

### ISL8487, ISL81483, ISL81487

1/8 Unit Load, 5V, Low Power, High Speed or Slew Rate Limited, RS-485/RS-422 Transceivers

FN6050 Rev 8.00 March 14, 2016

These Intersil RS-485/RS-422 devices are "fractional" unit load (UL), BiCMOS, 5V powered, single transceivers that meet both the RS-485 and RS-422 standards for balanced communication. Unlike competitive devices, this Intersil family is specified for 10% tolerance supplies (4.5V to 5.5V).

The ISL81483 and ISL81487 present a 1/8 unit load to the RS-485 bus, which allows up to 256 transceivers on the network for large node count systems (e.g., process automation, remote meter reading systems). The 1/4 UL ISL8487 allows up to 128 transceivers on the bus. In a remote utility meter reading system, individual (apartments for example) utility meter readings are routed to a concentrator via an RS-485 network, so the high allowed node count minimizes the number of repeaters required to network all the meters. Data for all meters is then read out from the concentrator via a single access port, or a wireless link.

Slew rate limited drivers on the ISL8487 and ISL81483 reduce EMI, and minimize reflections from improperly terminated transmission lines, or unterminated stubs in multidrop and multipoint applications. Data rates up to 250kbps are achievable with these devices.

Data rates up to 5Mbps are achievable by using the ISL81487, which features higher slew rates.

Receiver (Rx) inputs feature a "fail-safe if open" design, which ensures a logic high Rx output if Rx inputs are floating.

Driver (Tx) outputs are short circuit protected, even for voltages exceeding the power supply voltage. Additionally, on-chip thermal shutdown circuitry disables the Tx outputs to prevent damage if power dissipation becomes excessive.

These half duplex devices multiplex the Rx inputs and Tx outputs to allow transceivers with Rx and Tx disable functions in 8 lead packages.

### **Features**

- · Fractional Unit Load Allows up to 256 Devices on the Bus
- · Specified for 10% Tolerance Supplies
- Class 3 ESD Protection (HBM) on all Pins. . . . . . >7kV
- High Data Rate Version (ISL81487)..... up to 5Mbps
- Slew Rate Limited Versions for Error Free Data Transmission (ISL8487, ISL81483) . . . . . . up to 250kbps
- Low Current Shutdown Mode (Except ISL81487) . .  $0.5\mu A$
- Low Quiescent Supply Current:
  - ISL8487, ISL81483......145μA (Max.)
  - ISL81487 . . . . . . . . . . . . . . . . . 420μA (Max.)
- -7V to +12V Common Mode Input Voltage Range
- · Three State Rx and Tx Outputs
- 30ns Propagation Delays, 5ns Skew (ISL81487)
- · Half Duplex Pinouts
- Operate from a Single +5V Supply (10% Tolerance)
- Current Limiting and Thermal Shutdown for Driver Overload Protection
- Drop-In Replacements for: MAX487 (ISL8487); MAX1483 (ISL81483); MAX1487, LMS1487 (ISL81487)
- · Pb-Free Plus Anneal Available (RoHS Compliant)

### **Applications**

- · High Node Count Networks
- · Automated Utility Meter Reading Systems
- Factory Automation
- · Security Networks
- Building Environmental Control Systems
- · Industrial/Process Control Networks

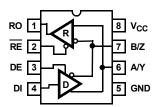
### TABLE 1. SUMMARY OF FEATURES

PART NUMBER	HALF/FULL DUPLEX	NO. OF DEVICES ALLOWED ON BUS	DATA RATE (Mbps)	SLEW-RATE LIMITED?	RECEIVER/ DRIVER ENABLE?	QUIESCENT I <sub>CC</sub> (μA)	LOW POWER SHUTDOWN?	PIN COUNT
ISL8487 (No longer available or supported)	Half	128	0.25	Yes	Yes	120	Yes	8
ISL81483	Half	256	0.25	Yes	Yes	120	Yes	8
ISL81487	Half	256	5	No	Yes	350	No	8

### **Pinout**

ISL8487, ISL81483, ISL81487 (PDIP, SOIC)

TOP VIEW



### **Truth Tables**

TRANSMITTING						
	INPUTS	OUTI	PUTS			
RE	DE	DI	Z	Y		
Х	1	1	0	1		
Х	1	0	1	0		
0	0	Х	High-Z	High-Z		
1	0	Х	High-Z *	High-Z *		

<sup>\*</sup>Shutdown Mode for ISL8487, ISL81483 (see Note 7)

RECEIVING						
	INPUTS OUTPUT					
RE	DE	A-B	RO			
0	0	≥ +0.2V	1			
0	0	≤ -0.2V	0			
0	0	Inputs Open	1			
1	0	X	High-Z *			
1	1	Х	High-Z			

<sup>\*</sup>Shutdown Mode for ISL8487, ISL81483 (see Note 7)

### **Ordering Information**

PART NO.	PART MARKING	TEMP. RANGE (°C)	PACKAGE	PKG. DWG. #
ISL8487IBZ (Note) (No longer available, recommended replacement ISL8487EIBZ)	8487IBZ	-40 to 85	8 Ld SOIC* (Pb-free)	M8.15
ISL8487IPZ (Note) (No longer available, recommended replacement ISL8487EIPZ)	8487IPZ	-40 to 85	8 Ld PDIP** (Pb-free)	E8.3
ISL81483IBZ (Note)	81483IBZ	-40 to 85	8 Ld SOIC* (Pb-free)	M8.15
ISL81483IPZ (Note)	81483IPZ	-40 to 85	8 Ld PDIP** (Pb-free)	E8.3
ISL81487IBZ (Note)	81487IBZ	-40 to 85	8 Ld SOIC* (Pb-free)	M8.15

<sup>\*</sup>SOIC also available in Tape and Reel; Add "-T" to suffix.

