Panasonic
ideas for life

High-sensitive human detection sensor with built-in amp.

PIR MOTION SENSOR
⁽⁽⁽(PaPIRs)⁾⁾⁾

WL series / VZ series

Standard type

Long distance detection type

NaPiOn series

Standard type

Slight motion detection type

Spot detection type

10m detection type

RoHS compliant

ADVANTAGES
- **Simplified circuitry with fully integrated circuit design**
- **1μA low current consumption with the proprietary design**
- **Excellent resistance to electromagnetic noise**
- **High Signal/Noise ratio to minimize false operation**
- **Environment-friendliness with "Lead-free" element**

TYPICAL APPLICATIONS
- **Lighting: lamp, automatic switch, street lighting**
- **Anti-crime devices: security camera, crime-prevention sensor**
- **Home appliance: air conditioner, air purifier, fan heater**
- **Commercial equipments: vending machine, copy machine**
- **Audio and Visual devices: TV, PC, display**

FEATURES

1. Sensing circuits enclosed in a TO5 can
The high-density embedded circuit design eliminates external sensing circuits. Advantages include reduced development and design schedules.

Lens · IC

PIR element · Chip parts

Capacitor

PC board · Shielded plate

Lens

Sensor module
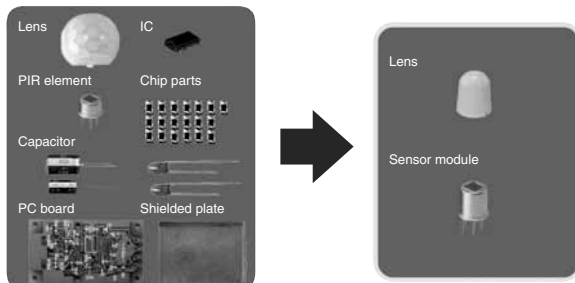
2. Super low current consumption
Reduction of current consumption allows battery life to be extended for battery driven products, including wireless based and low power consumption devices.

### 3. Excellent noise resistance
(Radiations noise, power supply noise)
The entire circuitry is enclosed in a metal package, which means it has high electromagnetic shielding capability.

Radiation noise

Power supply superimposed noise

Vd

OUT

GND
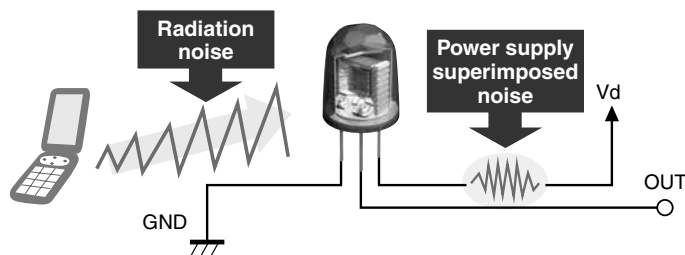
4. Miniaturized lenses with small elements
A short focal length is all that's required even when detecting at the same distance, which means both downsizing and high-sensitivity are achieved.

Small movement
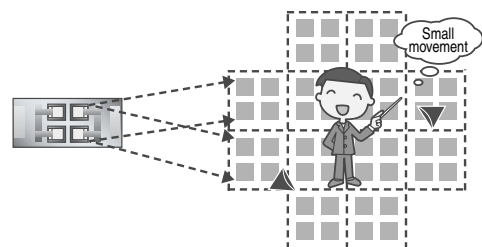
PIR Motion Sensor (EKMB, EKMC, AMN2, 3)

PRODUCT TYPES

1. WL series

Detection performance	Lens color	Consumption current		
		1µA	2µA	6µA
Standard type	White	EKMB1101111	EKMB1201111	EKMB1301111K
	Black	EKMB1101112	EKMB1201112	EKMB1301112K
	Pearl White	EKMB1101113	EKMB1201113	EKMB1301113K
Long distance detection type	White	EKMB1103111	EKMB1203111	EKMB1303111K
	Black	EKMB1103112	EKMB1203112	EKMB1303112K
	Pearl White	EKMB1103113	EKMB1203113	EKMB1303113K

2. VZ series

Detection performance	Lens color	Consumption current 170µA
Standard type	White	EKMC1601111
	Black	EKMC1601112
	Pearl White	EKMC1601113
Long distance detection type	White	EKMC1603111
	Black	EKMC1603112
	Pearl White	EKMC1603113

3. NaPiOn series

Detection performance	Lens color	Digital output	Analog output
Standard type	Black	AMN31111	AMN21111
	White	AMN31112	AMN21112
Slight motion detection type	Black	AMN32111	AMN22111
	White	AMN32112	AMN22112
Spot detection type	Black	AMN33111	AMN23111
	White	AMN33112	AMN23112
10m detection type	Black	AMN34111	AMN24111
	White	AMN34112	AMN24112

