted; see [Figure 13](#).

When V_{DDC} is connected to a supply greater than 9 V, an internal 6.5 V regulator connected to V_{DDG} can be used to provide the gate drive for the lower MOSFET; see [Figure 12](#). The V_{DDG} regulator is enabled by leaving the $VDDG_EN$ pin open resulting in this pin being pulled internally to 5 V. If an external supply is to be connected to V_{DDG} then the $VDDG_EN$ pin must be pulled low by connecting to V_{SSC} to disable the internal V_{DDG} regulator.

Table 3. V_{DDG} biasing

$VDDG_EN$	V_{DDG}
Open circuit	internal 6.5 V regulator used ($V_{DDC} > 9$ V)
V_{SSC}	connection to external supply required

8.5 3-state function

If the input to VI from the PWM controller becomes high impedance, then the VI input is driven to 2.5 V by an internal voltage divider. A voltage on the VI pin that is in-between the V_{IH} and V_{IL} levels and present for longer than $t_{d(3-state)}$, causes both MOSFETs to be turned off. Normal operation commences once the VI input is outside this window for longer than $t_{d(3-state)}$.

8.6 Automatic Dead-time Reduction (ADR)

Protection against cross-conduction (shoot-through) is achieved via by a delay (or dead-time) between the switching off of one MOSFET and the switching on of the other MOSFET. The automatic dead-time reduction feature continuously monitors the body diode of the lower MOSFET adjusting the dead-time to minimize body diode conduction. This reduces power loss in both the upper and lower MOSFETs due to the reduction in body diode conduction and reverse recovery charge. The lower power dissipation leads to higher system efficiency and enables higher frequency operation.

8.7 Overtemperature Protection (OTP)

Protection against over temperature is provided by an internal thermal shutdown incorporated into the control circuit. When the control circuit die temperature exceeds the upper thermal trip level, both MOSFETs are switched off and the internal V_{DDG} regulator disabled. This state continues until the die temperature falls below the lower trip temperature. This function is only operational when V_{DDC} is above the UVLO level.

8.8 Disable

This is the disable or enable function of the driver. Pulling the DISABLE pin LOW switches off both MOSFETs and disables the REG5V output. This pin is internally pulled LOW whilst V_{DDC} remains below the UVLO threshold. Once V_{DDC} exceeds the UVLO threshold, this pin is pulled HIGH by an internal resistor. In this way the driver will enable itself unless there is an external pull down. In multiphase applications, connecting the DISABLE pins of multiple PIP213-12M devices together will ensure that all devices will only become enabled when the voltage on the V_{DDC} pins of all of the devices has exceeded the UVLO threshold; see [Figure 10](#).

8.9 Reg5V

This function provides a low current regulated 5 V output voltage suitable for providing power to a PWM controller. It is operational when both PRDY and DISABLE are HIGH. Operation as a 5 V power supply is only guaranteed when V_{DDC} is > 7 V. This pin can also be used as part of an enable function for a PWM controller; this ensures that the PWM is enabled only when the PIP213-12M is fully operational (i.e. both PRDY and DISABLE are HIGH).

9. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V_{DDC}	control circuit supply voltage		-0.5	+15	V
V_{DDO}	output stage supply voltage		-0.5	+24	V
V_I	input voltage		-0.5	+12.6	V
V_{DDG}	gate driver supply voltage		-0.5	+12.6	V
V_O	output voltage		-0.5	$V_{DDO} + 0.5$	V
$V_{c(bs)}$	bootstrap capacitance voltage		-0.5	$V_O + 15$	V
$I_{O(AV)}$	average output current	$V_{DDC} = 12$ V; $T_{pcb} \leq 90$ °C; $f_i = 1$ MHz	-	25	A
I_{ORM}	repetitive peak output current	$V_{DDC} = 12$ V; $t_p \leq 10$ µs	[1] -	40	A
V_{PRDY}	voltage on pin PRDY		-0.5	+12.6	V
$V_{DISABLE}$	voltage on pin DISABLE		-0.5	+12.6	V
V_{REG5V}	voltage on pin REG5V		-0.5	+12.6	V
P_{tot}	total power dissipation	$T_{mb} = 25$ °C	-	21	W
		$T_{mb} = 90$ °C	[2] -	10	W
T_{stg}	storage temperature		-55	+150	°C
T_j	junction temperature		-55	+150	°C

[1] Pulse width and repetition rate limited by maximum value of T_j .
[2] Assumes a thermal resistance from junction to mounting base of 6 K/W.