NOTE: Intersil Pb-free plus anneal products employ special Pb-free material sets; molding compounds/die attach materials and 100% matte tin plate termination finish, which are RoHS compliant and compatible with both SnPb and Pb-free soldering operations. Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.



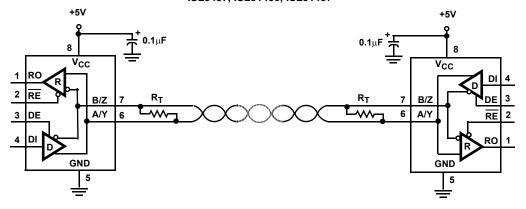
<sup>\*\*</sup>Pb-free PDIPs can be used for through hole wave solder processing only. They are not intended for use in Reflow solder processing applications.

### Pin Descriptions

PIN	FUNCTION
RO	Receiver output: If A > B by at least 0.2V, RO is high; If A < B by 0.2V or more, RO is low; RO = High if A and B are unconnected (floating).
RE	Receiver output enable. RO is enabled when RE is low; RO is high impedance when RE is high.
DE	Driver output enable. The driver outputs, Y and Z, are enabled by bringing DE high. They are high impedance when DE is low.
DI	Driver input. A low on DI forces output Y low and output Z high. Similarly, a high on DI forces output Y high and output Z low.
GND	Ground connection.
A/Y	RS-485/422 level, noninverting receiver input and noninverting driver output. Pin is an input (A) if DE = 0; pin is an output (Y) if DE = 1.
B/Z	RS-485/422 level, inverting receiver input and inverting driver output. Pin is an input (B) if DE = 0; pin is an output (Z) if DE = 1.
V <sub>CC</sub>	System power supply input (4.5V to 5.5V).

## **Typical Operating Circuits**

### ISL8487, ISL81483, ISL81487



# Absolute Maximum Ratings V<sub>CC</sub> to Ground 7V Input Voltages 0.5V to (V<sub>CC</sub> +0.5V) DI, DE, RE -0.5V to (V<sub>CC</sub> +0.5V) Input/Output Voltages -8V to +12.5V RO -0.5V to (V<sub>CC</sub> +0.5V) Short Circuit Duration Y, Z Continuous ESD Rating HBM (Per MIL-STD-883, Method 3015.7) >7kV

### **Thermal Information**

Thermal Resistance (Typical, Note 1)	$\theta_{JA}$ (°C/W)
8 Ld SOIC Package	170
8 Ld PDIP Package*	140
Maximum Junction Temperature (Plastic Package)	
Maximum Storage Temperature Range65	5°C to 150°C
Maximum Lead Temperature (Soldering 10s)	300°C
(SOIC - Lead Tips Only)	
*Pb-free PDIPs can be used for through hole v	wave solder

\*Pb-free PDIPs can be used for through hole wave solder processing only. They are not intended for use in Reflow solder processing applications.

### **Operating Conditions**

Temperature Range ISL8XXXIX ....-40°C to 85°C

CAUTION: Stresses above those listed in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

### NOTE:

1. θ<sub>JA</sub> is measured with the component mounted on a low effective thermal conductivity test board in free air. See Tech Brief TB379 for details.

**Electrical Specifications** Test Conditions:  $V_{CC} = 4.5V$  to 5.5V; Unless Otherwise Specified. Typicals are at  $V_{CC} = 5V$ ,  $T_A = 25^{\circ}C$ , (Note 2)