RATING

1. Absolute maximum rating (Measuring condition: ambient temperature = 25°C 77°F)

Power supply voltage	−0.3 to 7.0VDC (for VZ series, NaPiOn series), −0.3 to 4.5VDC (for WL series)
Usage ambient temperature	−20 to 60°C −3 to 140°F (No freezing and condensing at low temperature)
Storage temperature	−20 to 70°C −4 to 158°F

2. Electrical characteristics

1) WL series VZ series

Items	Symbol	WL series			VZ series	Measuring conditions
Rated consumption current (Stand by) Note)	Iw	1µA ave.	2µA ave.	6µA ave.	170µA ave.	Ambient temperature = 25°C 77°F Iout = 0 Operating voltage 5V (VZ) 3V (WL)
Rated operating voltage	Vdd	2.3VDC min. 4.0VDC max.			3.0VDC min. 6.0VDC max.	
Output current (When detecting)	Iout	100µA max.			100µA max.	Ambient temperature = 25°C 77°F Vout ≧ Vdd-0.5V Operating voltage 5V (VZ) 3V (WL)
Output voltage (When detecting)	Vout	Vdd-0.5VDC min.			Vdd-0.5VDC min.	Ambient temperature = 25°C 77°F Open when not detecting Operating voltage 5V (VZ) 3V (WL)
Circuit stability time	Twu	25s typ. 210s max.		10s max.	30s max.	Ambient temperature = 25°C 77°F Iout = 0 Operating voltage 5V (VZ) 3V (WL) Ts [°C] = Const. (WL)

Note: The current which is consumed during detection consist of the standby consumed current plus the output current.

2) NaPiOn series
a) Digital output

Items	Symbol	Specified value	Measuring conditions
Rated consumption current (Stand by) Note)	Iw	170μA ave.	Ambient temperature = 25°C 77°F Operating voltage = 5V Iout = 0
Rated operating voltage	Vdd	3.0VDC min. 6.0VDC max.	
Output current (When detecting)	Iout	100uA	Ambient temperature = 25°C 77°F Operating voltage = 5V Vout ≧ Vdd-0.5V
Output voltage (When detecting)	Vout	Vdd-0.5V	Ambient temperature = 25°C 77°F Operating voltage = 5V Open when not detecting
Circuit stability time	Twu	30s max.	Ambient temperature = 25°C 77°F Operating voltage = 5V

Note: The current which is consumed during detection consists of the standby consumed current plus the output current.

b) Analog output

Items	Symbol	Specified value	Measuring conditions
Consumption current	Iw	170μA ave.	Ambient temperature = 25°C 77°F Operating voltage = 5V Iout = 0
Operating voltage	Vdd	4.5VDC min. 5.5VDC max.	
Output current	Iout	50μA	Ambient temperature = 25°C 77°F Operating voltage = 5V
Output voltage range	Vout	0V min. VDD max.	Ambient temperature = 25°C 77°F Operating voltage = 5V
Output offset average voltage	Voff	2.3V min. 2.5V ave. 2.7V max.	Ambient temperature = 25°C 77°F Operating voltage = 5V Steady-state output voltage when not detecting
Steady-state noise	Vn	155mVpp ave. 300mVpp max.	Ambient temperature = 25°C 77°F Operating voltage = 5V
Detection sensitivity	Vh or Vl	0.45V	Ambient temperature = 25°C 77°F Operating voltage = 5V Temperature difference with background: 4°C 39.2°F
Circuit stability time	Twu	45s	Ambient temperature = 25°C 77°F Operating voltage = 5V

Note: To set the same detection performance as the digital output type, set the output voltage (2.5V) ±0.45V.

3. Detection performance
1) WL series VZ series

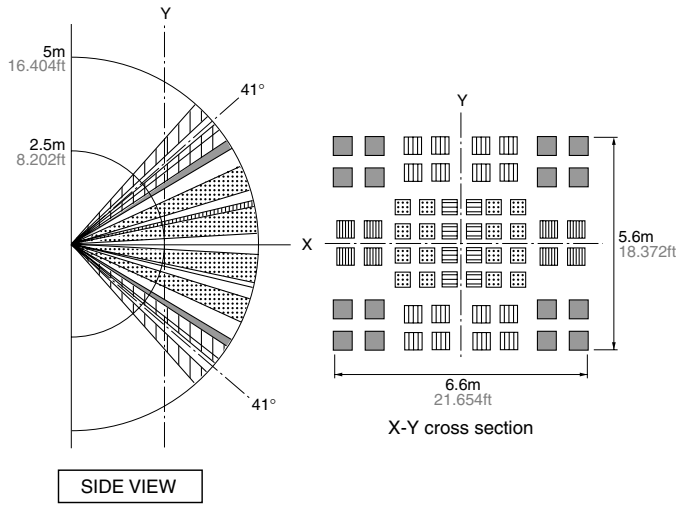| Items	Standard type	Long distance detection type	Measuring conditions
Detection distance	5m 16.404ft	12m 39.3696ft	1. Detectable difference in temperature between the target and background is more than 4°C 7.2°F. 2. Movement speed 1.0m/s 3. Detection object: human body (size is 700mm × 250mm 27.559inch × 9.843inch)
Detection range (Horizontal × Vertical)	94° × 82°	102° × 92°	
Detection zone	64 zones	92 zones	