10. Thermal characteristics

Table 5. Thermal characteristics

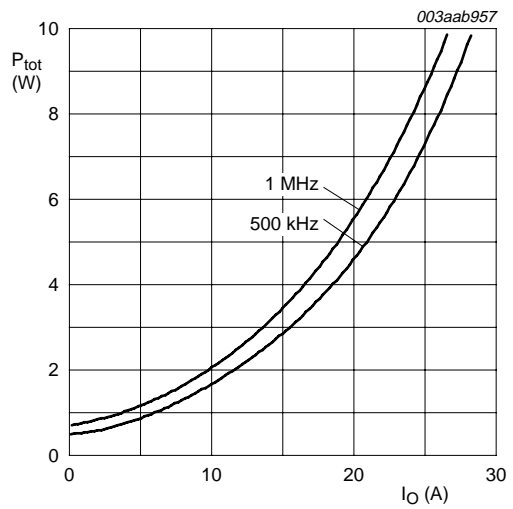
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$R_{th(j-mb)}$	thermal resistance from junction to mounting base	device tested with upper and lower MOSFETs in series	-	3	6	K/W

11. Characteristics

Table 6. Characteristics
 $V_{DDC} = 12\text{ V}$; $T_j = 25\text{ }^{\circ}\text{C}$ unless otherwise specified.

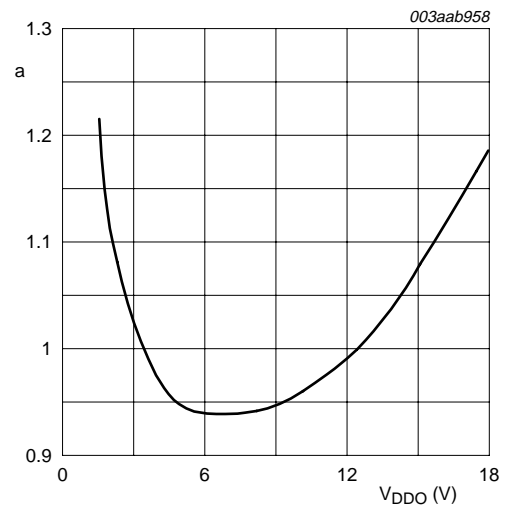
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Static characteristics						
V _{DDC}	control circuit supply voltage	25 °C ≤ T _J ≤ 150 °C	4.5	12	14	V
V _{th(UVLO)}	undervoltage lockout threshold voltage	turn on	4.05	4.2	4.45	V
		turn off	3.7	3.9	4.1	V
V _{th(CBP-CBN)}	threshold voltage between pin CBP and pin CBN	turn on	3.85	4.1	4.35	V
		turn off	2.35	2.6	2.85	V
V _{IH}	HIGH-level input voltage		[1] 3.3	3.5	3.7	V
V _{IL}	LOW-level input voltage		[1] 1.4	1.5	1.6	V
I _{LI}	input leakage current	0 V ≤ V _I ≤ 5 V	-	180	-	μA
I _{DDC}	control circuit supply current	f _i = 0 Hz, V _I = 0 V	-	8.2	-	mA
		f _i = 500 kHz, VDDG_EN = open	-	40	-	mA
		f _i = 500 kHz, VDDG_EN = ground	-	12	-	mA
V _{DDG}	gate driver supply voltage	I _L = 65 mA	5.75	6.5	7.25	V
V _{REG5V}	voltage on pin REG5V	I _L ≤ I _{REG5V} minimum, V _{DDC} > 7 V	4.5	5.0	5.5	V
I _{REG5V}	current on pin REG5V	V _{REG5V} = 4.5 V	18	-	-	mA
V _{th(en)}	enable threshold voltage	on pin DISABLE, V _{DDC} > 4.5 V	2.9	3.2	3.5	V
V _{th(dis)}	disable threshold voltage	on pin DISABLE, V _{DDC} > 4.5 V	1.4	1.6	1.8	V
T _{trip(otp)}	over-temperature protection trip temperature		-	160	-	°C
T _{trip(otp)hys}	hysteresis of over-temperature protection trip temperature		-	40	-	°C
P _{tot}	total power dissipation	V _{DDO} = 12 V; I _{O(AV)} = 20 A; V _O = 1.3 V; T _{pcb} = 90 °C;				
		f _i = 500 kHz	-	4.7	-	W
		f _i = 1 MHz	-	5.5	-	W
Upper MOSFET						
R _{DSon}	drain-source on-state resistance	I _O = 10 A; V _{CBP} = 12 V	-	6.5	-	mΩ
Lower MOSFET						
R _{DSon}	drain-source on-state resistance	I _O = 10 A; V _{DDG} = 12 V	-	3.8	-	mΩ
		I _O = 10 A; V _{DDG} = 6.5 V	-	4.5	-	mΩ
Dynamic characteristics						
t _{d(on)(IH-OH)}	turn-on delay time from input HIGH to output HIGH	V _{DDO} = 12 V; I _{O(AV)} = 12.5 A	-	-	80	ns
t _{d(off)(IL-OL)}	turn-off delay time from input LOW to output LOW		-	-	75	ns
t _{d(3-state)}	3-state delay time		-	90	-	ns

[1] If the input voltage remains between V_{IH} and V_{IL} (2.5 V typ) for longer than $t_{d(3-state)}$, then both MOSFETs are turned off.