PARAMETER	SYMBOL	TEST CONDITIONS		TEMP (°C)	MIN	TYP	MAX	UNITS
DC CHARACTERISTICS						ı	•	
Driver Differential V <sub>OUT</sub> (no load)	V <sub>OD1</sub>			Full	-	-	$V_{CC}$	V
Driver Differential V <sub>OUT</sub> (with load)	V <sub>OD2</sub>	R = $50\Omega$ (RS-422), (Figu	ire 1)	Full	2	3	-	V
		R = 27Ω (RS-485), (Figu	ire 1)	Full	1.5	2.3	5	V
Change in Magnitude of Driver Differential V <sub>OUT</sub> for Complementary Output States	ΔV <sub>OD</sub>	R = 27 $\Omega$ or 50 $\Omega$ , (Figure	1)	Full	-	0.01	0.2	V
Driver Common-Mode V <sub>OUT</sub>	V <sub>OC</sub>	R = $27\Omega$ or $50\Omega$ , (Figure	1)	Full	-	-	3	V
Change in Magnitude of Driver Common-Mode V <sub>OUT</sub> for Complementary Output States	ΔV <sub>OC</sub>	R = 27 $\Omega$ or 50 $\Omega$ , (Figure	R = $27\Omega$ or $50\Omega$ , (Figure 1)		-	0.01	0.2	V
Logic Input High Voltage	V <sub>IH</sub>	DE, DI, RE	DE, DI, RE		2	-	-	V
Logic Input Low Voltage	V <sub>IL</sub>	DE, DI, RE	DE, DI, RE		-	-	0.8	V
Logic Input Current	I <sub>IN1</sub>	DE, DI, RE		Full	-2	-	2	μА
Input Current (A/Y, B/Z), (Note 10)	I <sub>IN2</sub>	DE = 0V, V <sub>CC</sub> = 4.5 to 5.5V	V <sub>IN</sub> = 12V	Full	-	-	140	μА
(ISL81483, ISL81487)			V <sub>IN</sub> = -7V	Full	-	-	-120	μА
	I <sub>IN2</sub>	DE = 0V, V <sub>CC</sub> = 0V	V <sub>IN</sub> = 12V	Full	-	-	180	μА
			V <sub>IN</sub> = -7V	Full	-	-	-100	μА
Input Current (A/Y, B/Z), (Note 11)	I <sub>IN2</sub>	DE = 0V, V <sub>CC</sub> = 0V, or	V <sub>IN</sub> = 12V	Full	-	-	250	μА
(ISL8487 Only)		4.5 to 5.5V	V <sub>IN</sub> = -7V	Full	-	-	-100	μА
Receiver Differential Threshold Voltage	V <sub>TH</sub>	$-7V \le V_{CM} \le 12V$	-7V ≤ V <sub>CM</sub> ≤ 12V		-0.2	-	0.2	V
Receiver Input Hysteresis	$\Delta V_{TH}$	V <sub>CM</sub> = 0V		25	-	70	-	mV
Receiver Output High Voltage	V <sub>OH</sub>	I <sub>O</sub> = -4mA, V <sub>ID</sub> = 200mV		Full	3.5	-	-	V
Receiver Output Low Voltage	V <sub>OL</sub>	I <sub>O</sub> = -4mA, V <sub>ID</sub> = 200mV		Full	-	-	0.4	V
Three-State (high impedance) Receiver Output Current	lozr	$0.4V \le V_O \le 2.4V$		Full	-	-	±1	μА



# **Electrical Specifications** Test Conditions: $V_{CC}$ = 4.5V to 5.5V; Unless Otherwise Specified. Typicals are at $V_{CC}$ = 5V, $T_A$ = 25°C, (Note 2) (Continued)