2) NaPiOn series

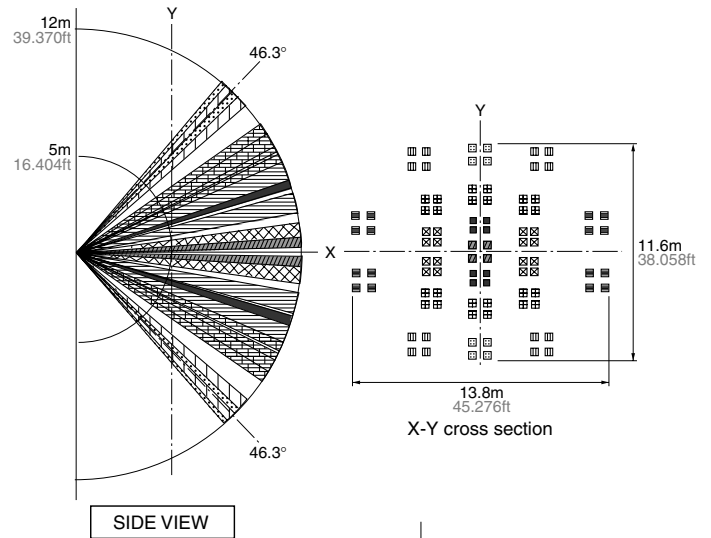| Items	Standard type	Slight motion detection type	Spot detection type	10m detection type	Measuring conditions

Detection distance	5m 16.404ft	2m 6.562ft	5m 16.404ft	10m 32.808ft	1. Detectable difference in temperature between the target and background is more than 4°C 7.2°F.
					2. Movement speed
					  1) Digital output type
					    Standard type/Spot type/10m detection type: 0.8 to 1.2m/s
					    Slight motion detection type: 0.5m/s
					  2) Analog output type
					    Standard type/Spot type/10m detection type: 0.5 to 1.5m/s
					    Slight motion detection type: 0.3 to 1.0m/s
					3. Detection object: human body (size is 700mm × 250mm 27.559inch × 9.843inch) (for the slight motion detection type, 200mm × 200mm 7.874inch × 7.874inch)

Detection range (Horizontal × Vertical)	100° × 82°	91° × 91°	38° × 22°	110° × 93°	
Detection zone	64 zones	104 zones	24 zones	80 zones	

PIR Motion Sensor (EKMB, EKMC, AMN2, 3)