$V_{DDC} = 12\text{ V}$; $V_{DDO} = 12\text{ V}$; $V_O = 1.3\text{ V}$; $f_i = 1\text{ MHz}$

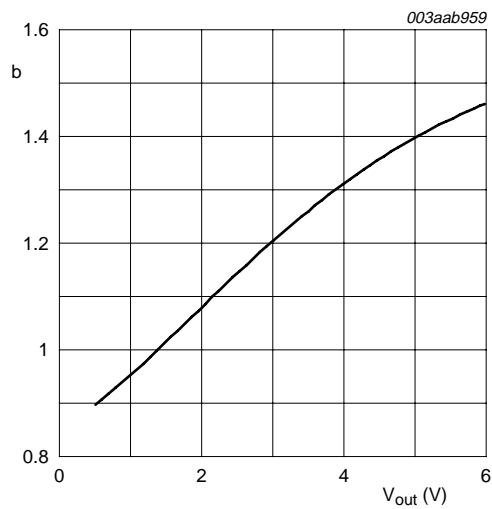
Fig 4. Total power dissipation as a function of average output current; typical values



$V_{DDC} = 12\text{ V}$; $V_O = 1.3\text{ V}$; $f_i = 1\text{ MHz}$; $I_{O(AV)} = 20\text{ A}$

$$a = \frac{P_{tot}}{P_{tot}(V_{DD0} = 12\text{ V})}$$

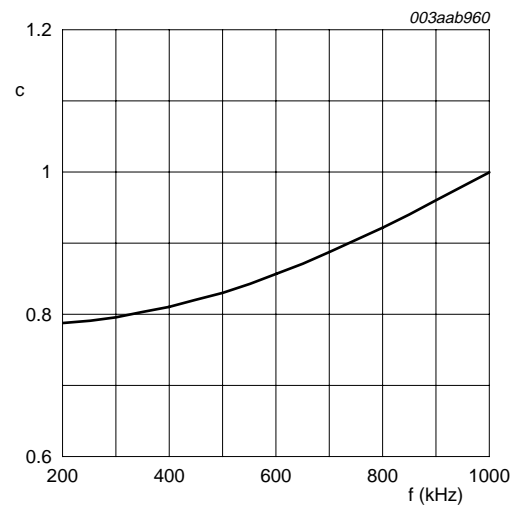
Fig 5. Normalized power dissipation as a function of output stage supply voltage; typical values



$V_{DDC} = 12\text{ V}$; $V_{DDO} = 12\text{ V}$; $f_i = 1\text{ MHz}$; $I_{O(AV)} = 20\text{ A}$

$$b = \frac{P_{tot}}{P_{tot}(V_O = 1.3\text{ V})}$$

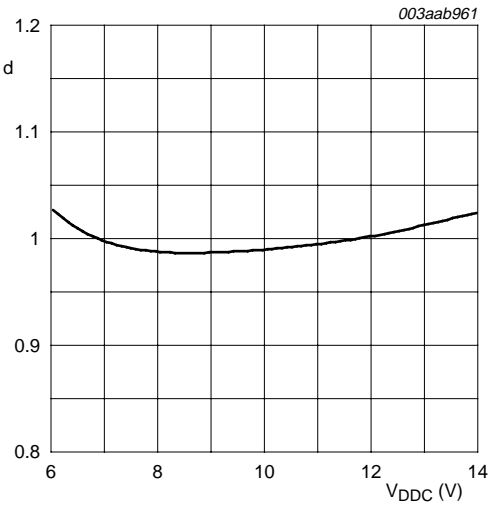
Fig 6. Normalized power dissipation as a function of output voltage; typical values



$V_{DDC} = 12\text{ V}$; $V_{DDO} = 12\text{ V}$; $V_O = 1.3\text{ V}$; $I_{O(AV)} = 20\text{ A}$

$$c = \frac{P_{tot}}{P_{tot}(f_i = 1\text{ MHz})}$$

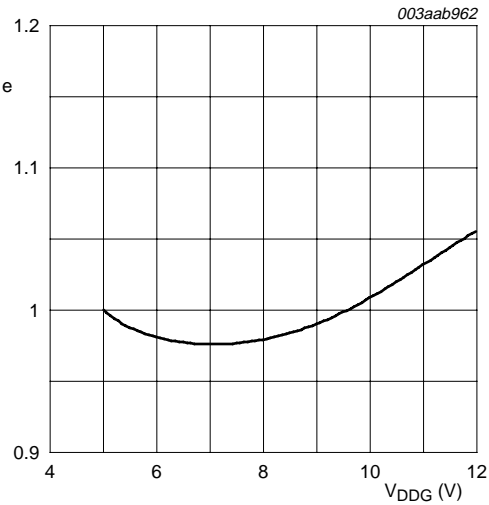
Fig 7. Normalized power dissipation as a function of input frequency; typical values



V_{DDC} = 12 V; V_O = 1.3 V; f_i = 1 MHz; I_{O(AV)} = 20 A

$$d = \frac{P_{tot}}{P_{tot}(V_{DDC} = 12\text{ V})}$$

Fig 8. Normalized power dissipation as a function of control circuit supply voltage; typical values