PARAMETER	SYMBOL	TEST CONDITIONS		TEMP (°C)	MIN	TYP	MAX	UNITS
Receiver Input Resistance	R <sub>IN</sub>	$-7V \le V_{CM} \le 12V$	ISL81483, ISL81487	Full	96	-	-	kΩ
			ISL8487	Full	48	-	-	kΩ
No-Load Supply Current, (Note 3)	I <sub>CC</sub>	ISL81487, DI, RE = 0V	DE = V <sub>CC</sub>	Full	-	400	500	μΑ
		or V <sub>CC</sub>	DE = 0V	Full	-	350	420	μΑ
		ISL8487, ISL81483, DI,	DE = V <sub>CC</sub>	Full	-	160	200	μΑ
		RE = 0V or V <sub>CC</sub>	DE = 0V	Full	-	120	145	μΑ
Shutdown Supply Current	I <sub>SHDN</sub>	(Note 7), DE = 0V, RE =	V <sub>CC</sub> , DI = 0V or V <sub>CC</sub>	Full	-	0.5	8	μΑ
Driver Short-Circuit Current, V <sub>O</sub> = High or Low	I <sub>OSD1</sub>	DE = $V_{CC}$ , $-7V \le V_Y$ or $V_{CC}$	/ <sub>Z</sub> ≤ 12V, (Note 4)	Full	35	-	250	mA
Receiver Short-Circuit Current	I <sub>OSR</sub>	$0V \leq V_O \leq V_{CC}$		Full	7	-	85	mA
SWITCHING CHARACTERISTICS	(ISL81487)			l		1		
Driver Input to Output Delay	t <sub>PLH</sub> , t <sub>PHL</sub>	$R_{DIFF} = 54\Omega$ , $C_L = 100p$	F, (Figure 2)	Full	15	24	50	ns
Driver Output Skew	tskew	R <sub>DIFF</sub> = 54Ω, C <sub>L</sub> = 100p	F, (Figure 2)	Full	-	2	10	ns
Driver Differential Rise or Fall Time	t <sub>R</sub> , t <sub>F</sub>	$R_{DIFF} = 54\Omega$ , $C_L = 100p$	F, (Figure 2)	Full	3	12	25	ns
Driver Enable to Output High	t <sub>ZH</sub>	C <sub>L</sub> = 100pF, SW = GND,	(Figure 3)	Full		14	70	ns
Driver Enable to Output Low	t <sub>ZL</sub>	C <sub>L</sub> = 100pF, SW = V <sub>CC</sub> ,	(Figure 3)	Full		14	70	ns
Driver Disable from Output High	t <sub>HZ</sub>	C <sub>L</sub> = 15pF, SW = GND, (	(Figure 3)	Full		44	70	ns
Driver Disable from Output Low	t <sub>LZ</sub>	$C_L = 15pF, SW = V_{CC}, ($	Figure 3)	Full		21	70	ns
Receiver Input to Output Delay	t <sub>PLH</sub> , t <sub>PHL</sub>	(Figure 4)		Full	30	90	150	ns
Receiver Skew   t <sub>PLH</sub> - t <sub>PHL</sub>	tskd	(Figure 4)		25		5	-	ns
Receiver Enable to Output High	t <sub>ZH</sub>	C <sub>L</sub> = 15pF, SW = GND, (	(Figure 5)	Full		9	50	ns
Receiver Enable to Output Low	t <sub>ZL</sub>	$C_L = 15pF, SW = V_{CC}, ($	Figure 5)	Full	-	9	50	ns
Receiver Disable from Output High	t <sub>HZ</sub>	C <sub>L</sub> = 15pF, SW = GND, (	(Figure 5)	Full	-	9	50	ns
Receiver Disable from Output Low	t <sub>LZ</sub>	$C_L = 15pF, SW = V_{CC}, ($	Figure 5)	Full	-	9	50	ns
Maximum Data Rate	f <sub>MAX</sub>			Full	5	-	-	Mbps
SWITCHING CHARACTERISTICS	(ISL8487, ISI	L81483)		l		1		
Driver Input to Output Delay	t <sub>PLH</sub> , t <sub>PHL</sub>	$R_{DIFF} = 54\Omega$ , $C_L = 100p$	F, (Figure 2)	Full	250	650	2000	ns
Driver Output Skew	tskew	R <sub>DIFF</sub> = 54Ω, C <sub>L</sub> = 100p	F, (Figure 2)	Full	-	160	800	ns
Driver Differential Rise or Fall Time	t <sub>R</sub> , t <sub>F</sub>	R <sub>DIFF</sub> = 54Ω, C <sub>L</sub> = 100p	F, (Figure 2)	Full	250	900	2000	ns
Driver Enable to Output High	t <sub>ZH</sub>	C <sub>L</sub> = 100pF, SW = GND,	(Figure 3, Note 5)	Full	250	1000	2000	ns
Driver Enable to Output Low	t <sub>ZL</sub>	C <sub>L</sub> = 100pF, SW = V <sub>CC</sub> ,	(Figure 3, Note 5)	Full	250	860	2000	ns
Driver Disable from Output High	t <sub>HZ</sub>	C <sub>L</sub> = 15pF, SW = GND, (	(Figure 3)	Full	300	660	3000	ns
Driver Disable from Output Low	t <sub>LZ</sub>	$C_L = 15pF, SW = V_{CC}, ($	Figure 3)	Full	300	640	3000	ns
Receiver Input to Output Delay	t <sub>PLH</sub> , t <sub>PHL</sub>	(Figure 4)		Full	250	500	2000	ns
Receiver Skew   t <sub>PLH</sub> - t <sub>PHL</sub>	tskd	(Figure 4)		25	-	60	-	ns
Receiver Enable to Output High	t <sub>ZH</sub>	C <sub>L</sub> = 15pF, SW = GND, (Figure 5, Note 6)		Full	-	10	50	ns
Receiver Enable to Output Low	t <sub>ZL</sub>	$C_L = 15pF$ , SW = $V_{CC}$ , (Figure 5, Note 6)		Full		10	50	ns
Receiver Disable from Output High	t <sub>HZ</sub>	C <sub>L</sub> = 15pF, SW = GND, (Figure 5)		Full	-	10	50	ns
Receiver Disable from Output Low	t <sub>LZ</sub>	$C_L = 15pF$ , SW = $V_{CC}$ , (Figure 5)		Full	-	10	50	ns
Maximum Data Rate	f <sub>MAX</sub>			Full	250	-	-	kbps
Time to Shutdown	tshdn	(Note 7)		Full	50	120	600	ns



# **Electrical Specifications** Test Conditions: $V_{CC} = 4.5V$ to 5.5V; Unless Otherwise Specified. Typicals are at $V_{CC} = 5V$ , $T_A = 25^{\circ}C$ , (Note 2) (Continued)

PARAMETER	SYMBOL	TEST CONDITIONS	TEMP (°C)	MIN	TYP	MAX	UNITS
Driver Enable from Shutdown to Output High	t <sub>ZH(SHDN)</sub>	C <sub>L</sub> = 100pF, SW = GND, (Figure 3, Notes 7, 8)	Full	-	1000	2000	ns
Driver Enable from Shutdown to Output Low	<sup>t</sup> ZL(SHDN)	C <sub>L</sub> = 100pF, SW = V <sub>CC</sub> , (Figure 3, Notes 7, 8)	Full	-	1000	2000	ns
Receiver Enable from Shutdown to Output High	<sup>t</sup> ZH(SHDN)	C <sub>L</sub> = 15pF, SW = GND, (Figure 5, Notes 7, 9)	Full	-	800	2500	ns
Receiver Enable from Shutdown to Output Low	<sup>t</sup> ZL(SHDN)	C <sub>L</sub> = 15pF, SW = V <sub>CC</sub> , (Figure 5, Notes 7, 9)	Full	-	800	2500	ns

### NOTES:

- 2. All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.
- 3. Supply current specification is valid for loaded drivers when DE = 0V.
- 4. Applies to peak current. See "Typical Performance Curves" for more information.
- 5. When testing the ISL8487 and ISL81483, keep RE = 0 to prevent the device from entering SHDN.
- 6. When testing the ISL8487 and ISL81483, the RE signal high time must be short enough (typically <200ns) to prevent the device from entering SHDN.
- 7. The ISL8487 and ISL81483 are put into shutdown by bringing RE high and DE low. If the inputs are in this state for less than 50ns, the parts are guaranteed not to enter shutdown. If the inputs are in this state for at least 600ns, the parts are guaranteed to have entered shutdown. See "Low-Power Shutdown Mode" section.
- 8. Keep  $\overline{RE}$  =  $V_{CC}$ , and set the DE signal low time >600ns to ensure that the device enters SHDN.
- 9. Set the RE signal high time >600ns to ensure that the device enters SHDN.
- 10. Devices meeting these limits are denoted as "1/8 unit load (1/8 UL)" transceivers. The RS-485 standard allows up to 32 Unit Loads on the bus, so there can be 256 1/8 UL devices on a bus.
- 11. Devices meeting these limits are denoted as "1/4 unit load (1/4 UL)" transceivers. The RS-485 standard allows up to 32 Unit Loads on the bus, so there can be 128 1/4 UL devices on a bus.