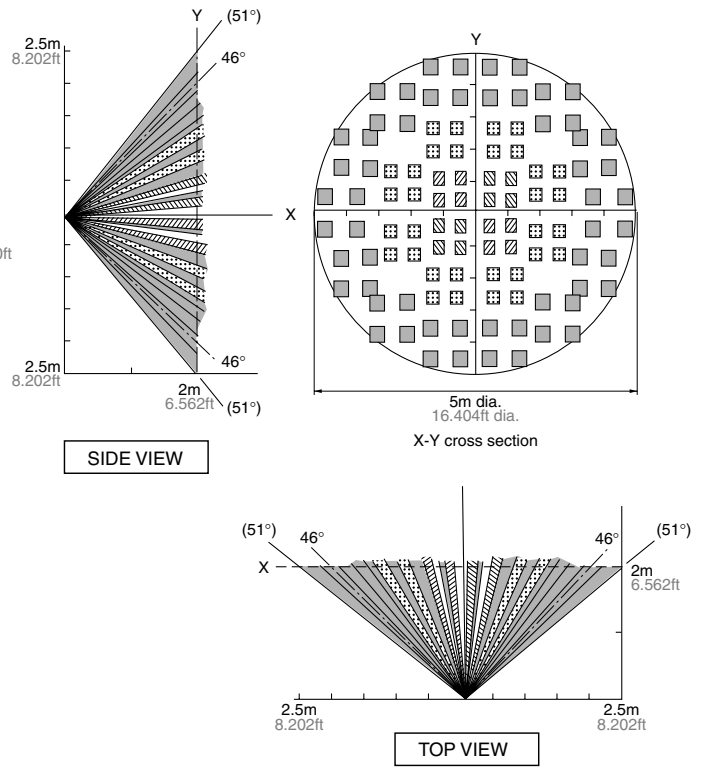## DETECTION PERFORMANCE

1. WLseries VZ series
Standard type

5m
16.404ft

2.5m
8.202ft

41°

Y

X

41°

5.6m
18.372ft

6.6m
21.654ft

X-Y cross section

SIDE VIEW

47°

47°

X

5m
16.404ft

2.5m
8.202ft

TOP VIEW

2. WL series VZ series
Long distance 12m detection type
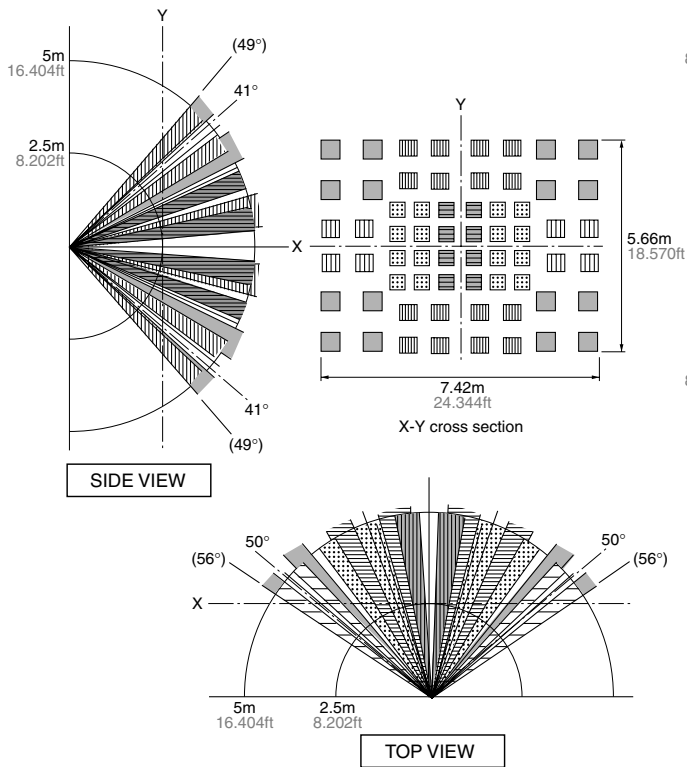
12m
39.370ft

5m
16.404ft

46.3°

Y

X

46.3°

11.6m
38.058ft

13.8m
45.276ft

X-Y cross section

SIDE VIEW

51.3°

51.3°

X

12m
39.370ft

5m
16.404ft

TOP VIEW

3. NaPiOn series
Standard type

5m
16.404ft

2.5m
8.202ft

(49°)

41°

Y

X

41°

(49°)

5.66m
18.570ft

7.42m
24.344ft

X-Y cross section

SIDE VIEW

50°

50°

(56°)

(56°)

X

5m
16.404ft

2.5m
8.202ft

TOP VIEW

4. NaPiOn series
Slight motion detection type

2.5m
8.202ft

(51°)

46°

Y

X

46°

2.5m
8.202ft

2m
6.562ft

(51°)

5m dia.
16.404ft dia.

X-Y cross section

SIDE VIEW

(51°)

46°

46°

(51°)

X

2m
6.562ft

2.5m
8.202ft

2.5m
8.202ft

TOP VIEW

5. NaPiOn series
Spot detection type

SIDE VIEW

X-Y cross section

TOP VIEW

6. NaPiOn series
10m detection type

X-Y cross section

SIDE VIEW

TOP VIEW
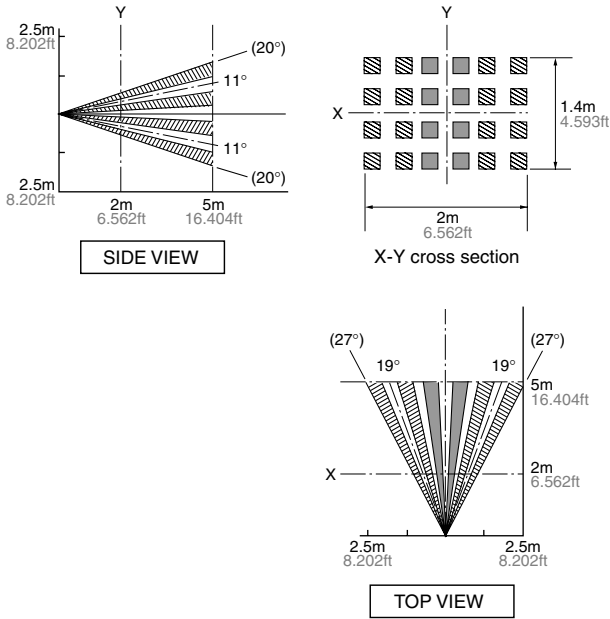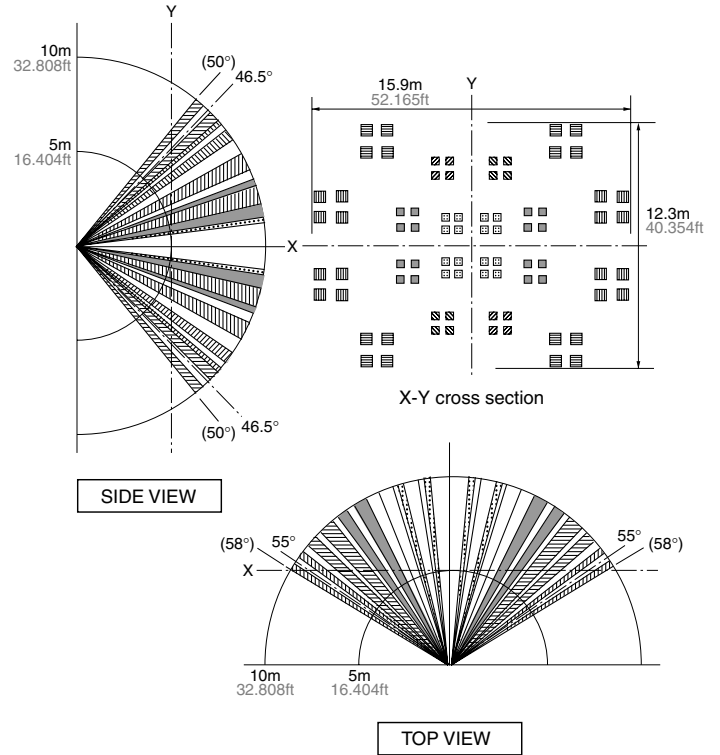
DIMENSIONS (mm inch)