V_{DDC} = 12 V; V_{DDO} = 12 V; f = 1 MHz; I_{O(AV)} = 20 A

$$e = \frac{P_{tot}}{P_{tot}(V_{DDG} = 5\text{ V})}$$

Fig 9. Normalized power dissipation as a function of gate driver supply voltage; typical values

12. Application information

12.1 Typical application

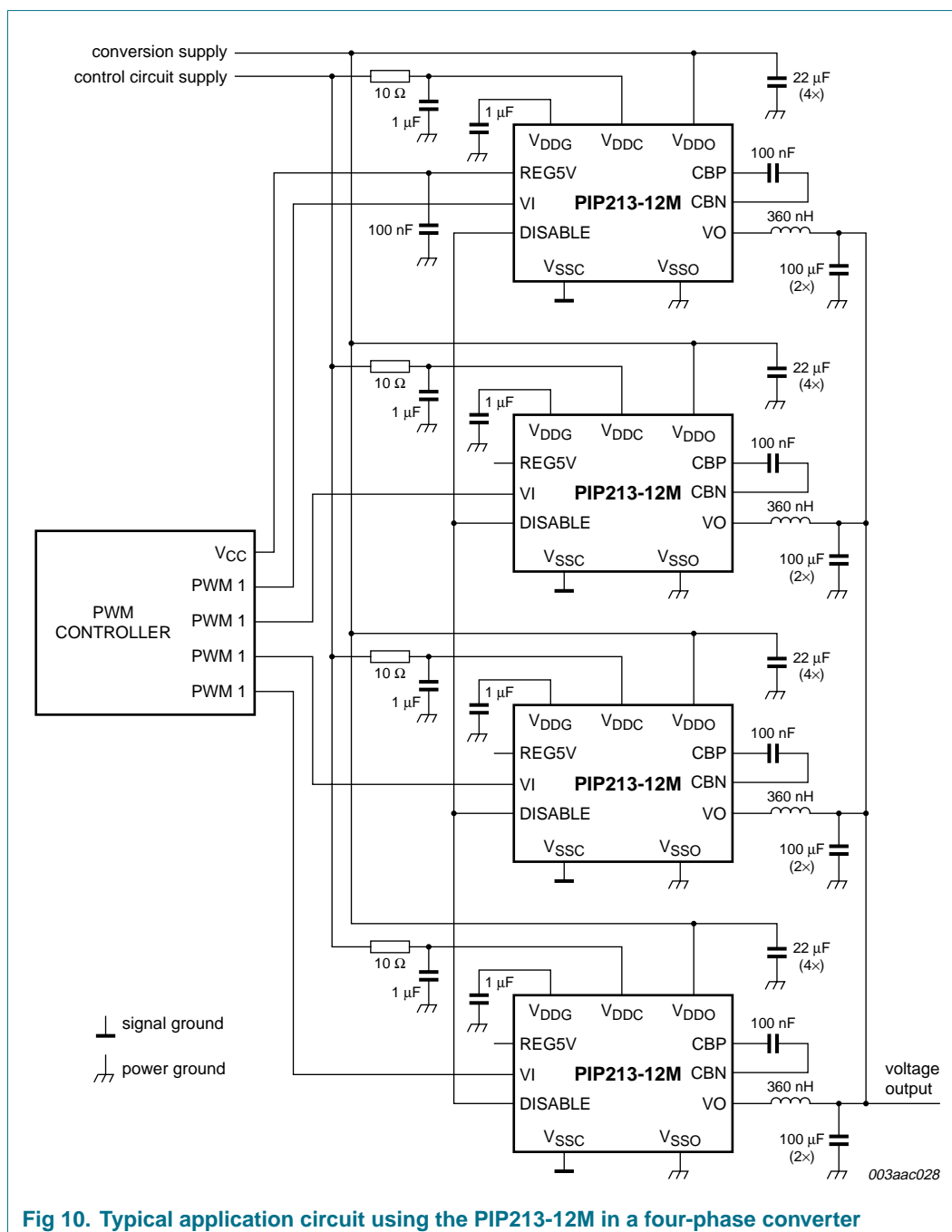


Fig 10. Typical application circuit using the PIP213-12M in a four-phase converter

A typical four-phase buck converter is shown in [Figure 10](#). This system uses four PIP213-12M devices to deliver a continuous output current of 100 A at an operating frequency of 500 kHz.

12.2 V_{DDG} supply options

The following options can be used for the lower MOSFET driver supply (V_{DDG}).