### Test Circuits and Waveforms

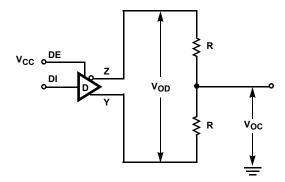
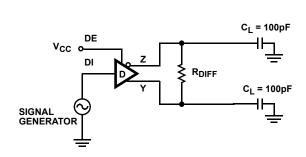
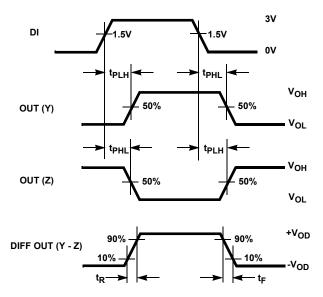


FIGURE 1. DRIVER  $V_{\mbox{\scriptsize OD}}$  and  $V_{\mbox{\scriptsize OC}}$ 

### Test Circuits and Waveforms (Continued)





SKEW =  $|t_{PLH} (Y \text{ or } Z) - t_{PHL} (Z \text{ or } Y)|$ 

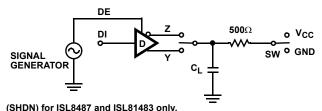
FIGURE 2A. TEST CIRCUIT

FIGURE 2B. MEASUREMENT POINTS

FIGURE 2. DRIVER PROPAGATION DELAY AND DIFFERENTIAL TRANSITION TIMES

DE

NOTE 7



(GIDN) for 1020407 and 10201403 only.						
PARAMETER	OUTPUT	RE	DI	SW	C <sub>L</sub> (pF)	
t <sub>HZ</sub>	Y/Z	Х	1/0	GND	15	
t <sub>LZ</sub>	Y/Z	Х	0/1	V <sub>CC</sub>	15	
t <sub>ZH</sub>	Y/Z	0 (Note 5)	1/0	GND	100	
t <sub>ZL</sub>	Y/Z	0 (Note 5)	0/1	V <sub>CC</sub>	100	
tzh(SHDN)	Y/Z	1 (Note 7)	1/0	GND	100	
tzi (SHDN)	Y/Z	1 (Note 7)	0/1	Vcc	100	

0V

t<sub>ZH</sub>, t<sub>ZH</sub>(SHDN)

NOTE 7

OUT (Y, Z)

t<sub>ZL</sub>, t<sub>ZL</sub>(SHDN)

NOTE 7

OUT (Y, Z)

v<sub>OH</sub> - 0.5V

VOH

VOH

VOH

VOH

VOL + 0.5V

VOL

FIGURE 3A. TEST CIRCUIT

FIGURE 3B. MEASUREMENT POINTS

FIGURE 3. DRIVER ENABLE AND DISABLE TIMES

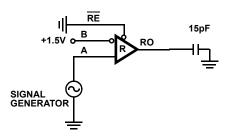


FIGURE 4A. TEST CIRCUIT

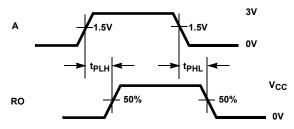


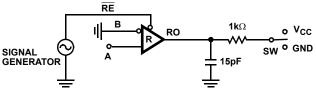
FIGURE 4B. MEASUREMENT POINTS

FIGURE 4. RECEIVER PROPAGATION DELAY



3V

### Test Circuits and Waveforms (Continued)



(SHDN) for ISL8487 and ISL81483 only.

PARAMETER	DE	Α	SW
t <sub>HZ</sub>	0	+1.5V	GND
t <sub>LZ</sub>	0	-1.5V	V <sub>CC</sub>
t <sub>ZH</sub> (Note 6)	0	+1.5V	GND
t <sub>ZL</sub> (Note 6)	0	-1.5V	V <sub>CC</sub>
t <sub>ZH(SHDN)</sub> (Note 7)	0	+1.5V	GND
t <sub>ZL(SHDN)</sub> (Note 7)	0	-1.5V	V <sub>CC</sub>

FIGURE 5A. TEST CIRCUIT

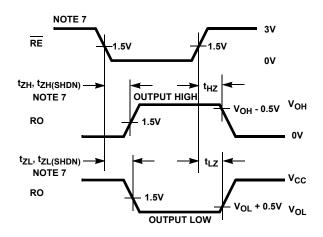


FIGURE 5B. MEASUREMENT POINTS

FIGURE 5. RECEIVER ENABLE AND DISABLE TIMES

### Application Information

RS-485 and RS-422 are differential (balanced) data transmission standards for use in long haul or noisy environments. RS-422 is a subset of RS-485, so RS-485 transceivers are also RS-422 compliant. RS-422 is a point-to-multipoint (multidrop) standard, which allows only one driver and up to 10 (assuming one unit load devices) receivers on each bus. RS-485 is a true multipoint standard, which allows up to 32 one unit load devices (any combination of drivers and receivers) on each bus. To allow for multipoint operation, the RS-485 spec requires that drivers must handle bus contention without sustaining any damage.