The CAD data of the products with a **CAD Data** mark can be downloaded from: http://industrial.panasonic.com/ac/e/

1. VZ series WL series
Standard type

CAD Data

9.5 dia.
.374 dia.

13 .512   14.4 .567

0.45±0.05 dia.
.018±.002 dia.

4.6 .181

11 dia.
.433 dia.

VDD

P.C.D. 5.08±0.2 dia.
.200±.008 dia.

GND   OUT

45°±4°   45°±4°
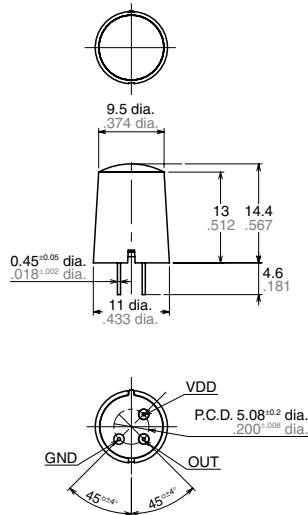
General tolerance ±0.5 ±.020

2. VZ series WL series
Long distance detection type

CAD Data

22 .866

20.7 dia.
.815 dia.

20.2 .795

7.3 .287

0.45±0.05 dia.
.018±.002 dia.

11 dia.
.433 dia.

4.6 .181

P.C.D. 5.08±0.2 dia.
.200±.008 dia.

VDD   2.5 .098   5 .197

GND   OUT

45°±4°   45°±4°
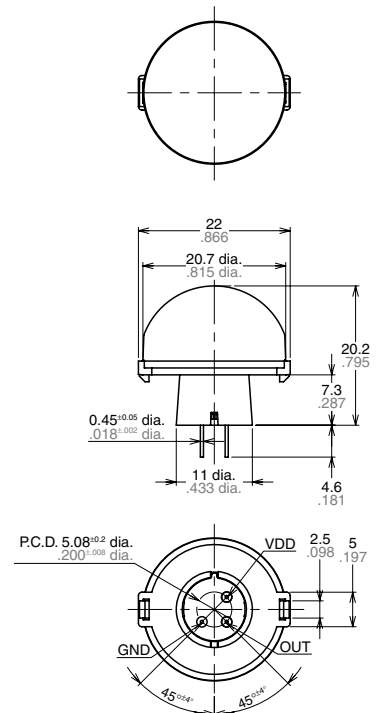
General tolerance ±0.5 ±.020

PIR Motion Sensor (EKMB, EKMC, AMN2, 3)

3. NaPiOn series
Standard type

CAD Data

9.5 dia.
.374 dia.

Molding gate

Note)

14.5
.571
11
.433

0.45±0.05 dia.
.018±.002 dia.

4.5
.177

11 dia.
.433 dia.

OUT   GND

P.C.D. 5.08±0.2 dia.
.200±.008 dia.

Vdd

45°±4°   45°±4°
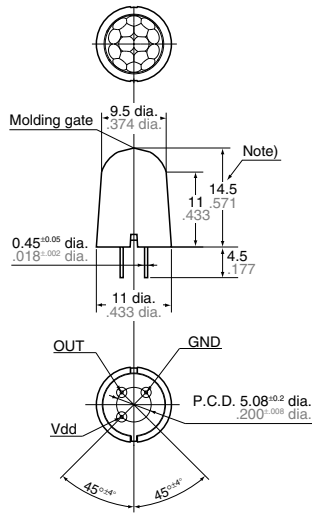
General tolerance ±0.5 ±.020

4. NaPiOn series
Slight motion detection type

CAD Data
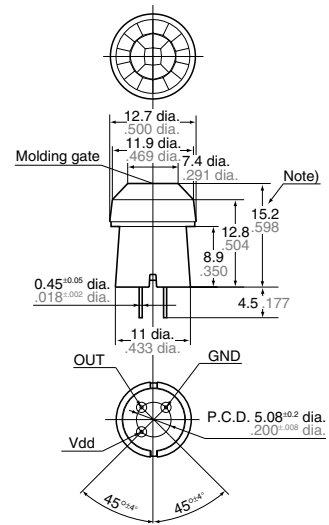
12.7 dia.
.500 dia.
11.9 dia.
.469 dia. 7.4 dia.
.291 dia.