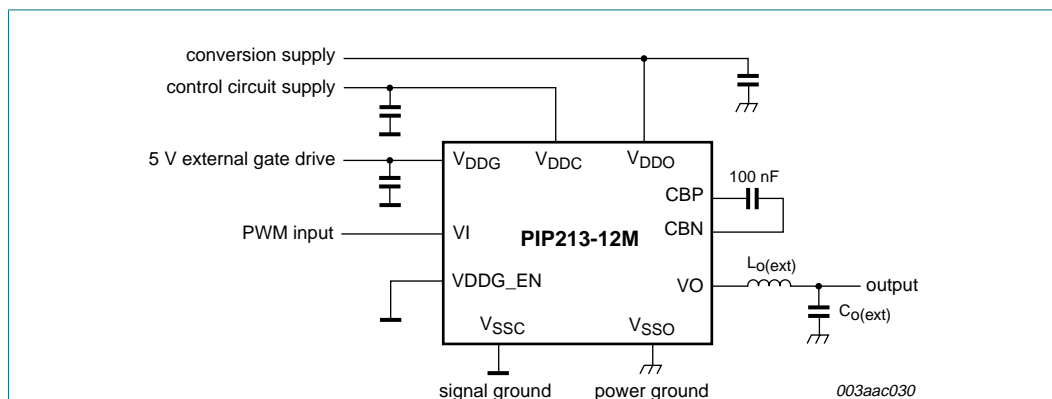


Fig 11. Dual supply operation using 5 V external supply for V_{DDG}

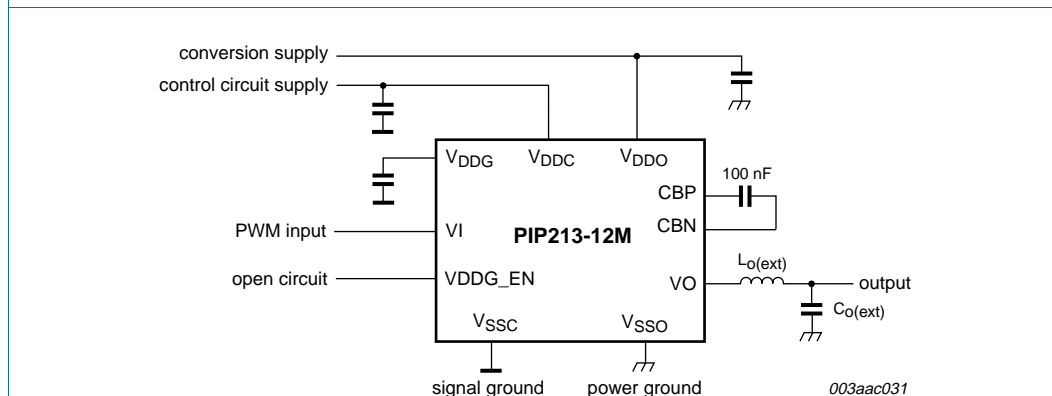


Fig 12. Single supply operation using internal supply for V_{DDG}

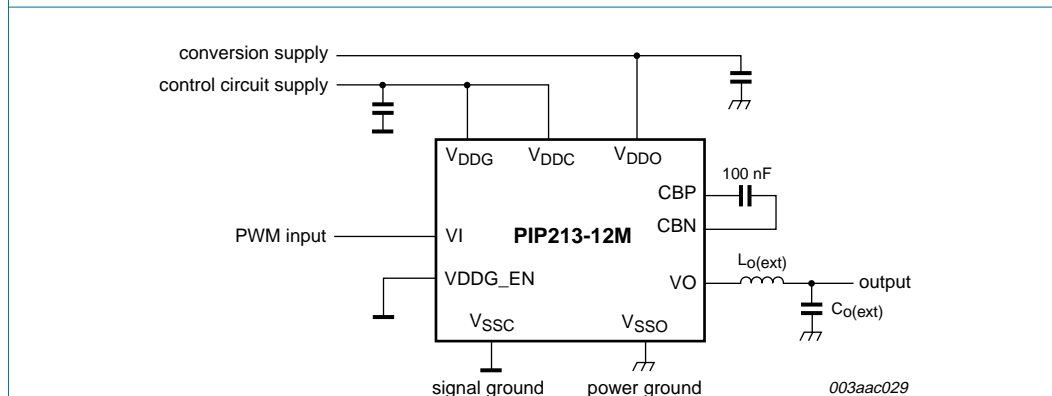


Fig 13. Single supply operation using external supply for V_{DDG}

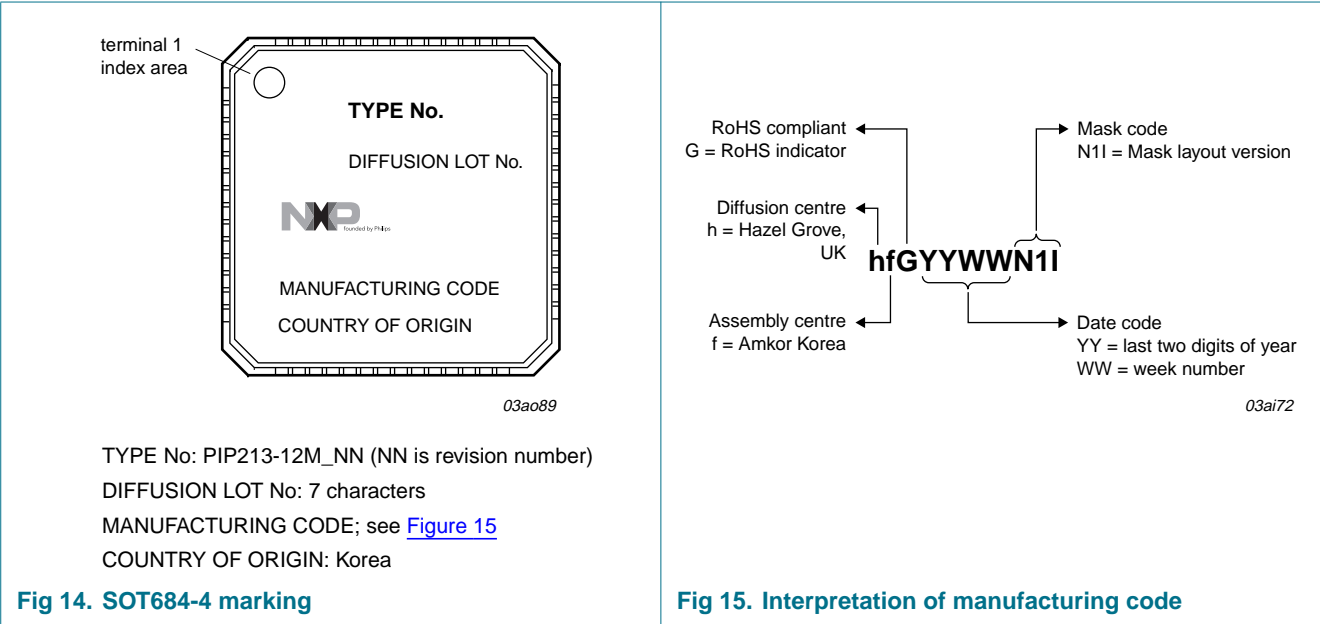
12.3 DrMOS compatibility

The PIP213-12M can be configured to be compatible with the Intel DrMOS specification. Conformance to the Intel DrMOS specification requires that an external power supply to the V_{DDG} pin is used and hence the internal V_{DDG} regulator must be disabled by connecting the V_{DDG_EN} pin to V_{SSC} .

The PRDY flag is not used and should be left unconnected on the PCB. The external boost capacitor should also be connected between CBP and V_O and not CBP and CBN with the CBN pin being left unconnected on the PCB. In addition, V_{SSC} pin 7 and V_{SSO} pin 39 to pin 41 should be left unconnected on the PCB. Note that the sizes of PAD 1, PAD 2 and PAD 3 can vary between different DrMOS vendors. The PCB footprint must be modified to take the pinning modifications and pad size differences into account.

To ensure footprint compatibility with other DrMOS products, it is recommended that the latest multiple vendor compatibility PCB footprint contained within the Intel DrMOS specification is used and that the relevant DrMOS product data sheet is checked for compatibility.

13. Marking



14. Package outline

HVQFN56: plastic thermal enhanced very thin quad flat package; no leads; 56 terminals; body 8 x 8 x 0.85 mm