Another important advantage of RS-485 is the extended common mode range (CMR), which specifies that the driver outputs and receiver inputs withstand signals that range from +12V to -7V. RS-422 and RS-485 are intended for runs as long as 4000', so the wide CMR is necessary to handle ground potential differences, as well as voltages induced in the cable by external fields.

### Receiver Features

These devices utilize a differential input receiver for maximum noise immunity and common mode rejection. Input sensitivity is  $\pm 200$ mV, as required by the RS-422 and RS-485 specifications.

Receiver input resistance of  $96k\Omega$  surpasses the RS-422 spec of  $4k\Omega$ , and is eight times the RS-485 "Unit Load (UL)" requirement of  $12k\Omega$  minimum. Thus, these products are known as "one-eighth UL" transceivers, and there can be up to 256 of these devices on a network while still complying with the RS-485 loading spec.

Receiver inputs function with common mode voltages as great as  $\pm 7V$  outside the power supplies (i.e.,  $\pm 12V$  and  $\pm 7V$ ), making them ideal for long networks where induced voltages are a realistic concern.

All the receivers include a "fail-safe if open" function that guarantees a high level receiver output if the receiver inputs are unconnected (floating).

Receivers easily meet the data rates supported by the corresponding driver, and receiver outputs are three-statable via the active low RE input.

### **Driver Features**

The RS-485 and RS-422 driver is a differential output device that delivers at least 1.5V across a  $54\Omega$  load (RS-485), and at least 2V across a  $100\Omega$  load (RS-422). The drivers feature low propagation delay skew to maximize bit width, and to minimize EMI.

Driver outputs are three-statable via the active high DE input.

The ISL8487 and ISL81483 driver outputs are slew rate limited to minimize EMI, and to minimize reflections in unterminated or improperly terminated networks. Data rate on these slew rate limited versions is a maximum of 250kbps. ISL81487 drivers are not limited, so faster output transition times allow data rates of at least 5Mbps.

### Data Rate, Cables, and Terminations

RS-485 and RS-422 are intended for network lengths up to 4000', but the maximum system data rate decreases as the transmission length increases. Devices operating at 5Mbps are limited to lengths less than a few hundred feet, while the



250kbps versions can operate at full data rates with lengths in excess of 1000'.

Twisted pair is the cable of choice for RS-485/RS-422 networks. Twisted pair cables tend to pick up noise and other electromagnetically induced voltages as common mode signals, which are effectively rejected by the differential receivers in these ICs.

To minimize reflections, proper termination is imperative when using the 5Mbps device. Short networks using the 250kbps versions need not be terminated, but, terminations are recommended unless power dissipation is an overriding concern.

In point-to-point, or point-to-multipoint (single driver on bus) networks, the main cable should be terminated in its characteristic impedance (typically  $120\Omega$ ) at the end farthest from the driver. In multi-receiver applications, stubs connecting receivers to the main cable should be kept as short as possible. Multipoint (multi-driver) systems require that the main cable be terminated in its characteristic impedance at both ends. Stubs connecting a transceiver to the main cable should be kept as short as possible.

### **Built-In Driver Overload Protection**

As stated previously, the RS-485 spec requires that drivers survive worst case bus contentions undamaged. These devices meet this requirement via driver output short circuit current limits, and on-chip thermal shutdown circuitry.

The driver output stages incorporate short circuit current limiting circuitry which ensures that the output current never

exceeds the RS-485 spec, even at the common mode voltage range extremes. Additionally, these devices utilize a foldback circuit which reduces the short circuit current, and thus the power dissipation, whenever the contending voltage exceeds either supply.

In the event of a major short circuit condition, these devices also include a thermal shutdown feature that disables the drivers whenever the die temperature becomes excessive. This eliminates the power dissipation, allowing the die to cool. The drivers automatically re-enable after the die temperature drops about 15 degrees. If the contention persists, the thermal shutdown/re-enable cycle repeats until the fault is cleared. Receivers stay operational during thermal shutdown.

### Low Power Shutdown Mode (Excluding ISL81487)

These CMOS transceivers all use a fraction of the power required by their bipolar counterparts, but the ISL8487 and ISL81483 include a shutdown feature that reduces the already low quiescent  $I_{CC}$  to a 500nA trickle. They enter shutdown whenever the receiver and driver are *simultaneously* disabled ( $\overline{RE} = V_{CC}$  and DE = GND) for a period of at least 600ns. Disabling both the driver and the receiver for less than 50ns guarantees that shutdown is not entered.

Note that receiver and driver enable times increase when enabling from shutdown. Refer to Notes 5-9, at the end of the Electrical Specification table, for more information.

