



KMZ10CM

Linear Magnetic Field Sensor

SPECIFICATIONS

- Magneto resistive sensor technology
- Linear signal output
- Over increased field range
- Very low hysteresis
- High sensitivity
- Substitutes KMZ10C / NXP

Due to its featured properties - high sensitivity and almost no hysteresis – the **KMZ10CM** sensor is used in a wide range of applications, like magnetic field measurement, revolution counters, proximity detection and position measurement

FEATURES

- Wheatstone bridge
- Passive output signal
- Linear signal output proportional to magnetic field strength
- 4 lead package for measurement of z direction

APPLICATIONS

Detection of small magnetic fields, as in:

- Contactless switch
- Contactless displacement measurement
- Current measurement
- Polarity detection of small magnetic fields

PERFORMANCE SPECIFICATIONS

Parameter	Symbol	Condition	Min	Тур	Max	Unit
A. Operating Limits 1)						
max. supply voltage	V _{CC,max}				10	V
operating temperature	Top		-40		+150	→C
storage temperature	T _{st}		-65		+165	→C
B. Sensor Specifications	(T = 25 °C ; I	H _x = 3 kA/m)				
supply voltage	Vcc			5	10	V
bridge resistance	R₀		1000	1400	1800	ū
offset voltage	Voff/Vcc	H _x =0	-1.5	0	+1.5	mV/V
sensitivity	S	note 2	1	1.2	2	(mV/V)/(kA/m)
hysteresis	V _{HYST}	note 3	-	-	100	μV/V
linearity deviation	FL	note 4	-	-	6.5	%
C. Sensor Specifications (T _{low} = 30 °C ; T _{high} = 80 °C ; H _X = 3 kA/m ; V _{CC} = 5 V)						
TC of sensitivity	TCS	note 5	-	- 0.35	-	%/K
TC of resistance	TCBR	note 6	-	+ 0.45	-	%/K
TC of offset	TCV _{off}	note 7,8, H _x =0	-4	0	+4	μV/V/K

- 1) Stress above one or more of the limiting values may cause permanent damage to the device. Exposure to limiting values for extended periods may affect device reliability.
- The sensitivity is defined as the average slope of characteristic between Hy=0 and 6 kA/m and Hx=3kA/m:

$$S \bullet \frac{V_0(H_y \bullet 6kA/m) \Re V_0(H_y \bullet 0)}{6*V_{CC}}$$

3) Hysteresis is defined as the difference between offset voltages measured without Hy-field after premagnetization by negative and positive Hy=±6 kA/m field:

$$V_{HYST} = V_0(H_1 \otimes_b H_0) \ \text{$N_0(\$H_1 \otimes_b H_0)$}; H_0 = 0; H_1 = 6\frac{kA}{m}; H_X = 3\frac{kA}{m}; V_{CC} = 5V$$

4) The linearity error is the deviation of output voltage measured at Hy=3 kA/m from the average of Hy=0 and 6 kA/m- output voltages, expressed as percentage of the output voltage difference measured between 0 and 6 kA/m:

$$FL = \frac{1}{2} \left. \frac{V_0(H_y - 3kA/m) \cdot (H_y - 0)}{V_0(H_y - 6kA/m) \cdot (H_y - 0)} \right| *100\%$$

5) The temperature coefficient of sensitivity is defined as the percentage change of the sensitivity per K referred to the value at $T_1 = -25$ °C; $T_2 = 0$ 0 operating temperature:

$$TCS = \frac{1}{(T_2 \Re T_1)} * \frac{S(T_2) \Re S(T_1)}{S(T_1)} * 100\%$$

The temperature coefficient of resistance is defined as the percentage change of the resistance per K referred to the value at $T_1 = -25$ °C; $T_2 =$ operating temperature:

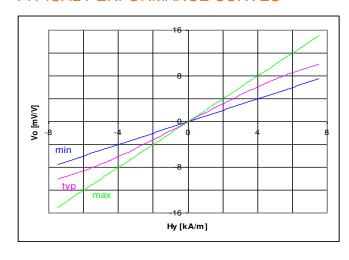
$$TCBR = \frac{1}{(T_2 \Re T_1)} * \frac{R(T_2) \Re R(T_1)}{R(T_1)} * 100\%$$

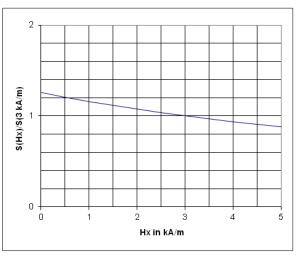
7) Temperature coefficient of offset voltage is defined as the voltage change per K expressed in $\mu V/V$:

$$TCV_{off} \bullet \frac{V_{off}(T_2) \Re V_{off}(T_1)}{(T_2 \Re T_1)}$$

8) Linear behaviour assumed

TYPICAL PERFORMANCE CURVES





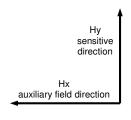
Typical output characteristic

Sensitivity as a function of auxiliary field strength

FUNCTION

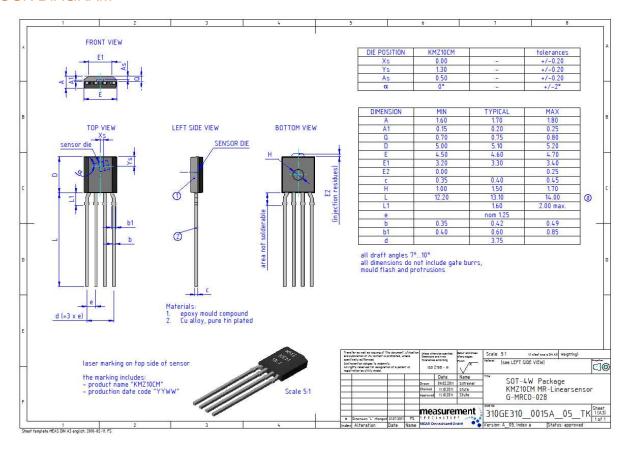
TERMINAL CONNECTIONS





Pin	Symbol	Function
1	+Vo	positive output voltage
2	GND	negative supply voltage
3	-Vo	negative output voltage
4	+Vcc	positive supply voltage

BLOCK DIAGRAM



ORDERING CODE

Product	Description	Part number		
KMZ10CM	KMZ10 CM Linear Field Sensor	G-MRCO-028		

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