SOT684-4

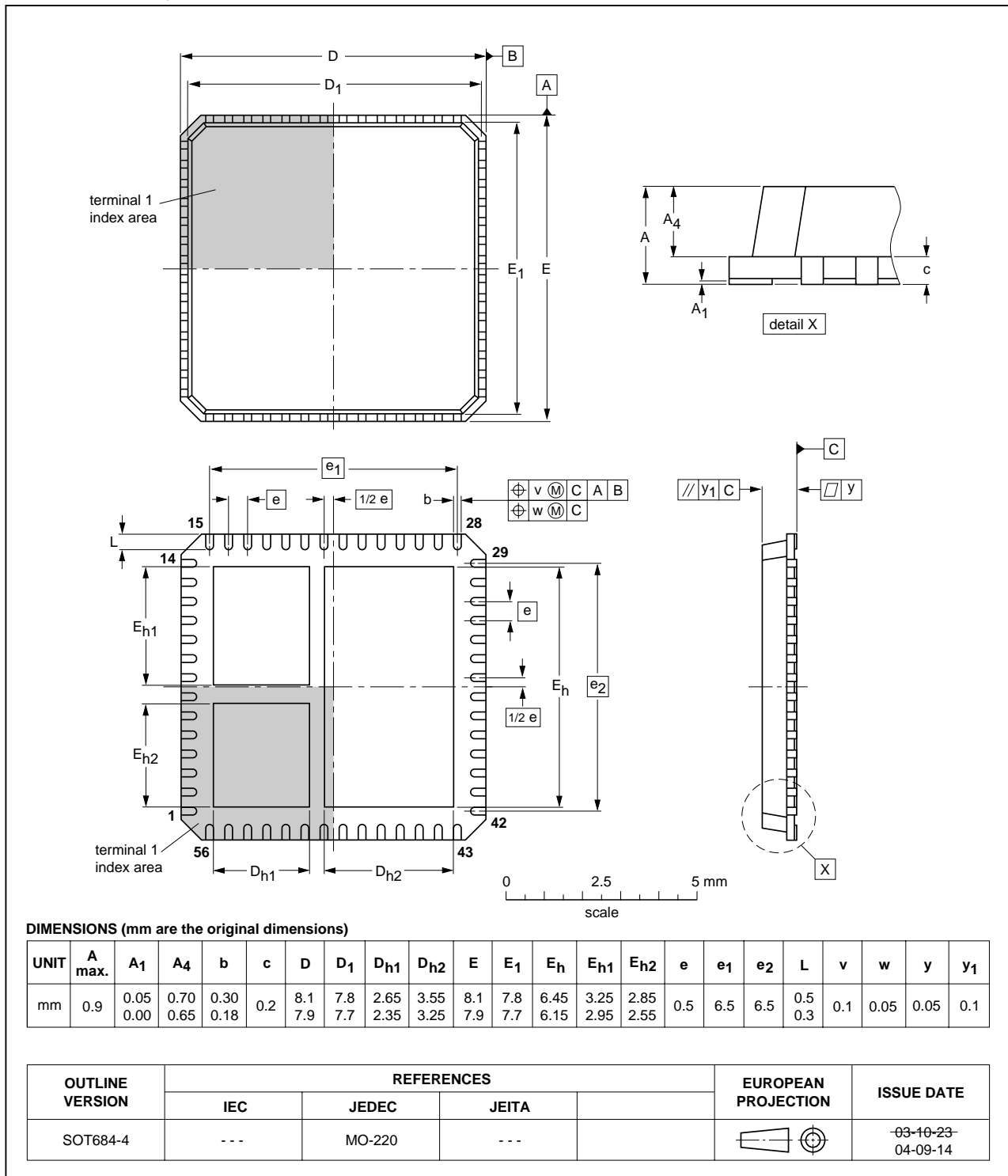


Fig 16. Package outline SOT684-4 (HVQFN56)

15. Soldering

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

15.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

15.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leadless or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leadless SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leadless packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus PbSn soldering

15.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

15.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 17](#)) than a PbSn process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 7](#) and [8](#)

Table 7. SnPb eutectic process (from J-STD-020C)

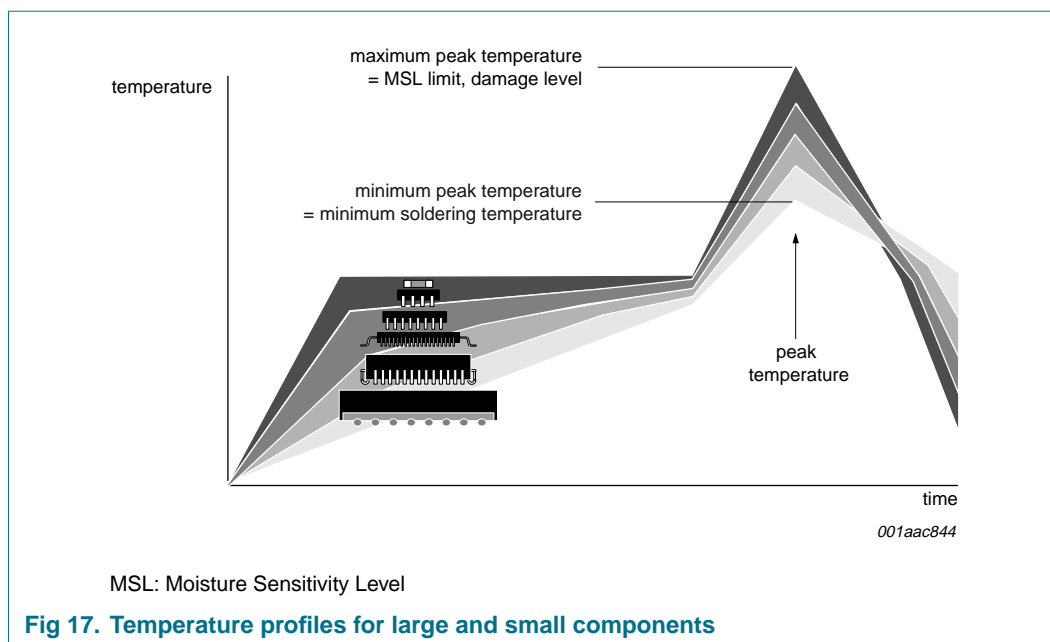
Package thickness (mm)	Package reflow temperature (°C)	
	Volume (mm ³)	
	< 350	≥ 350
< 2.5	235	220
≥ 2.5	220	220

Table 8. Lead-free process (from J-STD-020C)

Package thickness (mm)	Package reflow temperature (°C)		
	Volume (mm ³)		
	< 350	350 to 2000	> 2000
< 1.6	260	260	260
1.6 to 2.5	260	250	245
> 2.5	250	245	245

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 17](#).



For further information on temperature profiles, refer to Application Note *AN10365* “Surface mount reflow soldering description”.

