

GS-R400 Family

20W TO 140W STEP-DOWN **SWITCHING REGULATOR FAMILY**

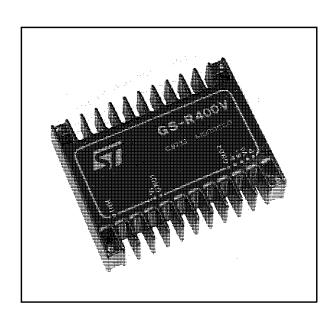
FEATURES

- MTBF in excess of 200,000 hours
- 4A max output current
- 46V max input voltage
- 4V max drop-out voltage
- Soft start
- Remote logic inhibit/enable
- Remote output voltage sense
- Non-latching overload and short circuit protection
- Crow-bar output overvoltage protection

DESCRIPTION

The GS-R400 series is a versatile family of high current, high voltage step-down switching voltage regulators.

The integral heatsink allows a large power handling capability and it provides also an effective shielding to minimize EMI.



SELECTION CHART

Туре	Output	Input	Output	Regulation		Efficiency		
Ordering Number	Voltage (V)	Voltage (V)	Ripple (mVpp)	Line (mV/V)	Load (mV/A)	(%)	Notes	
GS-R405	5.1 ± 2%	9 to 46	25	2	20	70	Fixed output voltage	
GS-R412	12.0 ± 4%	16 to 46	50	5	40	80	"	
GS-R415	15.0 ± 4%	19 to 46	65	5	60	85	33	
GS-R424	24.0 ± 4%	28 to 46	100	6	90	90	"	
GS-R405S	5.1 ± 2%	9 to 46	25	2	20	70	Reset output	
GS-R400V	5.1 to 40	Vo+4 to 46	25 to 100	6	20 to 90	70 to 90	Progr. output voltage	
GS-R400VB	5.1 to 40	Vo+4 to 46	25 to 100	6	20 to 90	70 to 90	Progr. output voltage and current. Frequency synchr.	

Note: The line regulation is measured at I_{out}=1A

The load regulation is measured at V_{in} =V₀+8V and l_{out}=1 to 3A For V₀ \geq 36V and l₀ = 4A an external heatsink or forced ventilation are required.

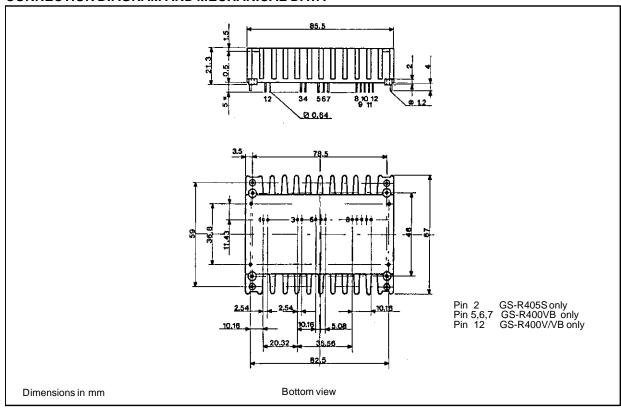
ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Value	Unit
Vi	DC Input Voltage	48	V
lrt*	Reset Output Sink Current	20	mA
Tstg	Storage Temperature Range	- 40 to +105	°C
T _{cop}	Operating Case Temperature Range	- 20 to +85	°C

GS-R405S only

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CONNECTION DIAGRAM AND MECHANICAL DATA



PIN DESCRIPTION

Pin	Function	Description	
1	Inhibit	The module is disabled by a high logic level applied to this pin.	
2	Reset	Reset output (GS-R405S only).	
3	+ Input	DC input voltage. Recommended maximum voltage is 46V.	
4	Input GND	Return for input voltage source.	
5	Oscillator	100kHz oscillator output. To be connected to Sync (pin 6) input if the unit is a master and left open if it is a slave (GS-R400VB only). See fig. 5.	
6	Sync	Synchronization input. To be connected to the Oscillator output (pin 5) of the master (GS-R400VB only). See fig. 5.	
7	Current limiting	A resistor ($\ge 2.2 \text{k}\Omega$) connected from this pin to pin 9 sets the current limiting level (GS-R400VB only).	
8	Output GND	Return for output current path. Internally connected to pin 4.	
9	- Sense	Senses the remote load return. Must be tied to pin 8 when the remote sensing feature is not used. See fig. 1.	
10	+ Sense	Senses the remote load high side. Must be tied to pin 11 when the remote load sensing feature is not used. See fig. 1.	
11	+ Output	Regulated DC output voltage.	
12	Program	A resistor (\leq 18k Ω) connected between this pin and pin 10 sets the output voltage (GS-R400V and GS-R400VB only).	