Typical Performance Curves V<sub>CC</sub> = 5V, T<sub>A</sub> = 25°C, ISL8487, ISL81483 and ISL81487; Unless Otherwise Specified

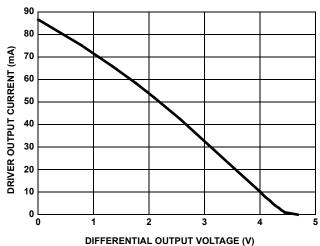


FIGURE 6. DRIVER OUTPUT CURRENT VS DIFFERENTIAL OUTPUT VOLTAGE

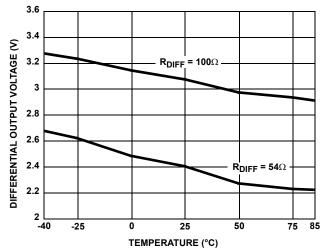


FIGURE 7. DRIVER DIFFERENTIAL OUTPUT VOLTAGE vs TEMPERATURE

# Typical Performance Curves V<sub>CC</sub> = 5V, T<sub>A</sub> = 25°C, ISL8487, ISL81483 and ISL81487; Unless Otherwise Specified (Continued)

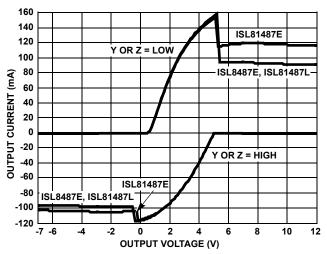
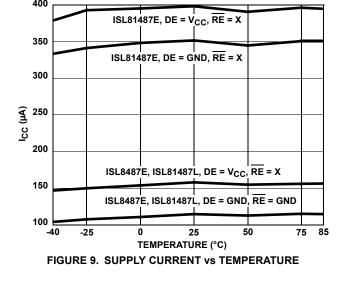


FIGURE 8. DRIVER OUTPUT CURRENT vs SHORT CIRCUIT VOLTAGE



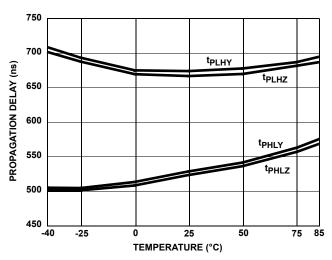


FIGURE 10. DRIVER PROPAGATION DELAY vs TEMPERATURE (ISL8487, ISL81483)

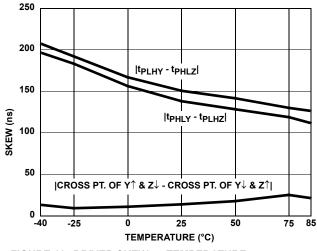


FIGURE 11. DRIVER SKEW vs TEMPERATURE (ISL8487, ISL81483)

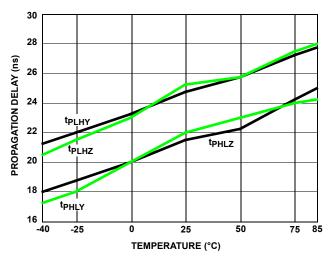


FIGURE 12. DRIVER PROPAGATION DELAY vs TEMPERATURE (ISL81487)

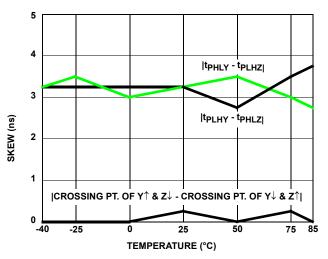
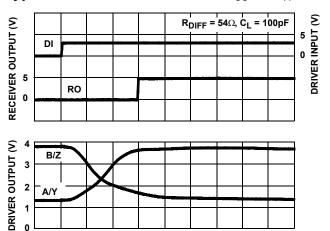


FIGURE 13. DRIVER SKEW vs TEMPERATURE (ISL81487)

### Typical Performance Curves V<sub>CC</sub> = 5V, T<sub>A</sub> = 25°C, ISL8487, ISL81483 and ISL81487; Unless Otherwise Specified (Continued)



TIME (400ns/DIV)

FIGURE 14. DRIVER AND RECEIVER WAVEFORMS, LOW TO HIGH (ISL8487, ISL81483)

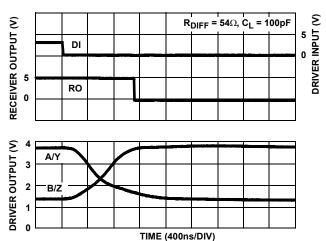


FIGURE 15. DRIVER AND RECEIVER WAVEFORMS, HIGH TO LOW (ISL8487, ISL81483)

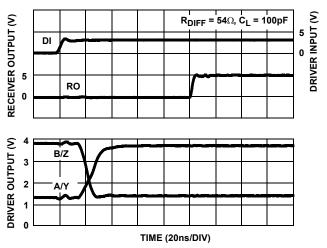


FIGURE 16. DRIVER AND RECEIVER WAVEFORMS, LOW TO HIGH (ISL81487)

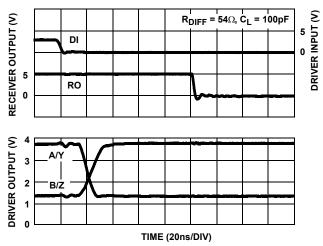


FIGURE 17. DRIVER AND RECEIVER WAVEFORMS, HIGH TO LOW (ISL81487)

### Die Characteristics

SUBSTRATE POTENTIAL (POWERED UP):

GND

TRANSISTOR COUNT:

518

PROCESS:

Si Gate CMOS

**Revision History** The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please go to the web to make sure that you have the latest revision.