Molding gate

Note)

15.2
.598
12.8
.504
8.9
.350

0.45±0.05 dia.
.018±.002 dia.

4.5
.177

11 dia.
.433 dia.

OUT   GND

P.C.D. 5.08±0.2 dia.
.200±.008 dia.

Vdd

45°±4°   45°±4°

General tolerance ±0.5 ±.020

Note: The height dimension does not include the remaining molding gate.
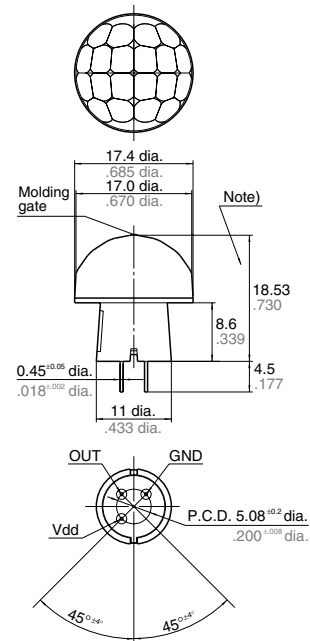
5. NaPiOn series
Spot detection type

CAD Data

8.9 dia.
.350 dia.   Note)

Molding gate

15.1
.594

0.45±0.05 dia.
.018±.002 dia.

4.5
.177

11
.433

OUT   GND

P.C.D. 5.08±0.2 dia.
.200±.008 dia.

Vdd

45°±4°   45°±4°
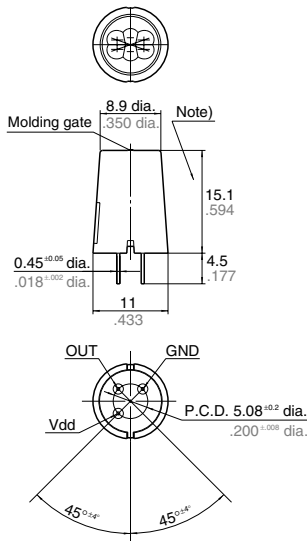
General tolerance ±0.5 ±.020

6. NaPiOn series
10m detection type

CAD Data

17.4 dia.
.685 dia.
17.0 dia.
.670 dia.

Molding gate

Note)

18.53
.730

8.6
.339

0.45±0.05 dia.
.018±.002 dia.

4.5
.177

11 dia.
.433 dia.

OUT   GND

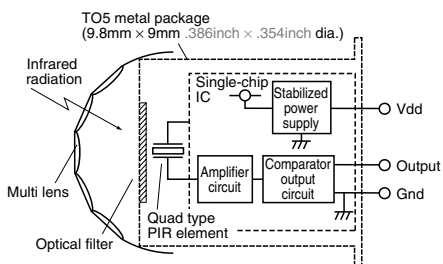P.C.D. 5.08±0.2 dia.
.200±.008 dia.

Vdd

45°±4°   45°±4°

General tolerance ±0.5 ±.020

Note: The height dimension does not include the remaining molding gate.

HOW TO USE
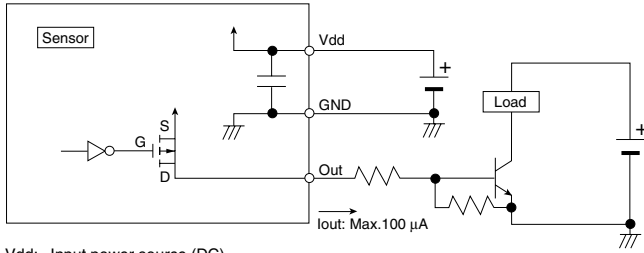
1. Block diagram output circuit
1) Digital output

TO5 metal package
(9.8mm × 9mm .386inch × .354inch dia.)

Infrared radiation

Single-chip IC

Stabilized power supply — Vdd

Amplifier circuit | Comparator output circuit — Output
— Gnd

Multi lens

Quad type PIR element

Optical filter

2) Analog output

TO5 metal package
(9.8mm × 9mm .386inch × .354inch dia.)

Infrared radiation

Single-chip IC

Stabilized power supply — Vdd

Amplifier circuit — Output
— Gnd

Multi lens

Quad type PIR element

Optical filter

2. Wiring diagram

1) Digital output

Vdd: Input power source (DC)
GND: GND
Out: Output (Comparator)