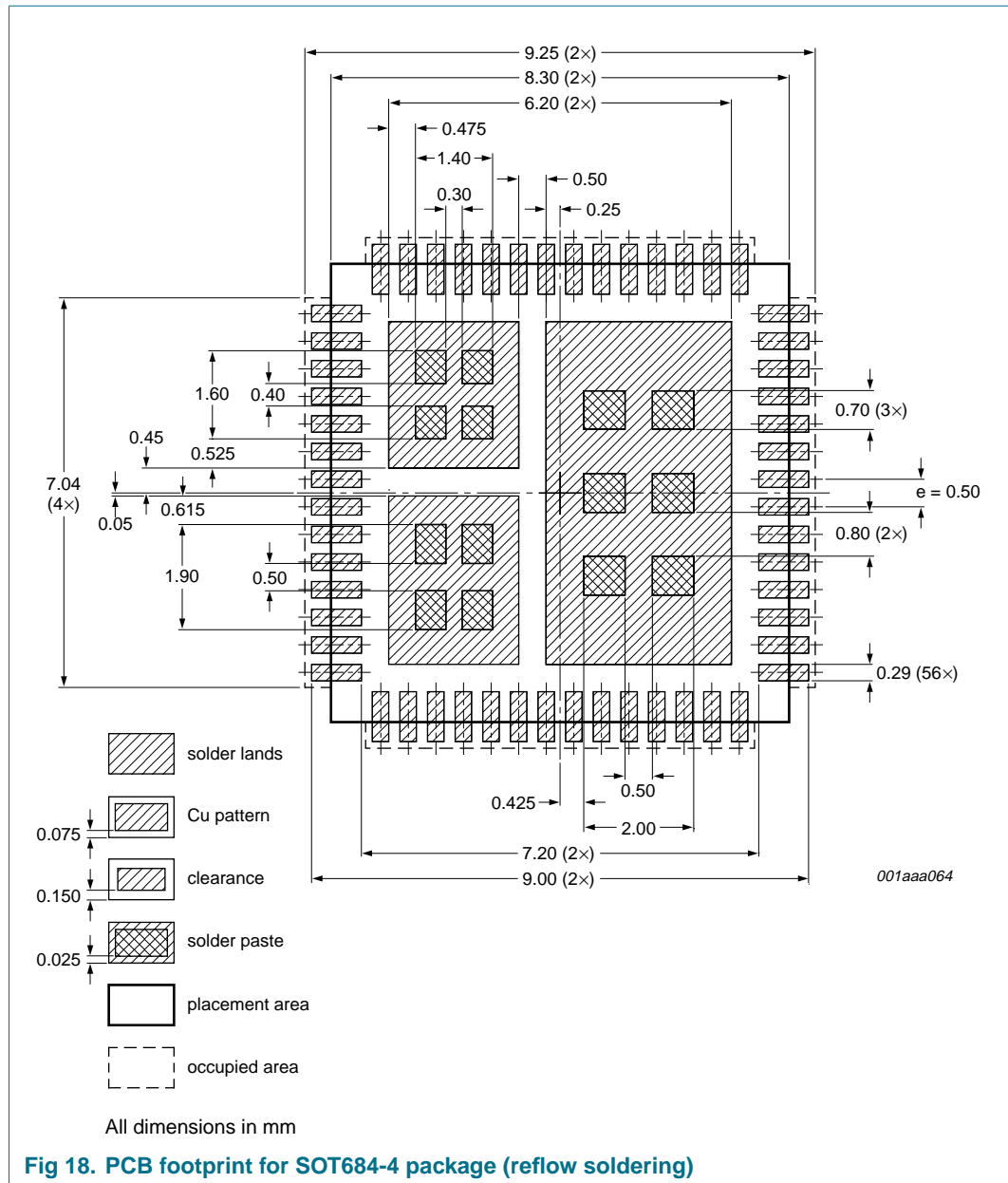
16. Mounting

16.1 PCB design guidelines

The terminals on the underside of the package are rectangular in shape with a rounded edge on the inside. Electrical connection between the package and the printed-circuit board is made by printing solder paste onto the PCB footprint followed by component placement and reflow soldering. The PCB footprint shown in [Figure 18](#) is designed to form reliable solder joints.

The use of solder resist between each solder land is recommended. PCB tracks should not be routed through the corner areas shown in [Figure 18](#). This is because there is a small, exposed remnant of the lead frame in each corner of the package, left over from the cropping process.

Good surface flatness of the PCB lands is desirable to ensure accuracy of placement after soldering. Printed-circuit boards that are finished with a roller tin process tend to leave small lumps of tin in the corners of each land. Levelling with a hot air knife improves flatness. Alternatively, an electro-less silver or silver immersion process produces completely flat PCB lands.



16.2 Solder paste printing

The process of printing the solder paste requires care because of the fine pitch and small size of the solder lands. A stencil thickness of 0.125 mm is recommended. The stencil apertures can be made the same size as the solder lands in [Figure 18](#).

The type of solder paste recommended for MLF (Micro Lead-Frame) packages is “No clean”, Type 3, due to the difficulty of cleaning flux residues from beneath the MLF package.

17. Revision history

Table 9. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
PIP213-12M_1	20070925	Product data sheet	-	-

18. Legal information

18.1 Data sheet status

Document status ^{[1][2]}	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

18.2 Definitions

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