DATE	REVISION	CHANGE
March 14, 2016	FN6050.8	Added Rev History and About Intersil Verbiage. Updated "Ordering Information" table on page 2. Updated M8.15 to current revision. POD revision changes are as follows: Note 1 "1982" to "1994 Changed in Typical Recommended Land Pattern the following: 2.41(0.095) to 2.20(0.087) 0.76 (0.030) to 0.60(0.023) 0.200 to 5.20(0.205) Updated to new POD format by removing table and moving dimensions onto drawing and adding land pattern.

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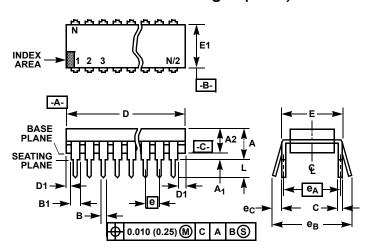
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### Dual-In-Line Plastic Packages (PDIP)



### NOTES:

- Controlling Dimensions: INCH. In case of conflict between English and Metric dimensions, the inch dimensions control.
- 2. Dimensioning and tolerancing per ANSI Y14.5M-1982.
- 3. Symbols are defined in the "MO Series Symbol List" in Section 2.2 of Publication No. 95.
- Dimensions A, A1 and L are measured with the package seated in JEDEC seating plane gauge GS-3.
- D, D1, and E1 dimensions do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.010 inch (0.25mm).
- E and eA are measured with the leads constrained to be perpendicular to datum -C-.
- 7.  $e_B$  and  $e_C$  are measured at the lead tips with the leads unconstrained.  $e_C$  must be zero or greater.
- 8. B1 maximum dimensions do not include dambar protrusions. Dambar protrusions shall not exceed 0.010 inch (0.25mm).
- 9. N is the maximum number of terminal positions.
- Corner leads (1, N, N/2 and N/2 + 1) for E8.3, E16.3, E18.3, E28.3, E42.6 will have a B1 dimension of 0.030 - 0.045 inch (0.76 - 1.14mm).

E8.3 (JEDEC MS-001-BA ISSUE D) 8 LEAD DUAL-IN-LINE PLASTIC PACKAGE

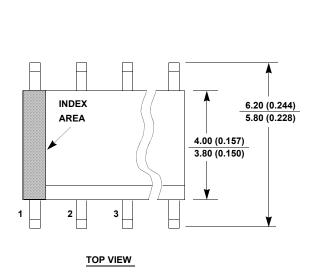
	INCHES		MILLIMETERS		
SYMBOL	MIN	MAX	MIN	MAX	NOTES
Α	-	0.210	-	5.33	4
A1	0.015	-	0.39	-	4
A2	0.115	0.195	2.93	4.95	-
В	0.014	0.022	0.356	0.558	-
B1	0.045	0.070	1.15	1.77	8, 10
С	0.008	0.014	0.204	0.355	-
D	0.355	0.400	9.01	10.16	5
D1	0.005	-	0.13	-	5
Е	0.300	0.325	7.62	8.25	6
E1	0.240	0.280	6.10	7.11	5
е	0.100 BSC		2.54 BSC		-
e <sub>A</sub>	0.300 BSC		7.62 BSC		6
e <sub>B</sub>	-	0.430	-	10.92	7
L	0.115	0.150	2.93	3.81	4
N	8		8		9

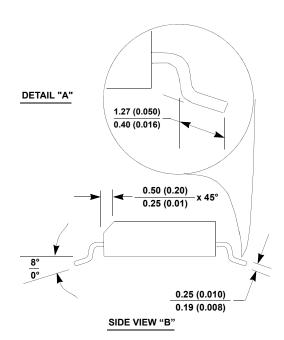
Rev. 0 12/93

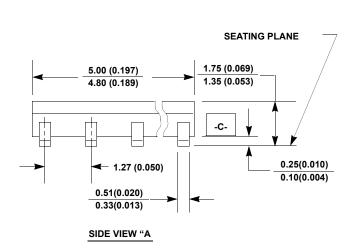
# **Package Outline Drawing**

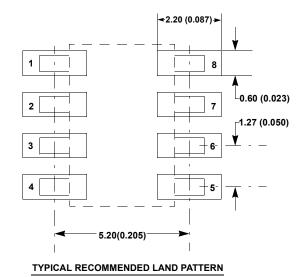
### M8.15

8 LEAD NARROW BODY SMALL OUTLINE PLASTIC PACKAGE Rev 4, 1/12









### NOTES:

- 1. Dimensioning and tolerancing per ANSI Y14.5M-1994.
- Package length does not include mold flash, protrusions or gate burrs.
   Mold flash, protrusion and gate burrs shall not exceed 0.15mm (0.006 inch) per side.
- 3. Package width does not include interlead flash or protrusions. Interlead flash and protrusions shall not exceed 0.25mm (0.010 inch) per side.
- 4. The chamfer on the body is optional. If it is not present, a visual index feature must be located within the crosshatched area.
- ${\bf 5.} \ \ {\bf Terminal\ numbers\ are\ shown\ for\ reference\ only.}$
- The lead width as measured 0.36mm (0.014 inch) or greater above the seating plane, shall not exceed a maximum value of 0.61mm (0.024 inch).
- Controlling dimension: MILLIMETER. Converted inch dimensions are not necessarily exact.
- 8. This outline conforms to JEDEC publication MS-012-AA ISSUE C.