Iout: Max.100 µA

2) Analog output

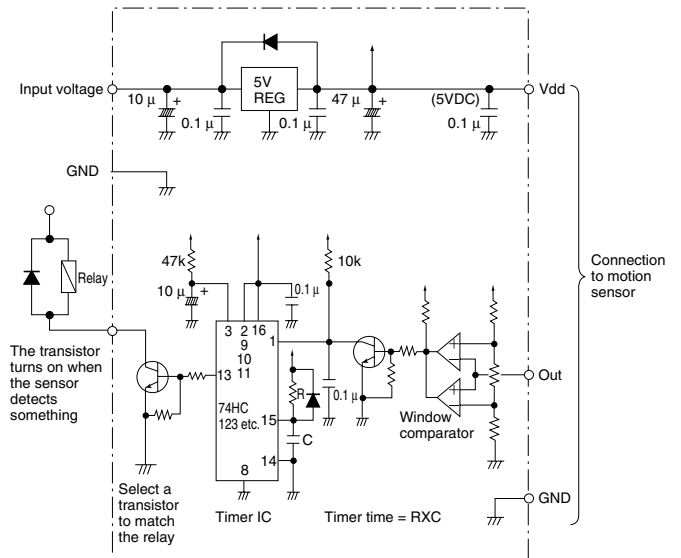Microcomputer, A/D converter etc.
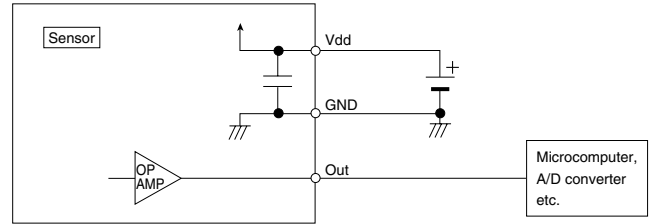
3. Timer circuit example

### 1) Digital output
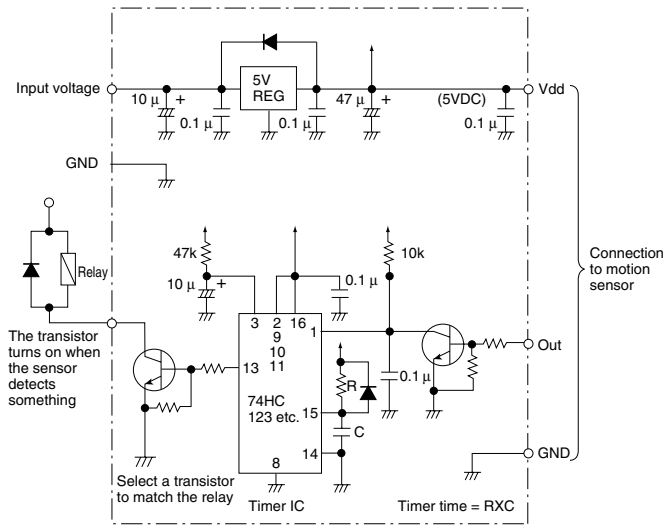
2) Analog output

Note: This is the reference circuit which drives the PIR motion sensor. Install a noise filter for applications requiring enhanced detection reliability and noise withstanding capability.
Differences in the specifications of electronic components to which the units are connected sometimes affect their correct operation; please check the units' performance and reliability for each application.
Panasonic Corporation, Ltd. accepts no responsibility for damages resulting from the use of this circuit.

4. Timing chart

1) Digital output
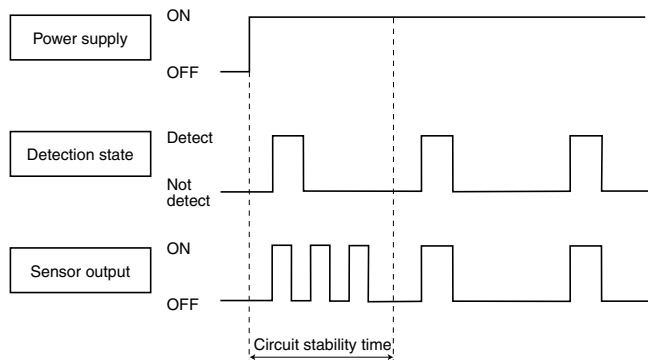
Note: Circuit stability time: 30s max.
While the circuitry is stabilizing after the power is turned on, the sensor output is not fixed in the "on" state or "off" state. This is true regardless of whether or not the sensor has detected anything.

2) Analog output
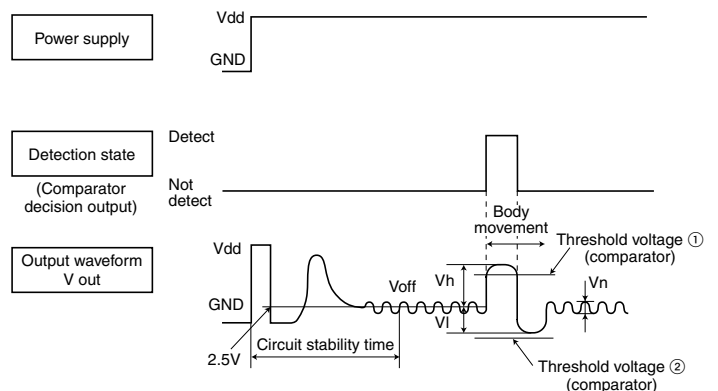
Note: Circuit stability time: 45s max.
While the circuitry is stabilizing after the power is turned on, the sensor output is not fixed in the "on" state or "off" state. This is true regardless of whether or not the sensor has detected anything.