ELECTRICAL CHARACTERISTICS	$(T_A = 25^{\circ}C \text{ unless otherwise specified})$
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Symbol	Parameter	Test Conditions	Min	Тур	Max	Unit
ΔV ₀ /ΔΤ	Temperature Stability	Vi = V ₀ +8V I ₀ = 1A		0.2/1.6		mv/°C
lo	Output Current	Vi = Vo+8V	0.2		4	Α
loL	Current Limit	V _i = V ₀ +8V		5	8	Α
lisc	Average Input Current	Vi = 46V Output Shorted		0.1	0.2	Α
fs	Switching Frequency	I ₀ = 1A		100		KHz
SVR	Supply Voltage Rejection	f ₀ = 100Hz Io =1A		4/12		mV/V
Vr	Ripple Voltage	I ₀ = 2A		25/150		mVpp
tss	Soft Start Time	V _i = V ₀ +8V		10/35		ms
Vinhl	Low Inhibit Voltage				0.8	V
Vinhh	High Inhibit Voltage		2		5.5	V
linhh	High Inhibit Input Current	Vinh = 5V			500	μΑ
tcb	Crow-bar Delay Time			5		μs
Vrh*	Reset High Level			5		V
Vrl*	Reset Low Level	Irl = 5mA Irl = 10mA			0.2 0.4	V
trd*	Reset Delay Time			100		ms
Vcth	Crowbar Intervention Threshold			Vo•1.25		٧
ΔV _O	Total Remote Sense Compensation				500	mV
Rth	Thermal Resistance	Case to ambient		5		°C/W

^{*} GS-R405S only

USER NOTES

Input Voltage

The recommended operating maximum DC input voltage is 46V inclusive of the ripple voltage.

Remote Sensing

The remote voltage sense compensation range is for a total drop of 500mV equally shared between the load connecting wires. It is a good practice to shield the sensing wires to avoid oscillation.

Each sense input must be connected to its companion output power pin when the remote sense capability is not used (see fig. 1).

Case Grounding

The module case is isolated from the electrical circuit of the switching regulator. It can be grounded using the 4 corner pins.

The PCB area below the module can be used as an effective sixth side shield against EMI.

Thermal Characteristics

The case-to-ambient thermal resistance of all the GS-R400 modules is about 5°C/W. This produces a 50°C temperature increase of the module surface for 10W of internal power dissipation.

Depending on the ambient temperature and/or on the power dissipation, an additional heatsink or forced ventilation may be required.

Input Impedance

The module has an internal capacitor connected between the input pins in order to assure PWM stability. This capacitor cannot handle large values of high frequency ripple current and it can be permanently damaged if the primary energy source impedance is not adequate. The use of an external low ESR, high ripple current capacitor located as close the module as possible is recommended. Suitable capacitors should have a RMS current capability of $2.5A_{RMS}$ with a working voltage of 50 Vpc and an ESR of 0.1Ω at 100~kHz. When space



is a limitation, a $22\mu F$ ceramic multilayer capacitor must be connected to the module input pins.

Output Voltage Programming

The GS-R400V and GS-R400VB output voltage is programmed by using a resistor (see pin function table and fig. 4). The resistor must be located very close the module and the PCB layout must mimimize injected noise. The value of the resistor is calculated by using the following formula:

$$R_V = 2.67 \left(\frac{V_0}{5.1} - 1 \right) k\Omega$$

Vo can be adjusted between 5.1 and 40V.

Current Limiting Programming

The GS-R400VB current limiting is programmed by using a resistor (see pin function table and fig. 4).

The value of the resistor is calculated by using the following formula:

$$R_i = [2.2 + (5 \bullet I_0)] k\Omega$$

Module Protection

The modules are protected against occasional and permanent short circuits of the output pin to ground, as well as against output current overload.

When the output current exceeds the maximum value, the output is automatically disabled. After a fixed time the module starts again in a soft mode. The cycle is repeated until the overload condition is removed.

A crowbar output overvoltage protection is activated whenever the output voltage exceeds the nominal output voltage by more than 25%.

Figure 1. Load Connection

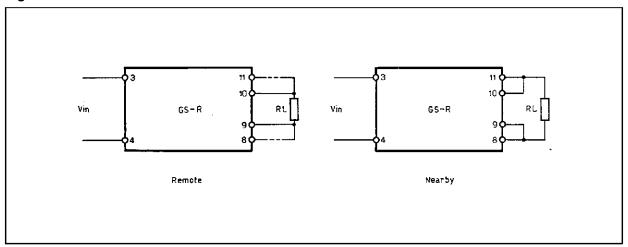


Figure 2. Remote Inhibit Operation

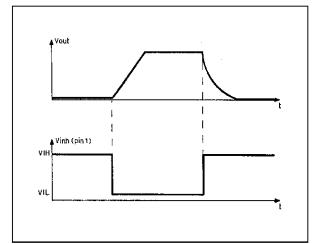


Figure 3. Reset Operation

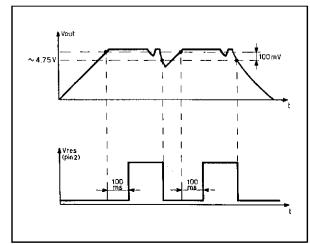


Figure 4. Voltage and Current Programming

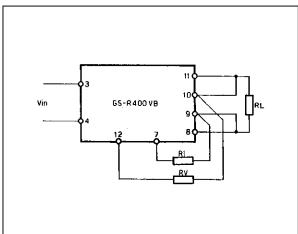
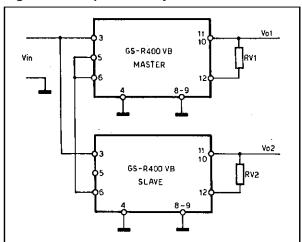


Figure 5. Multiple Units Synchronization



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