PIR Motion Sensor (EKMB, EKMC, AMN2, 3)

## MOUNTING DIRECTION

1) Detection area
As shown on the diagram, the detection zone is polarized. If a target enters the detection zones + and − at the same time, the signals are respectively cancelled and detection could become impossible at maximum detection range.
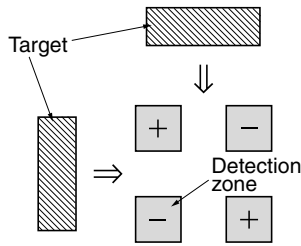
2) Direction
As detailed on the diagram, please install the sensor so that the expected trespassing direction corresponds to the axis X or axis Y.
In some cases, going back and forth towards the sensor (parallel movement to the axis Z), may not be detected.
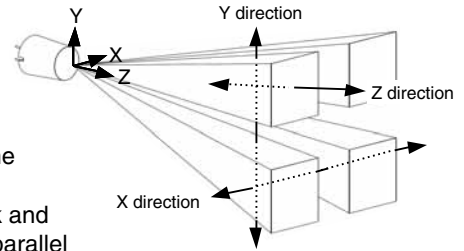
NOTES

1. Checkpoints relating to principal of operation

PaPIRs is a pyroelectric infrared sensor that detect variations in infrared rays. However, it may not detect in the following case: lack of movement, No temperature change in the heat source. Beside, it could also detect the presence of heat sources other than a human body. Efficiency and reliability of the system may vary depending actual operating conditions:
1) Detecting heat sources other than the human body, such as
(1) Small animals entering the detection area.
(2) When a heat source for example sunlight, incandescent light, car headlights etc, or strong light beam hit the sensor regardless inside or outside the detection area.
(3) Sudden temperature change inside or around the detection area caused by hot or cold wind from HVAC, or vapor from the humidifier, etc.
2) Difficulty in sensing the heat source
(1) Glass, acrylic or similar materials standing between the target and the sensor may not allow a correct transmission of infrared rays.
(2) Non-movement or quick movements of the heat source inside the detection area. (Please refer to the section on the detection performance ratings for details about movement speed.)
3) Expansion of the detection area
In case of considerable difference in the ambient temperature and the human body temperature, detection area may be wider apart from the configured detection area.
4) Malfunction/Detection error
Unnecessary detection signal might be outputted, on rare occasions, come from sudden outbreak output due to the nature of pyroelectric element. When the application does not accept such conditions strictly, please implement the countermeasure by introducing pulse count circuit etc.

2. Optimal operating environment conditions

1) Temperature: Refer to the absolute maximum rating.
2) Humidity degree: 15 to 85%Rh (Avoid condensation or freezing of this product)
3) Pressure: 86 to 106KPa
4) Overheating, oscillations, shocks can cause the sensor to malfunction.
5) This sensor is not waterproof or dustproof. Avoid use in environments subject to excessive moisture, condensation, frost, containing salt air or dust.
6) Avoid use in environments with corrosive gases.

3. Handling cautions

1) Do not solder with a soldering iron above 350°C 662°F, or for more than 3 seconds. This sensor should be hand soldered.
2) To maintain stability of the product, always mount on a printed circuit board.
3) Do not use liquids to wash the sensor. If washing fluid gets through the lens, it can reduce performance.
4) Do not use a sensor after it fell on the ground.
5) The sensor may be damaged by ±200 volts of static electricity. Avoid direct hand contact with the pins and be very careful when operating the product.
6) When wiring the product, always use shielded cables and minimize the wiring length to prevent noise disturbances.
7) The inner circuit board could be destroyed by a voltage surge.
Use of surge absorption elements is highly recommended.
Surge resistance: below the power supply voltage value indicated in the maximum rated values section.
8) Please use a stabilized power supply. Power supply noise can cause operating errors.
Noise resistance: ±20V or less (Square waves with a width of 50ns or 1μs)
To reduce the effect of power supply noise, install a capacitor on the sensor's power supply pin.

9) Operating errors can be caused by noise from static electricity, lightning, cell phone, amateur radio, broadcasting offices etc...
10) Detection performance can be reduced by dirt on the lens.
11) The lens is made of soft materials (Polyethylene). Please avoid adding weight or impacts that might change its shape, causing operating errors or reduce performance.
12) Operating "temperatures" and "humidity level" are suggested to prolong usage. However, they do not guarantee durability or environmental resistance. Generally, high temperatures or high humidity levels will accelerate the deterioration of electrical components. Please consider both the planned usage and environment to determine the expected reliability and length of life of the product.
13) Do not attempt to clean this product with any detergent or solvent, such as benzene or alcohol, as these can cause shape or color alterations.
14) Avoid storage in high, low temperature or liquid environments.
As well, avoid storage in environments containing corrosive gas, dust, salty air etc. It could cause performance deterioration and the sensor's main part or the metallic connectors could be damaged.

For Cautions for Use.